

# Chen Sun

ASSISTANT PROFESSOR · UNIVERSITY OF HONG KONG

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## Work Experience

- 2025.01 - Current **Adjunct Assistant Professor**, Mechanical and Mechatronics Engineering department, University of Waterloo
- 2024.12 - Current **Representative**, IEEE Intelligent Transportation Systems Society and Future Networks Committee
- 2024.09 - Current **Assistant Professor**, Department of Data and Systems Engineering, University of Hong Kong
- 2022.12 - 2024.09 **Postdoctoral Fellow**, Mechatronic Vehicle Systems Lab, University of Waterloo
- 2022.01 - 2023.06 **Consultant - Autonomous Driving Stack**, Waytous Inc., (Beijing, China)
- 2017.05 - 2018.08 **R&D Engineer - System Control**, Robot Control Branch-Xylem Inc. (Mississauga, Canada)

## Education

### University of Waterloo

Waterloo, ON, Canada

#### PH.D. MECHANICAL & MECHATRONICS ENGINEERING

2018.09 - 2022.12

- Dissertation: "Operational Design Domain Monitoring and Augmentation for Autonomous Driving"
- Advisor: Prof. Amir Khajepour

### University of Toronto

Toronto, ON, Canada

#### M.A.SC. ELECTRICAL & COMPUTER ENGINEERING

2014.09 - 2017.03

- Thesis: "Fast FDTD Algorithm based on Model Order Reduction"
- Advisor: Prof. Piero Triverio

### University of Electronic Science and Technology of China

Chengdu, Sichuan, China

#### B.ENG. SYSTEM CONTROL

2010.09 - 2014.07

- Honor's Thesis: "Top tension control of a flexible marine riser by using integral-barrier Lyapunov function"
- Undergrad research advisor: Prof. Shuzhi Sam Ge & Prof. Wei He

## Publications

### SELECTED JOURNAL PAPERS (CORRESPONDING AUTHOR \*)

- Zhang, R., **Sun, C. \***, Ning, M., Valiollahimehrizi, R., Lu, Y., Czarnecki, K., & Khajepour, A. (2025). Quantifying learning algorithm uncertainties in autonomous driving systems: Enhancing safety through Polynomial Chaos Expansion and High Definition maps. *Accident Analysis & Prevention*, 211, 107903.
- Zhang, R., **Sun, C. \***, Valiollahimehrizi, R., Czarnecki, K., & Khajepour, A. (2025). An Uncertainty-Aware, Dual-Tiered Decision-Making Method for Safe Autonomous Driving. *IEEE Transactions on Intelligent Transportation Systems*.
- Lu, Y., Zhen, R., Liu, Y., Zhong, J., **Sun, C. \***, Huang, Y., & Khajepour, A. (2025). Practical solution for attenuating industrial heavy vehicle vibration: A new gain-adaptive coordinated suspension control system. *Control Engineering Practice*, 154, 106125.
- Sun, C. \***, Cui, Y., Ning, M., Lu, Y., Cao, D., & Khajepour, A. (2024). Extending Operational Design Domain for Perception Systems Through Robust Learning. *IEEE Transactions on Intelligent Vehicles*.
- Ning, M., Khajepour, A., Hashemi, E., & **Sun, C. \*** (2024). A Novel Motion Planning for Autonomous Vehicles Using Point Cloud based Potential Field. *IEEE Transactions on Vehicular Technology*.
- Sun, C. \***, Ning, M., Deng, Z., & Khajepour, A. (2024). REAL-SAP: Real-time Evidence Aware Liable Safety Assessment for Perception in Autonomous Driving. *IEEE Transactions on Vehicular Technology*.
- Wang, X., Huang, J., Tian, Y., **Sun, C. \***, Yang, L., Lou, S., Lv, C., Sun, C. & Wang, F.Y., 2024. Parallel Driving with Big Models and Foundation Intelligence in Cyber-Physical-Social Spaces. *Research*. 7, p.0349.

- Lu, Y., Huang, Y., **Sun, C.**, Zhong, J., & Khajepour, A. (2024). An interconnected suspension with adjustable roll and pitch stiffness (IS-ARPS) to enhance anti-roll and anti-dive/squat characteristics. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*.
- Wang, H., Shao, W., **Sun, C.** \*, Yang, K., Cao, D., & Li, J. (2024). A Survey on an Emerging Safety Challenge for Autonomous Vehicles: Safety of the Intended Functionality. *Engineering*.
- Sun, C.**, Cui, Y., Đào, N. D., Mehrizi, R. V., Pirani, M., & Khajepour, A. (2023). Medium-Fidelity Evaluation and Modeling for Perception Systems of Intelligent and Connected Vehicles. *IEEE Transactions on Intelligent Vehicles*.
- Sun. C.** , Zhang, R., Cui, Y., Deng, Z., Cao, D., & Khajepour, A. (2023). Towards Ensuring Safety for Autonomous Driving Perception: Standardization Progress, Research Advances, and Perspectives. *IEEE Transactions on Intelligent Transportation Systems*
- Cui, Y., Huang, S., Zhong, J., Liu, Z., Wang, Y., **Sun, C.** \*, ... & Khajepour, A. (2023). DriveLLM: Charting the path toward full autonomous driving with large language models. *IEEE Transactions on Intelligent Vehicles*.
- Wu, X., Ma, Y., Fu, Q., **Sun, C.**, Zhu, B., & He, W. (2022). Anti-Disturbance Boundary Control for a Wave Equation With Input Disturbance. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, 53(4), 2236-2245.
- Sun, C.**, Li, S., Cao, D., Wang, F. Y., & Khajepour, A. (2022). Tabular Learning-Based Traffic Event Prediction for Intelligent Social Transportation System. *IEEE Transactions on Computational Social Systems*.
- Ma, Y., **Sun, C.**, Chen, J., Cao, D., & Xiong, L. (2022). Verification and validation methods for decision-making and planning of automated vehicles: A review. *IEEE Transactions on Intelligent Vehicles*.
- Su, L., **Sun. C.** \*, Cao, D., & Khajepour, A. (2022). Efficient driver anomaly detection via conditional temporal proposal and classification network. *IEEE Transactions on Computational Social Systems*, 10(2), 736-745.
- Sun. C.** , Deng, Z., Chu, W., Li, S., & Cao, D. (2021). Acclimatizing the operational design domain for autonomous driving systems. *IEEE Intelligent Transportation Systems Magazine*, 14(2), 10-24.
- Sun. C.** , Wang, C., Deng, Z., & Cao, D. (2020). Dimensionless model-based system tracking via augmented Kalman filter for multiscale unmanned ground vehicles. *IEEE/ASME Transactions on Mechatronics*, 26(2), 600-610.
- Sun. C.** , Vianney, J. M. U., Li, Y., Chen, L., Li, L., Wang, F. Y., ... & Cao, D. (2020). Proximity based automatic data annotation for autonomous driving. *IEEE/CAA Journal of Automatica Sinica*, 7(2), 395-404.

