



1. 设  $G(\vec{r}, \vec{r}')$  对  $\vec{r}$  作傅里叶变换为  $\tilde{G}(\vec{k}, \vec{r}')$

$$\text{则其逆变换为 } G(\vec{r}, \vec{r}') = \frac{1}{(2\pi)^3} \iiint \tilde{G}(\vec{k}, \vec{r}') \exp(i\vec{k} \cdot \vec{r}') d\vec{k}$$

$$= \frac{1}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \tilde{G}(\vec{k}, \vec{r}') \exp[i(k_x x + k_y y + k_z z)] dk_x dk_y dk_z$$

又有结论  $\mathcal{F}^3(\vec{x}) = \frac{1}{(2\pi)^3} \iiint \exp(i\vec{k} \cdot \vec{x}) d\vec{k} = \frac{1}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \exp[i(k_x x + k_y y + k_z z)] dk_x dk_y dk_z$   
其中设  $k'^2 = k_x^2 + k_y^2 + k_z^2$

将 ① ② 分别代入原方程得

$$\begin{aligned} & \frac{(\nabla^2 + k^2)}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \tilde{G}(\vec{k}, \vec{r}') \exp[i(k_x x + k_y y + k_z z)] dk_x dk_y dk_z \\ &= -\frac{1}{(2\pi)^3 \epsilon_0} \iiint \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] d\vec{k}' \end{aligned}$$

$$\Rightarrow \frac{1}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (\nabla^2 + k^2) \tilde{G}(\vec{k}, \vec{r}') \exp[i(k_x x + k_y y + k_z z)] dk_x dk_y dk_z$$
$$= -\frac{1}{(2\pi)^3 \epsilon_0} \iiint \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] d\vec{k}'$$

$$\Rightarrow \frac{1}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left\{ (-k_x^2 - k_y^2 - k_z^2) \tilde{G}(\vec{k}', \vec{r}') \exp[i(k_x x + k_y y + k_z z)] \right. \\ \left. + k^2 \tilde{G}(\vec{k}', \vec{r}') \exp[i(k_x x + k_y y + k_z z)] \right\} dk_x dk_y dk_z$$
$$= -\frac{1}{(2\pi)^3 \epsilon_0} \iiint \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] d\vec{k}'$$

$$\Rightarrow \frac{1}{(2\pi)^3} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (-k'^2 + k^2) \tilde{G}(\vec{k}', \vec{r}') \exp[i(k_x x + k_y y + k_z z)] dk_x dk_y dk_z$$
$$= -\frac{1}{(2\pi)^3 \epsilon_0} \iiint \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] d\vec{k}'$$

两边同时对  $\vec{r}'$  作傅里叶变换得

$$(-k'^2 + k^2) \tilde{G}(\vec{k}', \vec{r}') = -\frac{\exp(-i\vec{k} \cdot \vec{r}')}{\epsilon_0} \implies \tilde{G}(\vec{k}', \vec{r}') = -\frac{\exp(-i\vec{k} \cdot \vec{r}')}{\epsilon_0}$$

利用式 ① 逆变换

$$G(\vec{r}, \vec{r}') = \frac{i}{(2\pi)^3 \epsilon_0} \iiint \frac{\exp(-i\vec{k} \cdot \vec{r}')}{{k'}^2 - k^2} \exp(i\vec{k} \cdot \vec{r}') d\vec{k}'$$

以  $(\vec{r} - \vec{r}')$  方向为 Z 轴方向，转换到球坐标中

$$\begin{aligned} G(\vec{r}, \vec{r}') &= \frac{1}{(2\pi)^3 \epsilon_0} \int_0^{2\pi} \int_0^\pi \int_0^\pi \frac{\exp[i\vec{k} \cdot (\vec{r} - \vec{r}')]}}{{k'}^2 - k^2} k' \sin\theta dk' d\theta d\phi \\ &= \frac{1}{(2\pi)^3 \epsilon_0} \int_0^{2\pi} d\phi \int_0^\infty \frac{k'}{{k'}^2 - k^2} dk' \int_0^\pi \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] \cos\theta \sin\theta d\theta \\ &= \frac{1}{(2\pi)^2 \epsilon_0} \int_0^\infty \frac{k'}{{k'}^2 - k^2} dk' \int_0^\pi \exp[i\vec{k}' \cdot (\vec{r} - \vec{r}')] \cos\theta d\cos\theta \end{aligned}$$

$$\begin{aligned}
& t = \alpha \theta \\
& = \frac{1}{(2\pi)^2 \epsilon_0} \int_0^\infty \frac{k'^2}{k'^2 - k^2} dk' \int_{-1}^1 \exp(i k' |\vec{r} - \vec{r}'| t) \\
& = \frac{1}{(2\pi)^2 \epsilon_0} \int_0^\infty \frac{k'^2}{k'^2 - k^2} \frac{\exp(i k' |\vec{r} - \vec{r}'| t)}{i k' |\vec{r} - \vec{r}'|} dk' \\
& = \frac{1}{i(2\pi)^2 \epsilon_0 |\vec{r} - \vec{r}'|} \int_0^\infty \frac{k' [\exp(i k' |\vec{r} - \vec{r}'|) - \exp(-i k' |\vec{r} - \vec{r}'|)]}{k'^2 - k^2} dk' \\
& = \frac{1}{i(2\pi)^2 \epsilon_0 |\vec{r} - \vec{r}'|} \int_{-\infty}^{+\infty} \frac{k' \exp(i k' |\vec{r} - \vec{r}'|)}{k'^2 - k^2} dk \\
& = \frac{1}{i(2\pi)^2 \epsilon_0 |\vec{r} - \vec{r}'|} 2\pi i \operatorname{Res} \left[ \frac{k' \exp(i k' |\vec{r} - \vec{r}'|)}{k'^2 - k^2}, k \right] \text{(留数定理)} \\
& = \frac{1}{i(2\pi)^2 \epsilon_0 |\vec{r} - \vec{r}'|} 2\pi i \lim_{k \rightarrow k} \frac{k' \exp(i k' |\vec{r} - \vec{r}'|)}{k'^2 - k^2} (k' - k) \\
& = \frac{1}{i(2\pi)^2 \epsilon_0 |\vec{r} - \vec{r}'|} 2\pi i \frac{k \exp(i k' |\vec{r} - \vec{r}'|)}{k + k} \\
& = \frac{\exp(i k' |\vec{r} - \vec{r}'|)}{4\pi \epsilon_0 |\vec{r} - \vec{r}'|}
\end{aligned}$$

