

Systems of Ordinary Differential Equations > Linear Systems of Two Equations

16.
$$t^2 x_{tt}'' + a_1 t x_t' + b_1 t y_t' + c_1 x + d_1 y = 0$$
, $t^2 y_{tt}'' + a_2 t x_t' + b_2 t y_t' + c_2 x + d_2 y = 0$.

Linear system homogeneous in the independent variable (Euler type).

 1° . The general solution is determined by a linear combination of linearly independent particular solutions sought in the form of power-law functions,

$$x = A|t|^k$$
, $y = B|t|^k$,

by the method of undetermined coefficients. On substituting these expressions into the original system and collecting coefficients of A and B, one obtains a system for A and B:

$$[k^{2} + (a_{1} - 1)k + c_{1}]A + (b_{1}k + d_{1})B = 0,$$

$$(a_{2}k + c_{2})A + [k^{2} + (b_{2} - 1)k + d_{2}]B = 0.$$

The determinant of this system must vanish for nontrivial solutions to exist. Hence follows the characteristic equation for the exponent k:

$$[k^{2} + (a_{1} - 1)k + c_{1}][k^{2} + (b_{2} - 1)k + d_{2}] - (b_{1}k + d_{1})(a_{2}k + c_{2}) = 0.$$

If the roots of this equation, k_1, \ldots, k_4 , are all distinct, then the general solution of the original system of differential equations is expressed as

$$\begin{split} x &= -C_1(b_1k_1+d_1)|t|^{k_1} - C_2(b_1k_2+d_1)|t|^{k_2} - C_3(b_1k_1+d_1)|t|^{k_3} - C_4(b_1k_4+d_1)|t|^{k_4}, \\ y &= C_1[k_1^2 + (a_1-1)k_1 + c_1]|t|^{k_1} + C_2[k_2^2 + (a_1-1)k_2 + c_1]|t|^{k_2} \\ &\quad + C_3[k_3^2 + (a_1-1)k_3 + c_1]|t|^{k_3} + C_4[k_4^2 + (a_1-1)k_4 + c_1]|t|^{k_4}, \end{split}$$

where C_1, \ldots, C_4 are arbitrary constants.

 2° . The substitution $t = \sigma e^{\tau}$ ($\sigma \neq 0$) leads to the system of constant-coefficient linear differential equations

$$x''_{\tau\tau} + (a_1 - 1)x'_{\tau} + b_1 t y'_{\tau} + c_1 x + d_1 y = 0,$$

$$y''_{\tau\tau} + a_2 x'_{\tau} + (b_2 - 1)y'_{\tau} + c_2 x + d_2 y = 0.$$

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