# Learning Multiplex Graph with Inter-layer Coupling

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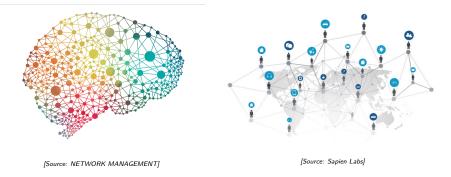
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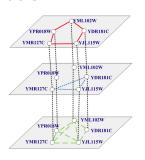
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## **Motivation**

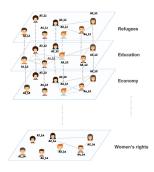


- ► Graphs are natural ways to represent *social*, *biology*, *transportation*, *power* networks, and others.
- ► Graph Signal Processing (GSP) extends signal processing to graph data and enables 'interpretable' inference of data.

### **Motivation**







Multilayer social network [Source: [Hanteer and Rossi, 2019]]

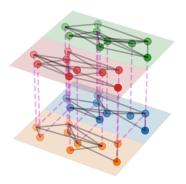
- ▶ Prior works consider closed systems with single layer of networks, but networks do not live in isolation [Kivelä et al., 2014].
- A general model is multiplex graph a node is present on ≥ 2 layers of graphs, each with different topology e.g., opinion dynamics on ≥ 2 topics, weather measurement stations, brain signals, etc.
- ▶ Note: We focus on *multi-attribute graph signals*.

### **Goals and Contributions**

To extend GSP methods to multiplex graphs: signal analysis, topology learning, etc. — we focus on graph topology learning.

#### Contributions:

- Multiplex Graph Filter for multi-attribute graph signals with nonlinear intra-/inter-layer couplings.
- Interpret TV/smoothness criterion as a matched filter criterion – extend to handle inter-layer couplings.
- ► Alternating Optimization Procedure for efficient multiplex graph learning.



#### **Related Works**

- Models for multi-way graph signals (on multiplex graphs)
  - [Zhang et al., 2023b] tensor GSP model, but it lacks inter-layer coupling dynamics.
  - ► [Natali et al., 2020, Grassi et al., 2017] considered product graph signal models which is a special case of multiplex graphs.

#### Multiplex graph topology learning

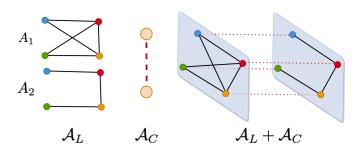
- [Kalaitzis et al., 2013] [Kadambari and Chepuri, 2021], [Einizade and Sardouie, 2023] learn product graphs using graph signals via smoothness, spectral template, etc.
- Our prior work [Zhang et al., 2023a] consider a fine-grained model for product graph learning.

#### ► Graph Machine Learning

- ► [Cen et al., 2019, Zhang et al., 2019] seek embeddings for graph representation on heterogeneous graph with HetGNN.
- ▶ [Butler et al., 2023] proposed a model for convolutional learning on multigraph.
- ▶ and many others ...

## **Multiplex Graph Model**

- ▶  $G = \langle V, \mathcal{E}, \mathcal{G}^C \rangle$  with nodes V, layer edges  $\mathcal{E}$ , coupling graph  $\mathcal{G}^C$ .
- ▶ There are |V| = N nodes and L layers.
- ▶ **Layer Graphs:** For  $\ell = 1, ..., L$ ,  $\mathcal{G}_{\ell}$  with supernodes  $V_{\ell}$ , edges  $E_{\ell}$ , representing intra-layer links with adjacency  $\mathbf{A}_{\ell}$ .
- **Coupling Graph:**  $\mathcal{G}^{\mathcal{C}}$  for inter-layer links with adjacency  $\mathcal{C}$ .
- ▶ Adjacency Matrix: Layer-wise  $\mathcal{A}_L = \mathsf{blkdiag}(\mathcal{A}_1, \dots, \mathcal{A}_L)$  and coupling  $\mathcal{A}_C = C \otimes I_N$ . e.g. supra-adjacency:  $\mathcal{A} = \mathcal{A}_L + \mathcal{A}_C$ .