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✓ - 0 pts Correct

- 3 pts The answer is wrong

- 6 pts wrong

$$\begin{aligned}
2. \quad & \frac{1}{2}\pi i^{\nu+1} [J_\nu(ix) + iN_\nu(ix)] \\
&= \frac{\pi}{2} i^{\nu+1} \left[ J_\nu(ix) + i \frac{J_\nu(ix) \cos \nu\pi - J_{-\nu}(ix)}{\sin \nu\pi} \right] \\
&= \frac{\pi}{2} i^{\nu+1} \left[ J_\nu(ix) + \frac{J_\nu(ix) \cos \nu\pi - J_{-\nu}(ix)}{-i \sin \nu\pi} \right] \\
&= \frac{\pi}{2} i^{\nu+1} \frac{J_\nu(ix) \cos \nu\pi - i J_\nu(ix) \sin \nu\pi - J_{-\nu}(ix)}{-i \sin \nu\pi} \\
&= \frac{\pi}{2} i^{\nu+2} \frac{J_\nu(ix) e^{-i\nu\pi} - J_{-\nu}(ix)}{\sin \nu\pi} \\
&= \frac{\pi}{2} i^{\nu+2} \frac{J_\nu(ix) [e^{-i\nu\pi}]^\nu - J_\nu(ix)}{\sin \nu\pi} \\
&= \frac{\pi}{2} i^{\nu+2} \frac{J_\nu(ix) (-1)^\nu - J_\nu(ix)}{\sin \nu\pi} \\
&= \frac{\pi}{2} \frac{(-i)^\nu i^2 J_\nu(ix) - i^\nu i^2 J_{-\nu}(ix)}{\sin \nu\pi} \\
&= \frac{\pi}{2} \frac{i^\nu J_{-\nu}(ix) - (-i)^\nu J_\nu(ix)}{\sin \nu\pi}.
\end{aligned}$$

(根据第二类虚宗量贝塞尔函数定义)

$$\begin{aligned}
K_\nu(x) &\stackrel{\Delta}{=} \frac{\pi}{2} \frac{J_{-\nu}(x) - J_\nu(x)}{\sin \nu\pi} \\
&= \frac{\pi}{2} \frac{(-i)^{-\nu} J_{-\nu}(ix) - (-i)^\nu J_\nu(ix)}{\sin \nu\pi} \\
&= \frac{\pi}{2} \frac{i^\nu J_{-\nu}(ix) - (-i)^\nu J_\nu(ix)}{\sin \nu\pi}
\end{aligned}$$

$$\text{故 } \frac{1}{2}\pi i^{\nu+1} [J_\nu(ix) + iN_\nu(ix)] = K_\nu(x)$$

再根据 Hankel 函数定义  $H_\nu^{(0)}(x) \stackrel{\Delta}{=} J_\nu(x) + iN_\nu(x)$

$$\text{有 } K_\nu(x) = \frac{\pi}{2} i^{\nu+1} H_\nu^{(0)}(x) = \frac{\pi}{2} i^{\nu+1} [J_\nu(ix) + iN_\nu(ix)].$$

当  $\nu$  为整数  $n$  时, 取极限  $\lim_{n \rightarrow \infty} K_n(x) = \lim_{n \rightarrow \infty} \frac{\pi}{2} i^{n+1} H_n^{(0)}(x) = \lim_{n \rightarrow \infty} \frac{\pi}{2} i^{n+1} [J_n(ix) + iN_n(ix)]$

$$\text{得 } K_n(x) = \frac{\pi}{2} i^{n+1} H_n^{(0)}(x) = \frac{\pi}{2} i^{n+1} [J_n(ix) + iN_n(ix)].$$

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✓ - 0 pts Correct

- 10 pts blank/wrong

$$3. (1) \int x J_2(x) dx$$

利用递推公式  $J_2(x) = -J_0(x) + \frac{2}{x} J_1(x)$

$$\begin{aligned} \text{得 } \int x J_2(x) dx &= - \int x J_0(x) dx + 2 \int J_1(x) dx \\ &= -x J_1(x) - 2 J_0(x) \end{aligned}$$

$$(2) \int x^4 J_1(x) dx$$

$$\begin{aligned} \int x^4 J_1(x) dx &= \int x^2 [x^2 J_1(x)] dx = \int x^2 d[x^2 J_2(x)] \\ &= x^4 J_2(x) - 2 \int x^3 J_2(x) dx \\ &= x^4 J_2(x) - 2x^3 J_3(x). \end{aligned}$$

$$\text{又 } J_2(x) = \frac{2}{x} J_1(x) - J_0(x)$$

$$\text{得 } J_3(x) = \frac{4}{x} J_2(x) - J_1(x) = \frac{8}{x^2} J_1(x) - \frac{4}{x} J_0(x) - J_1(x)$$

$$\begin{aligned} \text{得 } \int x^4 J_1(x) dx &= x^4 \left[ \frac{2}{x} J_1(x) - J_0(x) \right] - 2x^3 \left[ \frac{8}{x^2} J_1(x) - \frac{4}{x} J_0(x) - J_1(x) \right] \\ &= (-x^4 + 8x^2) J_0(x) + 4(x^3 - 16x) J_1(x) \end{aligned}$$

$$(3) \int_0^R J_0(x) \cos x dx$$

$$\begin{aligned} \int_0^R J_0(x) \cos x dx &= x J_0(x) \cos x \Big|_0^R - \int_0^R x d[J_0(x) \cos x] \\ &= x J_0(x) \cos x \Big|_0^R - \int_0^R x [-J_1(x) \cos x - J_0(x) \sin x] dx \\ &= x J_0(x) \cos x \Big|_0^R + \int_0^R x J_1(x) \cos x dx + \int_0^R x J_0(x) \sin x dx \\ &= x J_0(x) \cos x \Big|_0^R + \int_0^R x J_1(x) \cos x dx + \int_0^R \sin x d[x J_1(x)] \\ &= x J_0(x) \cos x \Big|_0^R + \int_0^R x J_1(x) \cos x dx + x J_1(x) \sin x \Big|_0^R \\ &\quad - \int_0^R x J_1(x) d(\sin x) \\ &= x J_0(x) \cos x \Big|_0^R + \int_0^R x J_1(x) \cos x dx + x J_1(x) \sin x \Big|_0^R \\ &\quad - \int_0^R x J_1(x) \cos x dx \\ &= R J_0(R) \cos R + R J_1(R) \sin R \end{aligned}$$

$$(4) 3 J_0'(x) + 4 J_0''(x)$$

$$J_0'(x) = -J_1(x)$$

$$J_0''(x) = -\frac{d^2}{dx^2} J_1(x) = -\frac{1}{2} \frac{d}{dx} [J_0(x) - J_1(x)] = \frac{1}{2} J_1(x) + \frac{1}{2} \frac{d}{dx} [J_2(x)]$$

$$= \frac{1}{2} J_1(x) + \frac{1}{4} J_1(x) + \frac{1}{4} J_3(x) = \frac{3}{4} J_1(x) + \frac{1}{4} J_3(x)$$

$$\text{代入原式得 } 3J_0'(x) + 4J_0''(x) = J_3(x)$$

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✓ - 0 pts Correct

- 3 pts 1 the answer is wrong
- 3 pts 2 the answer is wrong
- 3 pts 3 the answer is wrong
- 3 pts 4 the answer is wrong

