```
二阶偏微分方程标准形式变换A(x,y) rac{\partial^2 u}{\partial x^2} + 2B rac{\partial^2 u}{\partial x \partial y} + C rac{\partial^2 u}{\partial y^2} + D rac{\partial u}{\partial x} + E rac{\partial u}{\partial y} + Fu = G
              偏微分方程的定解问题
                                                                                                                                                                                                                                                                                                           为使a, c = 0. \xi和\eta需満足A(\frac{\partial W}{\partial x})^2 + 2B\frac{\partial W}{\partial x}\frac{\partial W}{\partial y} + C(\frac{\partial W}{\partial y})^2 = 0令 \frac{dy}{dx} = -\frac{\partial W}{\partial x}/\frac{\partial W}{\partial y} 得
 常微分方程 含一元未知函数u=u(x),x及其若干阶导数F(x,u,\frac{du}{dx},...,\frac{d^nu}{dx^n})=0
                                                                                                                                                                                                                                                                                                        偏微分方程 含多元未知函u(x_1,...,x_n)及其若干阶偏导F(x,u,\frac{\partial u}{\partial x_1})
                                                                                                                                                                                                                                                                                                                 \frac{\partial^m u}{\partial x_1^{m_1} \cdots \partial x_n^{m_n}}) = 0,其中m = \sum_{i=1}^n m_i-阶数
 线性偏微分方程与未知函数有关的部分仅是u及其偏导数的线性组合, 否则(如含
                                                                                                                                                                                                                                                                                                                                               a = A(\frac{\partial \xi}{\partial x})^2 + 2B\frac{\partial \xi}{\partial x}\frac{\partial \xi}{\partial y} + C(\frac{\partial \xi}{\partial y})^2
b = A\frac{\partial \xi}{\partial x}\frac{\partial \eta}{\partial x} + B(\frac{\partial \xi}{\partial x}\frac{\partial \eta}{\partial y} + \frac{\partial \xi}{\partial y}\frac{\partial \eta}{\partial y}) + C\frac{\partial \xi}{\partial y}\frac{\partial \eta}{\partial y}
c = A(\frac{\partial \eta}{\partial x})^2 + 2B\frac{\partial \eta}{\partial x}\frac{\partial \eta}{\partial y} + C(\frac{\partial \eta}{\partial y})^2
 有u_x^2,\cos u)为非线性偏微分方程,仅含x的项(\mathrm{mcos}\,x)不是非线性项,非线性项或造成混沌
                                                                                            非齐次方程 含对u运算之外的驱动项f(x,t)或非零自由项
 齐次方程 仅含对u的各种运算
d = A\frac{\partial^{2}\xi}{\partial x^{2}} + 2B\frac{\partial^{2}\xi}{\partial x\partial y} + C\frac{\partial^{2}\xi}{\partial y^{2}} + D\frac{\partial\xi}{\partial x} + E\frac{\partial\xi}{\partial y}
e = A\frac{\partial^{2}\eta}{\partial x^{2}} + 2B\frac{\partial^{2}\eta}{\partial x\partial y} + C\frac{\partial^{2}\eta}{\partial y^{2}} + D\frac{\partial\eta}{\partial x} + E\frac{\partial\eta}{\partial y}
           水平方向牛二-T_a\cos\alpha_a+T_b\cos\alpha_b=0 其中\sin\alpha=\frac{\partial u}{\partial x}, \Delta s=b-a, T_a=T_b=T_0
          \implies \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x, t)
          其中a^2 = \frac{T_0}{\rho}, f(x,t) = \frac{f_0(x,t)}{\rho}, u(x,t)—时刻t弦上x处振幅, T_0—张力, \rho—线密度, f_0—外力线密度
 f=0—无外力自由振动 f=const—常外力强迫振动 f=-2brac{\partial u}{\partial t}, 2b=rac{k}{
ho},k—阻力密度与速度之比—阻尼振动
                                                                                                                                                                                                                                                                                                                         得双曲形方程 \frac{\partial^2 u}{\partial \xi \partial \eta} = -\frac{1}{2b} \left( d \frac{\partial u}{\partial \xi} + e \frac{\partial u}{\partial \eta} + f u - g \right)
               \frac{\partial^2 u}{\partial t^2} = \left\{ \begin{array}{ll} a^2 (\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}) + f(x,y,t) & -2 \text{$\mathfrak{t}$} (\text{如膜的振动}) \\ \frac{\partial^2 u}{\partial t^2} = a^2 \nabla^2 u + f(x,y,z,t) & -2 \text{$\mathfrak{t}$} (\text{如空气中的声波}) \end{array} \right.
                                                                                                                                                                                                                                                                                                            若\Delta = 0,解得特征线\sqrt{A} \frac{\partial \xi}{\partial x} + \sqrt{C} \frac{\partial \xi}{\partial y} = 0,取\eta使\frac{\partial (\xi, \eta)}{\partial (x, y)} \neq 0
                                                                                                                                                                                                                                                                                                                         得抛物型方程\sqrt{A}\frac{\partial \xi}{\partial x} + \sqrt{C}\frac{\partial \xi}{\partial y} = 0
热传导方程描述非平衡态及其转换的弛豫,如三种输运过程:速度梯度→粘滞现象(动量传递),温度梯度→热传导现象(能量
                                                                                                                                                                                                                                                                                                            若\Delta < 0,解得特征线y(x,y) = y_1(x,y) + iy_2(x,y),作变换\xi = y_1, \eta = y_2
                                                                                                                                                                                                                                                                                                                         得椭圆形方程 \frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial \eta^2} = -\frac{1}{a} \left( d \frac{\partial u}{\partial \xi} + e \frac{\partial u}{\partial \eta} + f u - g \right)
 沿任一方向热流密度与该方向上温度梯度成正比, 菲克定律J(\mathbf{r}, t) = -\kappa \nabla u(\mathbf{r}, t)
                                                                                                                                                                                                                                                                                               双曲型——维弦振动方程 抛物型——维热传导方程 椭圆型—二维拉普拉斯方程
          (一维如均匀细杆热传导)对一小段[x,x+\Delta x],\; -kS\Delta t(\frac{\partial u}{\partial x}|_{x}-\frac{\partial u}{\partial x}|_{x+\Delta x})=c\rho S\Delta x\Delta u
                                                                                                                                                                                                                                                                                              叠加原理 对齐次线性微分方程,若u_1和u_2均为其解,则线性组合u=au_1+bu_2亦为其解
          \implies \frac{\partial u}{\partial t} = a^2 \frac{\partial^2 u}{\partial x^2}
                                                                              其中S-截面积, c-比热, \rho-体密度, a^2 = \frac{k}{c\rho}
                                                                                                                                                                                                                                                                                                        对非齐次线性微分方程,若u_1为其解,u_2为相应齐次微分方程解,则叠加u=u_1+au_2亦为其解
               \frac{\partial u}{\partial t} = \begin{cases} a^2 (\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}) + f(x, y, t) & \exists \\ a^2 \nabla^2 u + f(x, y, z, t) & \exists \end{cases}
                                                                                                                                                                                                                                                                                               对自变量平面\mathbf{R}上任一点\mathbf{P} 为确定\mathbf{P}点的值必须给定\mathbf{k}数\mathbf{E}中点的值 影响区中点的值随着\mathbf{P}点的值的变化而变化
                                                                                                                                                                                其中 f 描述物体内热源
                                                                                                                                                                                                                                                                                                        对双曲型方程,影响区-P点时间后两条特征线之间的区域,依赖区-P点时间前的两特征线之间的区域
              稳态下\frac{\partial u}{\partial t} = 0 = \frac{\partial^2 u}{\partial x^2} \Longrightarrow u = Ax + B
                                                                                                                                                                                                                                                                                                         对抛物型方程,过P点仅一条特征线,依赖区与影响区以特征线为界
                                                                                                                                                                                                                                                                                                         对椭圆型方程,特征线是虚的,与特征线线相关的数值方法不适用,信息不受影响区和依赖区的限制,可以沿各个方向传播
              一般方法: 对体积元,热量(t_2) — 热量(t_2) = (t_1 \sim t_2)经边界流入热量+(t_1 \sim t_2)内部生成热量
                                                                                                                                                                                                                                                                                               初始值+边界条件=定解条件 定解条件+偏微分方程(污定方程)=定解问题
          \textstyle \int_{V} cu(x,y,z,t_2) \rho dV - \int_{V} cu(*,t_1) \rho dV = \int_{t_1}^{t_2} [\int_{\partial V} k \nabla u \cdot d\mathbf{S}] dt + \int_{t_1}^{t_2} [\int_{V} f_0(*,t) \rho dV] dt
                                                                                                                                                                                                                                                                                               初值(Cauchy)问题 定解条件=初始条件 边值问题 定解条件=边界条件
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    混合问题 定解条件=初始+边界条件
           \Longrightarrow \int_{t_1}^{t_2} [\int_V \frac{\partial c \rho u}{\partial t} dV] dt = \int_{t_1}^{t_2} [\int_V \nabla \cdot (k \nabla u) + f_0 \rho dV] dt \\ \Longrightarrow \frac{\partial [c \rho u]}{\partial t} = \nabla \cdot (k \nabla u) + f_0 \rho dV dt
                                                                                                                                                                                                                                                                                               第一类(Dirichlet)边界条件 已知边界位移(温度/电势)u|_S=f_1
如静电场\nabla^2 \phi = \begin{cases} -\frac{\rho}{\epsilon_0} \\ 0 \end{cases}
                                                                                                                                                                                                                                                                                               第二类(Neumann)边界条件 已知边界速度(热流/电场)rac{\partial u}{\partial n}|_S=f_2
                                                                                                                                                                                                                                                                                               第三类边界条件 已知边界弹性受力(热交换)(u+hrac{\partial u}{\partial n})|_S=f_3
                                                                                                                                                                                                                                                                                                       Chap6分离变量法 Chap7分离变量法的应用 Chap8本征函数法
                                                                                                                                                                                                                                                                                                                                                                                                                                                                        当\lambda = 0, X = A + Bx由边界条件得平庸
 分离变量法适用条件(必要而不充分)泛定方程线性齐次,且边界条件齐次
                                                                                                                                                                                                                                                                                               解A=B=0 当\lambda < 0, X=A\exp(\sqrt{-\lambda}x)+B\exp(-\sqrt{-\lambda}x)由边界条件亦得平庸解A=B=0
                          对泛定方程Lu(x,t)=0写出形式解u(x,t)=X(x)T(t)2. 分离变量得空间函数本征值问
                                                                                                                                                                                                                                                                                                         \exists \lambda > 0, X_n(x) = A \cos \beta x + B_n \sin \beta x, \beta = \sqrt{\lambda}, \tan \beta_n L = -\beta_n h
              F_{x}X_{n}(x)=\lambda_{n}X_{n}(x) \Longrightarrow \left\{egin{array}{ccc} \Delta\epsilon\ell\lambda_{n} & 3. \end{array}\right. 代入时间方程解出T(t)得本征解u_{n}(x,t)=0 过界条件
                                                                                                                                                                                                                                                                                                        代入时间方程得T_n(t)=A_n\exp(-\beta_n^2a^2t),一般解u(x,t)=\sum_{n=1}^\infty C_n\exp(-\beta_n^2a^2t)\sin\beta_nx
           边界条件
                                                                                                                                                                                                                                                                                                        \sharp \Phi C_n = \frac{1}{L_n} \int_0^L \phi(x) \sin \beta_n x dx, L_n = \int_0^L \sin^2 \beta_n x dx = \frac{L}{2} \left(1 - \frac{\sin 2\mu_n}{2\mu_n}\right)
  X_n(x)T_n(t) 4. 利用叠加原理得一般解u(x,t)=\sum_n u_n(x,t) 5. 代入初始条件得待定系数
                                                                                                                                                                                                                                                                                              二维自由波动方程 \begin{cases} \frac{\partial^2 u}{\partial t^2} = c^2(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}) & 0 < x < a, 0 < y < b \\ u|_{t=0} = \phi(x,y), \ u_t|_{t=0} = \psi(x,y) & u_{x=0} = u|_{x=a} = u|_{y=0} = u|_{y=b} = 0 \end{cases}
 本征函数法基本步骤 1. 选择空间函数的本征函数集\{X_n(x)\},写出泛定方程的形式解u(x,t)=\sum_n T_n(t)X_n(x) 2. 将
 形式解代入泛定方程,直接得时间函数的常微分方程
 有界弦的自由振动  \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} \\ u|_{x=0} = 0 \end{cases} 
                                                                                              0\,<\,x\,<\,L\,,\,t\,>\,0
                                                                                                                                                                                                                                                                                                        首次分离变量u(x,y,t)=V(x,y)T(t)\Longrightarrow \left\{ \begin{array}{l} \frac{\partial^2 V}{\partial x^2}+\frac{\partial^2 V}{\partial y^2}+\lambda V=0 \\ T''+\lambda c^2T=0 \end{array} \right. 再次V(x,y)=X(x)Y(y)
                                                                                                                                                        设分离变量解u(x,t) = X(x)T(t)
                                                                                                    u|_{x=L}=0
                                        u|_{t=0} = \phi(x)
                                                                                               u_t|_{t=0}=\psi(x)
                                                                                                                                                                                                                                                                                                         \Rightarrow \frac{X^{\prime\prime}}{X} = -\frac{Y^{\prime\prime} + \lambda Y}{Y} = -\mu \Rightarrow \left\{ \begin{array}{cc} X^{\prime\prime} + \mu X = 0 & X(0) = X(a) = 0 \\ Y^{\prime\prime} + \nu Y = 0 & Y(0) = Y(b) = 0 \end{array} \right.
