

Math, Inner Product Space#3

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1. (4.2)

D should take the form of $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$

$p_D(z) = \det(zI - D) = z^3$. If $p_D(z) = 0$, it indicates that eigenvalue of D is 0 with the algebraic multiplicity of 3. Also $\mathcal{N}(0I - D) = \mathcal{N}(-D) = \text{span}\{[x, 0, 0]^T\}$. The geometric multiplicity is 1, since $\dim(\mathcal{N}(-D)) = 1$.

2. (4.4)

Using 4.3, we could show if $(\text{tr}(A)^2 - 4\det(A))$ is non-negative, then the matrix only got real eigenvalues, otherwise, it only gets imaginary eigenvalues.

i. If the matrix is Hermitian, the $A = \begin{bmatrix} a & b \\ b & d \end{bmatrix}$, then $(\text{tr}(A)^2 - 4\det(A)) = (a - d)^2 + 4b^2 \geq 0$

ii. If the matrix is skew-Hermitian, then $\begin{bmatrix} 0 & b \\ -b & 0 \end{bmatrix}$. Therefore, $(\text{tr}(A)^2 - 4\det(A)) = -4b^2 < 0$ for $b \neq 0$

3. (4.6)

Let $A_{n \times n}$ be an upper triangular matrix. $\det(\lambda I - A) = 0 \implies \prod_{i=1}^n (\lambda_i - a_{ii}) = 0$. Therefore, the eigenvalues of matrix A are its diagonal elements.

4. (4.8)

i. To prove $\{\sin(x), \cos(x), \sin(2x), \cos(2x)\}$ is the basis for V , we need to prove they are linearly independent. This is equivalent to prove that for $\forall x \in \mathbb{R}$, $a\sin(x) + b\cos(x) + c\sin(2x) + d\cos(2x) = 0$ only when $a = b = c = d = 0$. When $x = 0$, $b + d = 0$. When $x = \pi$, $-b + d = 0$. Therefore, $b = d = 0$. Also, when $x = \frac{\pi}{2}$, $a - d = 0 \implies a = 0$. Then $\forall x \in \mathbb{R}$, $d\cos(2x) = 0 \implies d = 0$. This completes the proof that S is a basis for V .

ii. $(a\sin(x) + b\cos(x) + c\sin(2x) + d\cos(2x))' = (-b)\sin(x) + a\cos(x) + (-2d)\sin(2x) + 2ccos(x)$. So the matrix representation of D is $\begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & 2 & 0 \end{bmatrix}$

iii.

5. (4.13)

Let $B = P^{-1}AP$, where B is a diagonal matrix. Since P is a non-singular matrix, it indicates that A is diagonalizable. According to the Theorem 4.3.7, A is also semisimple. Then columns of P are just the eigenvectors of A and B is a diagonal matrix with eigenvalues on its diagonal. $\lambda = 1$ and 0.4 . Therefore, we let $P = \begin{bmatrix} 2 & 1 \\ 1 & -1 \end{bmatrix}$

6. (4.15)

We will use Theorem 4.3.7 and Proposition 4.3.10 to prove this. According to Theorem 4.3.7, A is semisimple, therefore diagonalizable. We could write $D = P^{-1}AP$ where D is a diagonalizable matrix with eigenvalues of A on its diagonal. And columns of P form the eigenspace of A . According to Proposition 4.3.10, we know that for $i = 1, 2, \dots, n, D^i = P^{-1}A^iP$. Also, because P is a linear operator, we have $P^{-1}f(A)P = a_0I + a_1P^{-1}AP + \dots + a_nP^{-1}A^nP =$

$$a_0I + a_1D + \dots + a_nD^n. \text{ Since we know that } D^i = \begin{bmatrix} \lambda_1^i & & \\ & \ddots & \\ & & \lambda_n^i \end{bmatrix}, \text{ Then}$$

$$P^{-1}f(A)P = \begin{bmatrix} \sum_{i=0}^n a_i \lambda_1^i & & \\ & \ddots & \\ & & \sum_{i=0}^n a_i \lambda_n^i \end{bmatrix} = \begin{bmatrix} f(\lambda_1) & & \\ & \ddots & \\ & & f(\lambda_n) \end{bmatrix}$$

7. (4.16)

i. We have in 4.13 that $D = P^{-1}AP$, where $D = \begin{bmatrix} 1 & 0 \\ 0 & 0.4 \end{bmatrix}$ and $P = \begin{bmatrix} 2 & 1 \\ 1 & -1 \end{bmatrix}$.

