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- 6. 利用 igraph 的 shortest_paths 函數,找出最短路徑的 vertex & edges,並繪製地圖。

sfnetworks

整合 sf + igraph 功能

sfnetworks 0.5.1



Reference

Articles ▼

Changelog

Tidy Geospatial Networks in R

sfnetworks is an R package for analysis of geospatial networks. It connects the functionalities of the tidygraph package for network analysis and the sf package for spatial data science.



Background

Geospatial networks are graphs embedded in geographical space. That means that both the nodes and edges in the graph can be represented as geographic features: the nodes most commonly as points, and the edges as linestrings. They play an important role in many different domains, ranging from transportation planning and logistics to ecology and epidemiology. The structure and characteristics of geospatial networks go beyond standard graph topology, and therefore it is crucial to explicitly take space into account when analyzing them.

We created sfnetworks to facilitate such an integrated workflow. It combines the forces of two popular R packages: sf for spatial data science and tidygraph for standard graph analysis. The core of the package is a dedicated data structure for geospatial networks, that can be provided as input to both the graph analytical functions of tidygraph as well as the spatial analytical functions of sf, without the need for conversion. Additionally, we implemented a set of geospatial network specific functions, such as routines for shortest path calculation, network cleaning and topology modification. sfnetworks is designed as a general-purpose package suitable for usage across different application domains, and can be seamlessly integrated in tidyverse workflows.

https://luukvdmeer.github.io/sfnetworks

認識 sf 格式 & tmap

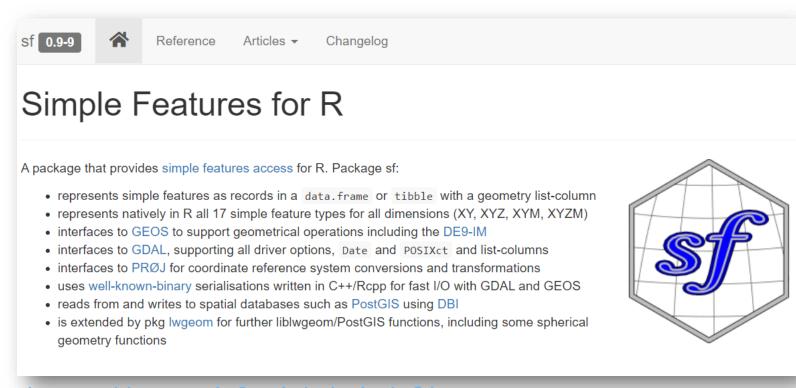
讀取 sf 資料 → 透過 tmap 畫地圖

Loading Data

```
> library(sfnetworks) → 如尚未安裝 請執行 install.packages("sfnetworks")
> library(sf)
> library(tmap)
> library(igraph)
> library(tidygraph)
> library(tidyverse)
> load("TPE_Road.Rdata")
> class(road_sf)
[1] "sf"
         "data.frame"
```

sf

A **simple feature** is defined by the OpenGIS Abstract specification to have both **spatial and non-spatial attributes**. Spatial attributes are geometry valued, and simple features are based on 2D geometry with linear interpolation between vertices.



https://r-spatial.github.io/sf/

sf - geometry types

type	description				
POINT	zero-dimensional geometry containing a single point				
LINESTRING	sequence of points connected by straight, non-self intersecting line pieces; one-dimensional geometry				
POLYGON	geometry with a positive area (two-dimensional); sequence of points form a closed, non-self intersecting ring; the first ring denotes the exterior ring, zero or more subsequent rings denote holes in this exterior ring				
MULTIPOINT	set of points; a MULTIPOINT is simple if no two Points in the MULTIPOINT are equal				
MULTILINESTRING	set of linestrings				
MULTIPOLYGON	set of polygons				
GEOMETRYCOLLECTION	set of geometries of any type except GEOMETRYCOLLECTION				