          代入原方程得 \frac{X^{\prime\prime}}{X}=\frac{T^{\prime\prime}}{aT}=-\lambda\Longrightarrow\left\{ \begin{array}{c} X+\lambda X=0 \\ T^{\prime\prime}+\lambda a^2T=0 \end{array} \right. 代入边界条件X(0)T(t)=0,X(L)T(t)=0
          因T(t) \neq 0,否则平庸解,故X(0) = X(L) = 0 \Longrightarrow \left\{ \begin{array}{c} X^{\prime\prime} + \lambda X = 0 \\ X(0) = X(L) = 0 \end{array} \right.
                                                                                                                                                                                                                                                                                                       本征值 \mu_m = (\frac{m\pi}{a})^2
                                                                                                                                                                                                                                                                                                                                                                          m,n=1,2,\cdots本征函数 \left\{egin{array}{l} X_{m}(x)=\sinrac{m\pi}{a}x\ Y_{n}(y)=\sinrac{n\pi}{b}y \end{array}
ight.
                                                                                                                                                                                                                                                                                                       当\lambda=0,通解为X(x)=A+Bx,由边界条件得A=B=0一平庸解
          \exists \lambda = 0. 迦解为\lambda(x) = A + Bx. 田边尹宗計刊名 = B = 0 一 和解

\exists \lambda < 0. 通解为\lambda(x) = A \exp(\sqrt{-\lambda}x) + B \exp(-\sqrt{-\lambda}x). 同理亦得平庸解

\exists \lambda > 0. 通解为\lambda(x) = A \cos\sqrt{\lambda}x + B \sin\sqrt{\lambda}x, 由边界条件得

本征值\lambda_n = (\frac{n\pi}{L})^2, 本征解\lambda_n(x) = B_n \sin\frac{n\pi}{L}x

\lambda_n代入时间方程得T''(t) + (\frac{n\pi}{L})^2T = 0得T_n(t) = C_n \cos\frac{n\pi}{L}t + D_n \sin\frac{n\pi}{L}x

原方程本征解为\lambda_n(t) = X_n(x)T_n(t) = (C_n \cos\frac{n\pi}{L}t + D_n \sin\frac{n\pi}{L}x)

\sum_{n=0}^{n(n)} \lambda_n(t) = \sum_{n=0}^{n(n
                                                                                                                                                                                                                                                                                                                        C_{mn} = \frac{4}{ab} \int_0^b \int_0^a \phi(x, y) \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y dx dy
D_{mn} = \frac{4}{ab\omega_{mn}} \int_0^b \int_0^a \psi(x, y) \sin \frac{m\pi}{a} x \sin \frac{n\pi}{b} y dx dy
                                                                                                                                                                                                                                                                                              二维热传导问题  \begin{cases} \frac{\partial u}{\partial t} = c^2(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}) & 0 < x < a, 0 < y < b, t > 0 \\ u|_{t=0} = \phi(x,y) & u|_{x=0} = u|_{x=a} = u|_{n=0} = 0 \end{cases} 
            -般解为u(x,t) = \sum_{n=1}^{\infty} u_n(x,t) = \sum_{n=1}^{\infty} (C_n \cos \frac{na\pi}{L} t + D_n \sin \frac{na\pi}{L} t) \sin \frac{n\pi}{L} x
                                                                                                                                                                                                                                                                                                                                                                                                                 u|_{x=0} = u|_{x=a} = u|_{y=0} = u|_{x=b} = 0
         一般睛分u(x,t) = \sum_{n=1}^{\infty} u_n(x,t) = \sum_{n=1}^{\infty} (C_n \cos \frac{1}{L} + D_n \sin \frac{1}{L} \cdot t) \sin \frac{1}{L} \cdot t 代入初始条件 \begin{cases} u_{|t=0} = \phi(x) = \sum_{n=1}^{\infty} C_n \sin \frac{n\pi}{L} x \\ u_{t|t=0} = \psi(x) = \sum_{n=1}^{\infty} D_n \frac{na\pi}{L} \sin \frac{n\pi}{L} x \end{cases} 符 \begin{cases} C_n = \frac{2}{L} \int_0^L \phi(x) \sin \frac{n\pi}{L} x dx \\ D_n = \frac{2}{n\pi a} \int_0^L \psi(x) \sin \frac{n\pi}{L} x dx \end{cases} 傳氏錄數是f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos \frac{2\pi n}{L} x + b \sin \frac{2\pi n}{L} x)其中 \begin{cases} a_n = \frac{7}{L} \int_0^L f(x) \cos \frac{2\pi n}{L} x dx \\ b_n = \frac{7}{L} \int_0^L f(x) \sin \frac{2\pi n}{L} x dx \end{cases}
                                                                                                                                                                                                                                                                                                        \#\omega_{mn} = c\pi\sqrt{(\frac{m}{a})^2 + (\frac{n}{b})^2}, u(x, y, t) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} C_{mn}e^{-\omega_{mn}^2 t} \sin\frac{m\pi}{a} x \sin\frac{n\pi}{b} y
                                                                                                                                                                                                                                                                                                                 其中C_{mn}=\frac{4}{ab}\int_0^b\int_0^a\phi(x)\sin\frac{m\pi}{a}x\sin\frac{n\pi}{b}ydxdy
                                                                                                                                                                                                                                                                                             分离变量得
                                                  \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x, t) \qquad 0 < x < L, t > 0
  两端固定阻尼弦振动 \begin{cases} u = 0 \\ u = 0 \end{cases}
                                                                                                                                                                                                                                                                                                       空间方程  \begin{cases} X'' + \lambda X = 0 \\ X(0) = X(a) = 0 \end{cases} \implies \begin{cases} \lambda_n = (\frac{n\pi}{a})^2 \\ X_n(x) = b_n \sin \frac{n\pi}{a} x \end{cases} 
                                                                                                                                    u|_{x=L} = 0
          其中阻尼項f(x,t) = -\frac{k}{\rho} \frac{\partial u}{\partial t} = -2b \frac{\partial u}{\partial t} 分离变量得 \frac{X''}{X} = \frac{T'' + 2bT}{a^2T} = -\lambda
                                                                                                                                                                                                                                                                                                        代入时间方程Y'' - \lambda Y = 0得Y_n(y) = c_n \cosh \frac{n\pi}{a} y + d_n \sinh \frac{n\pi}{a} y

-般解u(x,y) = \sum_{n=1}^{\infty} B_n \sin \frac{n\pi}{a} x \sinh \frac{n\pi}{a} y其中B_n = \frac{2}{a} \operatorname{csch} \frac{n\pi b}{a} \int_0^a f_2(x) \sin \frac{n\pi}{a} x dx
          特征方程 \begin{cases} X'' + \lambda X(x) = 0 \\ X(0) = X(L) = 0 \end{cases} \implies \begin{cases} \lambda_n = (\frac{n\pi}{L})^2 \\ X_n(x) = B_n \sin \frac{n\pi}{L} x \end{cases}  时方T'' + 2bT' + (\frac{n\pi a}{L})^2 T = 0
                                                                                                                                                                                                                                                                                              对一般性拉普拉斯边值问题  \begin{array}{c} u(x,0)=f_1(x) & u(x,b)=f_2(x) \\ u(0,y)=g_1(y) & u(a,y)=g_2(y) \end{array} \\ \eta(0,y)=g_1(y) & u(a,y)=g_2(y) \end{array}   \eta(x,t)=\sum_{n=1}^\infty A_n \sin \frac{n\pi}{a} x \sin \frac{n\pi}{a} x \sin \frac{n\pi}{a} y + \sum_{n=1}^\infty C_n \sinh \frac{n\pi}{b} (a-x) \sin \frac{n\pi}{b} y + \sum_{n=1}^\infty D_n \sinh \frac{n\pi}{b} x \sin \frac{n\pi}{b} \end{array} 
          设试探解e^{-\lambda t}满足方程\lambda^2-2b\lambda+(\frac{n\pi a}{L})^2=0,判别式\Delta=b^2-(\frac{n\pi a}{L})^2,并记q_n=\sqrt{|(\frac{n\pi a}{L})^2-b^2|}
                                                                                                                                                                                                                                                                                              圆形域内二维拉普拉斯方程 \begin{cases} \frac{1}{\rho}\frac{\partial}{\partial\rho}\left(\rho\frac{\partial u}{\partial\rho}\right)+\frac{1}{\rho^2}\frac{\partial^2 u}{\partial\theta^2}=0 \\ u(\rho_0,\theta)=f(\theta) \end{cases} 分离变量得 \frac{\rho^2R''+\rho R'}{R}=-\frac{\Phi''}{\Phi}=\lambda
          当立 > 0時代 \frac{\pi L}{\pi a} \Gamma_n(t) = \exp(-bt)(c_n \cos q_n t + a_n \sin q_n t) 

当\Delta = 0甲n = \frac{\pi L}{\pi a} , T_n(t) = c_n \exp(-bt) + d_n t \exp(-bt) 

当\Delta < 0甲n > \frac{bL}{\pi a} , T_n(t) = \exp(-bt)(c_n \cos q_n t + d_n \sin q_n t) 

欠限尼情况n > \frac{bL}{\pi a} 下、本征解为u_n(t) = \exp(-bt)(C_n \cos q_n t + D_n \sin q_n t) \sin \frac{n\pi}{L} x
                                                                                                                                                                                                                                                                                                                                                                                                                                        \left\{ \begin{array}{l} \mbox{ } 
                                                                                                                                                                                                                                                                                                                             角向方程 \Phi'' + \lambda \Phi = 0
                                                                                                                                                                                                                                                                                                                          周期性边界条件 \Phi(\theta + 2\pi) = \Phi(\theta)
               腹解u(x,t)=\sum_{n=1}^{\infty}u_n(x,t)代入初始条件 \begin{cases} \phi(x)=\sum_{n=1}^{\infty}C_n\sin\frac{n\pi}{L}x\\ \psi(x)=\sum_{n=1}^{\infty}(-C_nb+D_nq_n)\sin\frac{n\pi}{L}x \end{cases}
                                                                                                                                                                                                                                                                                                         当\lambda=0,\;\Phi(\theta)=A+B\theta=A 当\lambda<0,\;\Phi(\theta)=A\exp(\sqrt{-\lambda}\theta)+B\exp(-\sqrt{-\lambda}\theta)无法満足边界条件
                                                                                                                                                                                                                                                                                                         R_0(
ho)=c_0+d_0\ln
ho 考虑边界条件得  R_n(
ho)=c_n
ho^n+d_n
ho^{-n}, n=1,2,\cdots  考虑边界条件得  R_n(
ho)=c_n
ho^n
                                                                                                                                                                                                                                                                                                            \Re \mu(\rho,\theta) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos n\theta + b_n \sin n\theta)
                                                                                                                                                                                                     分离变量  \begin{cases} X'' + \lambda X = 0 \\ X(0) = X'(L) = 0 \end{cases} 
                                                                                                                                                                                                                                                                                              其中a_n=\frac{1}{\pi\rho_0^n}\int_0^{2\pi}f(\theta)\cos n\theta d\theta,b_n=\frac{1}{\pi\rho_0^n}\int_0^{2\pi}f(\theta)\sin n\theta d\theta 非齐次方程+齐次边界条件+任意初始条件,先解对应的齐次初始条件的非齐次方程,再与对应的相同边界条件的齐次方程解叠加
                                                                                                                                                                                                                                                                                             非齐次泛定方程+齐次初始条件(强迫弦振动)  \begin{cases} \frac{\partial^2 v}{\partial t^2} = a^2 \frac{\partial^2 v}{\partial x^2} + f(x,t) & 0 < x < L, t > 0 \\ \frac{\partial^2 v}{\partial t^2} = a^2 \frac{\partial^2 v}{\partial x^2} + f(x,t) & 0 < x < L, t > 0 \\ v|_{x=0} = v|_{x=L} = 0 & v|_{t=0} = v|_{t=0} = 0 \end{cases}  问题的解试探v(x,t) = \sum_{n=1}^{\infty} T_n(t) \sin \frac{n\pi}{L} x 原方程化为\sum_{n=1}^{\infty} [T_n''(t) + (\frac{n\sigma^2}{L})^2 T_n(t)] \sin \frac{n\pi}{L} x = f(x)  将非齐次项也按本征函数展开f(x,t) = \sum_{n=1}^{\infty} f_n(t) \sin \frac{n\pi}{L} x \quad \text{其中} f_n(t) = \frac{2}{L} \int_0^L f(x,t) \sin \frac{n\pi}{L} x dx  得一系列常微分方程问题  \begin{cases} T_n''(t) + (\frac{n\sigma^2}{L})^2 T_n(t) = 0 \\ T_n(0) = T_n'(0) = 0 \end{cases}  然后用拉普拉斯变换法求解 边界条件齐次化 选辅 助 函数u(x,t) = v(x,t) = 0
                                                                                   u|_{t=0} = \phi(x)
                                                                                                                                            u_t|_{t=0} = \psi(x)
          考虑边界条件本征值\lambda_n=\frac{(2n+1)^2\pi^2}{4l^2},本征函数X(x)=B_n\sin\frac{(2n+1)^2\pi}{2l}x, n=0,1,
          代入时间方程得T_n(t) = C_n' \cos \frac{(2n+1)\pi a}{2l} t + D_n' \sin \frac{(2n+1)\pi a}{2l} t
           - 般解为 u(x,t) = \sum_{n=0}^{\infty} (C_n \cos \frac{(2n+1)\pi a}{2l} t + D_n \sin \frac{(2n+1)\pi a}{2l} t) \sin \frac{(2n+1)\pi}{2l} x
          C_n = \frac{2}{L} \int_0^L \phi(x) \sin \frac{(2n+1)\pi}{2l} x dx
                                                                                                                                                                                                                                                                                              边界条件齐次化 选辅助函数u(x,t)=v(x,t)+\Omega(x,t)使关于v的问题边界条件齐次
热传导问题(第二类边界条件) \left\{ \begin{array}{ll} \frac{\partial u}{\partial t} = a^2 \frac{\partial^2 u}{\partial x^2} & 0 < x < L, t > 0 \\ u|_{t=0} = \phi(x) & u_x|_{x=0} = 0, u_x|_{x=L} = 0 \end{array} \right.
