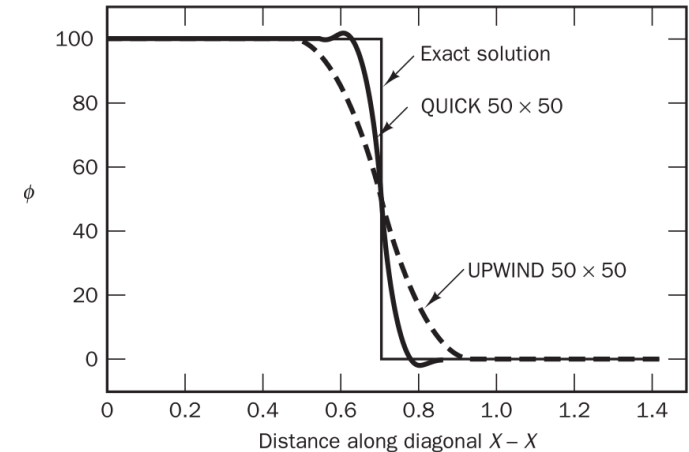


# **Total Variation Diminishing (TVD) methods**

# Wiggles (Spurious oscillations)

- High order methods such as QUICK, Central, 2<sup>nd</sup> order Upwind and so on give minor undershoots and overshoots, specially near discontinuity or sharp gradient points
- The class of TVD (total variation diminishing) schemes has been specially formulated to achieve oscillation-free solutions and has proved to be useful in CFD calculations



# TVD Schemes

- Upwind differencing (UD) scheme is the most stable and unconditionally bounded scheme, but it introduces a high level of false diffusion due to its low order of accuracy (first-order).
- Higher-order schemes can give spurious oscillations when the Peclet number is high
- When higher-order schemes are used to solve for turbulent quantities, wiggles can give physically unrealistic negative values and instability.
- TVD schemes are designed to address this undesirable oscillatory behaviour of higher-order schemes.

# Upwind-biased discretisation schemes

- Let's look at different schemes for the east face value of  $\phi_e$ :

Upwind differencing (UD):  $\phi_e = \phi_P$

Linear upwind differencing (LUD): 
$$\begin{aligned}\phi_e &= \phi_P + \frac{(\phi_P - \phi_W)}{\delta x} \frac{\delta x}{2} \\ &= \phi_P + \frac{1}{2}(\phi_P - \phi_W)\end{aligned}$$

Central differencing (CD): 
$$\begin{aligned}\phi_e &= \frac{(\phi_P + \phi_E)}{2} \\ &= \phi_P + \frac{1}{2}(\phi_E - \phi_P)\end{aligned}$$

QUICK: 
$$\phi_e = \phi_P + \frac{1}{8} [3\phi_E - 2\phi_P - \phi_W]$$

General form:

$$\phi_e = \phi_P + \frac{1}{2}\psi(\phi_E - \phi_P)$$

# Upwind-biased discretisation schemes

- In choosing this form we express the convective flux at the east face as the sum of the flux  $F_e \phi_P$  that is obtained when we use UD and an additional convective flux  $F_e \psi(\phi_E - \phi_P)/2$ .
- The extra contribution is connected in some way to the gradient of the transported quantity  $\phi$  at the east face, as indicated by its central difference approximation  $(\phi_E - \phi_P)$ .

$$\phi_e = \phi_P + \frac{1}{2} \psi (\phi_E - \phi_P)$$

CD:  $\psi = 1$

UD:  $\psi = 0$

LUD:  $\psi = (\phi_P - \phi_W)/(\phi_E - \phi_P)$

QUICK:  $\psi = \left( 3 + \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right) \frac{1}{4}$

$$\phi_e = \phi_P + \frac{1}{2} \left( \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right) (\phi_E - \phi_P)$$

$$\phi_e = \phi_P + \frac{1}{2} \left[ \left( 3 + \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right) \frac{1}{4} \right] (\phi_E - \phi_P)$$