## Multi-attribute Graph Filter and Signals.

We model multi-attribute graph signal as

$$\mathbf{y}^{(m)} = \mathcal{H}(\mathbf{A}_L, \mathbf{A}_C)\mathbf{x}^{(m)} + \mathbf{w}^{(m)} \in \mathbb{R}^{NL},$$
 (1)

▶  $\mathcal{H}(A_L, A_C)$  shall model the multiplex with distinct intra-layer and coupling dynamics  $\rightarrow$  a **general** multi-attribute graph filter model<sup>1</sup>:

$$\mathcal{H}(\mathcal{A}_{L}, \mathcal{A}_{C}) = \sum_{t=0}^{T-1} \sum_{j=0}^{2^{t}-1} h_{t,j} \prod_{i=1}^{t} \mathcal{A}_{L}^{b_{t,j}^{(i)}} \mathcal{A}_{C}^{1-b_{t,j}^{(i)}}, \quad b_{t,j}^{(i)} \in \{0,1\} \quad \text{(GF)}$$

▶ Remark: the tensor GSP model [Zhang et al., 2023b] essentially takes the polynomial filter of supra-adjacency matrix

$$\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C) = \sum_{t=0}^{T-1} h_t (\mathcal{A}_L + \mathcal{A}_C)^t.$$
 (GF-t)

<sup>&</sup>lt;sup>1</sup>Note: this is a multinomial with exponential number of coefficients. Similar observations are made in [Butler et al., 2023].

## **Expressibility of (GF): Multiplex Graph Dynamics**

It is necessary to use the model (GF) with

$$\mathcal{H}(\mathcal{A}_{L},\mathcal{A}_{C}) = \sum_{t=0}^{T-1} \sum_{i=0}^{2^{t}-1} h_{t,j} \prod_{i=1}^{t} \mathcal{A}_{L}^{b_{t,j}^{(i)}} \mathcal{A}_{C}^{1-b_{t,j}^{(i)}}, \quad b_{t,j}^{(i)} \in \{0,1\}$$

#### Supra-diffusion Process:

► E.g., dynamics of epidemics [Kivelä et al., 2014]:

$$\frac{d\mathbf{y}_{\ell}(t)}{dt} = -\mathbf{y}_{\ell}(t) + \underbrace{\mathbf{A}_{\ell}\mathbf{y}_{\ell}(t)}_{\text{intra-layer}} + \underbrace{\sum_{\ell'=1}^{L} C_{\ell,\ell'}\mathbf{y}_{\ell'}(t)}_{\text{inter-layer}} + \mathbf{x}_{\ell}^{(m)}.$$

Steady-state of the diffusion process:

$$\mathbf{y}^{(m)} = \lim_{t \to \infty} \mathbf{y}(t) = (\mathbf{I}_{NL} - (\mathcal{A}_L + \mathcal{A}_C))^{-1} \mathbf{x}^{(m)},$$

Fine with (GF) and (GF-t).

## **Expressibility of (GF): Multiplex Graph Dynamics**

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#### **Opinion Dynamics:**

**E**volution with mutual trust C and logical matrix  $A_{\ell}$ :

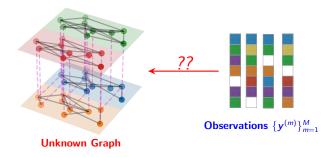
$$\mathbf{y}_{\ell}(t+1) = \underbrace{\mathbf{A}_{\ell} \sum_{\ell'=1}^{L} C_{\ell,\ell'} \mathbf{y}_{\ell'}(t)}_{ ext{coupled inter- and intra-layer}} + \mathbf{x}_{\ell}^{(m)},$$

Steady-state opinions:

$$oldsymbol{y}^{(m)} = \lim_{t o \infty} oldsymbol{y}(t) = (oldsymbol{I}_{NL} - oldsymbol{\mathcal{A}}_L oldsymbol{\mathcal{A}}_C)^{-1} oldsymbol{x}^{(m)}.$$

► Fine with by (GF) but not (GF-t).

## **Multiplex Graph Learning**



**Task**: Given graph signals  $\{y^{(m)}\}_{m=1}^M$ , estimate multiplex graph  $\mathcal{A}_L$ ,  $\mathcal{A}_C$ .

General idea: Following [Dong et al., 2016], exploit smoothness of multi-attribute graph signals → how to leverage (GF)?