                                                                                                                                                                                                                                                                                              足が末円がれた。とこれが自然のは、、、、。 \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x) 同时齐次化(当自由項f和边界条件均不含t) \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x) \\ u|_{x=0} = b, u|_{x=L} = c \end{cases}
          解空间方程同前,本征值\lambda_n=(\frac{n\pi}{L})^2,本征函数X_n(x)=A\cos\frac{n\pi}{L}x, n=1,2,\cdots
                                                                                                                                                                                                                                                                                                                                                                                              u|_{t=0} = \phi(x), u_t|_{t=0} = \psi(x)
          代入时间方程T_n(t)=c_n\exp[-(\frac{na\pi}{L})^2t]一般解u(x,t)=\frac{C_0}{2}+\sum_{n=1}^{\infty}C_n\exp[-(\frac{na\pi}{L})^2t]\cos\frac{n\pi}{L}x
                                                                                                                                                                                                                                                                                                          \left\{ \begin{array}{l} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + a^2 \frac{\partial^2 \Omega}{\partial x^2} + f(x) \\ v(0) + \Omega(0) = b, v(L) + \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \frac{\partial^2 \Omega}{\partial t^2} + f(x) = 0 \\ \Omega(0) = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial^2 u}{\partial t^2} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \end{array} \right. \\ \left. \begin{array}{l} \partial u}{\partial t} + f(x) = 0 \\ \partial u = b, \Omega(L) = c \\ \partial u = b, \Omega(L
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 $\Omega(x) = b + \frac{c - b}{L}x + F(x) + \frac{F(0) + F(L)}{L}x - F(0), F(x) = -\frac{1}{a^2} \int [\int f(x) dx] dx$

当稳态, $u(x, \infty) = C_0$

無性 $C_R = \sum_{j=0}^{N} \int_0^{\phi(x)} e^{i(x)} dx$ 上 一 热传导问题 (第三类边界条件) $\begin{cases} \frac{\partial u}{\partial t} = a^2 \frac{\partial^2 u}{\partial x^2} & 0 < x < L, t > 0 \\ u(0,t) = 0, u(x,0) = \phi(x) & u(L,t) + hu_t(L,t) = 0 \end{cases}$

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Chap9施图姆-刘维尔理论及其应用
                                                                                                                    函数空间的内积(f_1,f_2)=\int_a^b f_1^*(x)f_2(x)dx 同样满足1. 对称性 2. 线性 3. 正定性
任一二阶线性偏微分方程y'' + a(x)y' + b(x)y + \lambda c(x)y = 0
                                                                                                                    函数空间函数集的完备性对任一函数f(x), 展开级数\sum_{i=1}^{\infty}c_if_i(x)平均收敛于f(x), 即\lim_{n\to\infty}\int_a^b|f(x)| -
均可化为施图姆-刘维尔型方程 \frac{d}{dx}[k(x)\frac{dy}{dx}] - q(x)y + \lambda \rho(x)y = 0
                                                                                                                    \sum_{i=1}^{\infty} c_i f_i(x)|^2 dx = 0,称正交归一函数集\{f_i, i=1,2,\cdots\}完备
     其中k(x) = e^{\int a(x)dx}, -q(x) = b(x)e^{\int a(x)dx}, \lambda-本征值, \rho(x) = c(x)e^{\int a(x)dx}
                                                                                                                    广义函数内积(f_1, f_2) = \int_a^b \rho(x) f_1^*(x) f_2(x) dx
                                                                                                                    伴算符 L和M为定义在一定函数空间的微分算符, 若对\forall u, v恒有(v, Lu)
对k(x), q(x), \rho(x) \ge 0的S-L方程,若k(x), k'(x), q(x)在(a,b)上连续,且最多以x = a, x = b为一阶极点,则存
在无限多个本征值,相应有无限多个本征函数,且本征值均非负
    对应不同本征值的本征函数在区间[a,b]带权重\rho(x)正交\int_a^b \rho(x)y_m(x)y_n(x)dx=0, n\neq m
    本征函数集完备,即若函数f(x)满足广义Dirichlet条件: (1)具有连续一阶导和分段连续二阶导;(2)满足本征函数集满足的
边界条件,则必可展开为绝对且一致收敛和广义傅里叶级数f(x)=\sum_{n=1}^{\infty}f_ny_n(x)(对于任意函数f(x),则为平均收敛)
    f_{n} = \frac{1}{N_{\infty}^{2}} \int_{a}^{b} \rho(\xi) f(\xi) y_{n}(\xi) d\xi, N_{n}^{2} = \int_{a}^{b} \rho(\xi) [y_{n}(\xi)]^{2} d\xi
当Q因子Q = k(x)[y_n(0)y'_m(0) - y_m(0)y'_n(0)] - k(L)[y_n(L)y'_m(L) - y_m(L)y'_n(L)] =
0,本征函数在区间[0,L]带权重\rho(x)正交
矢量空间对n维矢量空间,选定一组基\{e_i,i=1,2,\cdots,n\},空间中任一矢量x均可用这组基的线性组合表示x=1,2,\cdots,n\}
\sum_{i=1}^{n} x_i e_i, 满足空间加法和数乘封闭
内积(x,y)=\sum_{i=1}^{\infty}x_i^*y_i=(y,x)^* 内积空间:定义了内积的矢量空间,满足
    1. 对称性(\boldsymbol{x}, \boldsymbol{y}) = (\boldsymbol{y}, \boldsymbol{x})^* 2. 线性(a\boldsymbol{x} + b\boldsymbol{z}, \boldsymbol{y}) = a(\boldsymbol{x}, \boldsymbol{y}) + b(\boldsymbol{z}, \boldsymbol{y})
    3. 正定性(\boldsymbol{x}, \boldsymbol{x}) \geq 0, (\boldsymbol{x}, \boldsymbol{x}) = 0 \Leftrightarrow \boldsymbol{x} = 0
矢量正交当(x, y),两矢量正交
正交归一矢量集的完备性:有限维矢量空间中,若一正交归一矢量集不包含在另一更大的正交归一矢量集中,则称该正交归一矢量集
函数空间对加法 ((f_1+f_2)(x)=f_1(x)+f_2(x)) 和乘法 ((\alpha f)(x)=\alpha f(x)) 封闭的平方可积 (积分\int_a^b|f(x)|^2dx 存
     Chap10行波法
一阶线性常微分方程 \frac{dy}{dx}+P(x)y=Q(x)的通解为y=e^{-\int P(x)dx}[\int Q(x)e^{\int P(x)dx}dx+C]
特征线法解含两个自变量的一阶线性常微分方程a(x,y)\frac{\partial u}{\partial x}+b(x,y)\frac{\partial u}{\partial y}+c(x,y)u=f(x,y)
     由特征方程a(x,y)dy - b(x,y)dx = 0解得特征线y = y(x) + C
     做变换\xi=y-y(x),取\eta使\frac{\partial(\xi,\eta)}{\partial(x,y)}\neq 0(或直接做代换y=y(x))
     原方程化为仅含一个自变量的一阶常微分方程\left(a\frac{\partial \eta}{\partial x} + b\frac{\partial \eta}{\partial u}\right)\frac{\partial u}{\partial n} + cu = f
     求解得u(\xi,\eta)(积分常数中含\xi), 回代并结合初始条件得到u(x,y)
二阶线性偏微分方程降阶求解(波动方程) \frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = (\frac{\partial}{\partial t} + a \frac{\partial}{\partial x})(\frac{\partial}{\partial t} - a \frac{\partial}{\partial x})u = 0
            \int \frac{\partial u}{\partial t} - \frac{\partial u}{\partial x} = v
     \Longrightarrow \left\{ \begin{array}{c} \frac{\partial t}{\partial v} & \sigma x \\ \frac{\partial v}{\partial t} + a \frac{\partial v}{\partial x} = 0 \end{array} \right.
                                          还可化成标准形式(双曲型)两次积分并结合初始条件求解
波动方程Cauchy问题(无界弦自由振动)  \left\{ \begin{array}{ll} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} & -\infty < x < +\infty, t > 0 \\ u|_{t=0} = \phi(x) & \frac{\partial u}{\partial t}|_{t=0} = \psi(x) \end{array} \right. 
