Basic image processing



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References

- http://szeliski.org/Book/
- http://www.cs.cornell.edu/courses/cs5670/2019sp/lectures/lectures.html
- http://www.cs.cmu.edu/~16385/

Some motivation



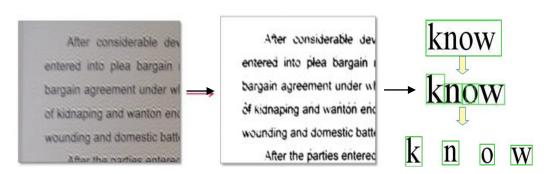
Low contrast image

Contrast stretching

Histogram equalization



Art (Photoshop color grading)



Robotics (OCR – optical character recognition)

Science and space (image enhancement)



Agriculture (color ripeness detection)

contents

- Image representation
- Pixel-wise operations
- Histogram equalization
- Template matching
- Morphology operators
- Connected components
- Color space

Image representation

• We can think of an image as a 3d matrix of discrete RGB values.

The values mark the intensity of each color channel and are usually of type

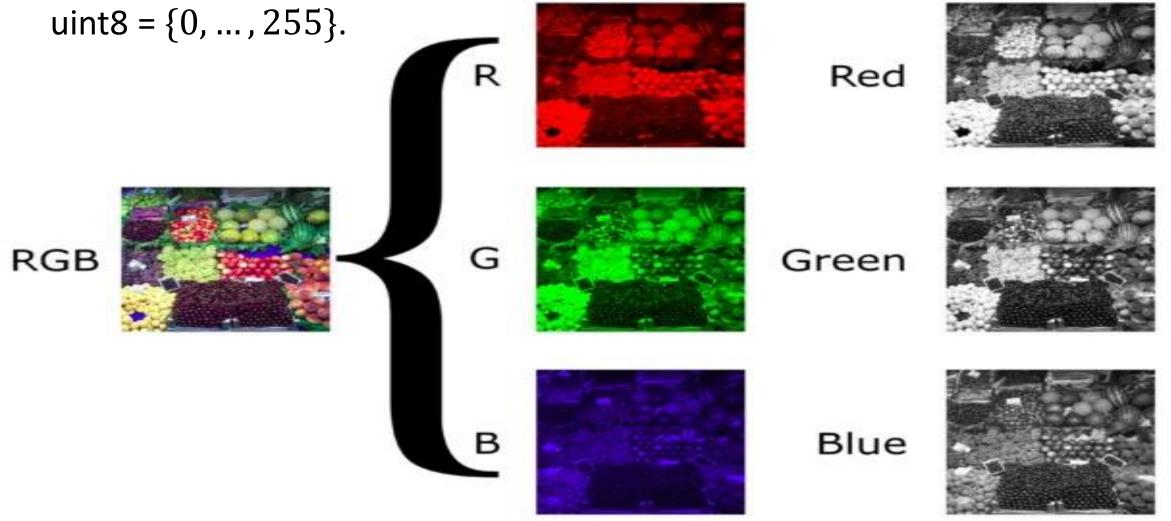
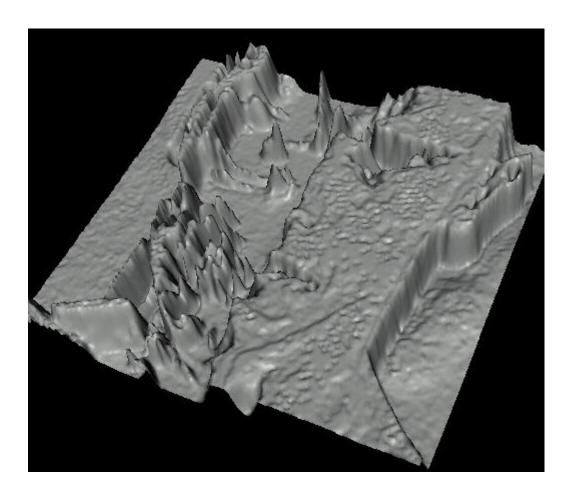


Image representation

• We can also think of an image as a function f(x, y).





contents

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• Pixel-wise operators, or point operators, are defined as such that each output pixel's value depends on only the corresponding input pixel value.

