

## MM32-LINK MINI User Guide

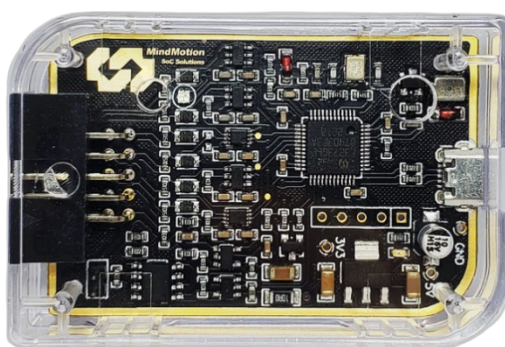
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### Introduction

The basic functions and the use methods of MM32-LINK MINI emulator are introduced in this paper, as well as the solutions of FAQ.

MM32-LINK MINI basic functions:

- Support MM32 whole series emulating and debugging
- Support CDC virtual serial port
- Support updating and configuring via USB drive



# 1 Basic Functions

The basic functions of MM32-LINK MINI(hereinafter referred to as MINI) are as follows:

Functions	Descriptions	Notes
MM32-V1 Debug	Programming via SWD port under USB-HID mode. CMSIS debug channel is compliant.	No drivers are required under all Windows systems (Win98 and later versions).
CDC virtual serial port	Logging, tracing and terminal emulation.	-
MSC updating / configuring	Firmware updating and functional configurations via USB drive.	-

## 2 Use Methods

### 2.1 MM32-V1 Debug

#### 2.1.1 Fundamentals

MM32-V1 Debug adopts CMSIS-DAP Protocol and uses USB-HID communication mode internal to realize MM32 Cortex-M whole series MCU emulating and debugging requirements.

#### 2.1.2 Interface Circuit

MINI debugger has one Micro-USB interface and 10-pin ARM Cortex debugging connector socket. The interface designation of debugging connector and the definition of factory configuration cable are as follows.

Pin Name	Cable Color	Descriptions
TVCC	● Red	Power line of target board. Support 3.3V / 5V configuration and 200mA maximum limiting current.
VREF	● Orange	Power feedback line of target board. VREF can be connected to TVCC directly internal and does no need other wires in this condition.
GND	● Black	GND
CLK	● Blue	SWD clock line
DIO	● Yellow	SWD data line
nRST	● Gray	Reset line: connected with reset pin on target board.

Pin Name	Cable Color	Descriptions
TXD	● Green	Virtual serial port TX line: connected with RX pin on target board.
RXD	○ White	Virtual serial port RX line: connected with TX pin on target board.
SWO	● Purple	Serial port trace output line

The specific connecting way is shown in Figure 1:

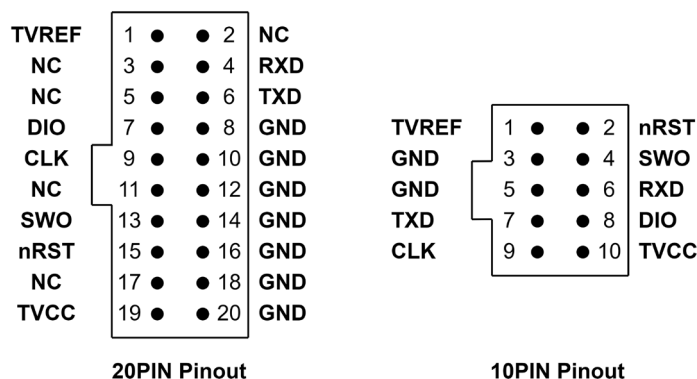


Figure 1 10P-To-20P connections

### 2.1.3 Device Serial Number

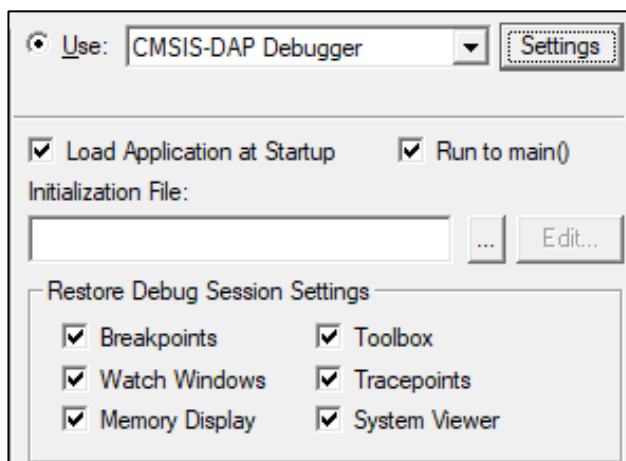
The device serial number of MM32-LINK Series is encoded in 19 bits. The specific rules are as follows:

Member	Bit width	Contents
Board ID	Total 3 bit. Bit [0] – Bit [2].	“088”: MB-088
Chip UID	Total 16 bit. Bit [9] – Bit [24].	MCU-UUID 64 bit

### 2.1.4 Tutorial

#### 2.1.4.1 Keil

- ① Open the *Options for Target – Debug* dialog to choose driver.