      通解为达朗贝尔公式u(x,t) = f_1(x+at) + f_2(x-at)
= \left[\frac{1}{2}\phi(x+at) + \frac{1}{2a}\int_0^{x+at}\psi(\xi)d\xi + \frac{C}{2}\right] + \left[\frac{1}{2}\phi(x-at) - \frac{1}{2a}\int_0^{x-at}\psi(\xi)d\xi - \frac{C}{2}\right]
= \frac{1}{2} [\phi(x+at) + \phi(x-at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi
特解u(x,t)仅取决于依赖区间[x-at,x+at]上的初始条件
决定区域的边界为x - at = X_1, x + at = X_2, t > 0
区间[X_1, X_2]影响区域的边界为x = X_1 - at, x = X_2 + at, t > 0
     边界的平行线为特征线x+at=C_1(C_1\geq X_1), x-at=C_2(C_2\leq X_2)
半无界弦振动达朗贝尔解法 端点固定  \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} & 0 < x < \infty & t > 0 \\ u(x,0) = \phi(x) & u_t(x,0) = \psi(x) & u(0,t) = 0 \end{cases} 
     将\phi(x)和\psi(x)在实轴上作奇延拓化为无界弦的自由振动问题得
     在端点条件影响区(x \ge 0, x - at < 0): u(x,t) = \frac{1}{2} [\phi(x + at) - \phi(at - x)] + c
\frac{1}{2a} \int_{at-x}^{x+at} \psi(\xi) d\xi
     在初始条件决定区(x \ge 0, x - at \ge 0): u(x,t) = \frac{1}{2} [\phi(x + at) + \phi(x - at)] +
\frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi
     端点自由  \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} & 0 < x < \infty \qquad t > 0 \\ u(x,0) = \phi(x) & u_t(x,0) = \psi(x) & u_t(0,t) = 0 \end{cases} 
     对\phi(x)和\psi(x)在实轴上做偶延拓化为无界弦的自由振动问题得
     \int_0^{at-x} \psi(\xi) d\xi
     \begin{array}{l} \frac{\partial^2 w}{\partial t^2} = a^2 \frac{\partial^2 w}{\partial x^2} \\ w(x,0) = w_t(x,0) = 0 \\ w(0,t) = \mu(t) \end{array} \quad \begin{array}{l} \underset{\neg}{\text{H}} w = \left\{ \begin{array}{l} \mu(-\frac{x-at}{a}) & x-at < 0 \\ 0 & x-at \geq 0 \end{array} \right. \end{array}
         \frac{\partial^2 w}{\partial t^2} = a^2 \frac{\partial^2 w}{\partial x^2}
      萬与对应端点固定问题解v叠加即得原端点受迫振动问题的解u(x,t) = v(x,t) + w(x,t)
     积分微商定理 若U(x)=\int_a^x f(x,\tau)d	au,则 \frac{d}{dx}U(x)=f(x,x)+\int_a^x \frac{\partial}{\partial x}f(x,\tau)d	au
     Chap11积分变换法
傅里叶变换F(\omega)=\mathcal{F}[f(t)]=\int_{-\infty}^{+\infty}f(t)e^{-i\omega t}dt,\omega\in(-\infty,+\infty)
傅里叶逆变换f(t) = \mathcal{F}^{-1}[F(\omega)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} F(\omega) e^{i\omega t} d\omega(变换存在的条件: 通常要
求f(x)绝对可积)
傅里叶变换的性质 线性\mathcal{F}[af_1(t) + bf_2(t)] = a[f_1(t)] + b[f_2(t)]
```

对称性设 $\mathcal{F}[f(t)] = F(\omega)$,则 $\mathcal{F}[F(t)] = 2\pi f(-\omega)$

 $\mathcal{F}[e^{i\omega_0 t} f(t)] = F(\omega - \omega_0)$

位移性 $\mathcal{F}[f(t-t_0)] = e^{-i\omega t_0} F(\omega)$ $\mathcal{F}^{-1}[F(\omega-\omega_0)] = e^{i\omega_0 t} f(t)$

微分性 原函数的微分性 若 $\lim_{|t|\to+\infty}f(t)=0$,则 $\mathcal{F}[f'(t)]=i\omega F(\omega)$

像函数的微分性 $F'(\omega) = -i\mathcal{F}[tf(t)]$ $\mathcal{F}[tf(t)] = iF'(\omega)$ 积分性 若 $\lim_{t \to +\infty} \int_{-\infty}^{t} f(\tau) d\tau = 0$,则 $\mathcal{F}[\int_{-\infty}^{t} f(\tau) d\tau] = \frac{1}{i\omega} F(\omega)$ 卷积 $f_1(t) * f_2(t) = \int_{-\infty}^{+\infty} f_1(s) f_2(t-s) ds$

卷积的性质 交换律f*g=g*f 分配律f*(g+h)=f*g+f*h

若 $\lim_{|t|\to+\infty} f^{(k)}(t) = 0$,则 $\mathcal{F}[f^{(k)}(t)] = (i\omega)^k F(\omega)$

相似性 $\mathcal{F}[f(at)] = \frac{1}{|a|}F(\frac{\omega}{a})$ $\mathcal{F}^{-1}[F(a\omega)] = \frac{1}{|a|}f(\frac{t}{a})(a \neq 0)$

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拉普拉斯变换的性质 线性\mathcal{L}[af_1(t)+bf_2(t)]=aF_1(p)+bF_2(p)
    延迟性\mathcal{L}[f(t-t_0)u(t-t_0)] = e^{-pt_0}F(p) 平移性\mathcal{L}[e^{p_0t}f(t)] = F(p-p_0)
    微分性 \mathcal{L}[f'(t)] = pF(p) - f(0) F'(p) = -\mathcal{L}[tf(t)] \qquad F^{(n)}(p) = (-1)^n \mathcal{L}[t^n f(t)]
    积分性\mathcal{L}[\int_0^t f(s)ds] = \frac{F(p)}{p} \int_p^{+\infty} F(s)ds = \mathcal{L}[\frac{f(t)}{t}]
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(Mv,u)即\int_a^b v^*(Lu)dx = \int_a^b (Mv)^*udx,则称M是L的伴算符
自伴算符: 伴算符为自身的算符, 即对\forall u, v恒有(v, Lu) = (Lv, u)
若L为自伴算符,则方程Ly(x) = \lambda y(x)称自伴算符L的本征问题
自伴算符的性质 1. 存在性自伴算符的本征值必存在 2. 且为实数
      3. 正交性自伴算符的对应不同本征值的本征函数必正交
      4. 完备性自伴算符的本征函数构成一个完备函数集,即任一在区间[a,b]有连续二阶导且
和自伴算符边界条件相同的函数f(x),均可按本征函数\{y_n(x)\}展开成绝对且一致收敛的级数
      f(x) = \sum_{n=1}^{\infty} c_n f_n(x), \ \ \mbox{\sharp} \ \ \mbox{\ddagger} c_n = \frac{\int_a^b f(x) y_n^*(x) dx}{\int_a^b y_n(x) y_n^*(x) dx}
算符自伴性与本征值问题有解之间的关系: 充分不必要, 如L是自伴算符, iL必非自伴算符,
但i\lambda是iL的本征值
非自伴算符的本征值不一定是实数,本征函数也不一定具有正交性
引入算符L = -\frac{d}{dx}[k(x)\frac{d}{dx}] + q(x), S-L方程化为Ly = \lambda \rho(x)y
 令u(x) = \sqrt{\rho(x)}y(x),S-L方程化为L'u(x) = \lambda u(x),其中L' = -\frac{d}{dx}[\phi(x)\frac{d}{dx}] +
\psi(x), \phi(x) = \frac{k(x)}{\rho(x)}, \psi(x) = -\frac{1}{\sqrt{\rho(x)}} \frac{d}{dx} [k(x) \frac{d}{dx} \frac{1}{\sqrt{\rho(x)}}] + \frac{q(x)}{\rho(x)}
在边界条件\phi(x)(u_1^* \frac{du_2}{dx} - u_2 \frac{u_1^*}{dx})|_a^b = 0下,L'是自伴算符
在边界条件p(x)(y_1^* \frac{dy_2}{dx} - y_2 \frac{dy_1^*}{dx})|_a^b = 0下,L是自伴算符
齐次化原理  \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} & -\infty < x < +\infty, t > 0 \\ u(x,0) = \phi(x) & \frac{\partial u}{\partial t}(x,0) = \psi(x) \end{cases}  利用达朗贝尔公式解得
              u_1(x,t) = \frac{1}{2} [\phi(x+at) + \phi(x-at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi
              \begin{cases} \frac{\partial t^2}{\partial t} & \frac{\partial t^2}{\partial t} \\ w|_{t-\tau=0} = 0 & \frac{\partial w}{\partial t}|_{t-\tau=0} = f(x,\tau) \end{cases}
                    w(x,t;\tau)=\frac{1}{2a}\int_{x-a(t-\tau)}^{x+a(t-\tau)}f(\xi,\tau)d\xi, 由齐次化原理(积分微商定理)
       \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x, t) & -\infty < x < +\infty, t > 0 \end{cases}
        u(x,0) = 0
                                                        \frac{\partial u}{\partial t}(x,0) = 0
             u_2(x,t) = \int_0^t w(x,t;\tau)d\tau = \frac{1}{2a} \int_0^t \int_{x-a(t-\tau)}^{x+a(t-\tau)} f(\xi,\tau)d\xi d\tau
  \int \frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + f(x,t) \quad -\infty < x < +\infty, t > 0 \quad \text{in $k$ in $\mathbb{Z}$ in $\mathbb{Z}$ in $\mathbb{Z}$} 
 u(x,0) = \phi(x)
                                                 \frac{\partial u}{\partial t}(x,0) = \psi(x)
\mathbb{m}u(x,t) = u_1(x,t) + u_2(x,t) = \frac{1}{2}[\phi(x+at) + \phi(x-at)] + \frac{1}{2a}\int_{x-at}^{x+at}\psi(\xi)d\xi + \frac{1}{2a}\int_{x-at}^{x+at}\psi(\xi)d\xi
\frac{1}{2a} \int_0^t \int_{x-a(t-\tau)}^{x+a(t-\tau)} f(\xi,\tau) d\xi d\tau
高维波动方程的行波解法 中心对称的球面波 \left\{ \begin{array}{ll} \frac{\partial^2 u}{\partial t^2} = a^2 \nabla^2 u & r,t>0 \\ u(r,0) = \phi(r) & u(r,0) = \psi(r) \end{array} \right.
      做代换v=ru得  \begin{cases} \frac{\partial^2 v}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial r^2} & r,t>0 \\ u(r,0) = \phi(r) & u(r,0) = \psi(r) \end{cases}  利用达朗贝尔公式得
       在端点条件影响\vec{E}(r \ge 0, r - at < 0): u(r,t) = \frac{1}{2r}[(r + at)\phi(r + at) - (at - at)]
r)\phi(at-r)] + \frac{1}{2ar} \int_{at-r}^{r+at} \xi \psi(\xi) d\xi
       在初始条件决定区(r \ge 0, r-at \ge 0): u(r,t) = \frac{1}{2r}[(r+at)\phi(r+at) + (r-at)\phi(r-at)]
at)]+\frac{1}{2ar}\int_{r-at}^{r+at}\xi\psi(\xi)d\xi
       一般形式的三维齐次波动方程(非球对称)  \left\{ \begin{array}{ll} \frac{\partial^2 u}{\partial t^2} = a \nabla^2 u & -\infty < x,y,z < +\infty \\ u|_{t=0} = f(x,y,z) & u_t|_{t=0} = g(x,y,z) \end{array} \right. 
                                                                                                           -\infty < x,y,z < +\infty
      泊松公式为u(x,y,z,t)=\frac{\partial}{\partial t}(\frac{t}{4\pi a^2t^2}\oint_{S_{at}^M}f(\xi,\eta,\zeta)dS)+\frac{t}{4\pi a^2t^2}\oint_{S_{at}^M}g(\xi,\eta,\zeta)dS=
 \frac{\partial}{\partial t} \left[ \frac{t}{4\pi} \int_0^{2\pi} \int_0^{\pi} f(\xi, \eta, \zeta) \sin\theta d\theta d\phi \right] + \frac{t}{4\pi} \int_0^{2\pi} \int_0^{\pi} g(\xi, \eta, \zeta) \sin\theta d\theta d\phi
       其中S^M_{at} –以(x,y,z)为中心,r=at为半径的球面,\xi=x+at\sin\theta\cos\phi,\eta=
y+at\sin\sin\phi , \zeta=z+at\cos\theta 

奔次化原理  \begin{cases} u_{tt}=a\nabla^2 u & \mathbf{x}\in R^3, t>0 \\ u(\mathbf{x},0)=f(\mathbf{x}) & u_t(\mathbf{x},0)=g(\mathbf{x}) \end{cases}  利用泊松公式解得
     u_1(\boldsymbol{x},t) = \frac{1}{4\pi a} \frac{\partial}{\partial t} \oint_{S}^{M}_{at} \frac{f(\xi,\eta,\zeta)}{r} \, dS + \frac{1}{4\pi a} \oint_{S}^{M}_{at} \frac{g(\xi,\eta,\zeta)}{r} \, dS
           \left\{ \begin{array}{ll} w_{tt} = a \nabla^2 w & at & at \\ w(\mathbf{x}, 0) = 0, w_t|_{t=\tau} = F(\mathbf{x}, \tau) & \text{用油检公式得} w(\mathbf{x}, t; \tau) = \frac{1}{4\pi a} \oint_{S} \frac{F(\xi, \eta, \zeta, \tau)}{a(t-\tau)} dS \\ \end{array} \right. 