original



darken



lower contrast



Gamma compression



 \boldsymbol{x}

invert



lighten



raise contrast

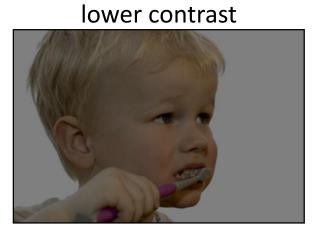


Gamma expansion



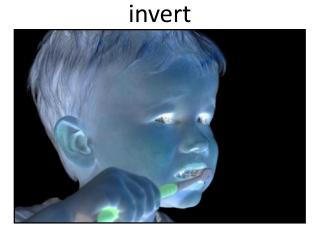


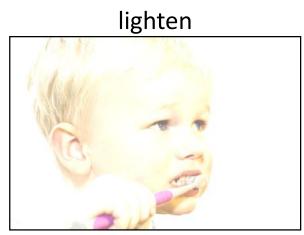


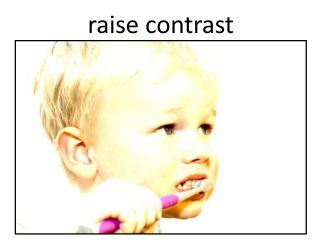




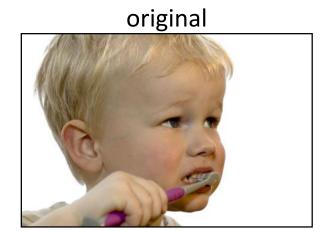
 \boldsymbol{x}



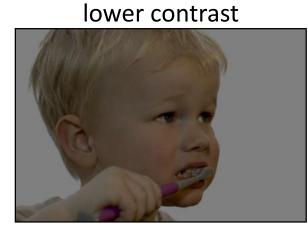


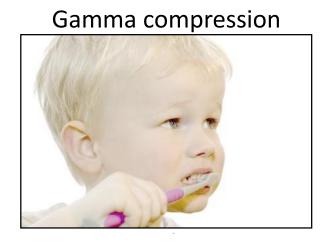






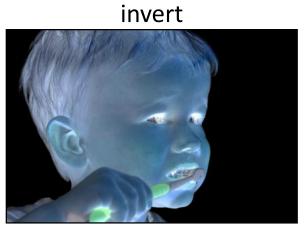


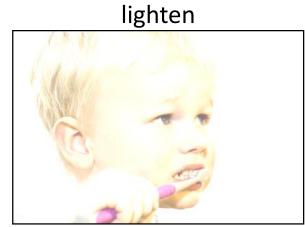


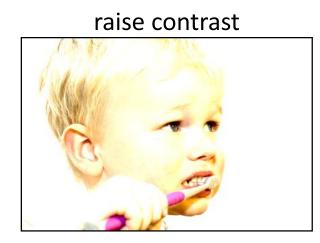


 \boldsymbol{x}

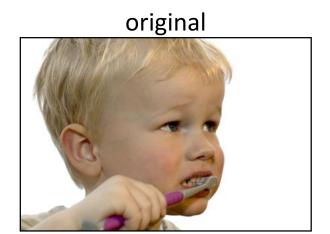
x - 128



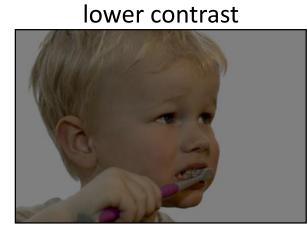


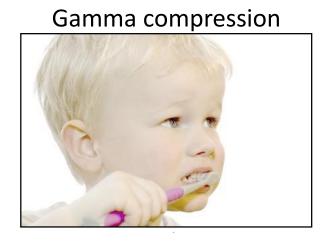






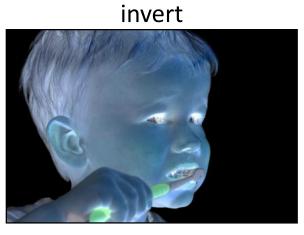


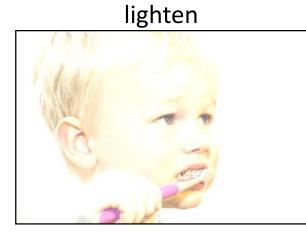


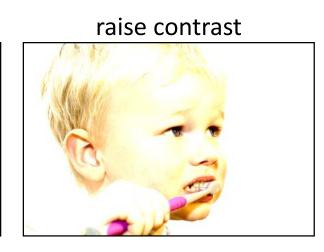


 \boldsymbol{x}

x - 128



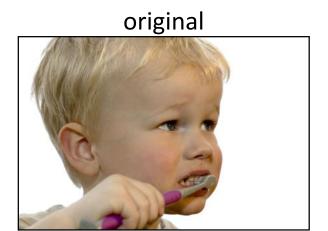




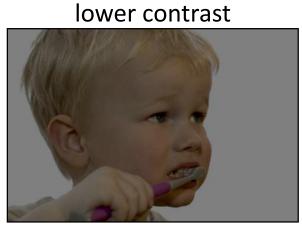


255 - x

x + 128









x

x-128

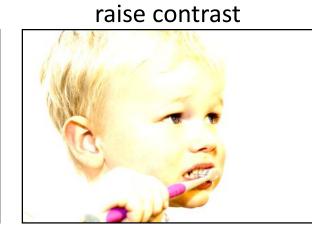
 $rac{x}{2}$



invert

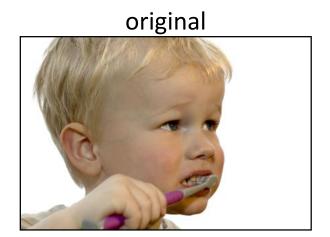




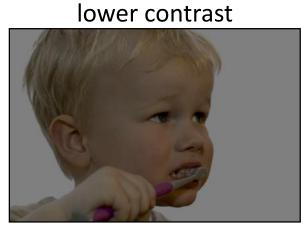


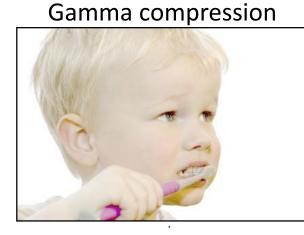
255 - x

x + 128









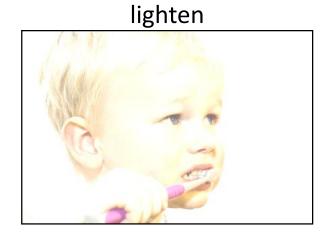
x

x - 128

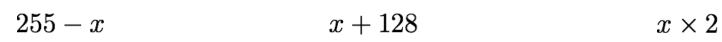
 $rac{x}{2}$



invert





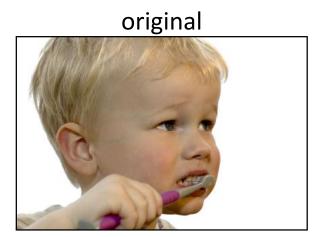


Contrast

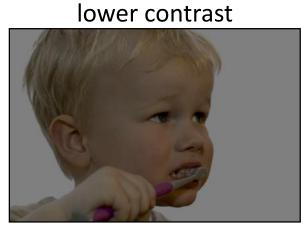
- Contrast in visual perception is the difference in appearance of two or more parts of a seen field.
- The human visual system is more sensitive to contrast than absolute luminance;
- Contrast ratio, or dynamic range, is the ratio between the largest and smallest values of the image or:

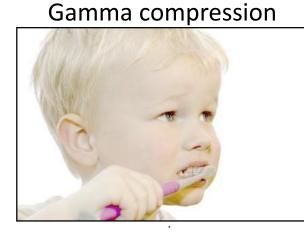
$$CR = \frac{V_{max}}{V_{min}}$$











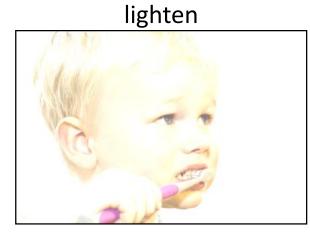
x

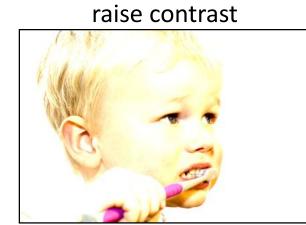
x-128

 $\frac{x}{2}$



invert



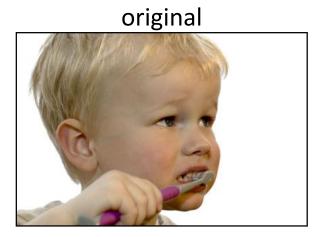




255 - x

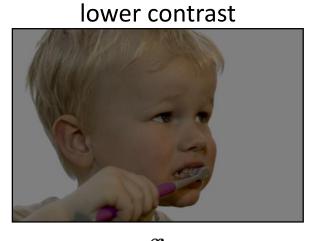
x + 128

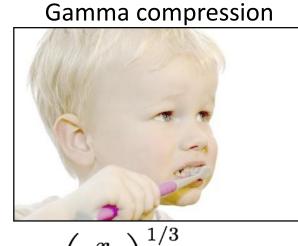
 $x \times 2$





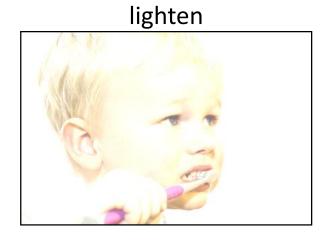
x - 128

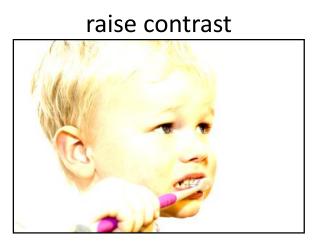




 $\times 255$

x invert



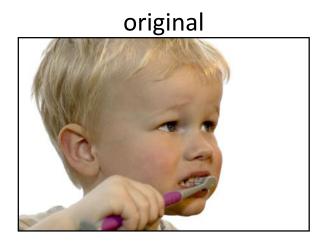




255 - x

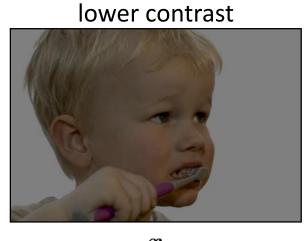
x + 128

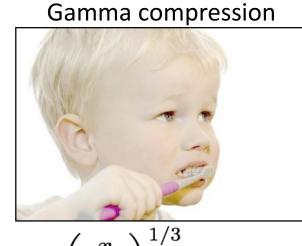
 $x \times 2$





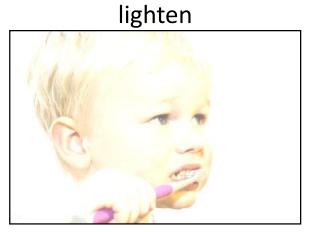
x - 128

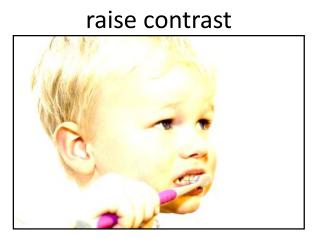




 $\times 255$









255 - x

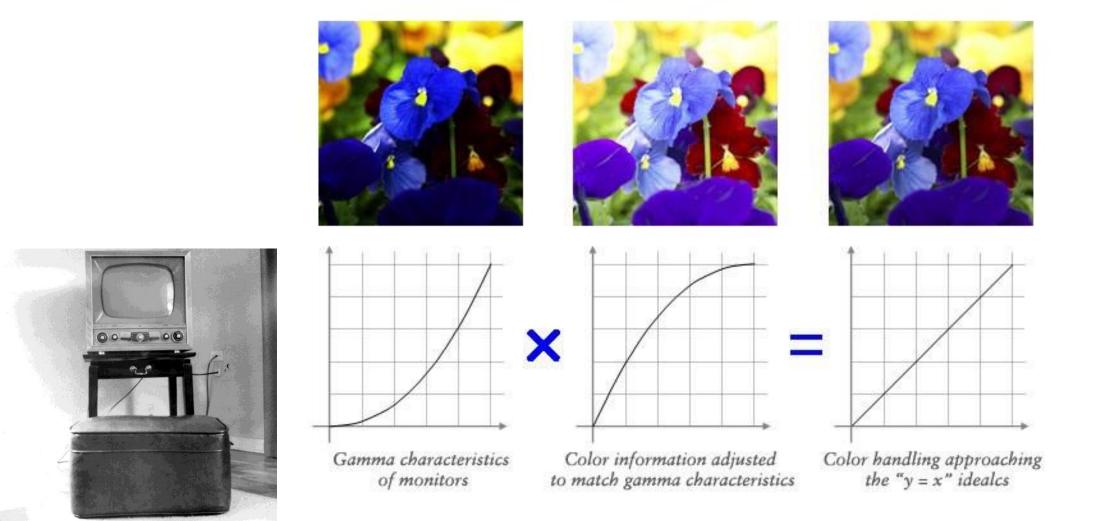
x + 128

 $x \times 2$

 $\left(\frac{x}{255}\right)^2 \times 255$

Gamma correction

• Originally, Due to non-linearities in the old CRT televisions, intensities was seen different then they are.



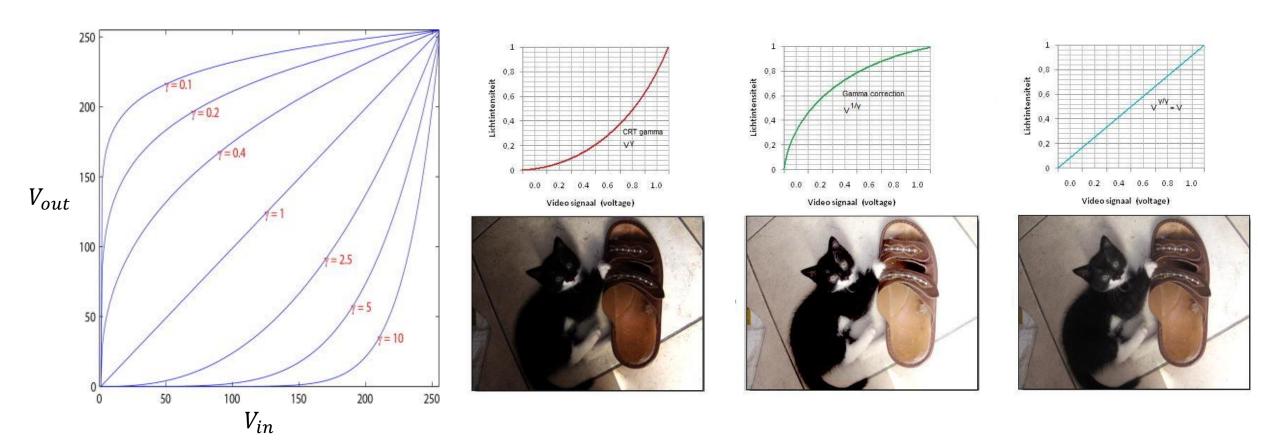


Gamma correction

• To correct this non-linear transformation, gamma correction was done:

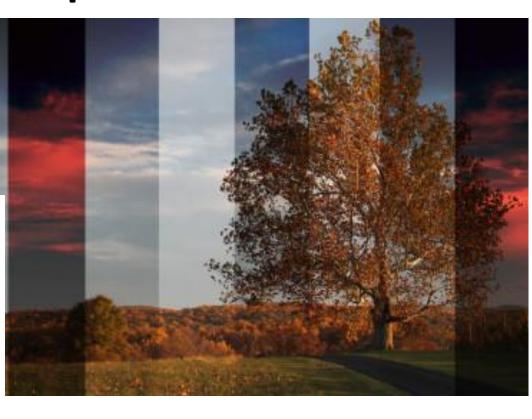
$$V_{out} = \left(\frac{V_{in}}{255}\right)^{\gamma} \cdot 255$$
 $(V_{in}, V_{out} \in \{0, 1, ..., 255\})$

• This is, of course, also applicable for image enhancements.



Some more point- wise operators





contents

- Image representation
- Pixel-wise operations
- Histogram equalization
- Template matching
- Morphology operators
- Connected components
- Color space

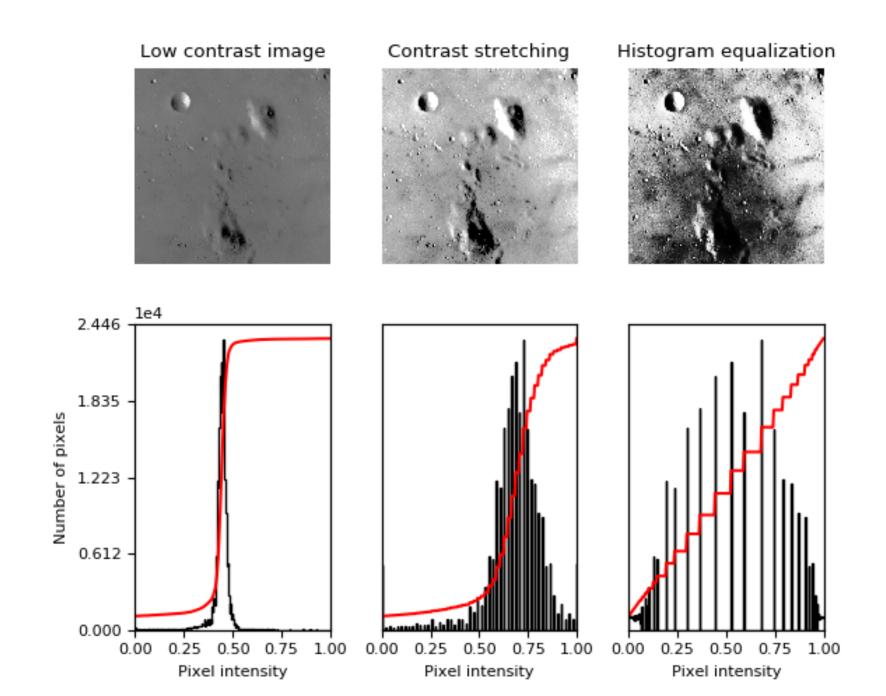
Histogram equalization

- **Histogram equalization** is a method in image processing of contrast adjustment using the image's histogram.
- This method is used to increase the global contrast of an image and is useful in images with backgrounds and foregrounds that are both bright or both dark.

Histogram equalization accomplishes this by effectively spreading out the

most frequent intensity values.

