# Anjun Chen

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## WORK EXPERIENCE

Xiamen University Xiamen, CN

Assistant Professor, School of Informatics

Jul 2025 - Now

Research Interest: Embodied AI, Robotics, Computer Vision

# **EDUCATION**

Zhejiang University Hangzhou, CN

Ph.D. Student, College of Control Science and Engineering Mar 2022 – June 2025

Area of Study: Computer Vision and Robotics Advisor: Prof. Qi Ye, Prof. Jiming Chen

Zhejiang University Hangzhou, CN

*M.E. Student*, Polytechnic Institute Sep 2019 – Mar 2022

Major: Control Engineering

Jilin University Changchun, CN

B.E., College of Communication Engineering Sep 2015 – Jun 2019

Major: Measurement Technology

#### RESEARCH EXPERIENCE

University of Pennsylvania Philadelphia, US

Visiting Student, GRASP Lab

Aug 2024 – Feb 2025

Research Topic: Gaussian Avatar

Advisor: Prof. Lingjie Liu

NetEase Hangzhou, CN

Research Intern, Fuxi AI Lab Nov 2023 – Mar 2024

Research Topic: Multi-Modal Matching

# **PUBLICATIONS**

# Conferences

1. Vid2Sim: Generalizable, Video-based Reconstruction of Geometry and Physical Property for Mesh-free Simulation

C. Chen, Z. Dou, C. Wang, Y. Huang, A. Chen, Q. Feng, J. Gu, and L. Liu.

IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR) 2025

2. TaskExp: Enhancing Generalization of Multi-Robot Exploration with Multi-Task Pre-Training S. Zhu, Y. Xu, A. Chen, and J. Xu.

IEEE International Conference on Robotics and Automation (ICRA), 2025

3. UpViTaL: Unpaired Visual-Tactile Self-Supervised Representation Learning for Dexterous Robotic Manipulation

G. Han, Q. Liu, Y. Cui, A. Chen, J. Chen, and Q. Ye.

IEEE International Conference on Robotics and Automation (ICRA), 2025

4. MAexp: A Generic Platform for RL-Based Multi-Agent Exploration

S. Zhu, J. Zhou, A. Chen, M. Bai, J. Chen, and J. Xu.

IEEE International Conference on Robotics and Automation (ICRA), 2024

5. InterRep: A Visual Interaction Representation for Robotic Grasping

Y. Cui, Q. Liu, A. Chen, Q. Ye, G. Li, and J. Chen.

IEEE International Conference on Robotics and Automation (ICRA), 2024

6. CAMInterHand: Cooperative Attention for Multi-View Interactive Hand Pose and Mesh Reconstruction G. Han, Q. Ye, A. Chen, and J. Chen.

IEEE International Conference on Robotics and Automation (ICRA), 2024

- 7. ImmFusion: Robust mmWave-RGB Fusion for 3D Human Body Reconstruction in All Weather Conditions A. Chen, X. Wang, K. Shi, S. Zhu, Y. Chen, B. Fang, J. Chen, Y. Huo, and Q. Ye. *IEEE International Conference on Robotics and Automation (ICRA)*, 2023
- 8. mmBody Benchmark: 3D Body Reconstruction Dataset and Analysis for Millimeter Wave Radar A. Chen, X. Wang, S. Zhu, Y. Li, J. Chen, and Q. Ye. *ACM International Conference on Multimedia (ACM MM)*, 2022

#### Journals

- 1. AdaptiveFusion: Adaptive Multi-Modal Multi-View Fusion for 3D Human Body Reconstruction A. Chen, X. Wang, Z. Xu, K. Shi, Y. Qin, Y. Huo, J. Chen, and Q. Ye. *IEEE Transactions on Multimedia (TMM)*, 2025
- 2. Towards Weather-Robust 3D Human Body Reconstruction: Millimeter-Wave Radar-Based Dataset, Benchmark, and Multi-Modal Fusion

**A.** Chen, X. Wang, Z. Xu, K. Shi, J. Chen, Y. Huo, and Q. Ye. *IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)*, 2024

- 3. Radar and Camera Fusion for Object Detection and Tracking: A Comprehensive Survey K. Shi, S. He, Z. Shi, A. Chen, J. Chen, and J. Luo. *IEEE Communications Surveys and Tutorials (COMST)*, 2024
- Road-Map Aided GM-PHD Filter for Multi-Vehicle Tracking with Automotive Radar K. Shi, Z. Shi, C. Yang, S. He, J. Chen, and A. Chen. IEEE Transactions on Industrial Informatics (TII), 2021

### **AWARDS & SCHOLARSHIPS**

Academic Scholarship of Zhejiang University
Outstanding Graduate Student of Zhejiang University

#### TEACHING AND SERVICE

Teaching: Embedded System, Xiamen University

Teaching Assistant: Computer Vision, Zhejiang University

Reviewer: CVPR, AAAI, ICRA, IROS, TCSVT

Spring 2022