     由齐次化原理得 \begin{cases} u_{tt} = a^2 \nabla^2 u + F(\mathbf{x}, t) & x \in R^3, t > 0 \\ u(\mathbf{x}, 0) = f(\mathbf{x}) & u_t(\mathbf{x}, 0) = g(\mathbf{x}) \end{cases}
          u_{tt}=a^2
a(t-	au) x\in R^3, t>0 的解为上述两问题解的叠加 u(x,0)=f(x) u_t(x,0)=g(x)
     u({\bm x},t) \ = \ u_1({\bm x},t) \ + \ u_2({\bm x},t) \ = \ \frac{1}{4\pi a} \, \frac{\partial}{\partial t} \, \oint_{S_{at}} \frac{f(\xi,\eta,\zeta)}{r} dS \ + \ \frac{1}{4\pi a} \, \oint_{S_{at}} \frac{g(\xi,\eta,\zeta)}{r} dS \ +
\tfrac{1}{4\pi a^2} \, \mathop{\rm Mir}\nolimits_{r \leq at} \, \tfrac{F(\xi,\eta,\zeta,t-\frac{r}{a})}{r} \, dv
             结合律f*(g*h) = (f*g)*h 数乘A(f*g) = (Af)*g = f*(Ag), A为常数
             求导\frac{d}{dt}(f*g(t)) = f'(t)*g(t) = f(t)*g'(t) f*\delta(t) = \delta*f(t) = f(t)
       卷积定理\mathcal{F}[f*g] = F(\omega) \cdot G(\omega) \mathcal{F}[f\cdot g] = \frac{1}{2\pi}F(\omega)*G(\omega)
用傅里叶变换解偏微分方程步骤 1. 方程和条件两边同对定义在(-\infty, +\infty)的变量(-\infty, +\infty)的变量(-\infty, +\infty)
是x)做傅里叶变换,像函数u(x,t) \to U(\omega,t),初始条件\phi(x) \to \Phi(\omega), \psi(x) \to \Psi(\omega)
      2. 解出U(\omega,t) 3. U(\omega,t)反演得u(x,t)
拉普拉斯变换F(p) = \mathcal{L}[f(t)] = \int_{a}^{+\infty} f(t)e^{-pt}dt
拉普拉斯逆变换f(t)=\mathcal{L}^{-1}[F(p)]=rac{1}{2\pi i}\int_{eta-i\infty}^{eta+i\infty}F(p)e^{pt}dp
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 $\mathcal{L}[f^{(n)}] = p^n F(p) - p^{n-1} f(0) - p^{n-2} f'(0) - \dots - f^{(n-1)}(0)$

```
周期性若f(t+T)=f(t),\mathcal{L}[f(t)]=rac{\int_0^T f(t)e^{-pt}dt}{1-e^{-pT}}
在区间[0,+\infty]的卷积f_1(t)*f_2(t)=\int_0^t f_1(s)f_2(t-s)ds
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Chap12格林函数法

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格林函数G(r,r_0) 位于r_0的单位点源在r处产生的电势
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步骤 1. 建立格林函数G的定解问题 2. 解定解问题得格林函数 3. 解的积分即为原问题的解

无界三维泊松方程 $\nabla^2 u(\mathbf{r}) = \rho(\mathbf{r}), G(\mathbf{r}; \mathbf{r}_0) = \frac{1}{4\pi |\mathbf{r} - \mathbf{r}_0|} \implies u(\mathbf{r}) = \iiint \rho(\mathbf{r}_0) G(\mathbf{r}, \mathbf{r}_0) d\mathbf{r}_0$ 无界二维泊 $u_{yy} = \rho(x,y), G(x,y;\xi,\eta) = -\frac{1}{2\pi} \ln \frac{1}{|\boldsymbol{r} - \boldsymbol{r}_0|} \Longrightarrow u(x,y) = \iint \rho(\boldsymbol{r}_0) G(x,y;\xi,\eta) d\xi d\eta$

重要な $|\mathbf{r}-\mathbf{r}_0|$ と $|\mathbf{r}-\mathbf{r}-\mathbf{r}_0|$ と $|\mathbf{r}-\mathbf{r}_0|$ と

Chap13贝塞尔函数

从S-L型方程出发 $\frac{d}{dx}[k(x)\frac{dy}{dx}]-q(x)y+\lambda\rho(x)y=0$

当 $k=1, q=0, \rho=1$ 化为亥姆霍兹方程 $\frac{d^y}{dx^2}+\lambda y=0$

当 $k=x,q=m^2/x,
ho=x$ 化为参数形式的贝塞尔方程,当 $\lambda=1$ 化为贝塞尔方程

当 $k=x^2,q=\omega^2,
ho=1$ 化为球贝塞尔方程 $\frac{d}{dx}[x^2\frac{dy}{dx}]-\omega^2y+\lambda x^2y=0$,当 $\lambda=0$ 化为欧拉方程

当 $k=1-x^2, q=\frac{m^2}{1-x^2}, \rho=1$ 化为连带勒让德方程 $\frac{dx}{dx}[(1-x^2)\frac{dy}{dx}]-\frac{m^2}{1-x^2}y+\lambda y=0$ 当加 = 0化为勒让德方程

伽马函数 $\Gamma(x)=\int_0^\infty e^{-t}t^{x-1}dt\;(x>0)$

 $\Gamma(\frac{1}{2}) = \sqrt{\pi} \qquad \Gamma(n + \frac{1}{2}) = \frac{(2n)^2}{2^{2n}n!} \sqrt{\pi} \qquad \Gamma(n + \frac{1}{2} + 1) = \frac{(2n+1)!}{2^{2n+1}n!} \sqrt{\pi}$ 对大的n有斯特林近似式 $n! = \sqrt{\frac{2-n!}{2\pi n}} n^n e^{-n}$ 余元公式 $\Gamma(x)$ $\Gamma(1-x) = \frac{\pi}{\sin \pi x}$ 贝塔函数 $B(x,y) = \int_0^1 t^{x-1} (1-t)^{y-1} dt = \frac{(x-1)!(y-1)!}{(x+y-1)!}$

贝塞尔方程的求解 ν 阶贝塞尔方程 $x^2\frac{d^2y}{dx^2}+x\frac{dy}{dx}+(x^2u^2)y=0$ 的解称贝塞尔函数

 ν 阶第一类贝氏函数 $J_{\nu}(x) = \sum_{m=0}^{\infty} \frac{dx^2}{m!\Gamma(\frac{\pi}{2})^{2m+\nu}}$ $J_0(0) = 1$ $J_{\nu}(0) = 0, (\nu > 0)$ 当 ν 取非负整数得整数阶贝氏函数 $J_n(x) = \sum_{m=0}^{\infty} \frac{(-1)^m}{m!(m+n)!} (\frac{x}{2})^{2m+n}$ 若 $C = -\nu$,则得 $J_{-\nu}(x) = \sum_{m=0}^{\infty} \frac{(-1)^m (\frac{x}{2})^{2m-\nu}}{m!(m-\nu+1)}$

 $J_{\nu}(x)$ 和 $J_{-\nu}(x)$ 线性独立(ν 非整数) 但 $J_{n}(x)$ 和 $J_{-n}(x)$ 线性相关

为构建与 J_n 线性无关的解,引入**诺依曼函数(第二类贝氏函数)** $Y_{\nu} = \begin{cases} \frac{J_{\nu}(x)\cos\nu x - J_{-\nu}(x)}{\sin\nu x} \\ \lim_{\alpha \to \nu} \frac{J_{\alpha}(x)\cos\alpha \pi - J_{-\alpha}(x)}{\sin\alpha \pi} \end{cases}, \quad \nu$ 非整数

积分表示 $Y_n(x) = \frac{1}{\pi} \int_0^\pi \sin(x \sin \theta - n\theta) d\theta - \frac{1}{\pi} \int_0^\infty [e^{nt} + (-1)^n e^{-nt}] e^{-x \sinh t} dt$

u阶贝塞尔方程通解 $y(x) = \begin{cases}
AJ_{\nu}(x) + BY_{\nu}(x) \\
AJ_{\nu}(x) + BJ_{-\nu}(x), & \nu$ 非整数

生成函数级数展开式的系数是贝塞尔函数的函数 $f(x,r) = \sum_n J_n(x) r^n$

整数阶贝塞尔函数的生成函数 $\exp[\frac{x}{2}(r-\frac{1}{r})] = \sum_{n=-\infty}^{\infty} J_n(x)r^n$

递推公式($\forall \nu$) $\left\{ \begin{array}{l} \frac{d}{dx}[x^{\nu}J_{\nu}(x)] = x^{\nu}J_{\nu-1}(x) \\ \frac{d}{dx}[x^{-\nu}J_{\nu}(x)] = -x^{-\nu}J_{\nu+1}(x) \end{array} \right.$ $\frac{d}{dx}[J_0(x)] = -J_1(x) \qquad \frac{d}{dx}[xJ_1(x)] = xJ_0(x)$

 $\begin{cases} J_{\nu}'(x) = \frac{1}{2} [J_{\nu-1}(x) - J_{\nu+1}(x)] & \begin{cases} xJ_{\nu-1}(x) = \nu J_{\nu}(x) + xJ_{\nu}'(x) \end{cases} \end{cases}$ $\int_{\nu-1}^{\infty} J_{\nu+1}(x) + J_{\nu+1}(x) = \frac{2}{x} \nu J_{\nu}(x) \qquad \int_{\nu}^{\infty} x J_{\nu+1}(x) = \nu J_{\nu}(x) - x J_{\nu}'(x)$

积分递推公式 $\begin{cases} \int x^{\nu+1} J_{\nu}(x) dx = x^{\nu+1} J_{\nu+1}(x) \\ \int x^{-\nu+1} J_{\nu}(x) dx = -x^{-\nu+1} J_{\nu-1}(x) \end{cases}$

 $\frac{d}{dx}[x^{\nu}Y_{\nu}(x)] = x^{\nu}Y_{\nu-1}(x)$ $\frac{d}{dx}[x^{-\nu}Y_{\nu}(x)] = -x^{-\nu}Y_{\nu+1}(x)$ $Y_{\nu}'(x) = \frac{1}{2} [Y_{\nu-1}(x) - Y_{\nu+1}(x)]$ 第二类贝氏函数递推公式与第一类相同 $Y_{\nu-1}(x) + Y_{\nu+1}(x) = \frac{2\nu}{x} Y_{\nu}(x)$ $xY_{\nu-1}(x) = \nu Y_{\nu}(x) + xY'_{\nu}(x)$ $xY_{\nu+1}(x) = \nu Y_{\nu}(x) - xY'_{\nu}(x)$

勒让德多项式

勒让德方程 $\frac{1}{\sin\theta} \frac{d}{d\theta} (\sin\theta \frac{d\Theta}{d\theta}) = l(l+1)\Theta$

或令 $x=\cos\theta,y(x)=\Theta(\theta)$ 化为 $(1-x^2)y^{\prime\prime}-2xy^{\prime}+l(l+1)y=0$

方程通解为 $y(x) = C_0 y_0(x) + C_1 y_1(x)$ $\begin{cases} y_0(x) = 1 - \frac{l(l+1)}{2!} x^2 + \frac{(l-2)l(l+1)(l+3)}{4!} x^4 - \frac{(l-4)(l-2)l(l+1)(l+3)(l+5)}{6!} \end{cases}$ $1 - \frac{2!}{2!}x^2 + \frac{4!}{2!}x - \frac{1}{2!}x^3 + \frac{4!}{2!}x - \frac{1}{2!}x^3 + \frac{4!}{2!}x^3 + \frac{4!}{2!}x^3$

 $y_1(x) = x - \frac{(l-1)(l+2)}{3!} x^3 + \frac{(l-3)(l-1)(l+2)(l+4)}{5!} x^5 - \frac{(l-5)(l-3)(l-1)(l+2)(l+4)(l+6)}{7!} x^7 + \cdots$

收敛半径 $R = \lim_{k \to \infty} |\frac{C_k}{C_{k+2}}| = 1$

当取很數、則 $y_0(x)$ 截断为偶次幂多項式 $y_0(x)=C_0+C_2x^2+\cdots+C_lx^l$ 当取l奇數、則 $y_1(x)$ 截断为奇次幂多項式 $y_1(x)=C_1+C_3x^3+\cdots+C_lx^l$ 取 $C_l=\frac{(2l)!}{2^l(l!)^2}$ 得l阶勒让德多项式 $P_l(x)=\frac{1}{2^l}\sum_{m=0}^M(-1)^m\frac{(2l-2m)!}{m!(l-m)!(l-2m)!}x^{l-2m}$

其中 $M = \begin{cases} \frac{l}{2} & (l = 0, 2, 4, \cdots) \\ \frac{l-1}{2} & (l = 1, 3, 5, \cdots) \end{cases}$

 $P_0(x) = 1$ $P_1(x) = x$ 低阶多项式 $P_2(x) = \frac{1}{2}(3x^2 - 1)$ $P_3(x) = \frac{1}{2}(5x^3 - 3x)$ $P_4(x) = \frac{1}{8}(35x^4 - 30x^2 + 3) \quad P_5(x) = \frac{1}{8}(63x^5 - 70x^3 + 15x)$