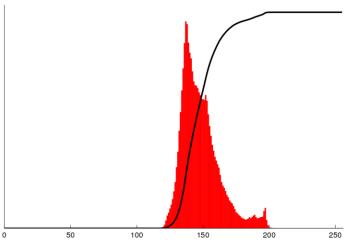




Histogram equalization

- A histogram is a discrete form representation of the distribution of numerical data.
- We will assume at first that our image is continues in the range [0,255] for better understanding.
- Instead of a histogram we will talk about the **probability density function (PDF)** $f_X(x)$ of the data.





PDF and CDF

• cumulative distribution function (CDF) of a real-valued random variable X is the probability that X will take a value less than or equal to x:

$$F_X(x) = P(X \le x)$$

Properties of CDF:

$$-\lim_{x \to -\infty} F_X(x) = 0, \quad \lim_{x \to +\infty} F_X(x) = 1$$

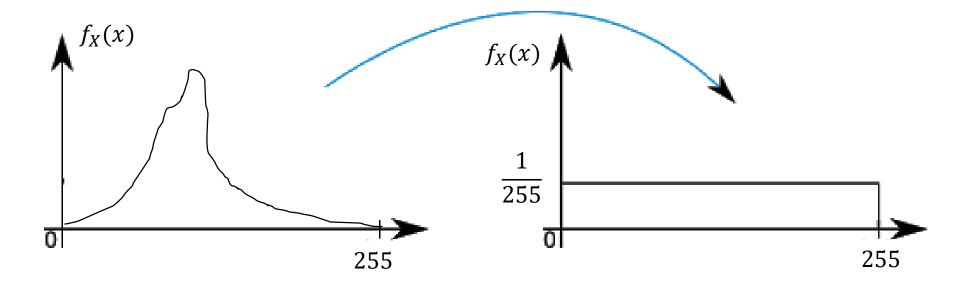
- Monotonically non decreasing.
- The **probability density function (PDF)** of a continuous random variable can be determined from the cumulative distribution function by differentiating.

$$f_X(x) = \frac{dF_X(x)}{dx}$$
 OR $F_X(x) = \int_{-\infty}^x f_X(t) dt$

PDF equalization

- We want that our resulting PDF will be constant for any value in the range [0,255].
- If the PDF is constant, that means that the CDF is linear in [0,255], and so we get the final CDF as:

$$F_Y(y) = P(Y \le y) = \begin{cases} 0 & : \ y < 0 \\ y & : \ 0 \le y \le 255 \\ 1 & : \ y > 255 \end{cases}$$



PDF equalization

So we are looking for a transformation function such that:

$$y = T(x)$$

• In the interesting area [0,1]:

$$P(Y \le y) = y$$

 $P(T(X) \le y) = y$
assuming T is invertible: $P(X \le T^{-1}(y)) = y$
change of variables $z = T^{-1}(y)$: $P(X \le z) = T(z)$

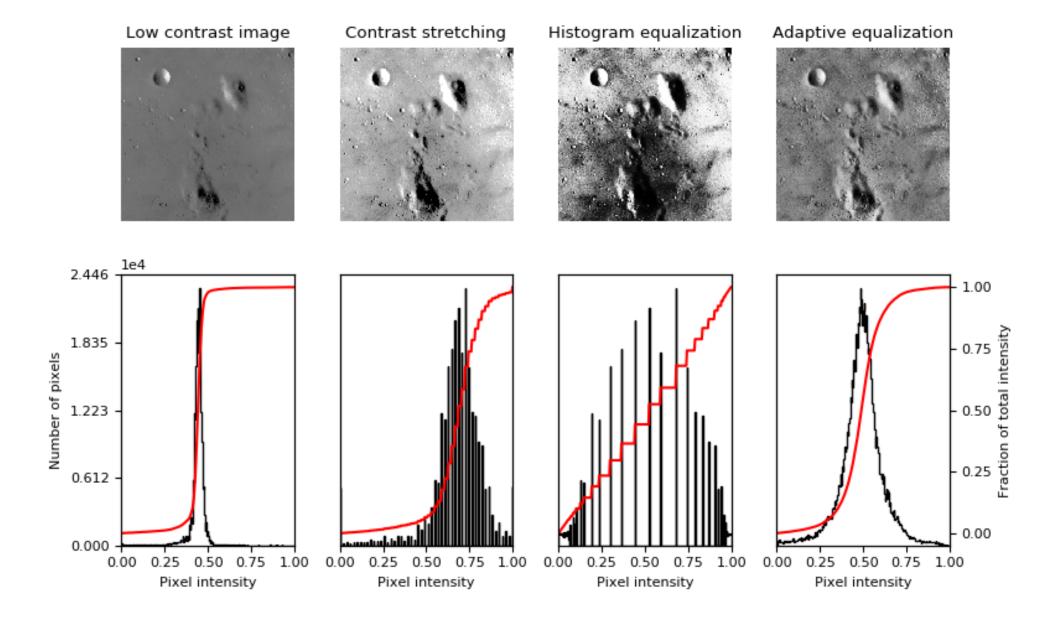
• The answer is $F_X(x) = T(x)$, and in fact T is invertible since F_X is Monotonically non decreasing

Back to histogram equalization

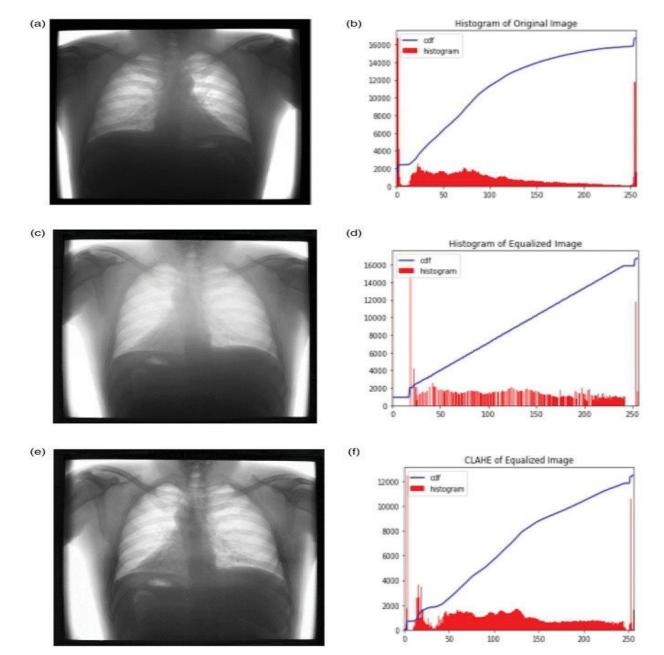
- The same result is also applicable for discrete space like actual images and their histograms.
 - Build histogram of a given image.
 - To make the histogram act like a discrete pdf, we will normalize the PDF: divide each bin by the sum of all bins.
 - Build the discrete CDF.
 - Un-normalize the CDF and round the results back to uint8:

$$f_eq(x) = round(CDF(x) * 255)$$

Other variants of histogram equalization



Other variants of histogram equalization

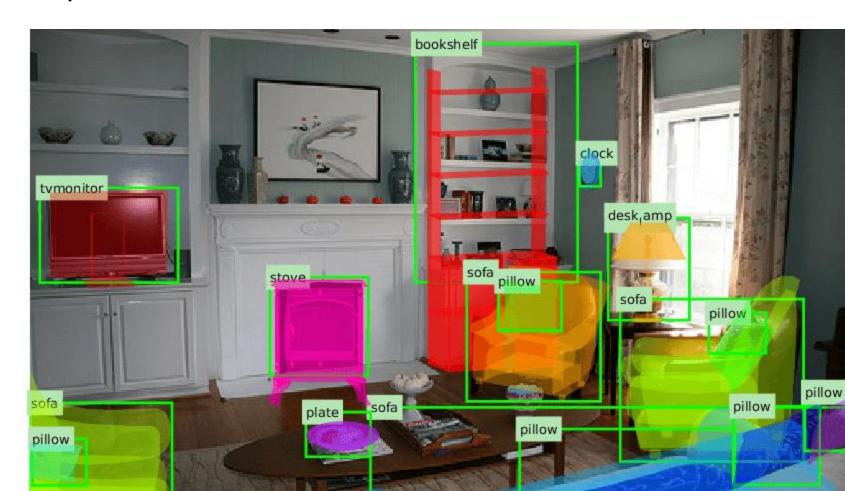


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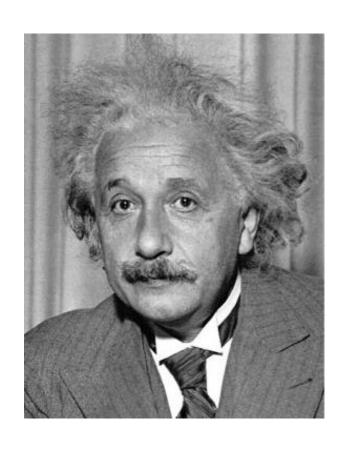
Template matching

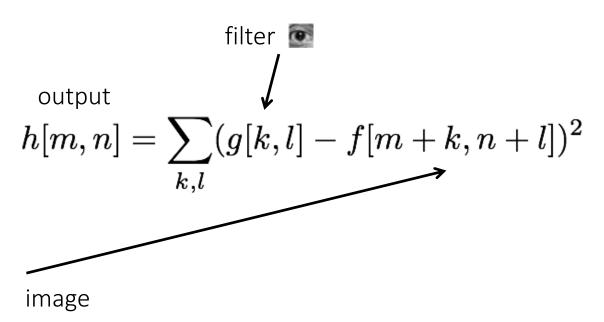
- Given an image template- find it in another image.
- Template matching is a sub-field in **object recognition**.
 - We will see it a lot of this topic in this course:
 - SSD
 - Cross correlation
 - Feature based SIFT
 - Neural networks



SSD – sum squared distances

How do we detect the template **m** in he following image?

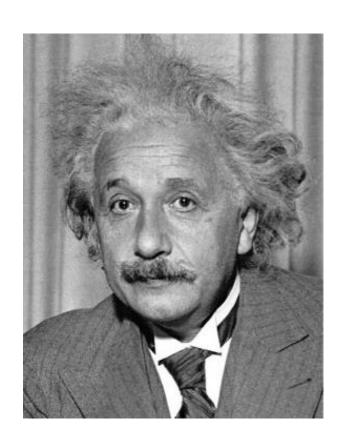




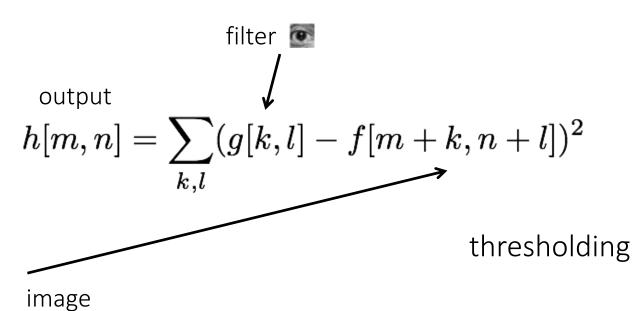
What will the output look like?

SSD – sum squared distances

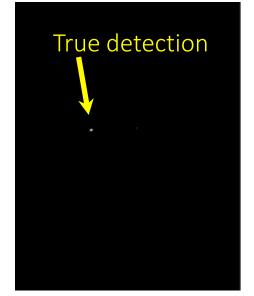
How do we detect the template **m** in he following image?



1-output





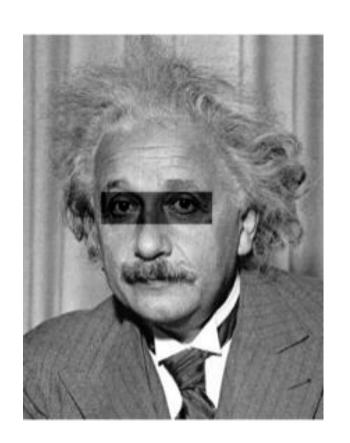


What could go wrong?

SSD – sum squared distances

How do we detect the template **m** in he following image?

image



1-output

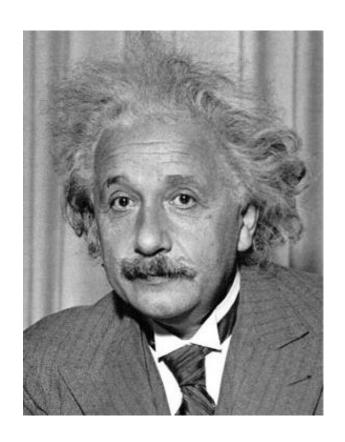


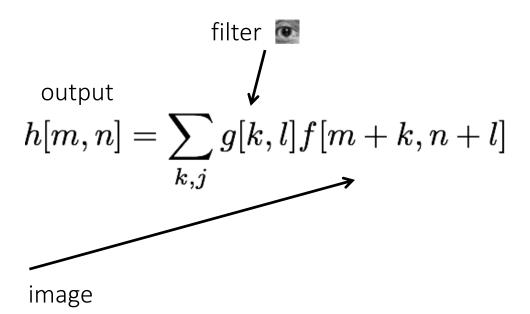
output
$$h[m,n] = \sum_{k,l} (g[k,l] - f[m+k,n+l])^2$$

Not robust to local intensity changes

CC – cross correlation

How do we detect the template **n** in he following image?

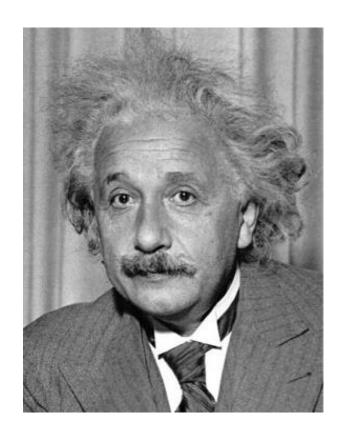


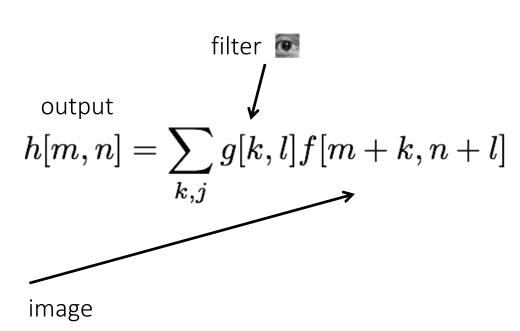


What will the output look like?

CC – cross correlation

How do we detect the template **n** in he following image?