Enable Use and select CMSIS-DAP Debugger in pull-down list.

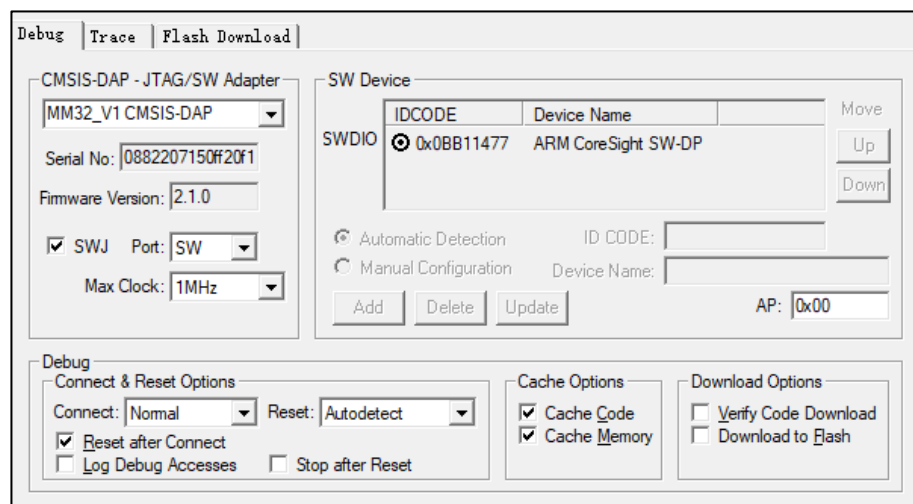
② Click Settings button and configure debugging option.

*Cortex-M Target Driver Setup* dialog pop out, consisting of three sets of information and configurations which are shown in table below:

### CMSIS-DAP JTAG/SW Adapter

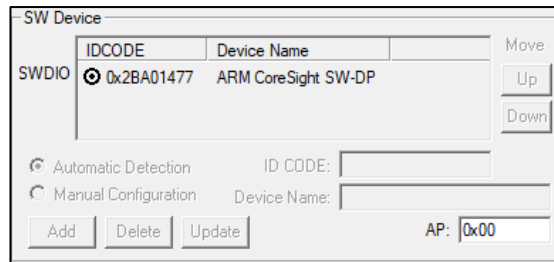
Info.	Descriptions	Notes
Serial No	Display the identifier of the debugger adapter in use. When more adapters are connected, use the drop-down list to specify the adapter or driver.	MM32-LINK Series specifications: Board[3] + UUID[16]
Firmware Version	Display the firmware version detected on the device.	-
SWJ	Enable the driver to switch between JTAG and SW mode.	Enable (Recommended)
Port	Set the internal debugging interface: SW or JTAG.	SW default in MM32 whole series.
Max Clock	Set the debugging clock rate for communicating to the target board.	Suggest 5MHz maximum. Update later.

Choose MM32\_V1 CMSIS-DAP adapter in use. Dialog is shown in figure below:



### SW Device

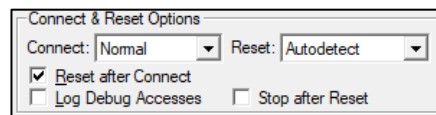
SW Device shows one or more debug targets connected through the Serial Wire interface. The IDCODE and Device Name are displayed automatically for each device.



## Debug

The Debug section provides controls for connecting and resetting the device, and caching and downloading the code. The settings are applied each time a debugging session is started.

### ➤ Connect & Reset Options



Choose Normal as connecting way and Autodetect as reset way by default.

### ➤ Cache Options

By default, caching options are enabled to get maximum performance.

### ➤ Download Options

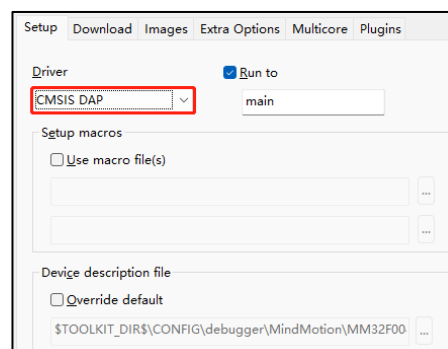
Download Options control the downloading of code to the target system when starting a debugging session.