4.  $J_\nu(x)$  和  $J_{-\nu}(x)$  是贝塞尔方程  $\frac{d^2y}{dx^2} + \frac{1}{x} \frac{dy}{dx} + \frac{x^2 - \nu^2}{x^2} y = 0$  的两个线性独立解

解

$$\text{解 } \begin{cases} \frac{d^2 J_\nu(x)}{dx^2} + \frac{1}{x} \frac{d J_\nu(x)}{dx} + \frac{x^2 - \nu^2}{x^2} J_\nu(x) = 0 & ① \\ \frac{d^2 J_{-\nu}(x)}{dx^2} + \frac{1}{x} \frac{d J_{-\nu}(x)}{dx} + \frac{x^2 - \nu^2}{x^2} J_{-\nu}(x) = 0 & ② \end{cases}$$

$$① \cdot J_{-\nu}(x) - ② \cdot J_\nu(x) \stackrel{!}{=} 0$$

$$\begin{aligned} J_{-\nu}(x) \frac{d^2 J_\nu(x)}{dx^2} + \frac{1}{x} J_{-\nu}(x) \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d^2 J_{-\nu}(x)}{dx^2} - \frac{1}{x} J_\nu(x) \frac{d J_{-\nu}(x)}{dx} &= 0 \\ \Rightarrow [J_{-\nu}(x) \frac{d^2 J_\nu(x)}{dx^2} + \frac{d J_{-\nu}(x)}{dx} \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d^2 J_{-\nu}(x)}{dx^2} - \frac{d J_\nu(x)}{dx} \frac{d J_{-\nu}(x)}{dx}] \\ &+ \frac{1}{x} [J_{-\nu}(x) \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d J_{-\nu}(x)}{dx}] = 0 \\ \Rightarrow \frac{d}{dx} [J_\nu(x) \frac{d J_{-\nu}(x)}{dx} - J_{-\nu}(x) \frac{d J_\nu(x)}{dx}] + \frac{1}{x} [J_\nu(x) \frac{d J_{-\nu}(x)}{dx} - J_{-\nu}(x) \frac{d J_\nu(x)}{dx}] \\ &= 0 \end{aligned}$$

$$\Rightarrow \frac{d}{dx} W[J_\nu(x), J_{-\nu}(x)] = -\frac{1}{x} W[J_\nu(x), J_{-\nu}(x)].$$

$$\Rightarrow \ln W[J_\nu(x), J_{-\nu}(x)] = -\int \frac{1}{x} dx = -\ln x + B_1$$

$$\Rightarrow W[J_\nu(x), J_{-\nu}(x)] = e^{-\ln x + B_1} = \frac{C_1}{x}$$

$$\text{当 } x \rightarrow 0, W[J_\nu(x), J_{-\nu}(x)] = \begin{vmatrix} \frac{1}{\Gamma(\nu+1)} \left(\frac{x}{2}\right)^\nu & \frac{1}{\Gamma(-\nu+1)} \left(\frac{x}{2}\right)^{-\nu} \\ \frac{1}{2\Gamma(\nu)} \left(\frac{x}{2}\right)^\nu & \frac{1}{2\Gamma(-\nu)} \left(\frac{x}{2}\right)^{-\nu-1} \end{vmatrix}$$

$$= \frac{1}{x} \left[ \frac{1}{\Gamma(\nu+1)\Gamma(-\nu)} - \frac{1}{\Gamma(-\nu+1)\Gamma(\nu)} \right]$$

$$= \frac{1}{x} \left[ \frac{1}{\nu\Gamma(\nu)\Gamma(-\nu)} + \frac{1}{\nu\Gamma(-\nu)\Gamma(\nu)} \right]$$

$$= -\frac{2}{x} \frac{1}{\Gamma(\nu)\Gamma(-\nu)} = -\frac{2}{x} \frac{\sin \pi\nu}{\pi} (\text{利用公式})$$

$$\Rightarrow C_1 = -\frac{2\sin \pi\nu}{\pi}$$

$$\therefore W[J_\nu(x), J_{-\nu}(x)] = -\frac{2\sin \pi\nu}{\pi x}$$

同理,  $J_\nu(x)$  和  $Y_\nu(x)$  也是贝塞尔方程  $\frac{d^2y}{dx^2} + \frac{1}{x} \frac{dy}{dx} + \frac{x^2 - \nu^2}{x^2} y = 0$  的两个线性独立解.

$$\text{BP} \quad \begin{cases} \frac{d^2 J_\nu(x)}{dx^2} + \frac{1}{x} \frac{d J_\nu(x)}{dx} + \frac{x^2 - \nu^2}{x^2} J_\nu(x) = 0 & \textcircled{3} \\ \frac{d^2 Y_\nu(x)}{dx^2} + \frac{1}{x} \frac{d Y_\nu(x)}{dx} + \frac{x^2 - \nu^2}{x^2} Y_\nu(x) = 0 & \textcircled{4} \end{cases}$$

$$\textcircled{3} \cdot Y_\nu(x) - \textcircled{4} \cdot J_\nu(x) \stackrel{?}{=} 0$$

$$\begin{aligned} & Y_\nu(x) \frac{d^2 J_\nu(x)}{dx^2} + \frac{1}{x} Y_\nu(x) \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d^2 Y_\nu(x)}{dx^2} - \frac{1}{x} J_\nu(x) \frac{d Y_\nu(x)}{dx} = 0 \\ \Rightarrow & [Y_\nu(x) \frac{d^2 J_\nu(x)}{dx^2} + \frac{d Y_\nu(x)}{dx} \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d^2 Y_\nu(x)}{dx^2} - \frac{d J_\nu(x)}{dx} \frac{d Y_\nu(x)}{dx}] \\ & + \frac{1}{x} [Y_\nu(x) \frac{d J_\nu(x)}{dx} - J_\nu(x) \frac{d Y_\nu(x)}{dx}] = 0 \\ \Rightarrow & \frac{d}{dx} [J_\nu(x) \frac{d Y_\nu(x)}{dx} - Y_\nu(x) \frac{d J_\nu(x)}{dx}] + \frac{1}{x} [J_\nu(x) \frac{d Y_\nu(x)}{dx} - Y_\nu(x) \frac{d J_\nu(x)}{dx}] \end{aligned}$$

