ANJUN CHEN

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EDUCATION

Zhejiang University Hangzhou, CN

Ph.D. Student, College of Control Science and Engineering Mar 2022 – June 2025

Area of Study: Computer Vision and Robotics Advisor: Prof. Qi Ye, Prof. Jiming Chen

Zhejiang University Hangzhou, CN

M.E. Student, Polytechnic Institute Sep 2019 – Mar 2022

Major: Control Engineering

Jilin University Changchun, CN

B.E., College of Communication Engineering Sep 2015 – Jun 2019

Major: Measurement Technology

RESEARCH EXPERIENCE

University of Pennsylvania Philadelphia, US

Visiting Student, GRASP Lab

Aug 2024 – Feb 2025

Research Topic: Gaussian Avatar

Advisor: Prof. Lingjie Liu

NetEase Hangzhou, CN

Research Intern, Fuxi AI Lab Nov 2023 – Mar 2024

Research Topic: Multi-Modal Matching

PUBLICATIONS

Conferences

- 1. Vid2Sim: Generalizable, Video-based Reconstruction of Geometry and Physical Property for Mesh-free Simulation
 - C. Chen, Z. Dou, C. Wang, Y. Huang, A. Chen, Q. Feng, J. Gu, and L. Liu.

IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR) 2025

- 2. TaskExp: Enhancing Generalization of Multi-Robot Exploration with Multi-Task Pre-Training S. Zhu, Y. Xu, A. Chen, and J. Xu.
 - IEEE International Conference on Robotics and Automation (ICRA), 2025
- 3. UpViTaL: Unpaired Visual-Tactile Self-Supervised Representation Learning for Dexterous Robotic Manipulation
 - G. Han, Q. Liu, Y. Cui, A. Chen, J. Chen, and Q. Ye.

IEEE International Conference on Robotics and Automation (ICRA), 2025

- 4. MAexp: A Generic Platform for RL-Based Multi-Agent Exploration
 - S. Zhu, J. Zhou, A. Chen, M. Bai, J. Chen, and J. Xu.

IEEE International Conference on Robotics and Automation (ICRA), 2024

- 5. InterRep: A Visual Interaction Representation for Robotic Grasping
 - Y. Cui, Q. Liu, A. Chen, Q. Ye, G. Li, and J. Chen.

IEEE International Conference on Robotics and Automation (ICRA), 2024

- 6. CAMInterHand: Cooperative Attention for Multi-View Interactive Hand Pose and Mesh Reconstruction G. Han, Q. Ye, **A. Chen**, and J. Chen.
 - IEEE International Conference on Robotics and Automation (ICRA), 2024
- 7. ImmFusion: Robust mmWave-RGB Fusion for 3D Human Body Reconstruction in All Weather Conditions **A. Chen**, X. Wang, K. Shi, S. Zhu, Y. Chen, B. Fang, J. Chen, Y. Huo, and Q. Ye.

IEEE International Conference on Robotics and Automation (ICRA), 2023

8. mmBody Benchmark: 3D Body Reconstruction Dataset and Analysis for Millimeter Wave Radar A. Chen, X. Wang, S. Zhu, Y. Li, J. Chen, and Q. Ye. *ACM International Conference on Multimedia (ACM MM)*, 2022

Journals

- 1. AdaptiveFusion: Adaptive Multi-Modal Multi-View Fusion for 3D Human Body Reconstruction A. Chen, X. Wang, Z. Xu, K. Shi, Y. Qin, Y. Huo, J. Chen, and Q. Ye. *IEEE Transactions on Multimedia (TMM)*, 2025
- 2. Towards Weather-Robust 3D Human Body Reconstruction: Millimeter-Wave Radar-Based Dataset, Benchmark, and Multi-Modal Fusion
 - **A.** Chen, X. Wang, Z. Xu, K. Shi, J. Chen, Y. Huo, and Q. Ye. *IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)*, 2024
- 3. Radar and Camera Fusion for Object Detection and Tracking: A Comprehensive Survey K. Shi, S. He, Z. Shi, A. Chen, J. Chen, and J. Luo. *IEEE Communications Surveys and Tutorials (COMST)*, 2024
- 4. Road-Map Aided GM-PHD Filter for Multi-Vehicle Tracking with Automotive Radar K. Shi, Z. Shi, C. Yang, S. He, J. Chen, and **A. Chen**. *IEEE Transactions on Industrial Informatics (TII)*, 2021

AWARDS & SCHOLARSHIPS

Academic Scholarship of Zhejiang University Outstanding Graduate Student of Zhejiang University

PROGRAMMING EXPERIENCE

Python, C++, C, Java, Matlab

TEACHING AND SERVICE

Reviewer: CVPR, ICRA, IROS, TCSVT, IOTJ, RAL

Teaching Assistant: Computer Vision, Zhejiang University Spring 2022