sf object

> road_sf

Simple feature collection with 932 features and 3 fields

Geometry type: LINESTRING

Dimension: XY

Bounding box: xmin: 296597.4 ymin: 2761987 xmax: 312903.7 ymax: 2786095

Projected CRS: TWD97 / TM2 zone 121

First 10 features:

```
      STREET_NAM INDEX_NAM CLASS
      geometry

      1
      文林北路
      <NA>
      7 LINESTRING (301553.8 277814...

      2
      中正路
      <NA>
      7 LINESTRING (303246.7 277649...

      3
      福林路
      台2甲
      3 LINESTRING (303254.7 277626...

      4
      中山北路五段
      <NA>
      7 LINESTRING (309466.6 277471...

      5
      成功路三段
      <NA>
      7 LINESTRING (309466.6 277471...
```

road_sf\$CLASS

^	STREET_NAM [‡]	INDEX_NAM [‡]	CLASS 4	geometry
1	文林北路	NA	7	c(301553.793852566, 301987.820541679, 302144.01076671
2	中正路	NA	7	c(303246.728873303, 303670.725721997, 2776490.7329940
3	福林路	台2甲	3	c(303254.721439943, 303670.725721997, 2776262.7308826
4	中山北路五段	NA	7	c(303254.721439943, 303268.727128404, 303246.72887330
5	成功路三段	NA	7	c(309466.55002184, 309458.326425038, 309534.23566675,

tmap - sf visualization

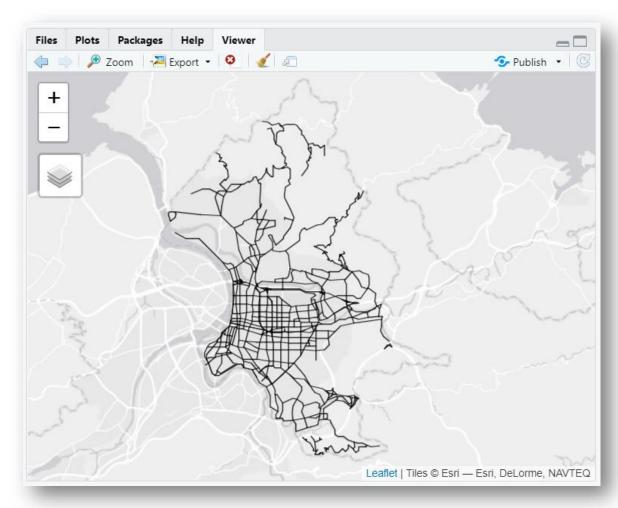
```
> tmap_mode("view") #interactive viewing
```

> map = tm_shape(road_sf) + tm_lines()

> map

P.S. quick tmap

> qtm(road_sf)



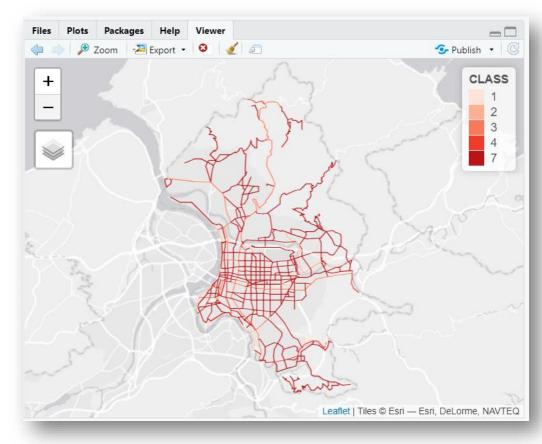
tmap format

```
tm_shape (sf) + tm_polygons ("欄位", 圖層美觀設計) #面資料
                      #面資料
             tm_borders
                      #線資料
             tm_lines
             tm_dots #點資料
             tm_symbols #點資料
```

> tm_shape(road_sf) + tm_lines("CLASS",palette = "Reds")

tmap: get started!

https://cran.r-project.org/web/packages/ tmap/vignettes/tmap-getstarted.html



Read Shapefile

GIS-T交通網路地理資訊倉儲系統

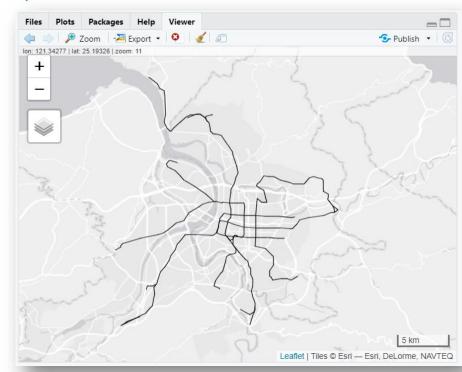
https://gist.motc.gov.tw/gist_web/MapDataService/Retrieval