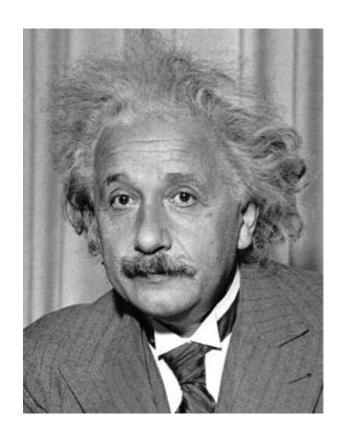


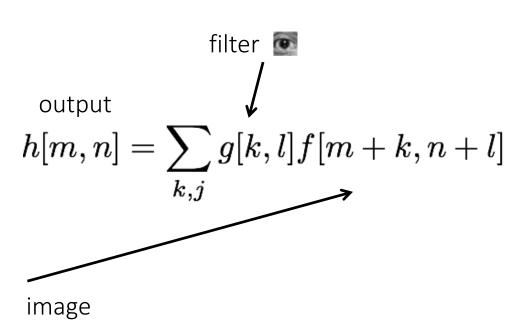


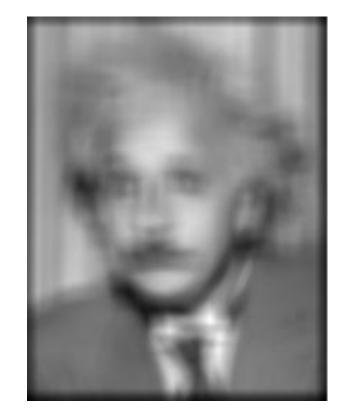
What went wrong?

CC – cross correlation

How do we detect the template **n** in he following image?



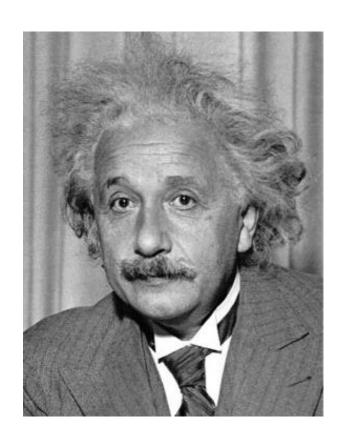


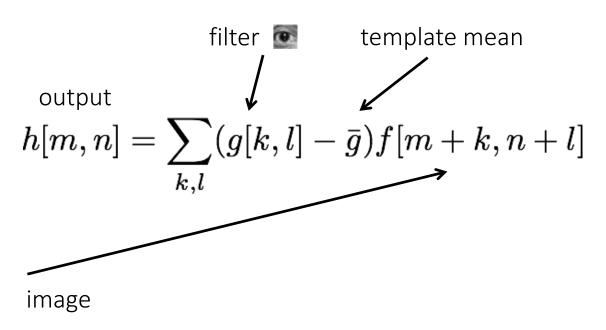


Increases for higher local intensities.

Zero mean cross correlation

How do we detect the template **n** in he following image?

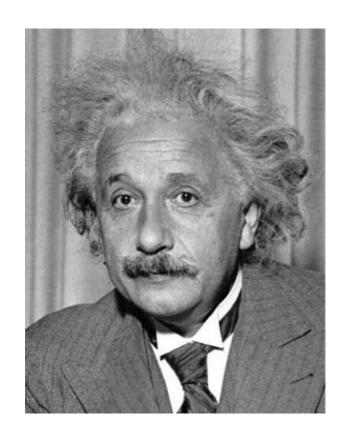




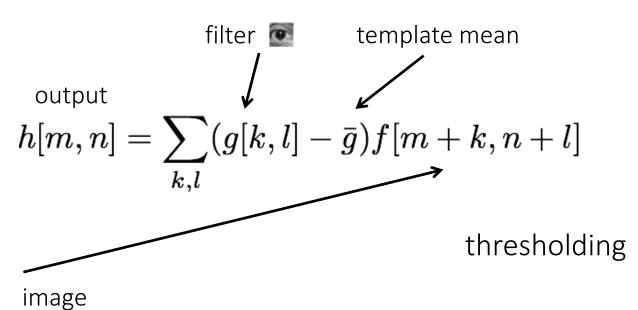
What will the output look like?

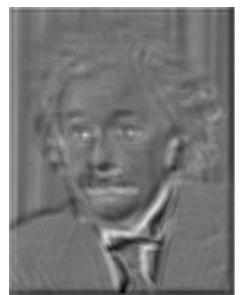
Zero mean cross correlation

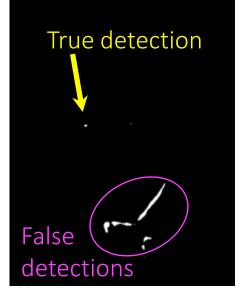
How do we detect the template **m** in he following image?



output





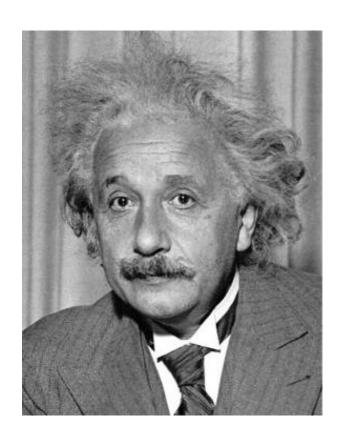


What went wrong?

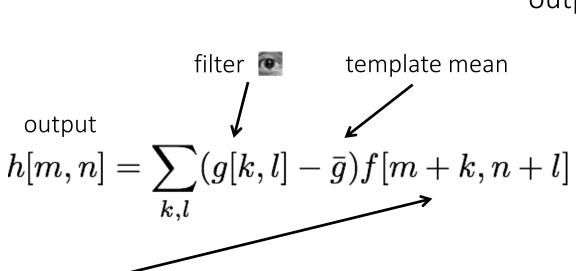
Zero mean cross correlation

How do we detect the template **m** in he following image?

image



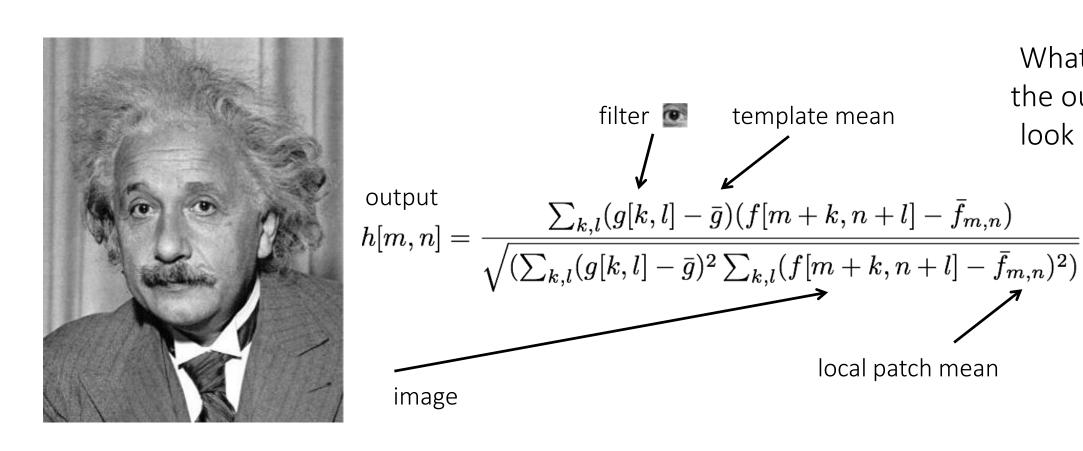
output



Not robust to highcontrast areas

ZNCC - zero mean normalized cross correlation

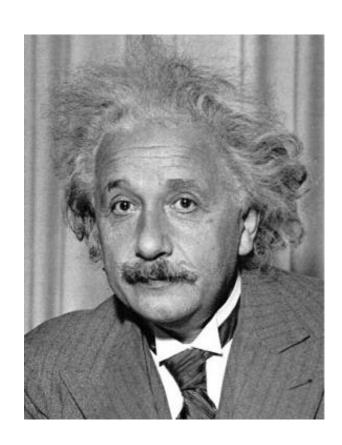
How do we detect the template **m** in he following image?



