

Assigned on 3/8, 2019. Due on 3/22, 2019

Problem 2-1:

- Derive the formulas of the DT State-Space System with Inner Time Delay
- See pages 20-21 of Lecture Note: DCS-11.
- Reference:
  - Bjorn Wittenmark, "Sampling of a system with a time delay," IEEE Transactions on Automatic Control, Vol. 30, No. 5, pp. 507-510, May 1985.
  - <https://ieeexplore.ieee.org/document/1103985>

Problem 2-2:

- Derive the discrete-time system corresponding to the following continuous-time system when a zero-order-hold circuit is used:

$$\begin{aligned}\frac{d}{dt}\mathbf{x} &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u \\ y &= \begin{bmatrix} 1 & 0 \end{bmatrix} \mathbf{x}\end{aligned}$$

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Problem 2-3:

- Use the z-transform to determine the output sequence of the difference equation:

$$y[k+2] - 1.5y[k+1] + 0.5y[k] = u[k+1]$$

- When  $u[k]$  is a step at  $k=0$  and when  $y[0] = 0.5$  and  $y[-1] = 1$ .

Problem 2-4:

- Sample the continuous-time system:

$$\frac{d}{dt}\mathbf{x}(t) = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u(t-0.2)$$

- Using the sampling interval  $h = 0.3$ . Determine the pulse-transfer operator.

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