查詢「台北捷運路線」 > 下載shp > 解壓縮

> MRT = st_read("D:/1092NT/VL0303V03.shp")

> qtm(MRT)

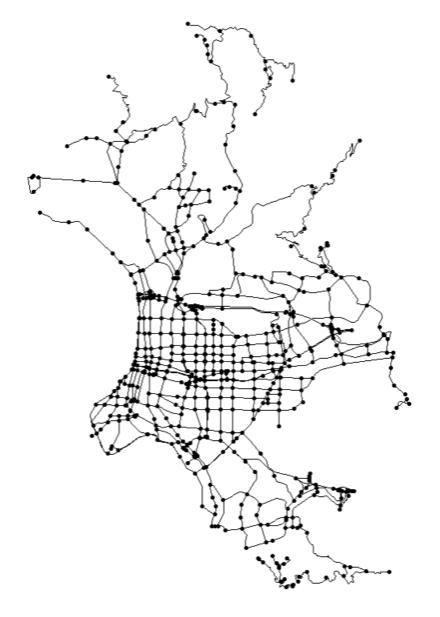
_ « Angus (D:) > 1092	v 0		
名稱 ^	修改日期	類型	大小
☐ VL0303V03.cpg	2016/12/28	CPG 檔案	1 KB
UL0303V03.dbf	2016/12/28	DBF 檔案	16 KB
UL0303V03.prj	2016/12/28	PRJ 檔案	1 KB
UL0303V03.sbn	2016/12/28	SBN 檔案	2 KB
UL0303V03.sbx	2016/12/28	SBX 檔案	1 KB
UL0303V03.shp	2016/12/28	SHP 檔案	78 KB
UL0303V03.shx	2016/12/28	SHX 檔案	2 KB



sf → sfnetwork

格式轉換 → 線圖資轉換成網絡資料

sfnetwork object



By default, the created network is a directed network. If you want to create an **undirected network**, set **directed = FALSE**.

sfnetwork object

```
> road_sfnet
# A sfnetwork with 618 nodes and 932 edges
 CRS: EPSG: 3826
 A directed multigraph with 3 components with spatially explicit edges
# Node Data:
               618 x 1 (active)
# Geometry type: POINT
# Dimension:
# Bounding box: xmin: 296761.5 ymin: 2761987 xmax: 312903.7 ymax: 2786095
           geometry
        <POINT [m7>
1 (301553.8 2778143)
   (302412 2777319)
3 (303246.7 2776491)
4 (303670.7 2776568)
5 (303254.7 2776263)
6 (309466.6 2774716)
 ... with 612 more rows
# Edge Data: 932 x 6
# Geometry type: LINESTRING
# Dimension:
                XY
# Bounding box: xmin: 296597.4 ymin: 2761987 xmax: 312903.7 ymax: 2786095
          to STREET_NAM INDEX_NAM CLASS
   from
                                                                                geometry
  <int> <int> <chr>
                       <chr>
                                  <chr>>
                                                                        <LINESTRING [m]>
           2 文林北路
                                      (301553.8 2778143, 301987.8 2777730, 302144 277~
                                                  (303246.7 2776491, 303670.7 2776568)
           4 中下路
                       台2甲
                                                  (303254.7 2776263, 303670.7 2776568)
  ... with 929 more rows
```

計算路網betweenness

計算台北市路網 node/edge betweenness → 繪製地圖

Node's Betweenness

針對nodes這個屬性

> road_sfnet = road_sfnet %>% activate("nodes") %>%

• 在 Node Data 新增一欄 bc 數值為節點betweenness中心性

Node Data: 618 x 2 (active) # Geometry type: POINT # Dimension: XY # Bounding box: xmin: 296761.5 ymin bc geometry <POINT [m]> <db1> 1 (301553.8 2778143) <u>23</u>393. (302412 2777319) 859. (303246.7 2776491) 5681. (303670.7 2776568) <u>6</u>903. 5 (303254.7 2776263) <u>5</u>133. (309466.6 2774716) 2227.