l偶 $P_l(x)$ 偶,l奇 $P_l(x)$ 奇 $P_l(1)=1, \forall l$ 通解为 $y(x)=AP_l(x)+Q_l(x)$ 其中 $P_l(x)$ —被截断多项式 勒氏多项式还可写成 $P_l(x)=$ $Q_l(x)$ -无穷级数

 $\frac{(2l-1)(2l-3)\cdots 1}{l!} \cdot \left[x^l - \frac{1}{2}\frac{l(l-1)}{(2l-1)}x^{l-2} + \frac{1}{2\cdot 4}\frac{l(l-1)(l-2)(l-3)}{(2l-1)(2l-3)}x^{l-4}\right] - \cdots$

微分表示(罗德里格斯公式) $P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l$

然后 $v(x,t)=\int_0^t u(x,t, au)d au$

得 $w(x,t) = \int_0^L \phi(x_0) G(x,x_0,t) dt + \int_0^t \int_0^L f(x_0,\tau) G(x_0,\tau) G(x,x_0,t-\tau) dx_0 d\tau$

用拉普拉斯变换解偏微分方程步骤与用傅里叶变换相似,针对定义在 $[0,\infty)$ 的变量

巻积定理 $\mathcal{L}[f_1(t) * f_2(t)] = \mathcal{L}[f_1]\mathcal{L}[f_2] = F_1(p)F_2(p)$

泊松方程边值问题基本积分公式 $u(r)=\iiint_V G(r,r_0)f(r)dV+\iint_{\Sigma}[G(r,r_0)\frac{\partial u(r)}{\partial n}-u(r)\frac{\partial G(r,r_0)}{\partial n}]dS=\iiint_V G(r,r_0)f(r_0)dV_0+\iint_{\Sigma}[G(r,r_0)\frac{\partial u(r_0)}{\partial n_0}-u(r)\frac{\partial G(r,r_0)}{\partial n_0}]dS_0$

泊松方程第一类边值问题 $u|_{\Sigma} = \phi(r_{\Sigma}), u(r) = \iiint_V G(r, r_0) f(r) dV - \iint_{\Sigma} u(r) \frac{\partial G(r, r_0)}{\partial n} dS =$ $\iiint_V G(\boldsymbol{r},\boldsymbol{r}_0) f(\boldsymbol{r}_0) dV_0 - \iint_{\Sigma} u(\boldsymbol{r}) \frac{\partial G(\boldsymbol{r},\boldsymbol{r}_0)}{\partial n_0} dS_0$

泊松方程第二类边值问题 $\frac{\partial u}{\partial n}|_{\Sigma} \ = \ \phi(r_{\Sigma}), u(r) \ = \ \iiint_V G(r,r_0)f(r)dV \ + \ \iint_{\Sigma} G(r,r_0)\frac{\partial u(r)}{\partial n}dS \ = \ \iint_{\Sigma} G(r,r_0)\frac{\partial u(r)}{\partial n}dS$ 0謝松防程第三类边值问题 $[\alpha u \ + \ eta rac{\partial u}{\partial n}]|_{Sigma} = 0, u(m{r}) = \iiint_V G(m{r}, m{r}_0) f(m{r}) dV$

 $\frac{1}{\beta}\iint_{\Sigma}\phi(\boldsymbol{r})G(\boldsymbol{r},\boldsymbol{r}_{0})dS=\iiint_{V}G(\boldsymbol{r},\boldsymbol{r}_{0})f(\boldsymbol{r}_{0})dV_{0}+\frac{1}{\beta}\iint_{\Sigma}\phi(\boldsymbol{r}_{0})G(\boldsymbol{r},\boldsymbol{r}_{0})dS_{0}$ 拉普拉斯类似

电像法真空中一半径为 R_0 接地导体球,距球心 $a(>R_0)$ 处一点电荷Q,镜像电荷 $Q'=-rac{R_0}{a}Q$ 位于距球心 $b=rac{R_0^2}{a}$ 处

奇数阶贝氏函数 $\begin{cases} J_{n+\frac{1}{2}}(x) = (-1)^n \sqrt{\frac{2}{\pi}} x^{n+\frac{1}{2}} (\frac{1}{x} \frac{d}{dx})^n (\frac{\sin x}{x}) \\ J_{-(n+\frac{1}{2})}(x) = \sqrt{\frac{2}{\pi}} x^{n+\frac{1}{2}} (\frac{1}{x} \frac{d}{dx})^n (\frac{\cos x}{x}) \end{cases}$

积分表示 $J_n(x) = \frac{1}{2\pi} \int_0^{\pi} \cos(x \sin \theta - n\theta) d\theta$ 证明思路:通过整数贝塞尔函数生成函数令 $r=e^{i\theta}$

比较实虚部得 $\begin{cases} \cos(x\sin\theta) = \sum_{n=-\infty}^{\infty} J_n(x)\cos n\theta \\ \sin(x\sin\theta) = \sum_{n=-\infty}^{\infty} J_n(x)\sin n\theta \end{cases}$

后两边同乘 $\cos m\theta$ 或 $\sin m\theta$ 并在 $[0,\pi]$ 积分即得

三角函数贝赛尔级数展开式 $\begin{cases} \cos x = J_0(x) + 2\sum_{n=1}^{\infty} (-1)^n J_{2n}(x) \\ \sin x = 2\sum_{n=0}^{\infty} (-1)^n J_{2n+1}(x) \end{cases}$

渐进公式 $J_n(x) \approx \sqrt{\frac{2}{\pi x}} \cos(x - \frac{x}{4} - \frac{n\pi}{2})$

参数形式的贝赛尔方程 $x^2 \frac{d^2y}{dx^2} + x \frac{dy}{dx} + (\lambda^2 x^2 - \nu^2)y = 0$

其S-L形式为 $\frac{d}{dx} (x \frac{dy}{dx}) - \frac{\nu^2}{x} y + \lambda^2 xy = 0$ 通解为 $y = AJ_{\nu}(\lambda x) + BY_{\nu}(\lambda x)$ 递推公式 $\begin{cases} \frac{d}{d(\lambda x)} [(\lambda x)^{-\nu} J_{\nu}(\lambda x)] = -(\lambda x)^{-\nu} J_{\nu+1}(\lambda x) \\ \frac{d}{d(\lambda x)} [(\lambda x)^{\nu} J_{\nu}(\lambda x)] = (\lambda x)^{\nu} J_{\nu-1}(\lambda x) \end{cases}$

 $\frac{d}{dx}J_0(\lambda x) = -\lambda J_1(\lambda x) \qquad \qquad \frac{d}{dx}\left[\frac{1}{x}J_1(\lambda x)\right] = -\frac{\lambda}{x}J_2(\lambda x)$ $\frac{d}{dx}[x^2J_2(\lambda x)] = \lambda x^2J_1(x)$ $\frac{d}{dx}[xJ_1(\lambda x)] = \lambda xJ_0(\lambda x)$

 $\det \lambda_{\nu m} = \frac{\mu_{\nu m}}{a}$ (前己将 $[0,\mu_{\nu m}]$ 上 $J_{\nu}(x)$ 对应到[0,1])将[0,1]上的 $J_{\nu}(\lambda_{\nu m}x)$ 对应到[0,a]上的 $J(\lambda_{\nu m})$

正交性&模值 $\int_0^a x J_{\nu}(\lambda_{\nu m}x) J_{\nu}(\lambda_{\nu k}x) dx = \frac{a^2}{2} J_{\nu+1}^2(\mu_{\nu m}) \delta_{mk}$

当a = 1比为 $\int_0^1 x J_{\nu}(\mu_{\nu m} x) J_{\nu}(\mu_{\nu k} x) dx = \frac{1}{2} J_{\nu+1}^2(\mu_{\nu m}) \delta_{mk}$ 贝氏函数的完备性 這续点

遊续点 f(x) 同断点 f(x-0)+f(x+0) $=\sum_{m=1}^{\infty}A_{m}J_{\nu}(\lambda_{\nu m}x)$ $+\Phi_{m}=\frac{2}{a^{2}J_{\nu\pm1}^{2}(\mu_{\nu m})}\int_{0}^{a}xJ_{\nu}(\lambda_{\nu m}x)f(x)dx$

球贝塞尔函数 $j_n(x) = \sqrt{\frac{\pi}{2x}} J_{n+\frac{1}{2}}(x)$

 $y_{nm}(x) = j_n(\lambda_{nm}x)$ 是球贝氏方程 $x^2y'' + 2xy' + [kx^2 - n(n+1)]y = 0$ 解

Hankel函数 发散波 $H_{\nu}^{(1)}(x) = J_{\nu}(x) + iN_{\nu}(x) \sim \sqrt{\frac{2}{\pi x}} \exp[i(x - \frac{\nu \pi}{2} - \frac{\pi}{4})]$

汇聚波 $H_{\nu}^{(2)}(x) = J_{\nu}(x) - iN_{\nu}(x) \sim \sqrt{\frac{2}{\pi x}} \exp[-i(x - \frac{\nu \pi}{2} - \frac{\pi}{4})]$

柱形边界条件总结 第一类边界条件 $R(\rho)|_{\rho=\rho_0}=0\Longrightarrow J_m(\lambda\rho_0)=0$

 $\Longrightarrow \lambda_{mn} = \frac{\mu_{mn}}{\rho_0} \Longrightarrow \int_0^{\rho_0} x [J_m(\lambda_{mn}x)]^2 dx = \frac{\rho_0^2}{2} [J_{m+1}(\mu_{mn})]^2$ 第二类边界条件 $\frac{dR}{d\rho}\Big|_{\rho_0}^{\rho_0}=0 \Longrightarrow J_m'(\lambda\rho_0)=0$ (此处 $\mu_{mn}-J_m'(x)$ 的第n个零点)

 $\Longrightarrow \lambda_{mn} = \frac{\mu_{mn}}{\rho_0} \Longrightarrow \int_0^{\rho_0} x [J_m(\lambda_{mn}x)]^2 dx = \frac{1}{2} (\rho_0^2 - \frac{m^2}{\lambda_{mn}^2}) [J_m(\mu_{mn})]^2$

第三类边界条件 $R(\rho_0) + HR'(\rho_0) = 0 \Longrightarrow J_m(\lambda \rho_0) + H\lambda J'_m(\lambda \rho_0) = 0$ (此处 $\mu_{nm} - J_m(x) + H\lambda J'_m(x)$ 零点) $\Longrightarrow \lambda_{mn} = \frac{\mu_{mn}}{\rho_0}$

 $\implies \int_0^{\rho_0} x [J_m(\lambda_{mn} x)]^2 dx = \frac{1}{2} (\rho_0^2 - \frac{m^2}{\lambda_{mn}^2} + \frac{\rho_0^2}{\lambda_{mn}^2}) [J_m(\mu_{mn})]^2$

积分表示 $P_l(x) = \frac{1}{2\pi} \int_0^{\pi} (x + \sqrt{x^2 - 1}\cos\phi)^l d\phi$

对施列夫利积分 $P_l(x) = \frac{1}{2^l 2\pi i} \oint_C \frac{(\xi^2 - 1)^l}{(\xi - x)^{l+1}} d\xi$ 取C为 $\xi = x + \sqrt{x^2 - 1} e^{i\phi}$

生成函数 $\frac{1}{\sqrt{1-2rx+r^2}} = \left\{ \begin{array}{ll} \sum_{i=0}^{\infty} r^l P_l(x) & |r| < 1 \\ \sum_{l=0}^{\infty} \frac{1}{r^l+1} P_l(x) & r > 1 \end{array} \right.$

递推公式 $\forall n=1,2,3,\cdots$ $\overline{n}(n+1)P_{n+1}(x)=(2n+1)xP_n(x)-nP_{n-1}(x)$ $P_n(x)=P'_{n+1}(x)-2xP'_n(x)+P'_{n-1}(x)$

 $\begin{aligned} & r_{n+1}(x) & = n \\ & r_{n-1}(x) & = n \\ & r_{n-1}(x) & = n \\ & r_{n-1}(x) \\ & r_{n-1}(x) & = (2n+1)P_n(x) \\ & r_{n+1}(x) + (n+1)P'_{n-1}(x) & = (2n+1)xP'_n(x) \\ & r_{n+1}(x) + (n+1)P'_{n-1}(x) & = (n+1)P_n(x) + xP'_x(x) \\ & r_{n+1}(x) & = (n+1)P_n(x) + xP'_x(x) \end{aligned}$

莱布尼兹乘积微分法 $\frac{d^n}{dx^n}(f \cdot g) = \sum_{k=0}^n \frac{n!}{(n-k)!k!} \frac{d^k f}{dx^k} \frac{d^{n-k} g}{dx^{n-k}}$