## TV Objective and Matched Graph Filter

(Let's take a slight detour ...)

- ▶ Let  $S \in \mathbb{R}^{N \times N}$  be the pairwise distance matrix of graph signals and we aim at learning the (simple) graph adjacency A.
- ► Consider the **Dirichlet energy criterion** in [Berger et al., 2020]<sup>2</sup>:

$$TV(\hat{\boldsymbol{A}}) := \sum_{i,j=1}^{N} \hat{A}_{ij} \frac{1}{M} \|\boldsymbol{y}_i - \boldsymbol{y}_j\|^2 = \sum_{i,j=1}^{N} \hat{A}_{ij} S_{ij} = \langle \hat{\boldsymbol{A}} | \boldsymbol{S} \rangle.$$
 (2)

With  $\mathbf{y}^{(m)} \approx \mathcal{H}(\mathbf{A})\mathbf{x}^{(m)}$  and under mild condition

$$\min_{\hat{\boldsymbol{A}}} \operatorname{TV}(\hat{\boldsymbol{A}}) \overset{approx.}{\iff} \max_{\hat{\boldsymbol{A}}} \langle \hat{\boldsymbol{A}} \mid \mathcal{H}^2(\boldsymbol{A}) \rangle.$$

- ▶ If  $\mathcal{H}^2(\mathbf{A})$  is a low-pass graph filter [Ramakrishna et al., 2020], then its first order approximation<sup>3</sup> is given by  $\mathcal{H}^2(\mathbf{A}) \approx \mathbf{A}$ .
- Criterion (2) can be interpreted as a matched filter criterion.

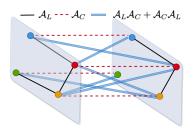
 $<sup>^2</sup>$ Graph learning methods based on quadratic TV such as [Dong et al., 2016] can be interpreted similarly.

 $<sup>^3</sup>$ In general  $\mathcal{H}(\textbf{A})$  is not known a-priori, 1st order approx is the best we can do.

## **Tractable Approximation to (GF)**

- ► (GF) is **intractable** in general : exponential no. of parameters.
- ▶ Inspired by the examples, consider the **approximation**<sup>4</sup>:

$$\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C) \approx \overline{\mathcal{H}}_1(\mathcal{A}_L) + \overline{\mathcal{H}}_2(\mathcal{A}_C) + \overline{\mathcal{H}}_3(\mathcal{A}_L \mathcal{A}_C + \mathcal{A}_C \mathcal{A}_L)$$
 (a-GF)



- $ightharpoonup \overline{\mathcal{H}}_1, \overline{\mathcal{H}}_2, \overline{\mathcal{H}}_3$  are polynomials.
- ightharpoons  $\overline{\mathcal{H}}_1(\mathcal{A}_L)$ ,  $\overline{\mathcal{H}}_2(\mathcal{A}_C)$  model intra- and inter-layer graph dynamics,
- $ightharpoonup \overline{\mathcal{H}}_3$  captures two-hops neighbors and cross-layer interactions.

<sup>&</sup>lt;sup>4</sup>Also assume that  $\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C)\mathcal{H}(\mathcal{A}_L, \mathcal{A}_C)^{\top}$  obeys a similar form.

## Matched Graph Filter for Multiplex Graph Learning

- ▶  $\mathbf{S} \in \mathbb{R}^{NL \times NL}$  = pairwise distance matrix of multi-attribute signals.
- Consider a generalized Dirichlet energy criterion

$$\text{TV}(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}) := \sum_{i,j=1}^{NL} \left[ \hat{h}\left(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}\right) \right]_{ij} S_{ij} = \langle \hat{h}\left(\boldsymbol{\mathcal{A}}_{L},\boldsymbol{\mathcal{A}}_{C}\right) | \boldsymbol{S} \rangle. \quad (3)$$

▶ With (a-GF), we have

$$m{S} pprox \overline{\mathcal{H}}_1(m{\mathcal{A}}_L) + \overline{\mathcal{H}}_2(m{\mathcal{A}}_C) + \overline{\mathcal{H}}_3(m{\mathcal{A}}_Lm{\mathcal{A}}_C + m{\mathcal{A}}_Cm{\mathcal{A}}_L).$$

- ▶ Assumption H1:  $\overline{\mathcal{H}}_1(\cdot), \overline{\mathcal{H}}_2(\cdot), \overline{\mathcal{H}}_3(\cdot)$  are low-pass graph filters.
- ► Under H1, the matched multiplex graph filter design:

$$\hat{h}(\mathcal{A}_L, \mathcal{A}_C) = \mathcal{A}_L + \mathcal{A}_C + \lambda (\mathcal{A}_C \mathcal{A}_L + \mathcal{A}_L \mathcal{A}_C).$$

→ A high-order smoothness metric!

