

$$5. \quad \frac{\partial u}{\partial t} = a\frac{\partial^2 u}{\partial x^2} + uf\left(\frac{u}{w}\right), \quad \frac{\partial w}{\partial t} = b\frac{\partial^2 w}{\partial x^2} + wg\left(\frac{u}{w}\right).$$

1°. Multiplicative separable solution:

$$u = [C_1 \sin(kx) + C_2 \cos(kx)]\varphi(t),$$
  

$$w = [C_1 \sin(kx) + C_2 \cos(kx)]\psi(t),$$

where  $C_1$ ,  $C_2$ , and k are arbitrary constants, and the functions  $\varphi = \varphi(t)$  and  $\psi = \psi(t)$  are determined by the system of ordinary differential equations

$$\varphi'_t = -ak^2\varphi + \varphi f(\varphi/\psi),$$
  
$$\psi'_t = -bk^2\psi + \psi g(\varphi/\psi).$$

2°. Multiplicative separable solution:

$$u = [C_1 \exp(kx) + C_2 \exp(-kx)]U(t),$$
  
 $w = [C_1 \exp(kx) + C_2 \exp(-kx)]W(t),$ 

where  $C_1$ ,  $C_2$ , and k are arbitrary constants, and the functions U = U(t) and W = W(t) are determined by the system of ordinary differential equations

$$U'_t = ak^2U + Uf(U/W),$$
  
$$W'_t = bk^2W + Wg(U/W).$$

3°. Degenerate solution:

$$u = (C_1x + C_2)U(t),$$
  
 $w = (C_1x + C_2)W(t),$ 

where  $C_1$  and  $C_2$ , and the functions U = U(t) and W = W(t) are determined by the system of ordinary differential equations

$$U'_t = Uf(U/W),$$
  

$$W'_t = Wg(U/W).$$

This autonomous system can be integrated, since it is reduced, on eliminating t, to a homogeneous first-order equation (the corresponding systems of Items  $1^{\circ}$  and  $2^{\circ}$  are integrated likewise).

4°. Multiplicative separable solution:

$$u = e^{-\lambda t} y(x), \quad w = e^{-\lambda t} z(x),$$

where  $\lambda$  is an arbitrary constant and the functions y = y(x) and z = z(x) are determined by the system of ordinary differential equations

$$ay''_{xx} + \lambda y + yf(y/z) = 0,$$
  
$$bz''_{xx} + \lambda z + zg(y/z) = 0.$$

 $5^{\circ}$ . Solution(generalizes the solution of Item  $4^{\circ}$ ):

$$u = e^{kx - \lambda t}y(\xi), \quad w = e^{kx - \lambda t}z(\xi), \quad \xi = \beta x - \gamma t,$$

where k,  $\lambda$ ,  $\beta$ , and  $\gamma$  are arbitrary constants, and the functions  $y = y(\xi)$  and  $z = z(\xi)$  are determined by the system of ordinary differential equations

$$a\beta^{2}y_{\xi\xi}'' + (2ak\beta + \gamma)y_{\xi}' + (ak^{2} + \lambda)y + yf(y/z) = 0,$$
  
$$b\beta^{2}z_{\xi\xi}'' + (2bk\beta + \gamma)z_{\xi}' + (bk^{2} + \lambda)z + zg(y/z) = 0.$$

To the special case  $k=\lambda=0$  there corresponds a traveling-wave solution. For  $k=\gamma=0$  and  $\beta=1$ , we have the solution of Item 3°.

## Reference

**Polyanin, A. D.,** Exact solutions of nonlinear systems of reaction-diffusion equations and mathematical biology equations, *Theor. Found. Chem. Eng.*, Vol. 37, No. 6, 2004.

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