According to proposition 4.3.10, $A^n = PD^nP^{-1}$. So $\lim_{n \rightarrow \infty} A^n = \lim_{n \rightarrow \infty} PD^nP^{-1} = P(\lim_{n \rightarrow \infty} D^n)P^{-1} = P \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} P^{-1} = \begin{bmatrix} \frac{2}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{1}{3} \end{bmatrix}$

ii. It doesn't matter.

iii. Since the eigenvalues of A are 1 and 0.4, according to Theorem 4.3.12, the eigenvalues are $3 + 5 * 1 + 1^3 = 9$ and $3 + 5 * 0.4 + 0.4^3 = 5.064$.

8. (4.18)

Since the characteristic polynomial of A and A^T is the same, therefore, A and A^T have the same eigenvalues. If λ is a eigenvalue of A , it's Also an eigenvalue of A^T . Therefore, \exists non-zero x , such that $A^T X = \lambda x \implies x^T A = \lambda x^T$.

9. (4.20)

Since A is Hermitian, $B = U^H A U \implies B^H = (U^H A U)^H = (U^H A^H U) = (U^H A U) = B$.

10. (4.24)

i. If A is Hermitian,

11. (4.31)

$$\begin{aligned}
 \text{i. } \|A\|_2 &= \sup_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2} \\
 &= \sup_{x \neq 0} \frac{\|U\Sigma V^H x\|_2}{\|x\|_2} \\
 &= \sup_{x \neq 0} \frac{\|\Sigma V^H x\|_2}{\|x\|_2} \quad (\text{invariant under multiplication by orthonormal matrix}) \\
 &= \sup_{x \neq 0} \frac{\|\Sigma y\|_2}{\|V y\|_2} \quad (\text{let } y = V^H x) \\
 &= \sup_{x \neq 0} \frac{\|\Sigma y\|_2}{\|y\|_2} \quad (\text{invariant under multiplication by orthonormal matrix}) \\
 &= \sup_{x \neq 0} \frac{(\sum_{i=1}^n |\sigma_i y_i|^2)^{\frac{1}{2}}}{(\sum_{i=1}^n |y_i|^2)^{\frac{1}{2}}}
 \end{aligned}$$

We let $y = [1, 0, \dots, 0]^H$, then $\|A\|_2 = \sigma_1$

ii. Since, based on singular value decomposition, $A^{-1} = (U\Sigma V^H)^{-1} = V\Sigma^{-1}U^H$. The diagonal elements of Σ^{-1} are $\frac{1}{\sigma_1}, \frac{1}{\sigma_2}, \dots, \frac{1}{\sigma_n}$, the biggest of which will be $\frac{1}{\sigma_n}$. Therefore, according to the result of i., we know that $\|A^{-1}\|_2 = \frac{1}{\sigma_n}$.

iii. It's easy to prove that $\|A\|_2^H = \|A\|_2^T = \|A\|_2$ since the Σ of their SVD is the same. $A^H A = V\Sigma^H U^H U \Sigma V^H = V\Sigma^H \Sigma V^H$. Since the diagonal elements of $\Sigma^H \Sigma$ are $\sigma_1^2, \sigma_2^2, \dots, \sigma_n^2$. By using the results of i., we could know that $\|A^H A\| = \sigma_1^2$.

iv. $\|UAV\|_2^2 = \|UAVV^H A^H U^H\|_2 = \|UAA^H U^H\|_2 = \|AA^H U^H\|_2 = \|(AA^H U^H)^H\|_2 = \|UAA^H\|_2 = \|AA^H\|_2 = \|A\|_2^2$

12. (4.25)