

1. (a) For problem (1), the boundary is

$$t^{(i)}(w^T x^{(i)} + b) \geq 1 - \xi_i, \quad \xi_i \geq 0, \text{ it is equivalent}$$

$$\text{to } \xi_i \geq \max(0, 1 - t^{(i)}(w^T x^{(i)} + b)),$$

Thus the problem (1) can be written as

$$\min_{w, b, \xi} \quad \frac{1}{2} \|w\|^2 + c \sum_{i=1}^N \xi_i,$$

$$\text{subject to } \xi_i \geq \max(0, 1 - t^{(i)}(w^T x^{(i)} + b)).$$

Now let's consider the problem from the perspective of final optimal value of  $w, b, \xi$ , set their optimal value of this problem is  $w^*, b^*, \xi^*$ . Since  $c > 0$ , we must have

$\xi_i^* = \max(0, 1 - t^{(i)}(w^{*T} x^{(i)} + b^*))$ , otherwise we can use  $\max(0, 1 - t^{(i)}(w^T x^{(i)} + b))$  to replace  $\xi_i^*$  and make the target function smaller. Therefore, whatever  $w^*, b^*$  is, the optimal  $\xi_i^*$  can be always represented by  $\max(0, 1 - t^{(i)}(w^T x^{(i)} + b))$ .

Thus the problem is equivalent to:

$$\min_{w, b} \quad \frac{1}{2} \|w\|^2 + c \sum_{i=1}^N \max(0, 1 - t^{(i)}(w^T x^{(i)} + b))$$

(b) The margin hyperplane  $t^{(i)}(w^* x + b^*) = 1$  can be written

$$\text{as } t^{(i)}(w^*)^T x + (t^{(i)} b^* - 1) = 0, \text{ then the distance is}$$

$$|r| = \frac{|t^{(i)}(w^*)^T x^{(i)} + t^{(i)} b^* - 1|}{\|t^{(i)} w^*\|}$$

$$= |\xi_i^*| \cdot \frac{1}{\|t^{(i)} w^*\|}$$

Obviously,  $|r|$  is proportional to  $\xi_i^*$  ( $\xi_i^* \geq 0$ )

(c) If for all  $i$ ,  $1 - t^{(i)}(w^T x^{(i)} + b) \neq 0$ , then

$$\nabla_w E(w, b) = w + c \sum_{i=1}^N -t^{(i)} x^{(i)} \cdot \mathbb{1}_{\{1 - t^{(i)}(w^T x^{(i)} + b) > 0\}}$$

$$\nabla_b E(w, b) = c \sum_{i=1}^N -t^{(i)} \cdot \mathbb{1}_{\{1 - t^{(i)}(w^T x^{(i)} + b) > 0\}}$$

If for some  $i$ ,  $1 - t^{(i)}(w^T x^{(i)} + b) = 0$ , & for other  $j$ ,  $1 - t^{(j)}(w^T x^{(j)} + b) \neq 0$ , then

the derivative is undefined at  $i$ , the subderivative is:

$$\nabla_w^- E(w, b) = w + c \sum_i -t^{(i)} x^{(i)} + c \sum_j -t^{(j)} x^{(j)} \mathbb{1}_{\{1-t^{(j)}(w^T x^{(j)} + b) > 0\}}$$

$$\nabla_w^+ E(w, b) = w + c \sum_j -t^{(j)} x^{(j)} \mathbb{1}_{\{1-t^{(j)}(w^T x^{(j)} + b) > 0\}}$$

$$\nabla_b^- E(w, b) = c \sum_i -t^{(i)} + c \sum_j -t^{(j)} \mathbb{1}_{\{1-t^{(j)}(w^T x^{(j)} + b) > 0\}}$$

$$\nabla_b^+ E(w, b) = c \sum_j -t^{(j)} \mathbb{1}_{\{1-t^{(j)}(w^T x^{(j)} + b) > 0\}}$$

(e) If for  $i$ ,  $1 - t^{(i)}(w^T x^{(i)} + b) \neq 0$ , then

$$\nabla_w E^{(i)}(w, b) = \frac{w}{N} + c(-t^{(i)} x^{(i)}) \cdot \mathbb{1}_{\{1-t^{(i)}(w^T x^{(i)} + b) > 0\}}$$

$$\nabla_b E^{(i)}(w, b) = -c t^{(i)} \mathbb{1}_{\{1-t^{(i)}(w^T x^{(i)} + b) > 0\}}$$