 $P_l(1) = 1 \quad P_l'(1) = \frac{l(l+1)}{2} \quad P_l(-1) = (-1)^l \quad P_l'(-1) = (-1)^{l-1} \frac{l(l+1)}{2}$

 $P_{2n}(0) = (-1)^n \frac{(2n)!}{2^{2n}(n!)^2} \quad P_{2n+1}(0) = 0$

 $P_{2n}(0) - P_{2n+2}(0) = (-1)^n \left(\frac{4n+3}{n+1}\right) \frac{(2n)!}{2^{2n+1}(n!)^2}$ $P_l(x)$ 与k < l次多项式正交 $\int_{-1}^1 f(x) P_l(x) dx = 0$

正交性&模值 $\int_{-1}^{1} P_l(x) P_m(x) = \frac{2}{2l+1} \delta_{lm}$

対 $l \neq m$ 有 $\int_{x}^{1} P_{l}(x) P_{m}(x) dx = -\int_{-1}^{x} = \frac{(1-x^{2})[P_{l}(x)P'_{m}(x) - P_{m}(x)P'_{l}(x)]}{m(m+1)-l(l+1)}$

完备性对在[-1,1]上(分段)光滑的f(x)按勒让德多项式级数展开

连续点 f(x) 间断点 $\frac{f(x-0)+f(x+0)}{2}$ $= \sum_{l=0}^{\infty} C_l P_l(x) \oplus C_l = \frac{2l+1}{2} \int_{-1}^{1} P_l(x) f(x) dx$

连带勒让德方程 $\frac{1}{\sin\theta} \frac{d}{d\theta} (\sin\theta \frac{d\Theta}{d\theta}) + [l(l+1) - \frac{m^2}{\sin^2\theta}]\Theta = 0 \quad m = 0, 1, 2, \cdots \quad l \in \mathbb{R}$ 令 $x = \cos \theta$ 化为 $(1-x^2)\frac{d^2y}{dx^2} - 2x\frac{dy}{dx} + [l(l+1) - \frac{m^2}{1-x^2}]y$ 其通解为

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连带勒让德函数 P_l^m(x) = (1-x^2)^{m/2} P_l^{(m)}(x) \quad m=0,\pm 1,\pm 2,\cdots,\pm l
       微分表示(罗德里格斯公式) P_l^m(x) = \frac{(1-x^2)^{\frac{m}{2}}}{2^l l!} \frac{d^l + m}{dx^l + m} (x^2-1)^l P_l^{-m}(x) = (-1)^m \frac{(l-m)!}{(l+m)!} P_l^m(x) = \frac{(1-x^2)^{-m/2}}{2^l l!} \frac{d^{l-m}}{dx^{l-m}} (x^2-1)^l 或\Theta(\theta) = P_l^m(\cos\theta) \quad m = 0, \pm 1, \pm 2, \cdots, \pm l \quad \pm m > l, \quad P_l^m(x) = 0
                                    P_l^0(x) = P_l(x)
                                    P_1^1(x) = \sqrt{1 - x^2}
                                                                                              P_1^{-1}(x) = -\frac{1}{2}\sqrt{1-x^2}
                                    \begin{array}{lll} P_1\left(x\right) = \sqrt{1-x} & P_1\left(x\right) = -\frac{1}{2}\sqrt{1-x^2} \\ P_2^1\left(x\right) = 3x\sqrt{1-x^2} & P_2^{-1}\left(x\right) = -\frac{1}{2}x\sqrt{1-x^2} \\ P_2^2\left(x\right) = 3(1-x^2) & P_2^{-2}\left(x\right) = \frac{1}{8}(1-x^2) \end{array}
低阶连带勒氏函数
                                    \begin{array}{ll} P_3^1(x) = \frac{3}{2}(1-x^2)^{\frac{1}{2}}(5x^2-1) & P_3^{-1}(x) = -\frac{1}{12}P_3^1(x) \\ P_3^2(x) = 15(1-x^2)x & P_3^{-2}(x) = \frac{1}{8}(1-x^2)x \end{array}
                                   P_3^3(x) = 15(1-x^2)^{\frac{3}{2}}
                                                                                                 P_3^{-3}(x) = -\frac{1}{48}(1-x^2)^{\frac{3}{2}}
积分表示(施列夫利积分)P_l^m(x)=rac{(1-x^2)^{rac{m}{2}}}{2^l}rac{1}{2\pi i}rac{(l+m)!}{l!}\oint_Crac{(z^2-1)^l}{(z-x)^l+m+1}dz
       其中C为围绕z=x的任一闭合回路,取C为半径为\sqrt{x^2-1}的圆周得拉普拉斯积分P_l^m(x)=\frac{i^m}{2\pi}\frac{(l+m)!}{l!}\int_{-\pi}^\pi e^{-im\psi}[\cos\theta+i\sin\theta\cos\psi]^ld\psi
                     (2k+1)xP_k^m(x) = (k+m)P_{k-1}^m(x) + (k-m+1)P_{k+1}^m(x)
                     (2k+1)(1-x^2)^{1/2}P_k^m(x) = P_{k+1}^{m+1}(x) - P_{k-1}^{m+1}(x)
                     (2k+1)(1-x^2)^{1/2}P_k^m(x) = (k+m)(k+m-1)P_{k-1}^{m-1}(x)
递推公式
                          -(k-m+2)(k-m+1)P_{k+1}^{m-1}(x)
                     (2k+1)(1-x^2)\frac{dP_k^m(x)}{dx} = (k+1)(k+m)P_{k-1}^m(x)
                        -k(k-m+1)P_{k+1}^{m}(x)
正交性&模值\int_{-1}^{1} P_{l}^{m}(x) P_{k}^{m}(x) = \frac{2}{2l+1} \frac{(l+m)!}{(l-m)!} \delta_{lk}
完备性对非负整数m,区间[-1,1]上分段光滑函数f(x)可作连带勒让德级数展开
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雄度 $\nabla \times E = [ijk; \frac{\partial}{\partial x} \frac{\partial}{\partial y} \frac{\partial}{\partial z}; E_x E_y E_x] = (\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z})i + (\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x})j + (\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y})k$ 标量场的機度无能 $\nabla \times \nabla \phi = 0$ 矢量场的旋度无能 $\nabla \times \nabla \times f = 0$ $\nabla (\phi \psi) = \phi \nabla \psi + \psi \nabla \phi$ $\nabla \cdot (\phi f) = (\nabla \phi) \cdot f + \phi \nabla f$ $\begin{array}{l} \nabla \times (\phi f) = (\nabla \phi) \times f + \phi \nabla \times f & \nabla \cdot (f \times g) = (\nabla \times f) \cdot g - f \cdot (\nabla \times g) \\ \nabla \times (f \times g) = (g \cdot \nabla) f + (\nabla \cdot g) f - (f \cdot \nabla) g - (\nabla \cdot f) g \end{array}$

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f(x) = \sum_{l=m}^{\infty} C_l P_l^m(x) 其中C_l = \frac{2l+1}{2} \frac{(l-m)!}{(l+m)!} \int_{-1}^1 f(x) P_l^m(x) dx
球谐函数Y_l^m(\theta,\phi) = P_l^{|m|}(\cos\theta)e^{im\phi} \begin{cases} l = 0,1,2,\cdots \\ -1,-1,2,\cdots \end{cases}
                                                                                                                     m = 0, \pm 1, \pm 2, \cdots, \pm l 
             是方程 \frac{1}{\sin\theta} \frac{\partial}{\partial \theta} (\sin\theta \frac{\partial Y}{\partial \theta}) + \frac{1}{\sin^2\theta} \frac{\partial^2 Y}{\partial \phi^2} + l(l+1)Y = 0的通解
 正交性&模值\int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} Y_l^m(\theta,\phi) Y_k^n(\theta,\phi) \sin\theta d\theta d\phi = \frac{4\pi}{2l+1} \frac{(l+m)!}{(l-m)!} \delta_{mn} \delta_{lk}
 低阶归一化球谐函数  \begin{cases} Y_{0,0}(\theta,\phi) = \frac{1}{\sqrt{4\pi}} & Y_{2,\pm 2} = \sqrt{\frac{15}{32\pi}}\sin^2\theta e^{\pm 2i\phi} \\ Y_{1,0} = \sqrt{\frac{3}{4\pi}}\cos\theta & Y_{1,\pm 1} = \mp\sqrt{\frac{3}{8\pi}}\sin\theta e^{\pm i\phi} \end{cases} 
                                                             Y_{2,0} = \sqrt{\frac{5}{16\pi}} (3\cos^2\theta - 1) Y_{2,\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \cos\theta \sin\theta e^{\pm i\phi}
 完备性定义在球面上函数f(\theta,\phi)可展开为f(\theta,\phi)=\sum_{l=1}^m\sum_{m=-l}^lC_l^mP_l^{|m|}(\cos\theta)e^{im\phi}=
 \sum_{m=0}^{\infty} \sum_{l=-m}^{m} C_l^m P_l^{|m|} (\cos \theta) e^{im\phi}
            珠谱函数另一种定义Y_l^m(\theta,\phi)=P_l^m(\cos\theta) \begin{cases} \sin m\phi \\ \cos m\phi \end{cases} \begin{cases} m=0,1,2,\cdots,l \\ l=0,1,2,\cdots \end{cases}
正交性&模值 \int_{-1}^{1} P_l^m(x) P_k^n(x) dx = \frac{(l+m)!}{(l-m)!} \frac{2}{2l+1} \delta_{mn} \delta lk 完备性定义在球面上函数f(\theta,\phi)先对\phi做傅里叶级数展开
         f(\theta,\phi) = \sum_{m=0}^{\infty} [A_m(\theta)\cos m\phi + B_m(\theta)\sin m\phi]
         \sharp \psi \left\{ \begin{array}{l} \Delta m = 0 \left[ \frac{1}{2} \sin \left( \phi \right) \sin \left( \phi \right) \sin \left( \phi \right) \right] \\ A m \left( \theta \right) = \frac{1}{\delta m} \int_{0}^{2\pi} f(\theta, \phi) \cos m \phi d\phi \\ B m \left( \theta \right) = \frac{1}{\pi} \int_{0}^{2\pi} f(\theta, \phi) \sin m \phi d\phi \end{array} \right., \, \delta_{m} = \left\{ \begin{array}{l} 2 & m = 0 \\ 1 & m = 1, 2, 3, \cdots \end{array} \right.