$\stackrel{=0}{\rightarrow}$

$$\Rightarrow \frac{d}{dx} W[J_\nu(x), Y_\nu(x)] = -\frac{1}{x} W[J_\nu(x), Y_\nu(x)]$$

$$\Rightarrow \ln W[J_\nu(x), Y_\nu(x)] = -\int \frac{1}{x} dx = -\ln x + B_2$$

$$\Rightarrow W[J_\nu(x), Y_\nu(x)] = e^{-\ln x + B_2} = \frac{C_2}{x}$$

$$\text{令 } x \rightarrow +\infty, W[J_\nu(x), Y_\nu(x)] = \left| \begin{array}{l} \frac{\sqrt{\frac{2}{\pi x}} \cos(x - \frac{\pi}{4} - \frac{\nu\pi}{2})}{-\sqrt{\frac{2}{\pi x}} \sin(x - \frac{\pi}{4} - \frac{\nu\pi}{2})} \quad \frac{\frac{\sqrt{2}}{\sqrt{\pi x}} \cos(x - \frac{\pi}{4} - \frac{\nu\pi}{2}) \cos \nu\pi}{-\frac{\sqrt{2}}{\sqrt{\pi x}} \sin(x - \frac{\pi}{4} + \frac{\nu\pi}{2})} \\ -\frac{\sqrt{\frac{2}{\pi x}} \sin(x - \frac{\pi}{4} + \frac{\nu\pi}{2})}{\sqrt{\frac{2}{\pi x}} \sin(x - \frac{\pi}{4} - \frac{\nu\pi}{2}) \cos \nu\pi} \quad \frac{\sin \nu\pi}{+\frac{\sqrt{2}}{\sqrt{\pi x}} \sin(x - \frac{\pi}{4} + \frac{\nu\pi}{2})} \end{array} \right|$$

$$= \frac{\frac{2}{\pi x} [\cos(x - \frac{\pi}{4} - \frac{\nu\pi}{2}) \sin(x - \frac{\pi}{4} + \frac{\nu\pi}{2}) - \sin(x - \frac{\pi}{4} - \frac{\nu\pi}{2}) \cos(x - \frac{\pi}{4} + \frac{\nu\pi}{2})]}{\sin \nu\pi}$$

$$= \frac{\frac{2}{\pi x} [\sin(x - \frac{\pi}{4} + \frac{\nu\pi}{2} - x + \frac{\pi}{4} + \frac{\nu\pi}{2})]}{\sin \nu\pi} = \frac{2}{\pi x}$$

$$\Rightarrow C_2 = \frac{2}{\pi}$$

$$\therefore W[J_\nu(x), Y_\nu(x)] = \frac{2}{\pi x}$$

$$(1) \int \frac{dx}{x J_\nu^2(x)} = \int \frac{\pi W[J_\nu(x), J_{-\nu}(x)]}{2 \sin \pi \nu J_\nu^2(x)} dx$$

$$= -\frac{\pi}{2 \sin \pi \nu} \int \frac{J_\nu(x) J'_\nu(x) - J'_\nu(x) J_\nu(x)}{J_\nu^2(x)} dx$$

$$= -\frac{\pi}{2 \sin \pi \nu} \int d \left[ \frac{J_\nu(x)}{J_\nu(x)} \right]$$

$$= -\frac{\pi J_{-\nu}(x)}{2 J_\nu(x) \sin \pi \nu} + C$$

$$(2) \int \frac{dx}{x Y_\nu^2(x)} = \int \frac{\pi W[J_\nu(x), Y_\nu(x)]}{2 Y_\nu^2(x)} dx$$

$$= -\frac{\pi}{2} \int \frac{Y_\nu(x) J'_\nu(x) - Y'_\nu(x) J_\nu(x)}{Y_\nu^2(x)} dx$$

$$= -\frac{\pi}{2} \int d \left[ \frac{J_\nu(x)}{Y_\nu(x)} \right]$$

$$= -\frac{\pi J_\nu(x)}{2 Y_\nu(x)} + C$$

$$(3) \int \frac{dx}{x J_\nu(x) Y_\nu(x)} = \int \frac{\pi W[J_\nu(x), Y_\nu(x)]}{2 J_\nu(x) Y_\nu(x)} dx$$

$$= \int \frac{\pi}{2} \frac{J_\nu(x) Y'_\nu(x) - J'_\nu(x) Y_\nu(x)}{J_\nu(x) Y_\nu(x)} dx$$

$$= \frac{\pi}{2} \left[ \int \frac{Y'_\nu(x)}{Y_\nu(x)} dx - \int \frac{J'_\nu(x)}{J_\nu(x)} dx \right]$$

$$= \frac{\pi}{2} \left[ \int \frac{d Y_\nu(x)}{Y_\nu(x)} - \int \frac{d J_\nu(x)}{J_\nu(x)} \right]$$

$$= \frac{\pi}{2} \ln \frac{Y_\nu(x)}{J_\nu(x)} + C$$

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✓ - 0 pts Correct

- 2 pts (1)wrong
- 2 pts (2)wrong
- 2 pts (3)wrong
- 9 pts blank/wrong

5. 方程两边同乘  $\frac{1}{z^{\alpha-2}}$  有

$$\frac{u''}{z^{\alpha-2}} + \frac{1-2\alpha}{z^{\alpha-1}} u' + [\beta^2 z^{2\alpha} + \frac{\alpha^2}{r^2 z^\alpha} - \frac{v^2}{z^\alpha}] u = 0$$

$$\Rightarrow \frac{1}{r^2} \frac{u''}{z^{\alpha-1}} + \frac{-r-2\alpha+1+r}{r^2} \frac{u'}{z^{\alpha-1}} + \frac{\alpha(r+\alpha)-\alpha r}{r^2 z^\alpha} u + [\beta^2 (z^r)^2 - v^2] \frac{u}{z^\alpha} = 0$$

$$\Rightarrow \frac{1}{r^2} \left[ \frac{u''}{z^{\alpha-2}} + (-r-2\alpha+1) \frac{u'}{z^{\alpha-1}} + \frac{\alpha(r+\alpha)}{z^\alpha} u \right] + \frac{1}{r z^{-1}} \left( \frac{u'}{z^\alpha} - \frac{\alpha u}{z^{\alpha+1}} \right) + [\beta^2 (z^r)^2 - v^2] \frac{u}{z^\alpha} = 0$$