If for  $i$ ,  $1 - t^{(i)}(w^T x^{(i)} + b) = 0$ , then

$$\nabla_w^- E^{(i)}(w, b) = \frac{w}{N} + c(-t^{(i)} x^{(i)})$$

$$\nabla_w^+ E^{(i)}(w, b) = \frac{w}{N}$$

$$\nabla_b^- E^{(i)}(w, b) = -c t^{(i)}$$

$$\nabla_b^+ E^{(i)}(w, b) = 0$$

$$(h) L(w, b, \lambda, v) = \frac{1}{2} \|w\|^2 + c \sum_{i=1}^N \xi_i + \sum_{i=1}^N \lambda_i (1 - \xi_i - t^{(i)}(w^T x^{(i)} + b)) - \sum_{i=1}^N v_i \xi_i$$

Then the dual problem is  $\max_{v, \lambda, \lambda_i, v_i \geq 0} \min_{w, b} L(w, b, \lambda, v)$

$$\frac{\partial L}{\partial w} = w - \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} = 0 \Rightarrow w = \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)}$$

$$\frac{\partial L}{\partial b} = -\sum_{i=1}^N \lambda_i t^{(i)} = 0, \quad \frac{\partial L}{\partial \xi_i} = c - \lambda_i - v_i = 0$$

$$\begin{aligned} \tilde{L}(\lambda, v) &= \frac{1}{2} \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right]^T \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right] + \sum_{i=1}^N (\lambda_i + v_i) \xi_i - \sum_{i=1}^N v_i \xi_i + \\ &\quad \sum_{i=1}^N \lambda_i (1 - \xi_i - t^{(i)} ((\sum_{j=1}^N \lambda_j t^{(j)} x^{(j)})^T x^{(i)} + b)) \\ &= \frac{1}{2} \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right]^T \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right] + \sum_{i=1}^N \lambda_i - \left( \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right)^T \left( \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right) \\ &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right]^T \left[ \sum_{i=1}^N \lambda_i t^{(i)} x^{(i)} \right] \\ \text{Set } k(x, z) &= x^T z \leftarrow = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j t^{(i)} t^{(j)} x^{(i)T} x^{(j)} = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j t^{(i)} t^{(j)} k(x^{(i)}, x^{(j)}) \end{aligned}$$

$\therefore$  The dual problem is:  $\min_{\lambda} \tilde{L}(\lambda) = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \lambda_i \lambda_j t^{(i)} t^{(j)} k(x^{(i)}, x^{(j)})$   
subject to:  $0 \leq \lambda_i \leq c,$   
 $\sum_{i=1}^N \lambda_i t^{(i)} = 0$

$$3. \quad (a) \quad k(u, v) = (\langle u, v \rangle + 1)^4 \\ = \langle u, v \rangle^4 + 4\langle u, v \rangle^3 + 6\langle u, v \rangle^2 + 4\langle u, v \rangle + 1$$

$$\text{For } d=3, \quad u = (u_1, u_2, u_3), \quad v = (v_1, v_2, v_3)$$

$$\text{For general mode, } \langle u, v \rangle^p = (u_1 v_1 + u_2 v_2 + u_3 v_3)^p = \sum_{j_1, j_2, j_3, \dots, j_p} \binom{p}{j_1, j_2, j_3, \dots, j_p} (u_1)^{j_1} (u_2)^{j_2} (u_3)^{j_3} \dots$$

$$\therefore \bar{\Phi}_p(x) = [\dots, \binom{p}{j_1, j_2, j_3}^{\frac{1}{2}} (u_1)^{j_1} (u_2)^{j_2} (u_3)^{j_3}, \dots] \quad (*)$$