Enable Verify Code Download option by default to ensure program correlation between the image loaded in target system and the image loaded in the  $\mu$ Vision debugger. Download to Flash option is disabled by default.

Users could set these options according to the project debugging requirements.

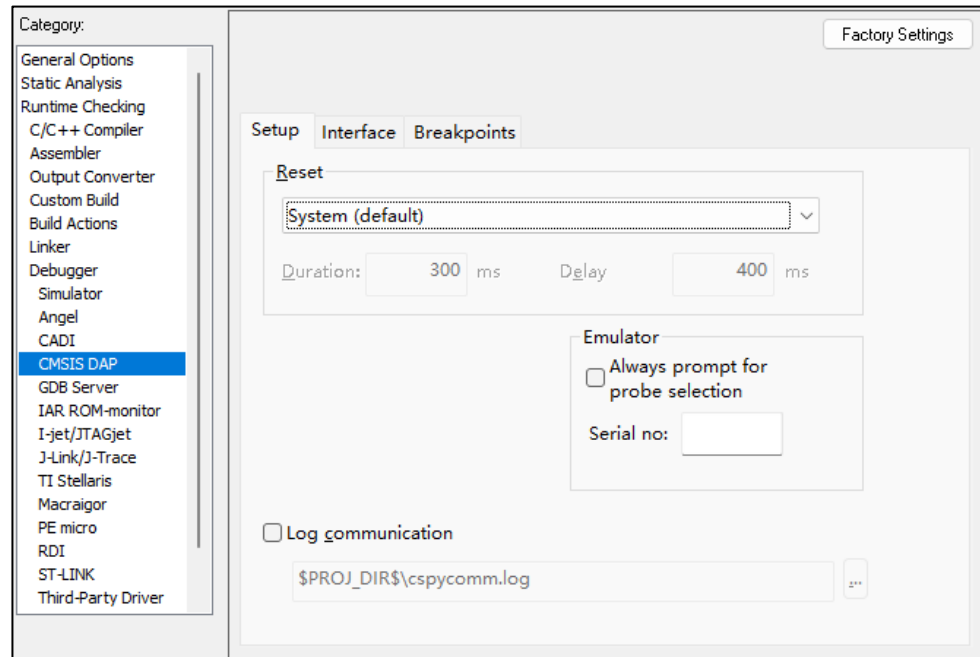
#### 2.1.4.2 IAR

- ① Open the *Project - Options – Debugger* dialog to select driver.

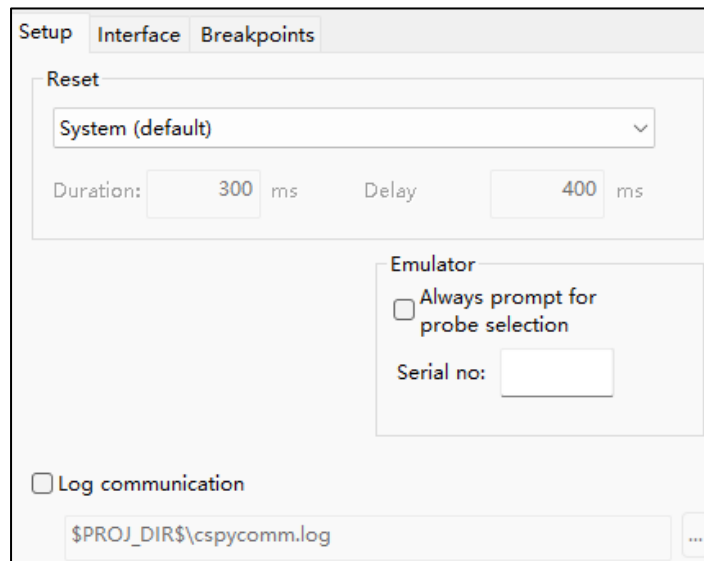


Select CMSIS DAP in pull-down list.

② Click CMSIS DAP on the left and set debugging options.