# Upwind-biased discretisation schemes

- It can be seen the ratio of upwind-side gradient to downwind-side gradient ( $r$ ) determines the value of function  $\psi$  and the nature of the scheme:

$$\psi = \psi(r)$$

$$r = \left( \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right)$$

$$\phi_e = \phi_P + \frac{1}{2} \psi(r) (\phi_E - \phi_P)$$

For the UD scheme  $\psi(r) = 0$

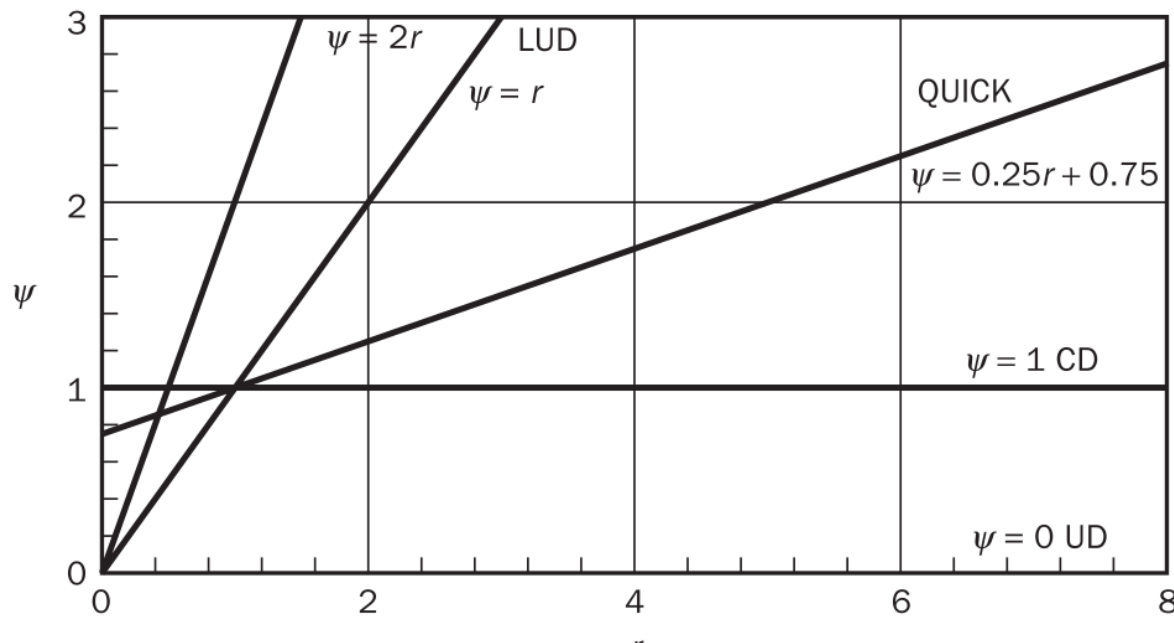
For the CD scheme  $\psi(r) = 1$

For the LUD scheme  $\psi(r) = r$

For the QUICK scheme  $\psi(r) = (3 + r)/4$

# Upwind-biased discretisation schemes

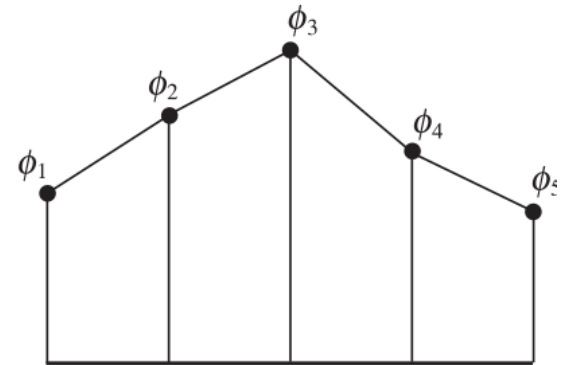
- The  $r$ - $\psi$  diagram is shown.
- It is assumed that the flow direction is positive (i.e. from west to east). Similar expressions exist for negative flow direction and  $r$  will still be the ratio of upwind-side gradient to downwind-side gradient.