$$p=4, \quad \bar{\Phi}_4(u) = [u_1^4, u_2^4, u_3^4, 2u_1^3 u_2, 2u_1^3 u_3, 2u_1 u_2^3, 2u_2^3 u_3, 2u_1 u_3^3, \\ 2u_2 u_3^3, \sqrt{6} u_1^2 u_2^2, \sqrt{6} u_1^2 u_3^2, \sqrt{6} u_2^2 u_3^2, 2\sqrt{3} u_1^2 u_2 u_3, 2\sqrt{3} u_1 u_2^2 u_3, 2\sqrt{3} u_1 u_3^2 u_2]$$

$$p=3, \quad \bar{\Phi}_3(u) = [u_1^3, u_2^3, u_3^3, \sqrt{3} u_1^2 u_2, \sqrt{3} u_1 u_2^2, \sqrt{3} u_1^2 u_3, \sqrt{3} u_1 u_3^2, \sqrt{3} u_2^2 u_3, \sqrt{3} u_2 u_3^2, \sqrt{6} u_1 u_2 u_3]$$

$$p=2, \quad \bar{\Phi}_2(u) = [u_1^2, u_2^2, u_3^2, \sqrt{2} u_1 u_2, \sqrt{2} u_1 u_3, \sqrt{2} u_2 u_3]$$

$$p=1, \quad \bar{\Phi}_1(u) = [u_1, u_2, u_3]$$

$$\text{Then for } u, \quad \phi(u) = (\bar{\Phi}_4(u), 2\bar{\Phi}_3(u), \sqrt{6}\bar{\Phi}_2(u), 2\bar{\Phi}_1(u), 1)$$

$$\text{Thus } k(u, v) = \phi(u)^T \phi(v)$$

For arbitrary dimension  $d$ , based on the conclusion (\*) above,

$$p=4, \quad \bar{\Phi}_4(u) = [u_1^4, \dots, u_d^4, 2u_1^3 u_2, \dots, \sqrt{6} u_1^2 u_2^2, \dots, 2\sqrt{3} u_1^2 u_2 u_3, \dots]$$

$$p=3, \quad \bar{\Phi}_3(u) = [u_1^3, \dots, u_d^3, \sqrt{3} u_1^2 u_2, \dots, \sqrt{6} u_1 u_2 u_3, \dots]$$

$$p=2, \quad \bar{\Phi}_2(u) = [u_1^2, \dots, u_d^2, \sqrt{2} u_1 u_2, \dots]$$

$$p=1, \quad \bar{\Phi}_1(u) = [u_1, \dots, u_d]$$

$$\text{Then for } u, \quad \phi(u) = (\bar{\Phi}_4(u), 2\bar{\Phi}_3(u), \sqrt{6}\bar{\Phi}_2(u), 2\bar{\Phi}_1(u), 1)$$

$$\text{satisfying } k(u, v) = \phi(u)^T \phi(v)$$

(b) From the definition of Gram matrix  $k$ , for a positive-definite kernel,  $k$  must be PSD,  $k_i = \phi^{(i)}(x) \phi^{(i)}(z)$  is a Gram matrix, for  $\forall a \in \mathbb{R}^n$ ,  $a^T k_i a \geq 0$

(i) It is kernel. Since  $k_i$  is kernel, for  $\forall a \in \mathbb{R}^n$ ,  $a^T k_i a \geq 0$ ,  $a^T k_1 a \geq 0$ ,  $a^T k_2 a \geq 0 \Rightarrow a^T k a = a^T (k_1 + k_2) a = a^T k_1 a + a^T k_2 a \geq 0$   
Thus  $k$  is kernel.

(ii) Not kernel. Set  $k_2 = 2k_1$ , then for  $\forall a \in \mathbb{R}^n$ ,  $a^T k_1 a \geq 0$  while  $a^T k a = a^T (k_1 - 2k_1) a = -a^T k_1 a \leq 0$

(iii) It is kernel. For  $\forall m \in \mathbb{R}^n$ ,  $m^T k_1 m \geq 0$ , then for  $a > 0$   
 $m^T k m = m^T (a k_1) m = a (m^T k_1 m) \geq 0$