透過centrality_betweenness函數來計算

Node's Betweenness

轉換成 sf 格式 → 透過 tmap 繪圖

> nodes_sf = st_as_sf(road_sfnet, "nodes")

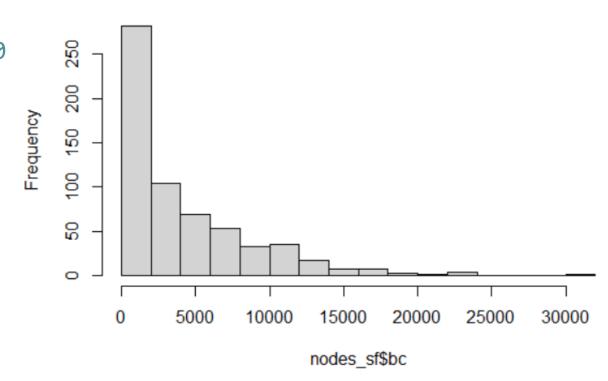
觀察數值分布

> hist(nodes_sf\$bc)

將bc數值除以10000

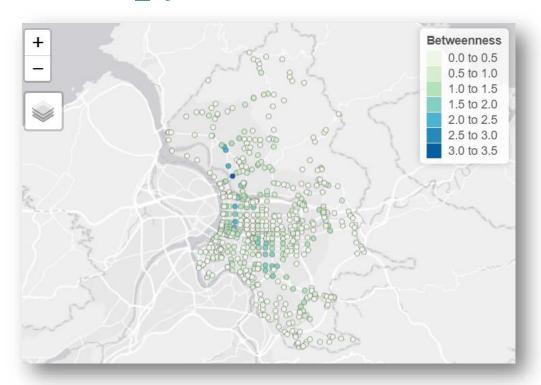
> nodes_sf\$bc = nodes_sf\$bc/10000

Histogram of nodes_sf\$bc

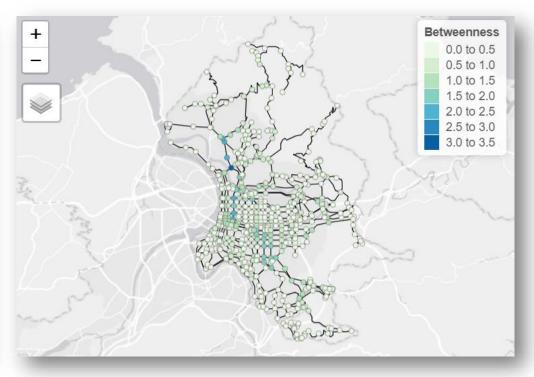


Node's Betweenness

> nodes_lyr



> map + nodes_lyr #疊圖



Edge's Betweenness

針對edges這個屬性

• 在 Edge Data 新增一欄 weight 數值為edge betweenness中心性 透過centrality_edge_betweenness函數來計算

```
# Edge Data: 932 x 7 (active)
# Geometry type: LINESTRING
# Dimension:
# Bounding box: xmin: 296597.4 ymin: 2761987 xmax: 312903.7 ymax: 2786095
  from
           to STREET_NAM INDEX_NAM CLASS
                                                                           geometry weight
  <int> <int> <chr> <chr>
                                                                   <LINESTRING [m]> <db1>
            2 文林北路
                        NA
                                         (301553.8 2778143, 301987.8 2777730, 302~
                                                                                    <u>1</u>410.
                                                                                    4016.
           4 中下路
                       NA
                                              (303246.7 2776491, 303670.7 2776568)
                                  3 (303254.7 2776263, 303670.7 2776568)
7 (303254.7 2776263, 303268.7 2776398, 303~
           5 福林路
                        台2甲
                                                                                    3325.
          5 中山北路五~ NA
                                                                                   1939.
                                      (309466.6 2774716, 309458.3 2774653, 309~
                                                                                    2546.
          7 成功路三段
                                                                                    2451.
           9 民族西路
                        NΑ
                                              (301827.1 2773487, 301537.1 2773492)
   .. with 926 more rows
```

Edge's Betweenness

轉換成 sf 格式 → 透過 tmap 繪圖

> edges_sf = st_as_sf(road_sfnet, "edges")