# TVD schemes

- The desirable property for a stable, non-oscillatory, higher-order scheme is monotonicity preserving.
- In simple terms, **monotonicity-preserving** schemes **do not create new undershoots and overshoots** in the solution or accentuate existing extremes.
- Monotonicity-preserving schemes have implications for the so-called **total variation** of discretised solutions.
- For monotonicity to be satisfied, TV must not increase

$$\begin{aligned} TV(\phi) &= |\phi_2 - \phi_1| + |\phi_3 - \phi_2| + |\phi_4 - \phi_3| + |\phi_5 - \phi_4| \\ &= |\phi_3 - \phi_1| + |\phi_5 - \phi_3| \end{aligned}$$





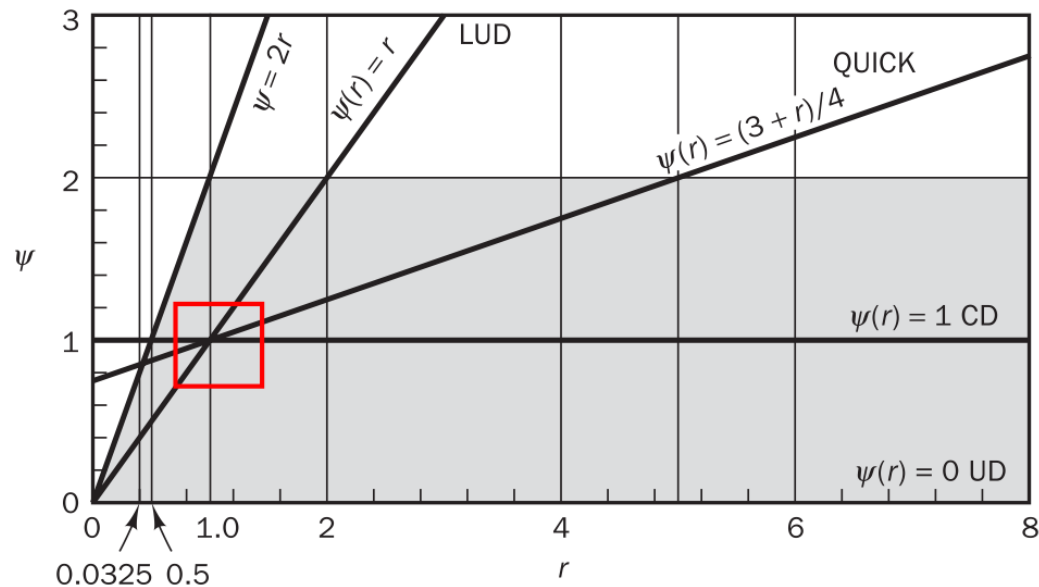
# TVD schemes

- Monotonicity-preserving schemes have the property that the total variation of the discrete solution should diminish with time.
- Hence they are called total variation diminishing or TVD schemes.
- Total variation is therefore considered at every time step and a solution is said to be total variation diminishing (or TVD) if