(iv) It is kernel.  $k(x, z) = k_1(x, z) k_2(x, z)$   

$$= \sum_i \phi_i^{(1)}(x) \phi_i^{(1)}(z) \cdot \sum_j \phi_j^{(2)}(x) \phi_j^{(2)}(z)$$

$$= \sum_i \sum_j \phi_i^{(1)}(x) \phi_i^{(1)}(z) \phi_j^{(2)}(x) \phi_j^{(2)}(z)$$

$$= \sum_i \sum_j [\phi_i^{(1)}(x) \phi_j^{(2)}(x)] \cdot [\phi_i^{(1)}(z) \phi_j^{(2)}(z)] = \sum_{i,j} \bar{\phi}_{i,j}(x) \bar{\phi}_{i,j}(z)$$

Thus  $k$  can be written as  $k(x, z) = \bar{\phi}(x)^T \bar{\phi}(z) \Rightarrow k$  is kernel.

(v) It is kernel. Let  $\varphi(x) = f(x)$ ,  $f: \mathbb{R}^D \rightarrow \mathbb{R}$

$$\therefore \varphi^T(x) = f^T(x) = f(x) = \varphi(x)$$

$$\therefore k(x, z) = \varphi(x) \cdot \varphi(z) = \varphi(x)^T \varphi(z) \Rightarrow k \text{ is kernel.}$$

(vi) It is kernel:  $k(x, z) = a_1 k_1(x, z) + \dots + a_p k_p(x, z)$

From (iv),  $k_1^p(x, z)$  is kernel, From (iii),  $a_p k_1^p(x, z)$  is kernel.

Then From (i),  $k(x, z) = \sum_i a_i k_i(x, z)$  is kernel.

(vii)  $k(x, z) = \exp(-\frac{\|x-z\|^2}{2\sigma^2}) = \exp(-\frac{x^T x}{2\sigma^2}) \exp(\frac{x^T z}{\sigma^2}) \exp(-\frac{z^T z}{2\sigma^2})$

It can be written as  $k(x, z) = f^T(x) \exp(\frac{x^T z}{\sigma^2}) f(z)$

By Taylor expansion,  $\exp(\frac{x^T z}{\sigma^2}) = \sum_{n=0}^{\infty} \frac{(\frac{x^T z}{\sigma^2})^n}{n!}$ ,

Noticing  $x^T z$  is a kernel, From (vi),  $\sum_{n=0}^{\infty} \frac{(x^T z)^n}{\sigma^{2n} n!}$  is a kernel.

Thus we can write  $\exp(\frac{x^T z}{\sigma^2})$  as  $\phi(x)^T \phi(z)$ , Then

$$k(x, z) = f(x) \langle \phi(x), \phi(z) \rangle f(z) = \langle f(x) \phi(x), f(z) \phi(z) \rangle$$

4(a)

$$\begin{aligned}
P^{-1} &= P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}SP^{-1} \\
&= P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}(R^{-1} + SP^{-1}Q)Q^{-1} - P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}SP^{-1} \\
&= P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}(R^{-1} + SP^{-1}Q - SP^{-1}Q)Q^{-1} \\
&= P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}R^{-1}Q^{-1}
\end{aligned}$$

From the description of the question, we have

$$(P + QRS)^{-1} = P^{-1}Q(R^{-1} + SP^{-1}Q)^{-1}R^{-1}Q^{-1}$$

with  $w = (\bar{\Phi}^T \bar{\Phi} + \lambda I)^{-1} \bar{\Phi}^T t$

Let  $P = \lambda I$ ,  $Q = \bar{\Phi}^T$ ,  $R = I$ ,  $S = \bar{\Phi}$ , we have

$$(\lambda I + \bar{\Phi}^T \bar{\Phi})^{-1} = (\lambda I)^{-1} \bar{\Phi}^T (I^{-1} + \bar{\Phi} (\lambda I)^{-1} \bar{\Phi}^T)^{-1} (I)^{-1} (\bar{\Phi}^T)^{-1}$$

$$(\lambda I + \bar{\Phi}^T \bar{\Phi})^{-1} = \frac{1}{\lambda} \bar{\Phi}^T (I + \frac{1}{\lambda} \bar{\Phi} \bar{\Phi}^T)^{-1} (\bar{\Phi}^T)^{-1}$$

$$(\lambda I + \bar{\Phi}^T \bar{\Phi})^{-1} \bar{\Phi}^T = \bar{\Phi}^T (\lambda I + \bar{\Phi} \bar{\Phi}^T)^{-1}$$