其中  $\frac{1}{r^2} \left[ \frac{u''}{z^{\alpha-2}} + (-r-2\alpha+1) \frac{u'}{z^{\alpha-1}} + \frac{\alpha(r+\alpha)}{z^\alpha} u \right]$

$$= \frac{1}{r^2} \left[ \frac{u''}{z^{\alpha-2}} - (r+\alpha-1) \frac{u'}{z^{\alpha-1}} - \frac{\alpha u'}{z^{\alpha-1}} + \frac{\alpha(r+\alpha)}{z^\alpha} u \right].$$

$$= \frac{(z^r)^2}{r} \frac{1}{r z^{r-1}} \left[ \frac{u''}{z^{r+\alpha-1}} - (r+\alpha-1) \frac{u'}{z^{r+\alpha}} - \frac{\alpha u'}{z^{r+\alpha}} + \frac{\alpha(r+\alpha)}{z^{r+\alpha+1}} u \right].$$

$$= \frac{(z^r)^2}{r} \frac{1}{\frac{d(z^r)}{dz}} \frac{d}{dz} \left[ \frac{u'}{z^{r+\alpha-1}} - \frac{\alpha u}{z^{r+\alpha}} \right]$$

$$= \frac{(z^r)^2}{r} \frac{d}{dz} \left[ \frac{1}{\frac{d(z^r)}{dz}} \frac{d}{dz} \left( \frac{u}{z^\alpha} \right) \right]$$

$$= (z^r)^2 \frac{d^2}{(dz^r)^2} \left( \frac{u}{z^\alpha} \right) \quad ①$$

$$\frac{1}{r z^{r-1}} \left( \frac{u'}{z^\alpha} - \frac{\alpha u}{z^{\alpha+1}} \right) = \frac{1}{\frac{d(z^r)}{dz}} \frac{d}{dz} \left( \frac{u}{z^\alpha} \right) = \frac{d}{dz} \left( \frac{u}{z^\alpha} \right) \quad ②$$

将 ① ② 同代入方程中得

$$(z^r)^2 \frac{d^2}{(dz^r)^2} \left( \frac{u}{z^\alpha} \right) + \frac{d}{dz} \left( \frac{u}{z^\alpha} \right) + [\beta^2 (z^r)^2 - v^2] \frac{u}{z^\alpha} = 0$$

设  $x = z^r$ ,  $y = \frac{u}{z^\alpha}$ , 有

$$x^2 \frac{d^2}{dx^2} y + \frac{d}{dx} y + [\beta^2 x^2 - v^2] y = 0$$

这是一个参数形式的贝塞尔函数，其通解为：

$$y = C_1 J_\nu(\beta x) + C_2 Y_\nu(\beta x) \quad ③$$

将  $x = z^r$ ,  $y = \frac{u}{z^\alpha}$  回代入 ③ 中得到原函数和通解:

$$\begin{aligned}\frac{u}{z^\alpha} &= C_1 J_\nu(\beta z^r) + C_2 Y_\nu(\beta z^r) \\ \Rightarrow u &= C_1 z^\alpha J_\nu(\beta z^r) + C_2 z^\alpha Y_\nu(\beta z^r)\end{aligned}$$

1.  $u'' + az^b u = 0$

在此方程中  $\begin{cases} 1 - 2\alpha = 0 \\ (\beta r)^2 = 1 \\ (z^{r-1})^2 = z^b \\ \alpha^2 - r^2 \nu = 0 \end{cases} \Rightarrow \begin{cases} \alpha = \frac{1}{2} \\ r = \frac{1}{b+1} \\ \beta = \frac{2}{b+1} \\ \nu = \frac{1}{b+1} \end{cases}$

故其通解为  $u = C_1 z^{\frac{1}{2}} J_{\frac{1}{b+1}}\left(\frac{2}{b+1} z^{\frac{b+1}{2}}\right) + C_2 z^{\frac{1}{2}} Y_{\frac{1}{b+1}}\left(\frac{2}{b+1} z^{\frac{b+1}{2}}\right)$

2.  $zu'' - 3u' + zu = 0$

$$\Rightarrow u'' - \frac{3}{2}u' + u = 0$$

在此方程中  $\begin{cases} 1 - 2\alpha = -3 \\ (\beta r)^2 = 1 \\ (z^{r-1})^2 = z \\ \alpha^2 - r^2 \nu = 0 \end{cases} \Rightarrow \begin{cases} \alpha = 2 \\ r = \frac{3}{2} \\ \beta = \frac{2}{3} \\ \nu = \frac{16}{9} \end{cases}$

故其通解为  $u = C_1 z^2 J_{\frac{16}{9}}\left(\frac{2}{3} z^{\frac{3}{2}}\right) + C_2 z^2 Y_{\frac{16}{9}}\left(\frac{2}{3} z^{\frac{3}{2}}\right)$

5  10 / 10

✓ - **0 pts** Correct

- **3 pts** (1) wrong

- **3 pts** (2) wrong

- **10 pts** blank/wrong

6. 分离变量  $U(P, t) = R(P)T(t)$

代入原方程得  $\frac{\partial T}{kT \partial t} = \frac{1}{PR} \frac{\partial}{\partial P} (P \frac{\partial R}{\partial P}) = -\lambda^2$

其中入是分离常数

$$\Rightarrow \begin{cases} T' + K\lambda^2 T = 0 & ① \\ \frac{\partial^2 R}{\partial P^2} + \frac{1}{P} \frac{\partial R}{\partial P} + \lambda^2 R = 0 & ② \end{cases}$$

由①得  $T(t) = C e^{-K\lambda^2 t}$

②为0阶贝塞尔方程，其通解为

$$R(P) = A J_0(\lambda P) + B Y_0(\lambda P)$$

$\because U|_{P=0}$  有界而  $Y_0(0)$  无界

$$\therefore B=0 \quad R(P)=A J_0(\lambda P).$$

$$\therefore \frac{\partial U}{\partial P}|_{P=a} = T \frac{\partial R}{\partial P}|_{P=a} = 0 \Rightarrow \frac{\partial J_0(\lambda P)}{\partial P}|_{P=a} = 0$$

$\therefore \lambda a = \mu'_m$  是  $J'_0(x)$  的第  $m+1$  个零点（其实也是  $J_1(x)$  的零点， $\mu'_0 = 0$ ）

$$\therefore \lambda a = \mu'_m \text{ 是 } J'_0(x) \text{ 的第 } m+1 \text{ 个零点}$$

综上：方程本征解为  $U_m(P, t) = A_m J_0(\mu'_m \frac{P}{a}) e^{-K\lambda^2 t}$

一般解为  $U(P, t) = \sum_{m=0}^{\infty} A_m J_0(\mu'_m \frac{P}{a}) e^{-K\lambda^2 t}$

利用初值条件  $U|_{t=0} = U_0(1 - \frac{P^2}{a^2})$

$$U_0(1 - \frac{P^2}{a^2}) = \sum_{m=0}^{\infty} A_m J_0(\mu'_m \frac{P}{a}) = A_0 + \sum_{m=1}^{\infty} A_m J_0(\mu'_m \frac{P}{a})$$