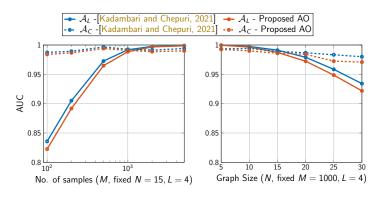
## Multiplex Graph Learning - Algorithm

Under H1, we formulate the **bi-convex** problem:

$$\min_{\hat{\mathcal{A}}_{L}, \hat{\mathcal{A}}_{C} \in \mathcal{A}} \left\langle \widehat{\mathcal{A}}_{L} + \widehat{\mathcal{A}}_{C} + \lambda \left( \widehat{\mathcal{A}}_{L} \widehat{\mathcal{A}}_{C} + \widehat{\mathcal{A}}_{C} \widehat{\mathcal{A}}_{L} \right) \mid \mathbf{S} \right\rangle + \alpha \left( \|\widehat{\mathcal{A}}_{L}\|_{F}^{2} + \|\widehat{\mathcal{A}}_{C}\|_{F}^{2} \right)$$
(4)

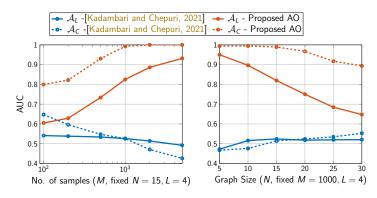
- ► **Algorithm**: alternating optimization (AO) can be applied:
  - $lackbox{ Fix }\widehat{oldsymbol{\mathcal{A}}}_{\mathcal{C}}$  and solve for  $\widehat{oldsymbol{\mathcal{A}}}_{\mathcal{L}} o$  fix  $\widehat{oldsymbol{\mathcal{A}}}_{\mathcal{L}}$  and solve for  $\widehat{oldsymbol{\mathcal{A}}}_{\mathcal{C}} o\cdots$
- ► The AO subproblems are separable and tractable each involves convex problems size of  $N \times N$  or  $L \times L$ .
- AO finds a stationary point of (4) as iteration number goes to  $\infty$  [Grippo and Sciandrone, 2000].
- ▶ **Remark**: when  $\lambda = 0$ , the problem reduces into that of [Kadambari and Chepuri, 2021].

## **Topology Reconstruction under strong coupling**



- ▶ Weak coupling:  $\mathcal{H}_{wk}(\mathcal{A}_L, \mathcal{A}_C) = (I \tau_{wk}(\mathcal{A}_L + \mathcal{A}_C))^{-1}$ .
- Observation: AUC performance generally improves as M increases/deteriorates as N increases.
- Proposed AO ( $\lambda = 0.1$ ) attains **similar** performance to the benchmark.

## **Topology Reconstruction under strong coupling**



- ► Strong coupling:  $\mathcal{H}_{\mathsf{str}}(\mathcal{A}_L, \mathcal{A}_C) = (I \tau_{\mathsf{str}} \mathcal{A}_L \mathcal{A}_C)^{-1}$ .
- Benchmark fails in estimating graph topologies under strong coupling.
- Proposed AO ( $\lambda = 5$ ) recovers topology effectively regardless of layer coupling **robustly**.

## **Summary**

**Takeaway**: Distinct **inter-layer and intra-layer interactions** dynamics require careful modeling for multiplex graph learning.

We have introduced a method for learning multiplex network structures from multi-attribute graph signals:

- ► General multiplex graph filter to model complex signal interactions.
- Matched filter perspective to graph learning by smoothness → a high-order smoothness metric aimed at inter-layer coupling.
- ► An efficient AO procedure for learning graph topologies.
- ► Future work: modeling of multiplex graph signals, adopting other GSP tools, ...

# Thank you!

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