$$TV(\phi^{n+1}) \leq TV(\phi^n)$$

# Criteria for TVD schemes

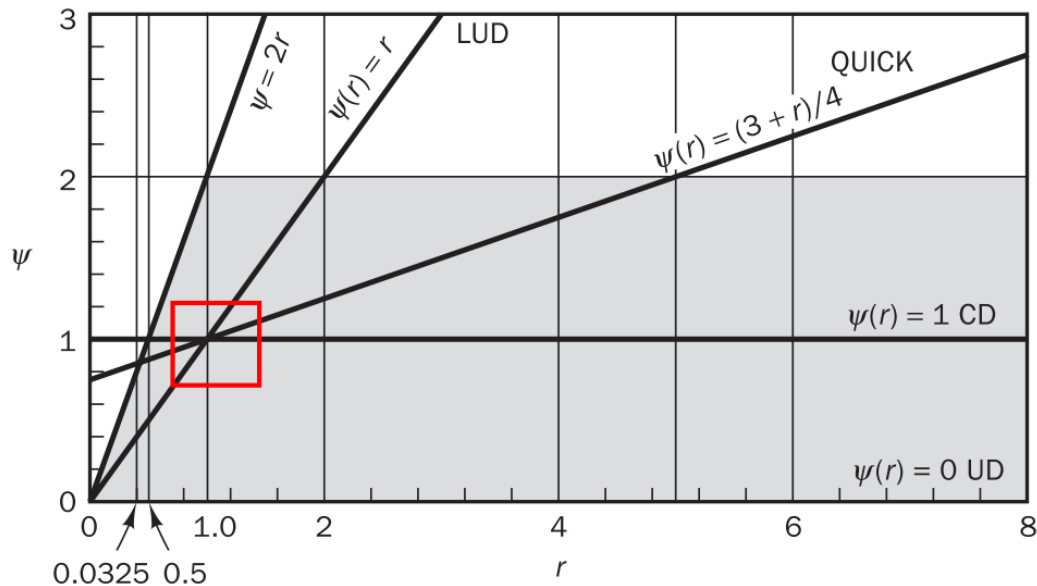
- Sweby (1984) has given necessary and sufficient conditions for a scheme to be TVD in terms of the  $r - \psi$  relationship



- If  $0 < r < 1$  the upper limit is  $\psi(r) = 2r$ , so for TVD schemes  $\psi(r) \leq 2r$
- If  $r \geq 1$  the upper limit is  $\psi(r) = 2$ , so for TVD schemes  $\psi(r) \leq 2$

# Criteria for TVD schemes

- the UD scheme is TVD
- the LUD scheme is not TVD for  $r > 2.0$
- the CD scheme is not TVD for  $r < 0.5$
- the QUICK scheme is not TVD for  $r < 3/7$  and  $r > 5$



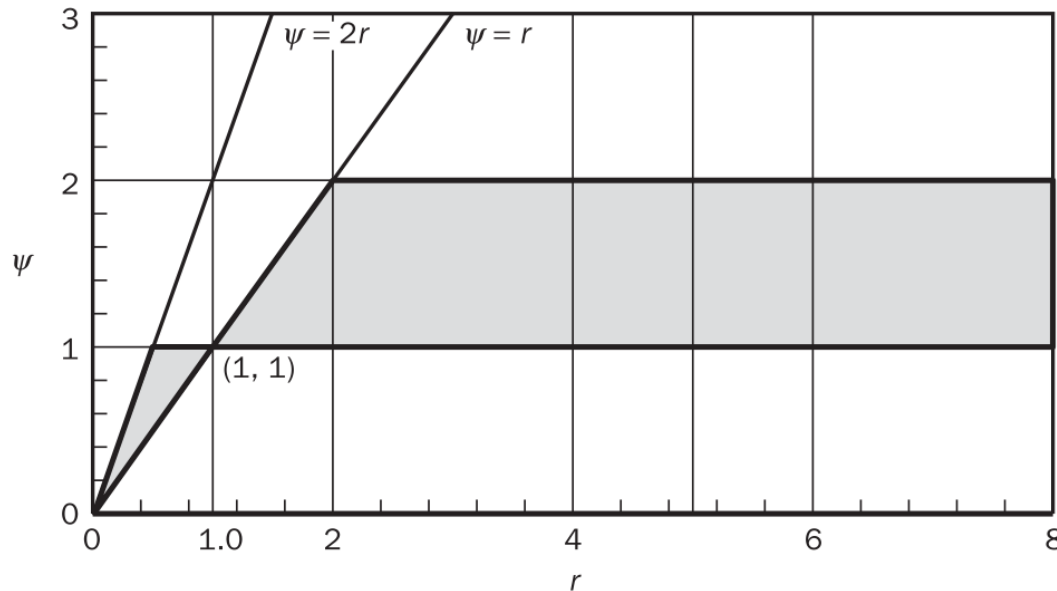
# Criteria for TVD schemes

- The idea of designing a TVD scheme is to introduce a modification to the above schemes so as to force the  $r$ - $\psi$  relationship to remain within the shaded region for all possible values of  $r$ .
- Since  $\psi(r)$  is limiting the estimated flux that is called a ***flux limiter*** function
- Sweby (1984) also introduced the following requirement for second-order accuracy in terms of the relationship  $\psi = \psi(r)$ :