这表明  $A_m$  是  $U_0(1 - \frac{P^2}{a^2})$  与  $J_0(\mu'_m \frac{P}{a})$  在区间  $[0, a]$  上的内积

$$A_0 = \frac{2}{a^2 J_0^2(\mu'_0)} \int_0^a P U_0(1 - \frac{P^2}{a^2}) J_0(\mu'_0 \frac{P}{a}) dP$$

$$= \frac{2 U_0}{a^2} \int_0^a (P - \frac{P^3}{a^2}) dP = \frac{U_0}{2}$$

$$A_m = \frac{2}{a^2 J_0^2(\mu'_m)} \int_0^a P U_0(1 - \frac{P^2}{a^2}) J_0(\mu'_m \frac{P}{a}) dP$$

$$= \frac{2 U_0}{a^2 J_0^2(\mu'_m)} \left[ \int_0^a P J_0(\mu'_m \frac{P}{a}) dP - \int_0^a \frac{P^3}{a^2} J_0(\mu'_m \frac{P}{a}) dP \right]$$

$$= \frac{2 U_0}{a^2 J_0^2(\mu'_m)} \left\{ \frac{a}{\mu'_m} \int_0^a d \left[ P J_1(\mu'_m \frac{P}{a}) \right] - \frac{1}{a \mu'_m} \int_0^a P^2 d \left[ P J_1(\mu'_m \frac{P}{a}) \right] \right\}$$

$$= \frac{2 U_0}{a^2 \mu'_m J_0^2(\mu'_m)} \left\{ a P J_1(\mu'_m \frac{P}{a}) \Big|_0^a - \frac{P^3}{a} J_1(\mu'_m \frac{P}{a}) \Big|_0^a + \frac{1}{a} \int_0^a P J_1(\mu'_m \frac{P}{a}) dP \right\}$$

$$\begin{aligned}
 &= \frac{4U_0}{\alpha^3 J_0^2(\alpha)} \int_0^\alpha \rho^2 J_1(\alpha \cdot \frac{\rho}{\alpha}) d\rho \\
 &= \frac{4U_0}{\alpha^2 J_0^2(\alpha)} \int_0^\alpha d[\rho J_2(\alpha \cdot \frac{\rho}{\alpha})] \\
 &= \frac{4U_0}{\alpha^2 J_0^2(\alpha)} \left. \rho^2 J_2(\alpha \cdot \frac{\rho}{\alpha}) \right|_0^\alpha \\
 &= \frac{4U_0 J_2(\alpha)}{J_0^2(\alpha)}
 \end{aligned}$$

根据递推公式  $J_0(x) + J_2(x) = \frac{2}{x} J_1(x)$ .  $\Rightarrow J_2(\alpha) = \frac{2}{\alpha} J_1(\alpha) - J_0(\alpha)$

$$= -J_0(\alpha)$$

$$\therefore A_m = -\frac{4U_0}{J_0^2(\alpha)}$$

综b: 杆体内温度分布与变化为

$$U = \frac{U_0}{2} - 4U_0 \sum_{m=1}^{\infty} \frac{1}{J_0^2(\alpha)} J_0(\alpha \cdot \frac{\rho}{\alpha}) e^{-K(\frac{\rho}{\alpha})^2 t}$$

问时间足够长时杆体达到稳定温度  $\lim_{t \rightarrow +\infty} U = \frac{U_0}{2}$

6 10 / 10

✓ - 0 pts Correct

- 3 pts the answer is wrong

$$7. \begin{cases} \frac{1}{P} \frac{\partial}{\partial P} (P \frac{\partial U}{\partial P}) + \frac{\partial^2 U}{\partial Z^2} = 0 \\ U|_{Z=0} = 0, \quad U|_{Z=h} = 0 \\ U|_{P=0} \text{ 为界}, \quad U|_{P=a} = U_0 \sin(2\pi \frac{Z}{h}) \end{cases}$$

分离变量，设  $U(P, Z) = R(P)Z(Z)$   
代入原方程得  $-\frac{Z''}{Z} = \frac{R'' + \frac{1}{P}R'}{R} = \lambda^2$

$$\Rightarrow \begin{cases} Z'' + \lambda^2 Z = 0 & ① \\ R'' + \frac{1}{P}R' - \lambda^2 R = 0 & ② \end{cases}$$

由①得  $Z(Z) = C \sin(\lambda Z) + D \cos(\lambda Z)$

由边界条件  $U|_{Z=0} = 0$  得  $D = 0$

由边界条件  $U|_{Z=h} = 0$  得  $\lambda_n = \frac{n\pi}{h}$   $\Rightarrow Z(Z) = C \sin(\frac{n\pi}{h} Z)$

②为 ODE 的复数解，其通解为

$$R(P) = A_0 I_0(\lambda P) + B K_0(\lambda P)$$

$\because U|_{P=0}$  为界而  $K_0(0)$  无界

$$\therefore B = 0 \quad R(P) = A_0 I_0(\lambda P) = A_0 I_0\left(\frac{n\pi}{h} P\right)$$

故原方程的本征解为  $u_n(P, Z) = A_n \sin\left(\frac{n\pi}{h} Z\right) I_0\left(\frac{n\pi}{h} P\right)$

-般解为  $U(P, Z) = \sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi}{h} Z\right) I_0\left(\frac{n\pi}{h} P\right)$ .

利用边界条件  $U|_{P=a} = U_0 \sin(2\pi \frac{Z}{h})$

$$\sum_{n=1}^{\infty} A_n \sin\left(\frac{n\pi}{h} Z\right) I_0\left(\frac{n\pi a}{h}\right) = U_0 \sin(2\pi \frac{Z}{h}).$$

$$\Rightarrow A_2 = \frac{U_0}{I_0\left(\frac{2\pi a}{h}\right)}$$

$$A_n = 0 \quad (n \neq 2).$$

$$\text{故 } U(P, Z) = \frac{U_0}{I_0\left(\frac{2\pi a}{h}\right)} \boxed{\sin\left(\frac{n\pi}{h} Z\right) I_0\left(\frac{n\pi}{h} P\right)}$$

7 8 / 10

- **0 pts** Correct
- ✓ - **2 pts** little mistake
- **5 pts** Mess
- **10 pts** No answer

$$8. \text{ Rodrigues' formula: } P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l$$

$$\begin{aligned} \int_{-1}^1 (1+x)^k P_l(x) dx &= \int_{-1}^1 (1+x)^k \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l dx \\ &= \frac{1}{2^l l!} \int_{-1}^1 (1+x)^k d \left[ \frac{d^{l-1}}{dx^{l-1}} (x^2 - 1)^l \right] \\ &= \left[ \frac{1}{2^l l!} (1+x)^k \frac{d^{l-1}}{dx^{l-1}} (x^2 - 1)^l \right] \Big|_{-1}^1 - \frac{1}{2^l l!} \int_{-1}^1 \frac{d^{l-1}}{dx^{l-1}} [(x^2 - 1)^l] d(1+x)^k \end{aligned}$$