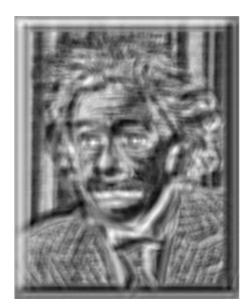
What will the output look like?

ZNCC – zero mean normalized cross correlation

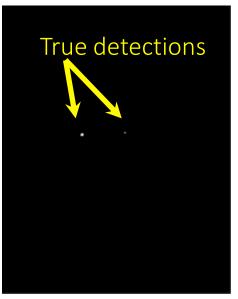
How do we detect the template **m** in he following image?



1-output

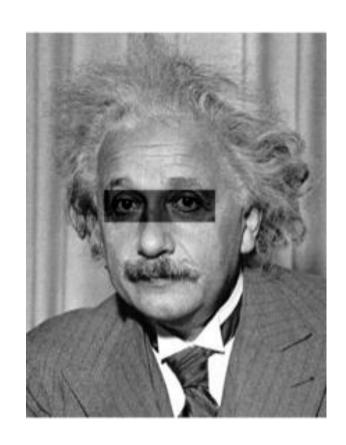


thresholding



ZNCC – zero mean normalized cross correlation

How do we detect the template **n** in he following image?

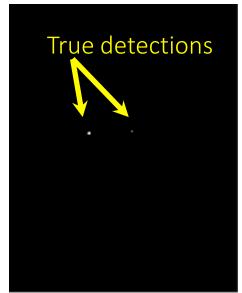


1-output



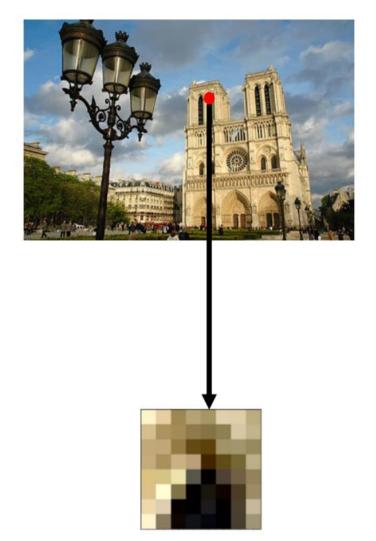
thresholding

robust to change in intensities

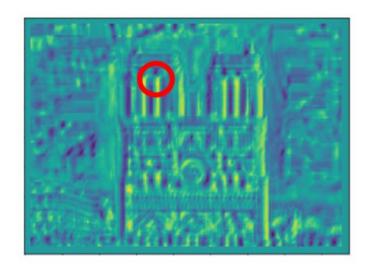


Template matching- SSD, ZNCC

- Good for very carefully constructed scenarios.
- Can't handle change in rotation and scale.







contents

- Image representation
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- Histogram equalization
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- Morphology operators
- Connected components
- Color space

- Handy tool whenever needed to clean up binary images.
- Each morphology operator is constructed as such:
 - 1. Select a structure element (binary kernel)

$$= \begin{vmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{vmatrix}$$

- Handy tool whenever needed to clean up binary images.
- Each morphology operator is constructed as such:
 - 1. Select a structure element (binary kernel)
 - 2. Cross-correlate with input binary image $g = f \star s$

$$= \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

- Handy tool whenever needed to clean up binary images.
- Each morphology operator is constructed as such:
 - 1. Select a structure element (binary kernel)

 - Threshold the output

$$\theta_{TH}(x,t) = \begin{cases} 1 & if & x \ge t, \\ 0 & else \end{cases}$$

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 - 3. Threshold the output

$$\theta_{TH}(x,t) = \begin{cases} 1 & if & x \ge t, \\ 0 & else \end{cases}$$

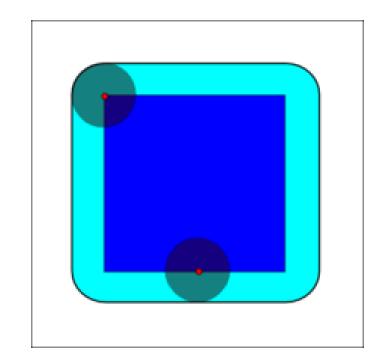
Overall morphologic operation should look like so:

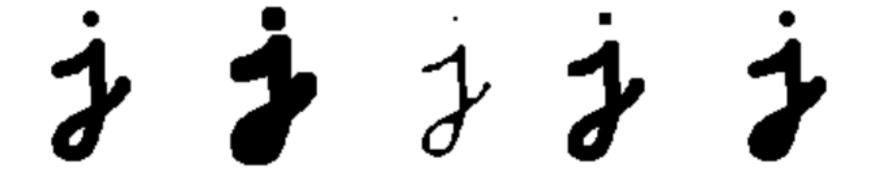
$$k = \theta_{TH}(f \star s, t)$$

Dilation

•
$$k = \theta_{TH}(f \star s, t)$$

- Dilation: t = 1
 - Skinny lines will get thicker

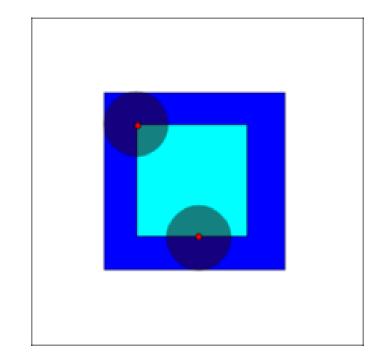




Erosion

•
$$k = \theta_{TH}(f \star s, t)$$

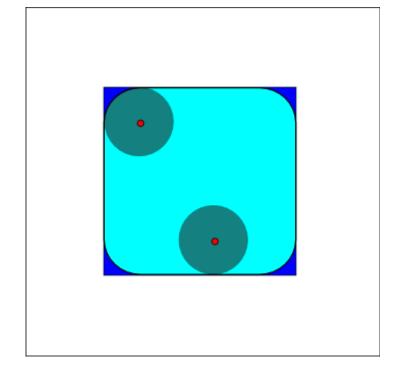
- Erosion: t = sum(s)
 - Thicker lines will get skinny





Opening

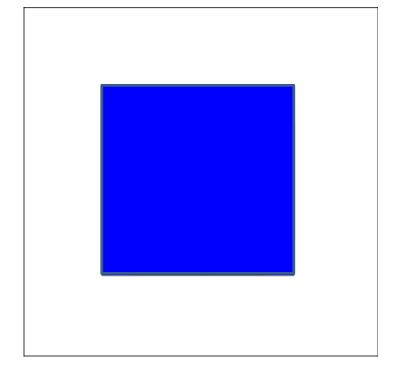
- Erosion followed by dilation.
 - The effect is of rounding off sharp edges.





Closing

- Dilation followed by erosion.
 - The effect is of closing of narrow gaps and holes.





contents

- Image representation
- Pixel-wise operations
- Histogram equalization
- Template matching
- Morphology operators
- Connected components
- Color space

Connected components

- Defined as regions of adjacent pixels that have the same value.
- Commonly used with binary images to find stand alone objects.
 - e.g.: letters in a document.