*The flux limiter function of a second-order accurate scheme should pass through the point (1, 1) in the  $r$ - $\psi$  diagram*

# Criteria for TVD schemes

- Sweby also showed that the range of possible second-order schemes is bounded by CD and LUD:



- If  $0 < r < 1$  the lower limit is  $\psi(r) = r$ , the upper limit is  $\psi(r) = 1$ , so for TVD schemes  $r \leq \psi(r) \leq 1$
- If  $r \geq 1$  the lower limit is  $\psi(r) = 1$ , the upper limit is  $\psi(r) = r$ , so for TVD schemes  $1 \leq \psi(r) \leq r$

# Criteria for TVD schemes

- Sweby finally introduced the symmetry property for limiter functions:

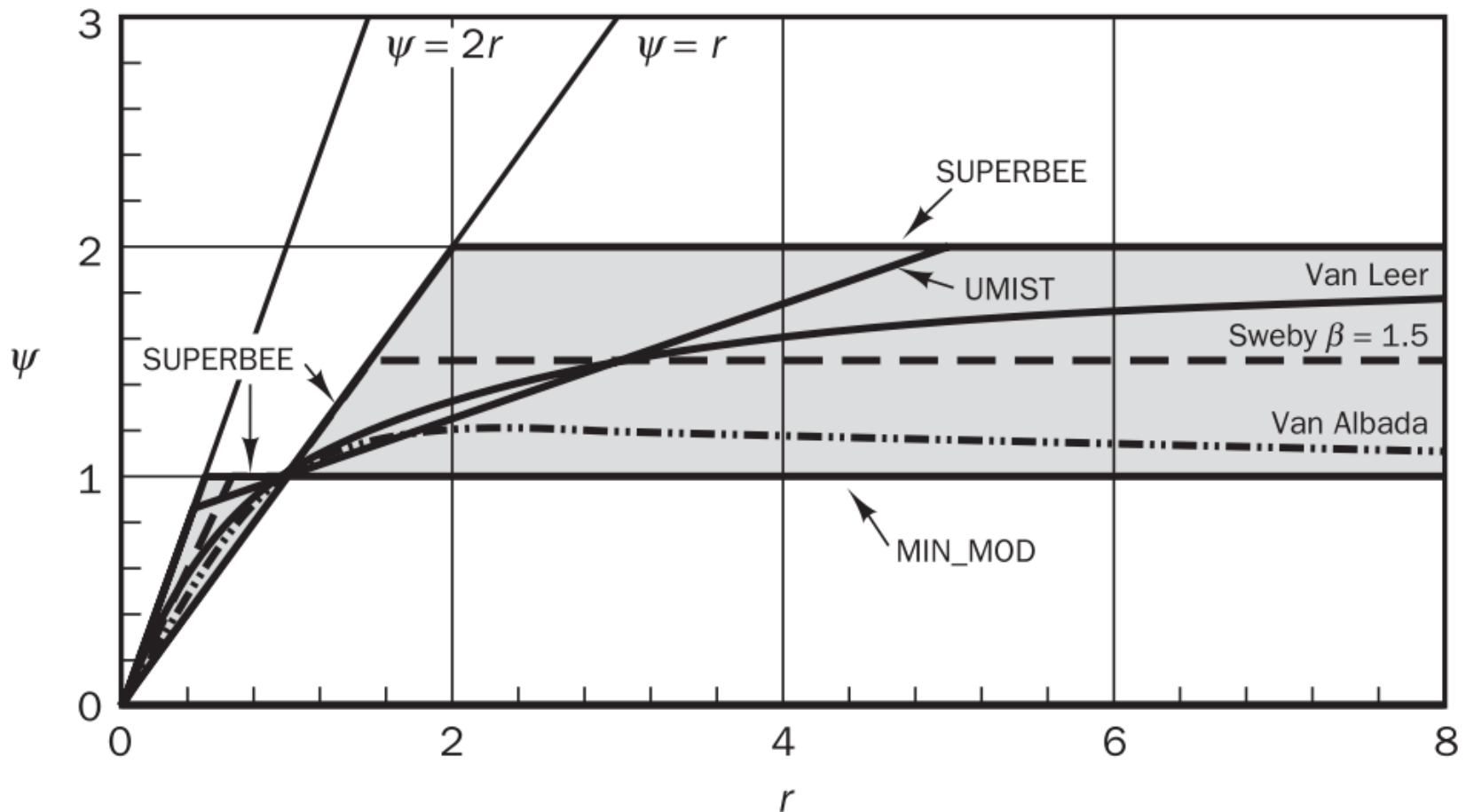
$$\frac{\psi(r)}{r} = \psi(1/r)$$

- A limiter function that satisfies the symmetry property ensures that backward- and forward-facing gradients are treated in the same fashion without the need for special coding.

# Flux limiter functions

<i>Name</i>	<i>Limiter function <math>\psi(r)</math></i>	<i>Source</i>
Van Leer	$\frac{r +  r }{1 + r}$	Van Leer (1974)
Van Albada	$\frac{r + r^2}{1 + r^2}$	Van Albada <i>et al.</i> (1982)
Min-Mod	$\psi(r) = \begin{cases} \min(r, 1) & \text{if } r > 0 \\ 0 & \text{if } r \leq 0 \end{cases}$	Roe (1985)
SUPERBEE	$\max[0, \min(2r, 1), \min(r, 2)]$	Roe (1985)
Sweby	$\max[0, \min(\beta r, 1), \min(r, \beta)]$	Sweby (1984)
QUICK	$\max[0, \min(2r, (3 + r)/4, 2)]$	Leonard (1988)
UMIST	$\max[0, \min(2r, (1 + 3r)/4, (3 + r)/4, 2)]$	Lien and Leschziner (1993)

# Flux limiter functions





# Flux limiter functions

- All the limiter functions stay inside the TVD region and pass through the point (1, 1), so they all represent second-order accurate TVD schemes.
- Van Leer and Van Albada's limiters are smooth functions, whereas all the others are piecewise linear expressions.
