Exact Solutions > Linear Partial Differential Equations > Second-Order Parabolic Partial Differential Equations > Generalized Tricomi Equation

4.2. Generalized Tricomi Equation $\frac{\partial^2 w}{\partial x^2} + f(x) \frac{\partial^2 w}{\partial u^2} = 0$

4.2-1. Particular solutions of the generalized Tricomi equation:

$$w = C_1 xy + C_2 y + C_3 x + C_4,$$

$$w = C_1 y^2 + C_2 xy + C_3 y + C_4 x - 2C_1 \int_a^x (x - t) f(t) dt + C_5,$$

$$w = C_1 y^3 + C_2 xy + C_3 y + C_4 x - 6C_1 y \int_a^x (x - t) f(t) dt + C_5,$$

$$w = (C_1 x + C_2) y^2 + C_3 xy + C_4 y + C_5 x - 2 \int_a^x (x - t) (C_1 t + C_2) f(t) dt + C_6,$$

where C_1 , C_2 , C_3 , C_4 , C_5 , and C_6 are arbitrary constants, a is any number.

4.2-2. Separable particular solution of the generalized Tricomi equation:

$$w = (C_1 e^{\lambda y} + C_2 e^{-\lambda y}) H(x),$$

where C_1 , C_2 , and λ are arbitrary constants, and the function H = H(x) is determined by the ordinary differential equation $H''_{xx} + \lambda^2 f(x)H = 0$.

4.2-3. Separable particular solution of the generalized Tricomi equation:

$$w = [C_1 \sin(\lambda y) + C_2 \cos(\lambda y)]Z(x),$$

where C_1 , C_2 , and λ are arbitrary constants, and the function Z = Z(x) is determined by the ordinary differential equation $Z''_{xx} - \lambda^2 f(x)Z = 0$.

4.2-4. Particular solutions of the generalized Tricomi equation with even powers of y:

$$w = \sum_{k=0}^{n} \varphi_k(x) y^{2k},$$

where the functions $\varphi_k = \varphi_k(x)$ are defined by the recurrence relations

$$\varphi_n(x) = A_n x + B_n, \quad \varphi_{k-1}(x) = A_k x + B_k - 2k(2k-1) \int_a^x (x-t)f(t)\varphi_k(t) dt,$$

where A_k and B_k are arbitrary constants (k = n, ..., 1), a is any number.

4.2-5. Particular solutions of the generalized Tricomi equation with odd powers of y:

$$w = \sum_{k=0}^{n} \psi_k(x) y^{2k+1},$$

where the functions $\psi_k = \psi_k(x)$ are defined by the recurrence relations

$$\psi_n(x) = A_n x + B_n, \quad \psi_{k-1}(x) = A_k x + B_k - 2k(2k+1) \int_a^x (x-t)f(t)\psi_k(t) dt,$$

where A_k and B_k are arbitrary constants (k = n, ..., 1), and a is any number.

Reference

Polyanin, A. D., Handbook of Linear Partial Differential Equations for Engineers and Scientists, Chapman & Hall/CRC, 2002.

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