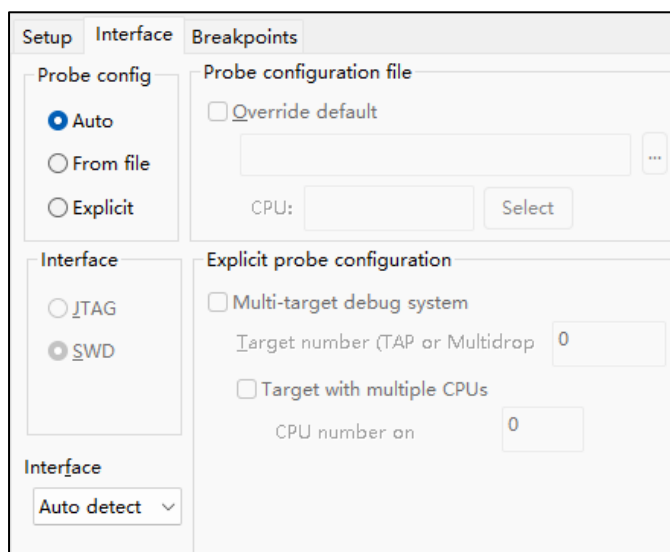


### ➤ Setup



Select System (default) as reset strategy. Switch to another reset strategy if download and debugging is abnormal due to the different target chip environments.

## ➤ Interface



Ensure SWD mode is selected and Auto Detect could be selected as maximum interface rate.

## 2.2 CDC Virtual Serial Port

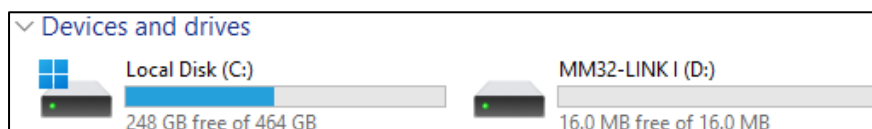
Bi-direction communication can be realized between MINI debugger serial port and target microcontroller. Support baud rate of 9600 / 14400 / 19200 / 28800 / 38400 / 56000 / 57600 / 115200 and so on.

## 2.3 USB Drive Updating / Configuring

### ➤ Firmware updating

By default, MM32LINK-Series latest firmware has been burned into MINI in factory. Users can update firmware as required. Specific operations are as follows:

#### ① Normal mode:



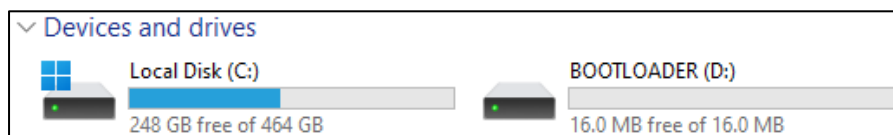
First, create a blank file named “*START\_BL.ACT*”; After ensuring the emulator is in idle mode, save the file under “MM32-LINK \*” USB drive content by sending or dragging.

Note: Identifier of MM32LINK Series USB drive

Identifier	Type	Notes
MM32-LINK A	MM32-LINK MAX	A: M <u>A</u> X
MM32-LINK I	MM32-LINK MINI	I: M <u>I</u> N

## ② Maintenance mode:

After MINI has been read and reset successfully, “BOOTLOADER” portable disk is displayed on PC interface.



## ③ Drag to update firmware

Drag “*mm32link\_mini\_xxxx.hex*” firmware file to USB drive. Emulator will exit maintenance mode automatically after updating is done.

### ➤ 3.3V / 5V configuration

5V output enable(default): First, create a blank file named “*VT\_5V.CFG*”; After ensuring the emulator is in idle mode, save the file under “MM32-LINK \*” USB drive content by sending or dragging.

3.3V output enable: File name is “*VT\_3V3.CFG*” and other configuration methods are the same.

Power off: File name is “*VT\_OFF.CFG*” and other configuration methods are the same.

### ➤ Beep configuration

Beep enable(default): First, create a blank file named “*BEEP\_ON.CFG*”; After ensuring the emulator is in idle mode, save the file under “MM32-LINK \*” USB drive content by sending or dragging.

Beep disable: File name is “*BEEP\_OFF.CFG*” and other configuration methods are the same.

## 3 FAQ

### 3.1 Power related

Q: What should user pay attention to when connecting target power feedback



line VREF and output line TVCC?

A: Emulator TVCC support 3.3V/5V power output and < 200mA working current. Do not suggest enabling TVCC output in other conditions. VREF and TVCC can be short connected internal by jumper cap.

(1) When 3.3V/5V power output is enabled, VREF and TVCC could be short connected only if  $VREF = TVCC$  and must not be short connected if  $VREF \neq TVCC$ .

(2) When target power output is disabled, VREF must be connected to power port of the target board.

### 3.2 IDE related

Q: How to solve the error in emulating and downloading process if CMSIS DAP debugging has been selected in IDE?

A: (1) Check USB cable or change it if necessary.

(2) Check interface mode is SWD and reduce SWD communication rate.

(3) Switch to suitable reset way: System (Recommended) / Hardware / Software;

## 4 Revision history

Table 4-1 Document revision history

Date	Revision	Changes
2022/7/29	1.00	Initial release