- The Min-Mod limiter function exactly traces the lower limit of the TVD region
- Roe's SUPERBEE scheme follows the upper limit.
- Sweby's expression is a generalisation of the Min-Mod and SUPERBEE limiters by means of a single parameter  $\beta$ . The limiter becomes the Min-Mod limiter when  $\beta = 1$  and the SUPERBEE limiter of Roe when  $\beta = 2$ .
- To stay within the TVD region we only consider the range of values  $1 \leq \beta \leq 2$ .
- Leonard's QUICK limiter function is the only one that is non-symmetric
- Lien and Leschziner's UMIST limiter function was designed as a symmetrical version of the QUICK limiter.

# Implementation of TVD schemes

- The diffusion term is discretised using central differencing as before, but the convective flux is now evaluated using a TVD scheme.

$$F_e \phi_e - F_w \phi_w = D_e(\phi_E - \phi_P) - D_w(\phi_P - \phi_W)$$

- For flow in the positive x-direction  $u > 0$

$$\begin{aligned} \phi_e &= \phi_P + \frac{1}{2}\psi(r_e)(\phi_E - \phi_P) \\ \phi_w &= \phi_W + \frac{1}{2}\psi(r_w)(\phi_P - \phi_W) \end{aligned} \quad \longrightarrow \quad \begin{aligned} &F_e \left[ \phi_P + \frac{1}{2}\psi(r_e)(\phi_E - \phi_P) \right] - F_w \left[ \phi_W + \frac{1}{2}\psi(r_w)(\phi_P - \phi_W) \right] \\ &= D_e(\phi_E - \phi_P) - D_w(\phi_P - \phi_W) \end{aligned}$$

$$\text{where } r_e = \left( \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right) \text{ and } r_w = \left( \frac{\phi_W - \phi_{WW}}{\phi_P - \phi_W} \right)$$

$$a_P \phi_P = a_W \phi_W + a_E \phi_E + S_u^{DC}$$

$$\text{where } a_W = D_w + F_w$$

$$a_E = D_e$$

$$a_P = a_W + a_E + (F_e - F_w)$$

$$S_u^{DC} = -F_e \left[ \frac{1}{2}\psi(r_e)(\phi_E - \phi_P) \right] + F_w \left[ \frac{1}{2}\psi(r_w)(\phi_P - \phi_W) \right]$$