(由于  $\frac{d^{l-1}}{dx^{l-1}} (x^2 - 1)^l$  中含有  $(x^2 - 1)^l$ , 故第一项为 0)

$$= -\frac{k}{2^l l!} \int_{-1}^1 (1+x)^{k-1} \frac{d^{l-1}}{dx^{l-1}} (x^2 - 1)^l dx$$

$$=(-1)^l \frac{k!}{2^l l! (k-l)!} \int_{-1}^1 (1+x)^{k-l} (x^2 - 1)^l dx$$

$$=\frac{k!}{2^l l! (k-l)!} \int_{-1}^1 (1+x)^k (1-x)^l dx$$

$$t = \frac{x+1}{2} \quad \Rightarrow \quad \frac{k!}{2^l l! (k-l)!} \int_0^1 (2t)^k (2-2t)^l d(2t-1)$$

$$=\frac{2^{k+1} k!}{l! (k-l)!} \int_0^1 t^{(k+1)-1} (1-t)^{(l+1)-1} dt$$

$$=\frac{2^{k+1} k!}{l! (k-l)!} B(k+1, l+1)$$

Beta 函数

$$=\frac{2^{k+1} k!}{l! (k-l)!} \frac{\Gamma(k+1) \Gamma(l+1)}{\Gamma(k+l+2)}$$

$$=\frac{2^{k+1} k!}{l! (k-l)!} \frac{k! l!}{(k+l+1)!}$$

$$=\frac{2^{k+1} (k!)^2}{(k-l)! (k+l+1)!}$$

$$\begin{aligned} \text{当 } k < l \text{ 时} \quad \int_{-1}^1 (1+x)^k P_l(x) dx &= (-1)^l \frac{k!}{2^l l! (k-l)!} \int_{-1}^1 \frac{d^l}{dx^l} [(1+x)^k] (x^2 - 1)^l dx \\ &= 0 \end{aligned}$$

8 100 10 / 10

✓ - 0 pts Correct

- 4 pts Not attempted

- 10 pts No right answer

$$9. \begin{cases} \nabla^2 u = 0, a < r < b \\ u|_{r=a} = u_0, u|_{r=b} = u_0 \cos^2 \theta \end{cases}$$

拉普拉斯方程在轴对称条件下的一般解法.

$$u(r, \theta) = \sum_{l=0}^{\infty} (A_l r^l + \frac{B_l}{r^{l+1}}) P_l(\cos \theta)$$

利用边界条件:

$$\begin{cases} u|_{r=a} = \sum_{l=0}^{\infty} (A_l a^l + \frac{B_l}{a^{l+1}}) P_l(\cos \theta) = u_0 = u_0 P_0(\cos \theta) + 0 \cdot P_2(\cos \theta) \\ u|_{r=b} = \sum_{l=0}^{\infty} (A_l b^l + \frac{B_l}{b^{l+1}}) P_l(\cos \theta) = u_0 \cos^2 \theta = \frac{1}{3} u_0 P_0(\cos \theta) + \frac{2}{3} u_0 P_2(\cos \theta) \end{cases}$$

$$\xrightarrow{\text{比较系数}} \left\{ \begin{array}{l} A_0 + \frac{B_0}{a} = u_0 \\ A_0 + \frac{B_0}{b} = \frac{1}{3} u_0 \\ A_2 a^2 + \frac{B_2}{a^3} = 0 \\ A_2 b^2 + \frac{B_2}{b^3} = \frac{2}{3} u_0 \\ A_l = 0, B_l = 0 \quad (l \neq 0, l \neq 2) \end{array} \right. \Rightarrow \left\{ \begin{array}{l} A_0 = \frac{(-3a+b)u_0}{3(b-a)} \\ B_0 = \frac{2abu_0}{3(b-a)} \\ A_2 = \frac{2b^3u_0}{3(b^5-a^5)} \\ B_2 = -\frac{2a^5b^3u_0}{3(b^5-a^5)} \\ A_l = 0, B_l = 0 \quad (l \neq 0, l \neq 2) \end{array} \right.$$

$$\therefore u(r, \theta) = \frac{(-3a+b)u_0}{3(b-a)} + \frac{2abu_0}{3(b-a)r} + \frac{2a^5b^3u_0}{3(b^5-a^5)} \left[ \left( \frac{r}{a} \right)^2 - \left( \frac{a}{r} \right)^2 \right] P_2(\cos \theta)$$

9  10 / 10

✓ - 0 pts Correct

- 2 pts calculate mistake

- 10 pts No answer

$$\begin{aligned}
 10. (1) & (\sin\theta - 2\cos^2\theta)\cos^2\varphi \\
 &= \frac{1}{2}(\sin\theta - 2\cos^2\theta) + \frac{1}{2}(\sin\theta - 2\cos^2\theta)\cos^2\varphi \\
 &= \frac{1}{2}\cos\theta - 2\cos^2\theta + \frac{1}{2}(\sin\theta - 2\cos^2\theta)(e^{2i\varphi} + e^{-2i\varphi})
 \end{aligned}$$

设  $\sin\theta - 2\cos^2\theta = \sum_{l=0}^{\infty} A_l P_l(\cos\theta)$

其中  $A_l = \frac{2l+1}{2} \int_{-1}^1 (\sin\theta - 2\cos^2\theta) P_l(\cos\theta) d\cos\theta$

当  $l$  为偶数,  $A_l = -(2l+1) \int_{-1}^1 \cos^2\theta P_l(\cos\theta) d\cos\theta$

$$\begin{aligned}
 &= -(2l+1) \int_{-1}^1 x^2 P_l(x) dx \\
 &= -[2l+1] \int_{-1}^1 \left[ \frac{1}{3} P_0(x) + \frac{1}{5} P_2(x) \right] P_l(x) dx \\
 &= \begin{cases} -\frac{2}{3}, & l=0 \\ -\frac{4}{3}, & l=2 \\ 0, & \text{otherwise} \end{cases}
 \end{aligned}$$

当  $l$  为奇数,  $A_l = \frac{2l+1}{2} \int_{-1}^1 \sin\theta P_l(\cos\theta) d\cos\theta$

$$= (2l+1) \int_{-1}^1 \sqrt{1-x^2} P_l(x) dx$$

设  $\sin\theta - 2\cos^2\theta = \sum_{l=0}^{\infty} B_l P_l^2(\cos\theta)$

其中  $B_l = \frac{2l+1}{2} \frac{(l+2)!}{(l-2)!} \int_{-1}^1 (\sin\theta - 2\cos^2\theta) P_l^2(\cos\theta) d\cos\theta$