$$\Rightarrow w = (\bar{\Phi}^T \bar{\Phi} + \lambda I)^{-1} \bar{\Phi}^T t = \bar{\Phi}^T (\lambda I + \bar{\Phi} \bar{\Phi}^T)^{-1} t = \bar{\Phi}^T a,$$

where  $a = (\lambda I + \bar{\Phi} \bar{\Phi}^T)^{-1} t$

$$f(x) = w^T \phi(x) = (\bar{\Phi}^T a)^T \phi(x) = a^T \bar{\Phi} \phi(x) = a^T k(x)$$

where  $k(x) = \bar{\Phi} \phi(x) = [k(x_1, x), \dots, k(x_n, x)]^T$

$$E(w) = (\bar{\Phi} w - t)^T (\bar{\Phi} w - t) + \lambda w^T w$$

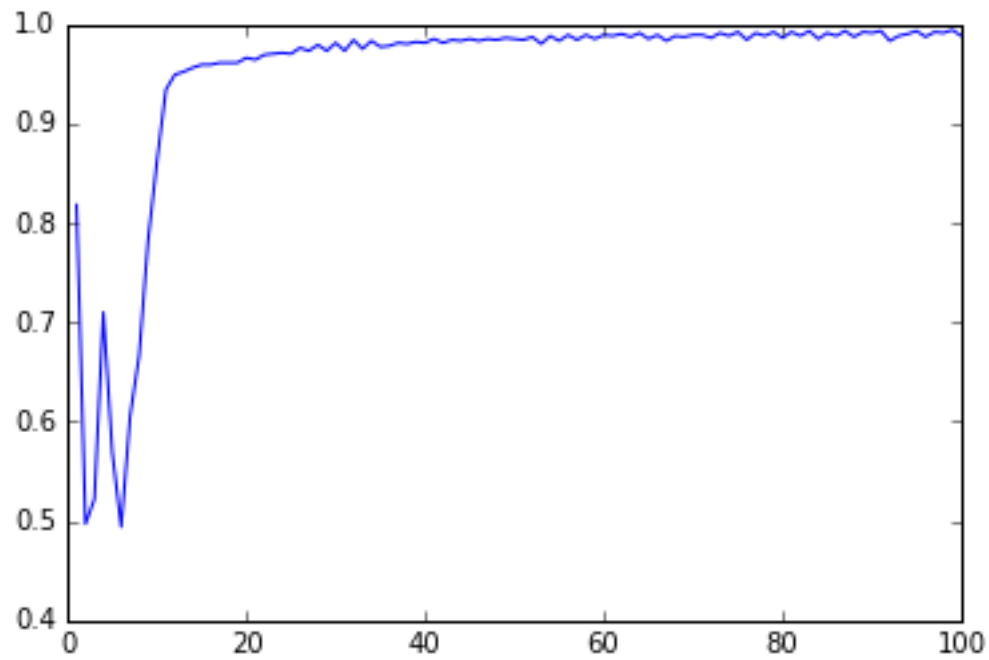
$$= w^T \bar{\Phi}^T \bar{\Phi} w - 2t^T \bar{\Phi} w + t^T t + \lambda a^T \bar{\Phi} \bar{\Phi}^T a$$