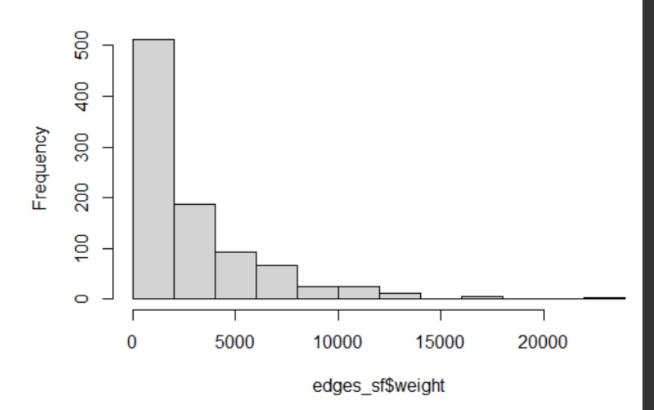
觀察數值分布

> hist(edges_sf\$weight)

將bc數值除以10000

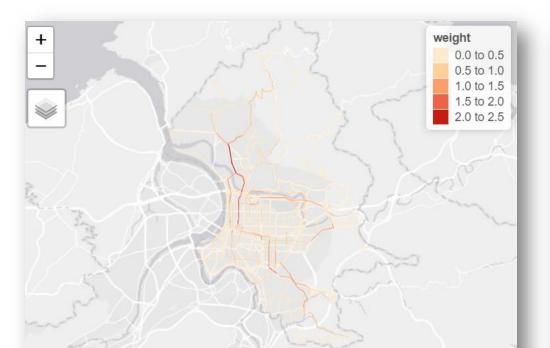
> edges_sf\$weight =
 edges_sf\$weight/10000

Histogram of edges_sf\$weight

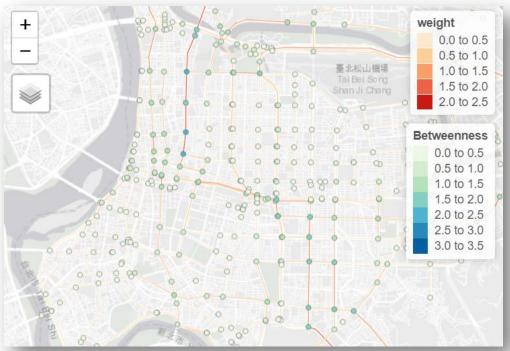


Edge's Betweenness

> edges_lyr



> edges_lyr + nodes_lyr

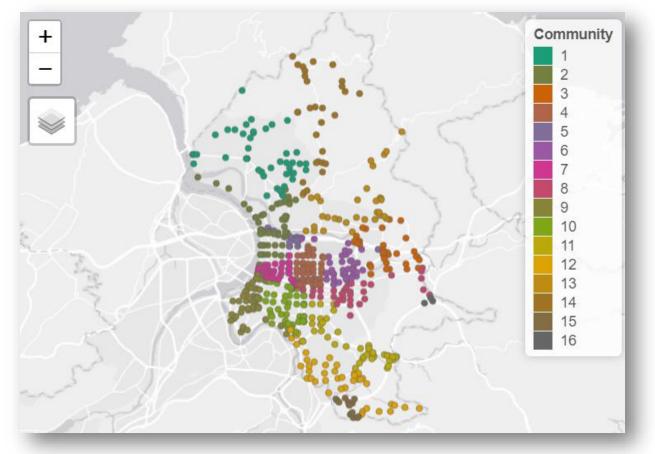


計算路網分群結構

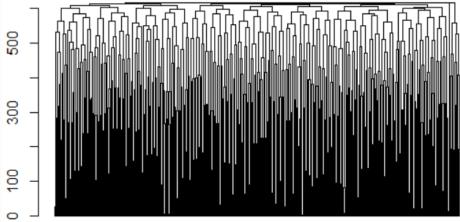
計算台北市路網 community structure → 繪製地圖

Community

> tm_shape(nodes_sf)+tm_dots("member",palette="Dark2",title="Community")



- > comm_dend = as.dendrogram(comm_eb)
- > plot(comm_dend)