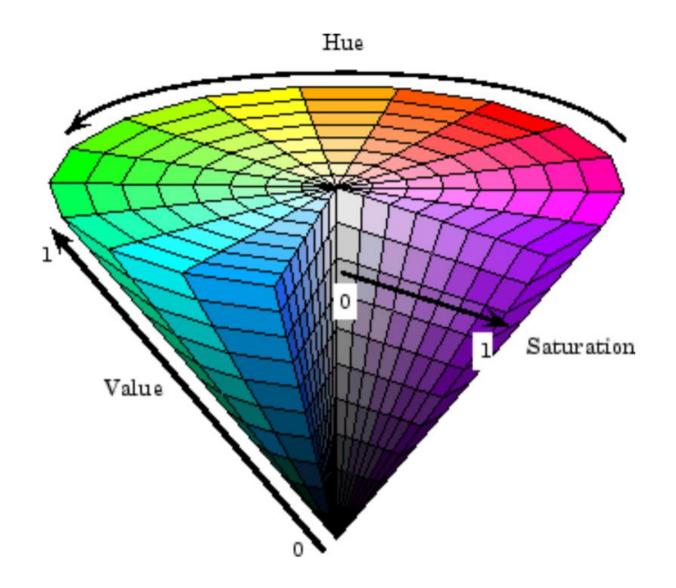




contents

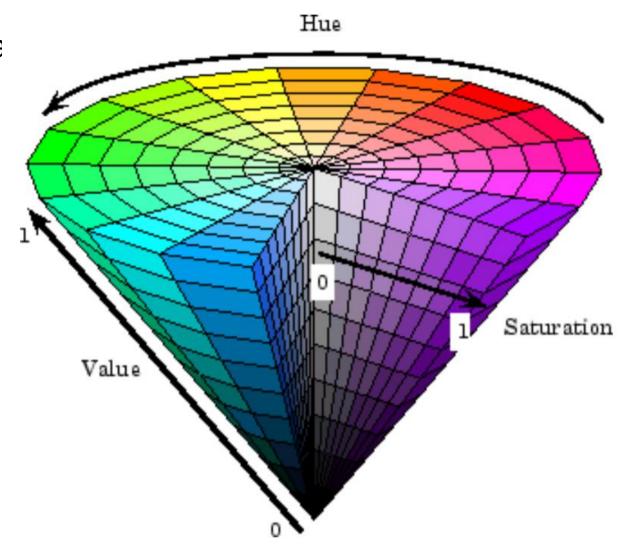
- Image representation
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HSV



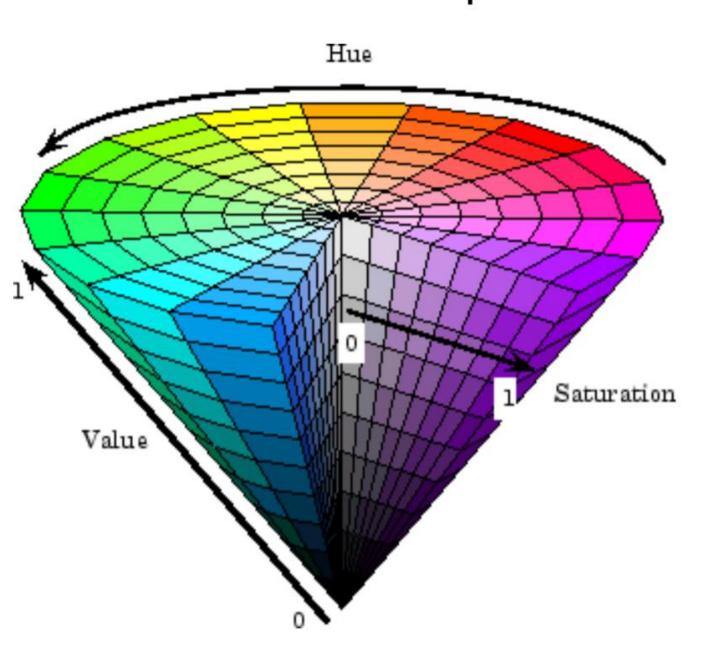
HSV

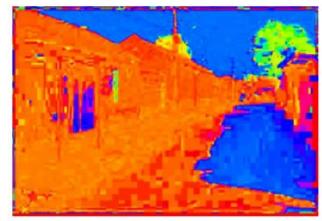
- Hue: The "attribute of a visual sensation according to which an area appears to be similar to one of the perceived colors: red, yellow, green, and blue, or to a combination of two of them"
- Saturation: The "colorfulness of a stimulus relative to its own brightness"
- Value: The "brightness relative to the brightness of a similarly illuminated white". Can also be called brightness or intensity.
 - [Wikipedia]





Original image





H (S=1,V=1)



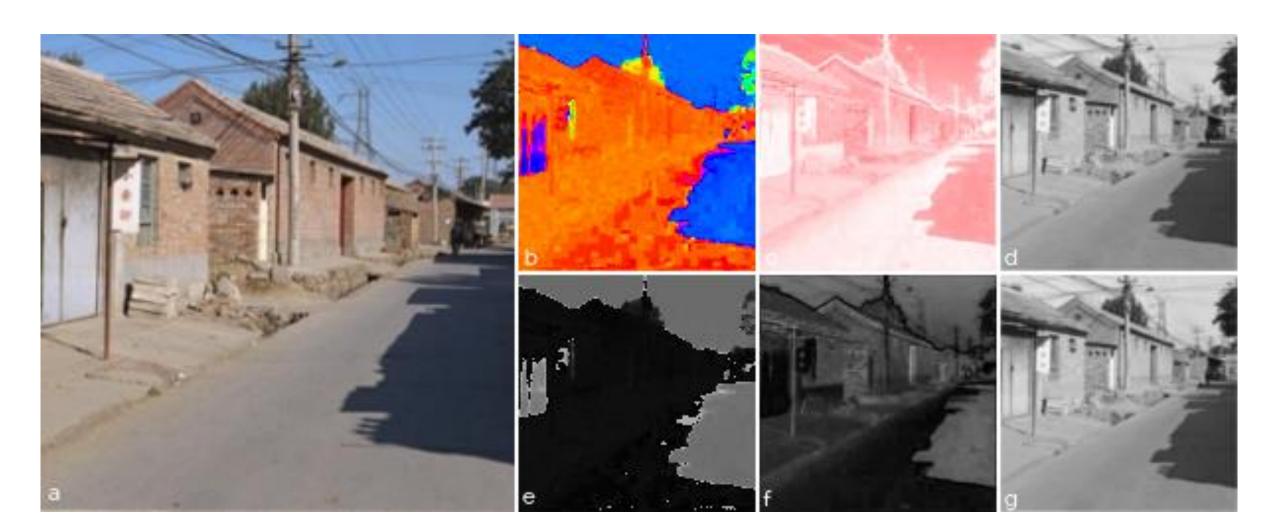
S (H=1,V=1)



V (H=1,S=0)

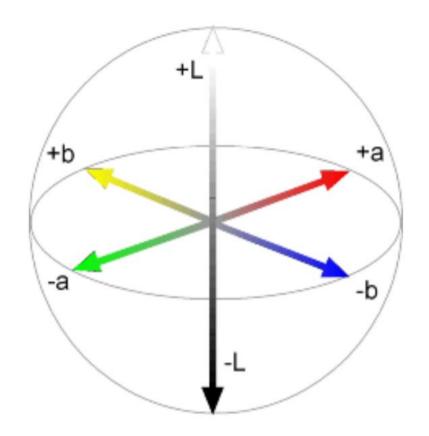
HSV

- In e, f, g: single channel image representation.
- Conclusion: people are much more responsive to intensity then chroma.



More color spaces: LAB

- L: lightness from black (0) to white (100).
- A: from green (-) to red (+).
- B: from blue (-) to yellow (+).





(a=0,b=0)



a (L=65,b=0)



b (L=65,a=0)

More color spaces: YUV

- Y: brightness/ intensity.
- U: blue projection.
- V: red projection.
- [Similar to YCbCr]