         再对A_m和B_m用P_l^m(\cos\theta)展开得 B_m(\theta) = \sum_{l=m}^{\infty} A_l^m P_l^m(\cos\theta)
                        \begin{aligned} & B_{m}(\theta) = \sum_{l=m}^{\infty} B_{l}^{m,l} P_{l}^{m}(\cos \theta) \\ & A_{l}^{m} = \frac{2l+1}{2} \frac{(l-m)!}{(l+m)!} \int_{0}^{\pi} A_{m}(\theta) P_{l}^{m}(\cos \theta) \sin \theta d\theta \\ & = \frac{2l+1}{2\pi\delta_{m}} \frac{(l+m)!}{(l+m)!} \int_{0}^{\pi} \int_{0}^{2\pi} f(\theta,\phi) P_{l}^{m}(\cos \theta) \cos m\phi \sin \theta d\theta \\ & B_{l}^{m} = \frac{2l+1}{2} \frac{(l-m)!}{(l+m)!} \int_{0}^{\pi} B_{m}(\theta) P_{l}^{m}(\cos \theta) \sin \theta d\theta \end{aligned}
                                =\frac{2l+1}{2\pi}\frac{(l-m)!}{(l+m)!}\int_0^\pi\int_0^{2\pi}f(\theta,\phi)P_l^m(\cos\theta)\sin m\phi\sin\theta d\theta d\phi
\begin{split} &\nabla (f \cdot g) = f \times (\nabla \times g) + (f \cdot \nabla)g + g \times (\nabla \times f) + (g \cdot \nabla)f \\ &\nabla \times (\nabla \times f) = \nabla (\nabla \cdot f) - \nabla^2 f \qquad a \times (b \times c) = b(a \cdot c) - c(a \cdot b) \\ & \| \text{ 簡斯定理} \iint_{\partial V} E \cdot dS = \iiint \nabla \cdot E dV \qquad \qquad \text{ 格林定理} \nabla \cdot (u \nabla v) = u \nabla \cdot \nabla v \cdot dV \end{split}
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格林定理 $\nabla \cdot (u \nabla v) = u \nabla \cdot \nabla v + (\nabla u) \cdot (\nabla v)$

	直角坐标系	柱坐标系	球坐标系	
直角	旦用土柳水	$x = \rho \cos \phi, y = \rho \sin \phi, z$	$x = r \sin \theta \cos \phi, y = r \sin \theta \sin \phi, z = r \cos \theta$	
柱	$\rho = \sqrt{x^2 + y^2}, \phi = \arctan(y/x), z = z$, ,,,	$\rho = r\sin\theta, \phi, z = r\cos\theta$	
球	$r = \sqrt{x^2 + y^2 + z^2}, \theta = \arccos(z/r), \phi = \arctan(y/x)$	$r = \sqrt{\rho^2 + z^2}, \theta = \arctan(\rho/z), \phi$		
矢量 A	$A_{\mathcal{X}}\hat{x} + A_{\mathcal{Y}}\hat{y} + A_{\mathcal{Z}}\hat{z}$	$A_{ ho}\hat{ ho} + A_{\phi}\hat{\phi} + A_{z}\hat{z}$	$A_{T}\hat{r}+A_{ heta}\hat{ heta}+A_{\phi}\hat{\phi}$	
梯度∇ƒ	$\frac{\partial f}{\partial x}\hat{x} + \frac{\partial f}{\partial y}\hat{y} + \frac{\partial f}{\partial z}\hat{z}$	$rac{\partial f}{\partial ho}\hat{ ho}+rac{1}{ ho}rac{\partial f}{\partial \phi}\hat{\phi}+rac{\partial f}{\partial z}\hat{z}$	$rac{\partial f}{\partial r}\hat{r}+rac{1}{r}rac{\partial f}{\partial heta}\hat{ heta}+rac{1}{r\sin heta}rac{\partial f}{\partial \phi}\hat{\phi}$	
散度 ▽ · A	$\frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$	$\frac{1}{ ho} \frac{\partial (\rho A_{ ho})}{\partial ho} + \frac{1}{ ho} \frac{\partial A_{\phi}}{\partial \phi} + \frac{\partial A_{z}}{\partial z}$	$\frac{1}{r^2}\frac{\partial (r^2A_r)}{\partial r} + \frac{1}{r\sin\theta}\frac{\partial (A_\theta\sin\theta)}{\partial \theta} + \frac{1}{r\sin\theta}\frac{\partial A_\phi}{\partial \phi}$	
旋度∇ × A	$ \begin{array}{l} (\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z})\hat{x} + (\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x})\hat{y} \\ + (\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y})\hat{z} \end{array} $	$(\frac{1}{\rho}\frac{\partial A_z}{\partial \phi} - \frac{\partial A_{\phi}}{\partial z})\hat{\rho} + (\frac{\partial A_{\rho}}{\partial z} - \frac{\partial A_{z}}{\partial \rho})\hat{\phi} + \frac{1}{\rho}(\frac{\partial (\rho A_{\phi})}{\partial \rho} - \frac{\partial A_{\rho}}{\partial \phi})\hat{z}$	$ \begin{array}{l} \frac{1}{r\sin\theta}(\frac{\partial(A_{\phi}\sin\theta)}{\partial\theta}-\frac{\partial A_{\theta}}{\partial\phi})\hat{r}+\frac{1}{r}(\frac{1}{\sin\theta}\frac{\partial A_{r}}{\partial\phi}-\frac{\partial(rA_{\phi})}{\partial r})\hat{\theta} \\ +\frac{1}{r}(\frac{\partial(rA_{\theta})}{\partial r}-\frac{\partial A_{r}}{\partial\theta})\hat{\phi} \end{array} $	
拉普拉斯算子▽ ²	$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$	$\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho \frac{\partial u}{\partial \rho}) + \frac{1}{\rho^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial z^2}$	$\frac{1}{r^2}\frac{\partial}{\partial r}(r^2\frac{\partial}{\partial r}) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial\theta}(\sin\theta\frac{\partial}{\partial\theta}) + \frac{1}{r^2\sin^2\theta}\frac{\partial^2}{\partial\phi^2}$	

斯多克斯定理 $\oint_{\partial S} \mathbf{E} \cdot d\mathbf{l} = \iint_{S} (\nabla \times \mathbf{E}) \cdot d\mathbf{S}$

泛定方程	$\frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2}$ 和 $\frac{\partial u}{\partial t} = a^2 \frac{\partial^2 u}{\partial x^2}$ (分离变量得方程 $X''(x) + \lambda X$	(x) = 0)的常用本征函数及其 x	本征值	
边界条件	本征值 λ_n	本征函数		
$u _{x=0} = 0, u _{x=L} = 0$	$\frac{(\frac{n\pi}{L})^2}{[\frac{(2n+1)\pi}{2L}]^2}$	$B_n \sin \frac{n\pi}{L} x, n = 1, 2, 3 \cdots$		
$u _{x=0} = 0, u_x _{x=L} = 0$	$\left[\frac{(2n+1)\pi}{2I}\right]^2$	$B_n \sin \frac{(2n+1)\pi}{2L} x, n = 0, 1, 2, \cdots$		
$u_x _{x=0} = 0, u _{x=L} = 0$	$[\frac{(2n+1)\pi}{2L}]^2$	$A_n \cos \frac{(2n+1)\pi}{2L} x, n = 0, 1, 2, \cdots$		
$ u_x _{x=0} = 0, u_x _{x=L} = 0 $	$\left[\frac{n\pi}{L}\right]^2$	$A_n \cos \frac{n\pi}{L} x, n = 0, 1, 2, \cdots$		
$u _{x=0} = 0, [u + u_x] _{x=L} = 0$	μ_n^2 , s.t. $\tan \mu_n L = -\mu_n$	$\sin \mu_n x, n = 1, 2, \cdots$		
$ u_x _{x=0} = 0, u+u_x _{x=L} = 0$	μ_n^2 , s.t. $\cot \mu_n L = \mu_n$	$\cos \mu_n x, n = 1, 2, \cdots$		
$u _{x=0} = 0, [u - u_x/2] _{x=L} = 0$	$-\mu_0^2, \mu_n^2$, s.t. $\tanh \mu_0 L = \mu_0/2, \tan \mu_n L = \mu_n/2$	$\sinh \mu_0 x, \sinh \mu_n x, n = 1, 2, \cdots$		
$u_x _{x=0} = 0, [u - u_x/2] _{x=L} = 0$	$-\mu_0^2, \mu_n^2$, s.t. $\coth \mu_0 L = \mu_0/2, \cot \mu_n L = -\mu_n/2$	$\cosh \mu_0 x, \cos \mu_n x, n = 1, 2, \cdots$		
$[u + u_x] _{x=0} = 0, [u + u_x] _{x=L} = 0$	$-1,(\frac{n\pi}{L})^2$	e^{-x} , $\frac{n\pi}{L}\cos\frac{n\pi}{L}x - \sin\frac{n\pi}{L}x$, $n = 1, 2, \cdots$		
$[u - u_x] _{x=0} = 0, [u - u_x] _{x=L} = 0$	$-1, (\frac{n\pi}{L})^2$	e^x , $\frac{n\pi}{L}\cos\frac{n\pi}{L}x + \sin\frac{n\pi}{L}x$, $n = 1, 2, \cdots$		
$[u - u_x] _{x=0} = 0, [u + u_x] _{x=L} = 0$	$-1, (\frac{n\pi}{L})^{2} \\ -1, (\frac{n\pi}{L})^{2} \\ \mu_{n}^{2}, \text{ s.t. } \tan \mu_{n} = \frac{2\mu_{n}}{\mu_{n}^{2} - 1}$	$\mu_n \cos \mu_n x + \sin \mu_n x, n = 1, 2, \cdots$		
$[u + u_x] _{x=0} = 0, [u - u_x] _{x=L} = 0$	$-\mu_0^2, \mu_n^2, \text{ s.t. } \tan \mu_0 = \frac{2\mu_0}{\mu_0^2 - 1}, \tan \mu_n = -\frac{2\mu_n}{\mu_n^2 - 1}$	$\mu_0 \cosh \mu_0 x - \sinh \mu_0 x, \mu_n \cos \mu_n x - \sin \mu_n x, n = 1, \cdots$		
	非齐次边界条件		非齐次边界条件辅助函数Ω	
	$=u_1(t), u _{x=L} = u_2(t)$	$[u_2(t) - u_1(t)]/L + u_1(t)$		
	$u_1(t), u_x _{x=L} = u_2(t)$	$u_2(t)x + u_1(t)$		
	$=u_1(t), u _{x=L} = u_2(t)$	$u_1(t)x + u_2(t) - Lu_1(t)$		
$u_x _{x=0}$ =	$=u_1(t), u_x _{x=L} = u_2(t)$	$\frac{[u_2(t)x - u_1(t)]/(2L) + u_1(t)x}{$ 拉普拉斯变换表		
$f(t) = \mathcal{F}^{-1}[F(\omega)]$	傅里叶变换表 $F(\omega) = \mathcal{F}[f(t)]$	$f(t) = \mathcal{L}^{-1}[F(p)]$	型音位用文件表 $F(p) = \mathcal{L}[f(t)]$	
(E 4 < T	$\epsilon_{\rm sin} \omega \tau$	$J(t) = \mathcal{L} [\Gamma(p)]$		
矩形脉冲 $\left\{egin{array}{ll} E & t \leq rac{ au}{2} \ 0 & ext{otherwise} \end{array} ight.$	$\begin{cases} 2E \frac{\sin 2}{\omega} & \omega \neq 0 \\ E\tau & \omega = 0 \end{cases}$	单位阶跃 $u(t)$	$\frac{1}{p}$	
半边指数衰减 $ \begin{cases} 0 & t < 0 \\ e^{-\beta t} & t \ge 0 \end{cases} $	$\frac{1}{\beta + i\omega}$	$\frac{t^m}{\Gamma(m+1)}, m > -1$	$\frac{1}{p^{m+1}}$	
双边指数衰减 $Ee^{-a t }$	$\frac{2aE}{a^2+\omega^2}$	$\frac{t^n}{n!}, n = 0, 1, 2, \cdots$	$\frac{1}{p^{n+1}}$	
钟形脉冲 $Ae^{-eta t^2}$	$\sqrt{\frac{\pi}{\beta}}Ae^{-\frac{\omega^2}{4\beta}}$	e^{kt}	$\frac{1}{p-k}$	
傅里叶核 $\frac{\sin \omega_0 t}{\pi t}$	$\begin{cases} 1 & \omega \leq \omega_0 \\ 0 & \text{otherwise} \end{cases}$	$\sin \beta t$	$\frac{\beta}{p^2 + \beta^2}$	
高斯分布 $\frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{t^2}{2\sigma^2}}$	$e^{-\frac{\sigma^2\omega^2}{2}}$	$\cos \beta t$	$\frac{p}{p^2+\beta^2}$	
単位脉冲δ(t)	1	$\sinh \beta t$	$\frac{\beta}{n^2-\beta^2}$	
余弦 $\cos \omega_0 t$	$\pi[\delta(\omega+\omega_0)+\delta(\omega-\omega_0)]$	$\cosh \beta t$	$ \frac{p}{p^2 + \beta^2} $ $ \frac{\beta}{p^2 - \beta^2} $ $ \frac{p}{p^2 - \beta^2} $	
正弦sin $\omega_0 t$	$i\pi[\delta(\omega+\omega_0)-\delta(\omega-\omega_0)]$	单位脉冲 $\delta(t)$	1	
单位阶跃 $u(t)$	$\frac{1}{i\omega} + \pi\delta(\omega)$	$\delta(t-a)$	e^{-ap}	
直流E	$2\pi E\delta(\omega)$	$\delta'(t)$	p	
指数 $e^{i\omega_0 t}$	$2\pi\delta(\omega-\omega_0)$	$\frac{1}{\sqrt{\pi t}}$	$\frac{p}{\frac{1}{\sqrt{p}}}$	
t	$2i\pi\delta'(\omega)$	$2\sqrt{\frac{t}{\pi}}$	$\frac{1}{p\sqrt{p}}$	
t^n	$2i^n\pi\delta^{(n)}(\omega)$	t	$\frac{1}{p^2}$	
$\frac{1}{a^2+t^2}$	$\frac{\pi}{a} e^{-a \omega }$	$a^{t/ au}$	$\frac{1}{p-(\ln a)/\tau}$	