計算距離矩陣

計算兩兩節點的距離矩陣

Distance Matrix

- 計算每個連結的長度
- 計算距離矩陣
- dist_matrix (618x618)

•	V1 [‡]	V2	V3 [‡]	V4 [‡]	V5
1	0.000	1193.836	2609.7422	3040.6737	2841.0353
2	1193.836	0.000	1415.9063	1846.8378	1647.1993
3	2609.742	1415.906	0.0000	430.9315	231.2930
4	3040.674	1846.838	430.9315	0.0000	515.8335
5	2841.035	1647.199	231.2930	515.8335	0.0000

最短路徑分析

shortest_paths 函數 → 找出最短路徑 vertex & edges → 繪製地圖

Index / From / To

```
※目標:從Node200走到Node500的最短距離
index 新增nodeID
> road_sfnet = road_sfnet %>% activate("nodes") %>%
                   mutate(nodeID = c(1:618))
from
> from_node = road_sfnet %>% activate(nodes) %>%
                    filter(nodeID == 200) %>% pull(nodeID)
                    篩選出nodeID為200的節點 把「nodeID欄位」抽取出來
# from node = 200
to
> to node = road sfnet %>% activate(nodes) %>%
                    filter(nodeID == 500) %>% pull(nodeID)
# to node = 500
```

Shortest Path

```
> mypath = shortest_paths(
       graph = road_sfnet,
       from = from_node, #200
       to = to_node, #500
       output = 'both',
       weights = road_sfnet %>% activate(edges) %>% pull(length)
> mypath
$vpath
$vpath[[1]]
+ 12/618 vertices, from a75af91:
 [1] 200 514 78 478 103 104 115 114 113 498 499 500
$epath
$epath[[1]]
+ 11/932 edges from a75af91:
 [1] 200--514 78--514 78--478 103--478 103--104 104--115 114--115 113--114 113--498
[10] 498--499 499--500
 200 \rightarrow 514 \rightarrow 78 \rightarrow 478 \rightarrow 103 \rightarrow 104 \rightarrow 115 \rightarrow 114 \rightarrow 113 \rightarrow 498 \rightarrow 499 \rightarrow 500
```

Shortest Path

... with 8 more rows

繪製最短距離 > mypath_graph = road_sfnet %>% subgraph.edges(eids = mypath\$epath %>% unlist()) %>% as_tbl_graph() > class(mypath graph) [1] "tbl graph" "igraph" > mypath_graph # A tbl_graph: 12 nodes and 11 edges # An unrooted tree # Node Data: 12 x 3 (active) geometry bc nodeID <POINT [m]> <db1> <int> 1 (306944.4 2770453) 9904. 2 (306459.1 2769560) <u>7</u>763. 103 3 (306250.3 2769181) 8179. 104 4 (304827.9 2768652) <u>17</u>973. 113 5 (305360.7 2768614) <u>17</u>006. 114 6 (305765.7 2768587) <u>15</u>904. 115 # ... with 6 more rows # Edge Data: 11 x 8 to STREET_NAM INDEX_NAM CLASS from geometry weight length <LINESTRING [m]> <db1> <int> <int> <chr> <chr> 3 基隆路二段 NA (306459.1 2769560, 306250.3 276~ <u>5</u>943. 432.4886

> (305360.7 2768614, 305305.4 276~ <u>5</u>983. 534.1439 (306250.3 2769181, 306108.5 276~ <u>8</u>341. 771.7017

Shortest Path

· 轉換成sf格式 → 繪圖

```
> epath_sf = mypath_graph %>% activate(edges) %>% as_tibble() %>% st_as_sf()
> mypath_lyr = tm_shape(epath_sf) + tm_lines(col="red", lwd=2)
> from_node_sf = road_sfnet %>%
       activate(nodes) %>%
       filter(nodeID == 200) %>%
       as_tibble() %>% st_as_sf()
> from_node_lyr = tm_shape(from_node_sf) +
        tm_dots(col="green") #to_node一樣方法
> map + mypath lyr +
       from_node_lyr + to_node_lyr
```



Self-Practice

- · 讀取GIS-T交通網路地理資訊倉儲系統的台北捷運路線
- · 計算介數中心性 (Betweenness Centrality)
- 進行分群