# Implementation of TVD schemes

- As mentioned earlier, the above derivation is for the positive flow direction. To note the flow direction we use a superscript '+'. Therefore both  $r_e$  and  $r_w$  are replaced with  $r_w^+$  and  $r_e^+$ .

$$S_u^{DC} = -F_e \left[ \frac{1}{2} \psi(r_e^+) (\phi_E - \phi_P) \right] + F_w \left[ \frac{1}{2} \psi(r_w^+) (\phi_P - \phi_W) \right]$$

- For  $u < 0$ , it can be shown in the same manner:

$$a_P \phi_P = a_W \phi_W + a_E \phi_E + S_u^{DC}$$

$$\text{where } a_W = D_w$$

$$a_E = D_e - F_e$$

$$a_P = a_W + a_E + (F_e - F_w)$$

$$S_u^{DC} = F_e \left[ \frac{1}{2} \psi(r_e^-) (\phi_E - \phi_P) \right] - F_w \left[ \frac{1}{2} \psi(r_w^-) (\phi_P - \phi_W) \right]$$

$$\text{where } r_e^- = \left( \frac{\phi_{EE} - \phi_E}{\phi_E - \phi_P} \right) \text{ and } r_w^- = \left( \frac{\phi_E - \phi_P}{\phi_P - \phi_W} \right)$$

# Implementation of TVD schemes

- Thus the TVD scheme for one-dimensional convection–diffusion problems may be written as

$$a_P \phi_P = a_W \phi_W + a_E \phi_E + S_u^{DC} \quad a_P = a_W + a_E + (F_e - F_w)$$

<i>TVD neighbour coefficients</i>	
$a_W$	$D_w + \max(F_w, 0)$
$a_E$	$D_e + \max(-F_e, 0)$
<i>TVD deferred correction source term</i>	
$S_u^{DC}$	$\frac{1}{2} F_e [(1 - \alpha_e) \psi(r_e^-) - \alpha_e \cdot \psi(r_e^+)] (\phi_E - \phi_P)$ $+ \frac{1}{2} F_w [\alpha_w \cdot \psi(r_w^+) - (1 - \alpha_w) \psi(r_w^-)] (\phi_P - \phi_W)$

where

$$\alpha_w = 1 \text{ for } F_w > 0 \text{ and } \alpha_e = 1 \text{ for } F_e > 0$$

$$\alpha_w = 0 \text{ for } F_w < 0 \text{ and } \alpha_e = 0 \text{ for } F_e < 0$$

# Treatment at the boundaries

- At inlet/outlet boundaries it is necessary to generate upstream/downstream values to evaluate the values of  $r$ .
- These can be obtained using the extra-polated mirror node practice that was demonstrated for the QUICK scheme

$$F_e \left[ \phi_P + \frac{1}{2} \psi(r_e)(\phi_E - \phi_P) \right] - F_A \phi_A = D_e(\phi_E - \phi_P) - D_A^*(\phi_P - \phi_A)$$

$$(D_e + F_e + D_A^*)\phi_P = D_e\phi_E + (D_A^* + F_A)\phi_A - F_e \frac{1}{2} \psi(r_e)(\phi_E - \phi_P)$$

with  $D_A^* = \Gamma / \delta x$

The problem is to find

$$r_e = \left( \frac{\phi_P - \phi_W}{\phi_E - \phi_P} \right) \longrightarrow \phi_o = 2\phi_A - \phi_P \quad \text{so} \quad r_e = \left( \frac{\phi_P - \phi_o}{\phi_E - \phi_P} \right) = \frac{2(\phi_P - \phi_A)}{\phi_E - \phi_P}$$