当  $l$  为偶数,  $B_l = -(2l+1) \frac{(l+2)!}{(l-2)!} \int_{-1}^1 \cos^2\theta P_l^2(\cos\theta) d\cos\theta$

$$= -(2l+1) \frac{(l+2)!}{(l-2)!} \int_{-1}^1 x^2 P_l^2(x) dx$$

当  $l$  为奇数,  $B_l = \frac{2l+1}{2} \frac{(l+2)!}{(l-2)!} \int_{-1}^1 \sin\theta P_l^2(\cos\theta) d\cos\theta$

$$= (2l+1) \frac{(l+2)!}{(l-2)!} \int_{-1}^1 \sqrt{1-x^2} P_l^2(x) dx$$

$$\therefore (\sin\theta - 2\cos^2\theta) \cos^2\varphi = \frac{1}{2} \sum_{l=0}^{\infty} \sqrt{\frac{4\pi}{2l+1}} A_l Y_l^0(\theta, \varphi) + \frac{1}{2} \sum_{l=0}^{\infty} \sqrt{\frac{4\pi}{2l+1}} B_l [Y_l^2(\theta, \varphi) + Y_l^{-2}(\theta, \varphi)]$$

其中  $A_l = \begin{cases} -\frac{2}{3}, & l=0 \\ -\frac{4}{3}, & l=2 \\ 0, & l \text{ 为偶数, } l=0, 2 \end{cases}$

$(2l+1) \int_{-1}^1 \sqrt{1-x^2} P_l(x) dx$ ,  $l$  为奇数.

$$B_l = \begin{cases} -(2l+1) \frac{(l+2)!}{(l-2)!} \int_{-1}^1 x^2 P_l^2(x) dx, & l \text{ 为偶数} \end{cases}$$

$$\begin{cases} (2l+1) \frac{(l+2)!}{(l-2)!} \int_{-1}^1 \sqrt{1-x^2} P_l^2(x) dx, & l \text{ 为奇数} \end{cases}$$

$$(2) (1 - 2\sin\theta)\cos\theta \cos\varphi$$

$$= \frac{1}{2}(1 - 2\sin\theta)\cos\theta(e^{i\varphi} + e^{-i\varphi})$$

$$\text{设 } (1 - 2\sin\theta)\cos\theta = \sum_{l=0}^{\infty} C_l P_l'(\cos\theta).$$

$$\text{其中 } C_l = \frac{2(l+1)}{2} \frac{(l+1)!}{(l-1)!} \int_{-1}^1 (1 - 2\sin\theta)\cos\theta P_l'(\cos\theta) d\cos\theta$$

$$\text{当 } l \text{ 为奇数, } C_l = -(2l+1) \frac{(l+1)!}{(l-1)!} \int_{-1}^1 \sin\theta \cos\theta P_l'(\cos\theta) d\cos\theta.$$

$$= -2(2l+1) \frac{(l+1)!}{(l-1)!} \int_0^1 \sqrt{1-x^2} x P_l'(x) dx.$$

$$\text{当 } l \text{ 为偶数, } C_l = \frac{2(l+1)}{2} \frac{(l+1)!}{(l-1)!} \int_{-1}^1 \cos\theta P_l'(\cos\theta) d\cos\theta$$

$$= (2l+1) \frac{(l+1)!}{(l-1)!} \int_0^1 x P_l'(x) dx.$$

$$\therefore (1 - 2\sin\theta)\cos\theta \cos\varphi = \frac{1}{2} \sum_{l=0}^{\infty} \sqrt{\frac{4\pi}{2l+1}} \frac{(l+1)!}{(l-1)!} C_l [Y_l'(x) + Y_l''(x)]$$

$$\text{其中 } C_l = \begin{cases} -2(2l+1) \frac{(l+1)!}{(l-1)!} \int_0^1 \sqrt{1-x^2} x P_l'(x) dx, & l \text{ 为奇数} \\ (2l+1) \frac{(l+1)!}{(l-1)!} \int_0^1 x P_l'(x) dx, & l \text{ 为偶数} \end{cases}$$

10  10 / 10

✓ - **0 pts** Correct

- **10 pts** No answer

- **4 pts** Not perfect/Half

$$11. \begin{cases} \nabla^2 u = A + Br^2 \sin^2 \theta \cos \varphi \\ u|_{r=a} = 0 \end{cases}$$

設方程通解為  $u(r, \theta, \varphi) = \sum_{l=0}^{\infty} \sum_{m=0}^l P_l^m(\cos \theta) [R_{l,m}(r) \sin m\varphi + S_{l,m}(r) \cos m\varphi]$

$$\begin{aligned} \text{代入方程得 } & \sum_{l=0}^{\infty} \sum_{m=0}^l \frac{1}{r^2} \left[ \frac{d}{dr} \left( r^2 \frac{dR_{l,m}}{dr} \right) - l(l+1) R_{l,m} \right] P_l^m(\cos \theta) \sin m\varphi \\ & + \sum_{l=0}^{\infty} \sum_{m=0}^l \frac{1}{r^2} \left[ \frac{d}{dr} \left( r^2 \frac{dS_{l,m}}{dr} \right) - l(l+1) S_{l,m} \right] P_l^m(\cos \theta) \cos m\varphi \\ & = A + Br^2 \sin^2 \theta \cos \varphi = AP_0^0(\cos \theta) - \frac{2}{3} Br^2 P_2^1(\cos \theta) \cos \varphi. \end{aligned}$$

$$\text{代入系数得 } \frac{d}{dr} \left( r^2 \frac{dR_{l,m}}{dr} \right) - l(l+1) R_{l,m} = 0.$$

$$\frac{d}{dr} \left( r^2 \frac{dS_{0,0}}{dr} \right) = Ar^2$$

$$\frac{d}{dr} \left( r^2 \frac{dS_{2,1}}{dr} \right) - 6S_{2,1} = -\frac{2}{3} Br^4$$

$$\frac{d}{dr} \left( r^2 \frac{dS_{l,m}}{dr} \right) - l(l+1) S_{l,m} = 0 \quad (\text{除 } (l,m)=(0,0) \text{ 及 } (l,m)=(2,1) \text{ 外})$$

由边界条件  $R_{l,m}(a) = 0, S_{l,m}(a) = 0$

由  $u|_{r=a} = 0$ ,  $R_{l,m}(0) \neq 0, S_{l,m}(0) \neq 0$ .

$$\therefore R_{l,m}(r) = 0.$$

$$S_{0,0}(r) = \frac{A}{2} (r^2 - a^2)$$

$$S_{2,1}(r) = \frac{Br^2}{24} (a^2 - r^2)$$

$$S_{l,m}(r) = 0 \quad (\text{除 } (l,m)=(0,0) \text{ 及 } (l,m)=(2,1) \text{ 外})$$

$$\begin{aligned} \therefore u(r, \theta, \varphi) &= \frac{A}{2} (r^2 - a^2) + \frac{B}{24} r^4 (a^2 - r^2) P_2^1(\cos \theta) \cos \varphi \\ &= \frac{A}{6} (r^2 - a^2) + \frac{B}{72} r^4 (a^2 - r^2) \sin^2 \theta \cos \varphi. \end{aligned}$$

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✓ - 0 pts Correct

- 2 pts calculate incorrect
- 6 pts method incorrect
- 10 pts No answer /Not right at all