$$= a^T K K a - 2t^T K a + t^T t + \lambda a^T K a$$

## Homework 3

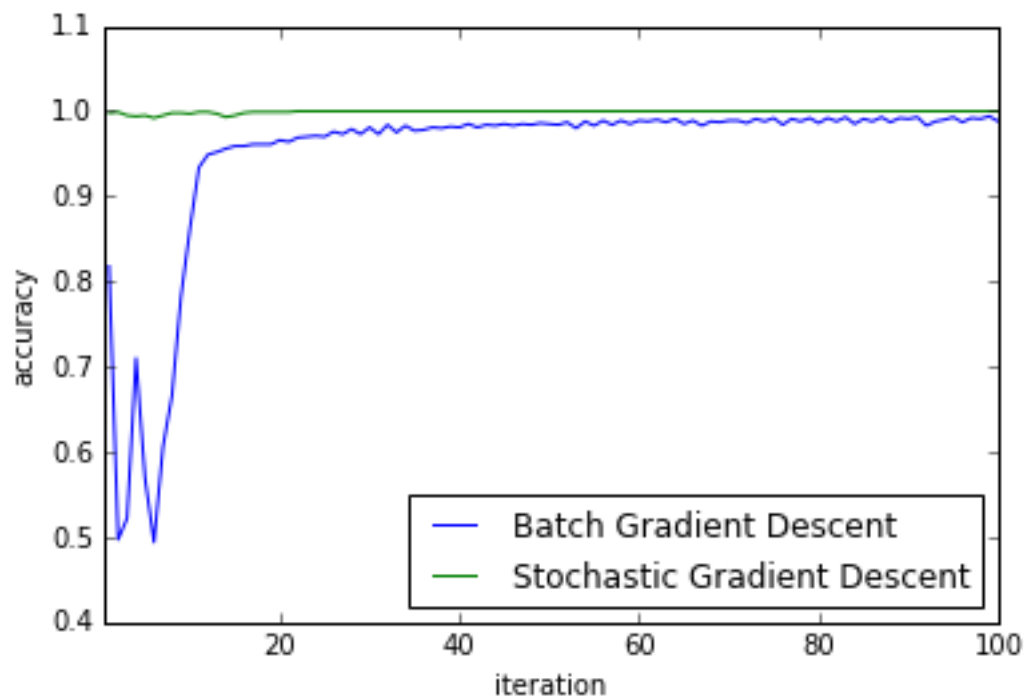
1(d)

The accuracy plot is the following:



1(f)

The accuracy plot is the following:

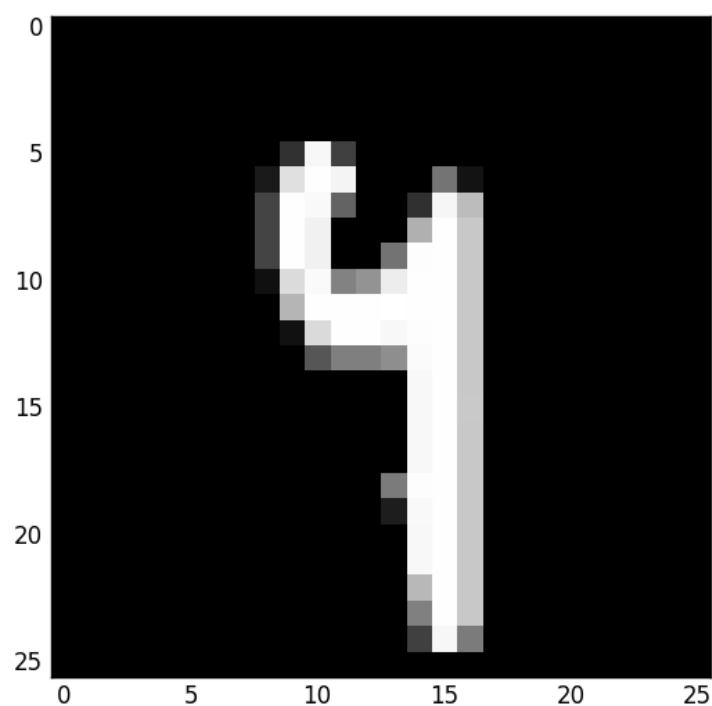


### 1(g)

The stochastic gradient descent converges faster than batch gradient decent. From the plot in 1(f), we can see the accuracy of stochastic gradient descent converges to 1 after approximate 30 iterations, while the batch gradient decent still has a little fluctuation. It is mainly because in the stochastic gradient descent, in each iteration,  $w$  &  $b$  are updated  $N$  times in 1 iteration. In batch gradient decent,  $w$  &  $b$  remain the same in 1 iteration.