## CONFERENCE PAPERS

- Sun. C.** , Cui, Y., Lu, Y., Cao, Y., Cao, D., & Khajepour, A. (2023, November). Robust Learning for Autonomous Driving Perception Tasks in Cyber-Physical-Social Systems. In *2023 IEEE 3rd International Conference on Digital Twins and Parallel Intelligence (DTPI)* (pp. 1-7). IEEE.
- Sun. C.** , Cui, Y., Đào, N. D., & Khajepour, A. (2023, August). Delay Mitigation for V2I-based Cooperative Autonomous Driving Applications. In the *28th IAVSD International Symposium on Dynamics of Vehicles on Roads and Tracks (IAVSD)*
- Sun. C.** , Tan, R., Deng, J., Zhou, R., Chen, L., Wang, F. Y., & Cao, D. (2021, July). Accident prediction in mesoscopic view: A cps-based social transportation approach. In *2021 IEEE 1st International Conference on Digital Twins and Parallel Intelligence (DTPI)* (pp. 306-311).
- Peng, M., Gong, Z., **Sun. C.** , Chen, L., & Cao, D. (2020, May). Imitative reinforcement learning fusing vision and pure pursuit for self-driving. In *2020 IEEE International Conference on Robotics and Automation (ICRA)* (pp. 3298-3304). IEEE.
- Sun. C.** , Su, L., Gu, S., Vianney, J. M. U., Qin, K., & Cao, D. (2019, October). Cross validation for CNN based affordance learning and control for autonomous driving. In *2019 IEEE Intelligent Transportation Systems Conference (ITSC)* (pp. 1519-1524). IEEE.

## Funding, Awards & Fellowships

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- 2023 **Canada Mitacs Accelerate internships**, Mitacs, Canada
- 2022 **Chinese Government Award for Outstanding Self-financed Students Abroad**,  
China Scholarship Council
- 2019 - 2022 **University of Waterloo Graduate Scholarship**, University of Waterloo
- 2021 **Outstanding paper award**, 2021 IEEE 1st International Conference on Digital  
Twins and Parallel Intelligence (DTPI)
- 2014 - 2016 **University of Toronto Rogers scholarship** , University of Toronto
- 2011 - 2014 **People's First Class Scholarship** , University of Electronic Science and  
Technology of China

## Teaching Experience

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Summer 2023	<b>Introduction to Autonomous Driving Systems (ME780)</b> , Guest Lecturer	<i>University of Waterloo</i>
Fall 2020	<b>Introduction to Control Systems (ME360)</b> , Teaching Assistant	<i>University of Waterloo</i>
2019 - 2021	<b>Introduction to Microprocessors and Digital Logic (ME262)</b> , Teaching Assistant	<i>University of Waterloo</i>
Summer 2019	<b>Advanced Calculus (MTE203)</b> , Teaching Assistant	<i>University of Waterloo</i>
2015 - 2016	<b>Digital Systems (ECE241)</b> , Teaching Assistant	<i>University of Toronto</i>
Fall 2015	<b>Introduction to Computer Programming (CSC108)</b> , Teaching Assistant	<i>University of Toronto</i>

## Mentorship Activities

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- 2024 - Current **Bruce Wang**, Undergraduate Research Assistant, University of Waterloo
- 2020 - 2021 **Lang Su**, Undergraduate Research Assistant, University of Waterloo

## Patent

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Wang, F., Chen, L., Cao, D., Tian, B., & **Sun, C.** (2024). Intelligent Driving System, U.S. Patent Application No. 18/035,639.

## Review Activities

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- IEEE Transactions on Intelligent Vehicles (TIV)
- IEEE Transactions on Cybernetics (TCYB)
- IEEE Transactions on Artificial Intelligence (TAI)
- EE/ASME Transactions on Mechatronics (TMECH)
- IEEE Transactions on Fuzzy Systems (TFS)
- Automotive Innovation (AUIN)
- IEEE Intelligent Transportation Systems Conference (ITSC)
- IEEE International Conference on Intelligent Robots and Systems (IROS)

## Languages and Tools

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- Proficient in **Python, MATLAB/Simulink, C++**
- Experience in **ROS, FPGA** and **PLC** programming