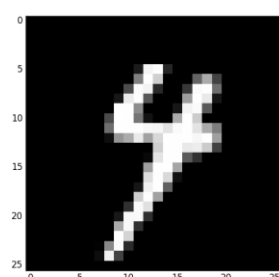
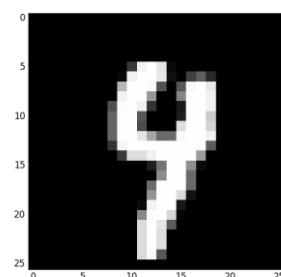
### 1(i)

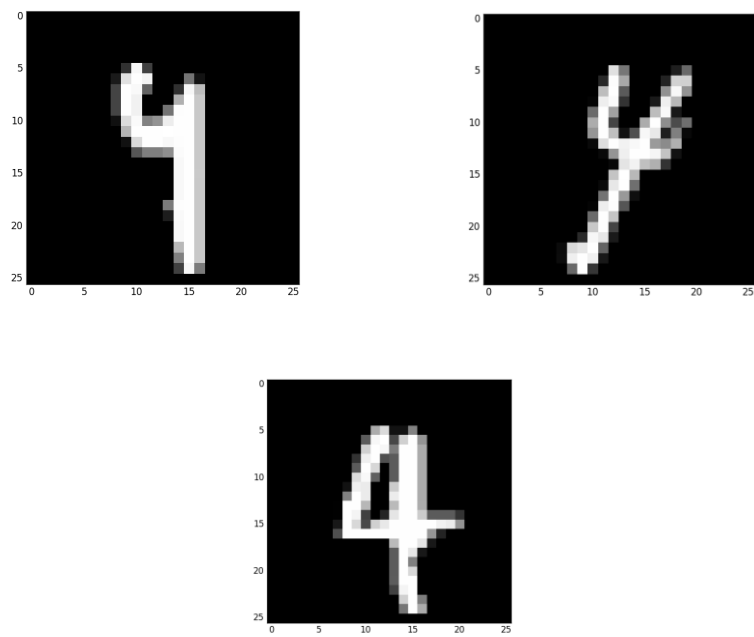
I choose  $\text{Gamma}=10^{-7}$ ,  $C=10$  in this problem. The accuracy of training data and test data is 99.9% and 99.8%. Therefore, there is only 1 misclassified test image. It is the 164<sup>th</sup> of the test labels, it is "9" initially, but the SVM labels it "4". The picture is shown as follows:



### 1(j)

Based on the separate final accuracy, there is no significant difference between LDA and SVM. The The accuracy of training data and test data is 99.7% and 90.4%. 5 of the misclassified test images are :





The first and the third are misclassified as “4” and the others are misclassified “9”.

#### 4b

The RMSE of the models are as follows:

	1	2	3	4
RMSE	7.412	4.831	2.962	13.199



Codes:

(1d)

```
import numpy as np
trainx = np.loadtxt("digits_training_data.csv",delimiter=",")
trainy=np.loadtxt("digits_training_labels.csv",delimiter=",")
w=np.zeros(676);b=0;
iterN=np.linspace(1,100,100);
for i in range(1000):
    if trainy[i]==4:
        trainy[i]=1;
    else:
        trainy[i]=-1;
from __future__ import division
def Ewb_grad(w,b):
    Ew=np.zeros(676)
    Eb=np.zeros((1000,1))
    for i in range(1000):
        if trainy[i]*(trainx[i,:].dot(w)+b)<1:
            Ew = Ew - trainy[i]*(trainx[i,:].T)
            Eb[i] = -3*trainy[i]
        else:
            Ew=Ew
            Eb[i]=0
    Ew_grad=Ew+w
    Eb_grad=np.sum(Eb)
    return Ew_grad, Eb_grad;
w0=w;b0=b;goal1=np.zeros(100)
for j in range(100):
    yita=0.001
    wgrad,bgrad=Ewb_grad(w0,b0)
    alpha=yita/(1+(j+1)*yita)
    w0=w0-alpha*wgrad
    b0=b0-alpha*bgrad
    yfit=trainy*(trainx.dot(w0)+b0)
    cali=np.zeros(1000)
    goal1[j]=np.sum(yfit>cali)/1000
from matplotlib import pyplot as plt
plt.plot(iterN,goal1)
```

(1f)

```
import numpy as np
trainx = np.loadtxt("digits_training_data.csv",delimiter=",")
trainy=np.loadtxt("digits_training_labels.csv",delimiter=",")
w=np.zeros(676);b=0;
```

```

iterN=np.linspace(1,100,100);
for i in range(1000):
    if trainy[i]==4:
        trainy[i]=1;
    else:
        trainy[i]=-1;
from __future__ import division
def wb_grad(w,b,j):
    Ew=np.zeros(676);
    w1=w;b1=b; yita=0.001;
    alpha=yita/(1+(j+1)*yita);
    r=np.random.permutation(1000)
    for i in r:
        if trainy[i]*(trainx[i,:].dot(w)+b)<1:
            Ew = 0.001*w1 - 3*trainy[i]*(trainx[i,:].T)
            Eb = -3*trainy[i]
            w1=w1-alpha*Ew
            b1=b1-alpha*Eb
        else:
            Ew=0.001*w1
            Eb=0
            w1=w1-alpha*Ew
            b1=b1-alpha*Eb
    return w1, b1;
w0=w;b0=b;goal=np.zeros(100)
for j in range(100):
    w0,b0=wb_grad(w0,b0,j)
    yfit=trainy*(trainx.dot(w0)+b0)
    cali=np.zeros(1000)
    goal[j]=np.sum(yfit>cali)/1000
from matplotlib import pyplot as plt
plt.plot(iterN,goal)
SVM1, =plt.plot(iterN,goal1,label='Batch Gradient Descent')
SVM2, =plt.plot(iterN,goal,label='Stochastic Gradient Descent')
plt.legend(handles=[SVM1,SVM2],loc='lower right')
plt.xlabel('iteration')
plt.ylabel('accuracy')
plt.axis([0.5,100,0.5,1.1])

```

(1i)

```

import numpy as np
from sklearn import svm
trainx = np.loadtxt("digits_training_data.csv",delimiter=",")
trainy=np.loadtxt("digits_training_labels.csv",delimiter=",")

```

```

testx= np.loadtxt("digits_test_data.csv",delimiter=",")
testy=np.loadtxt("digits_test_labels.csv",delimiter=",")
for i in range(500):
    if testy[i]==4:
        testy[i]=1;
    else:
        testy[i]=-1;
for i in range(1000):
    if trainy[i]==4:
        trainy[i]=1;
    else:
        trainy[i]=-1;
from __future__ import division
clf = svm.SVC(kernel='rbf',gamma=10**(-7), C=10)
clf.fit(trainx, trainy)
z=clf.predict(trainx)
goal=np.sum(z==trainy)/1000
clf = svm.SVC(kernel='rbf',gamma=10**(-7), C=10)
clf.fit(testx, testy)
z=clf.predict(testx)
goal1=np.sum(z==testy)/500
for i in range(500):
    if z[i]*testy[i]<0:
        k=i
import matplotlib.cm as cm
from matplotlib import pyplot as plt
plt.imshow(testx[k,:].reshape((26,26)), interpolation="nearest", cmap=cm.Greys_r)

```

(1j)

```

import numpy as np
trainx = np.loadtxt("digits_training_data.csv",delimiter=",")
trainy=np.loadtxt("digits_training_labels.csv",delimiter=",")
testx = np.loadtxt("digits_test_data.csv",delimiter=",")
testy=np.loadtxt("digits_test_labels.csv",delimiter=",")
for i in range(500):
    if testy[i]==4:
        testy[i]=1;
    else:
        testy[i]=-1;
for i in range(1000):
    if trainy[i]==4:
        trainy[i]=1;
    else:
        trainy[i]=-1;

```

```

from __future__ import division
trainx1=trainx[(trainy==1),]
trainx2=trainx[(trainy==1),]
mean1=np.reshape(np.mean(trainx1,0),(1,len(trainx1[0])))
mean2=np.reshape(np.mean(trainx2,0),(1,len(trainx2[0])))
trainx1norm=trainx1-mean1;
trainx2norm=trainx2-mean2;
trainxnorm=np.concatenate((trainx1norm,trainx2norm))
sigma=(trainxnorm.T.dot(trainxnorm))/1000
gamma1 = -
0.5*mean1.dot(np.linalg.pinv(sigma)).dot(mean1.T)+np.log(1.0*len(trainx1)/len(trainx))
beta1 = np.linalg.pinv(sigma).dot(mean1.T)
gamma2 = -
0.5*mean2.dot(np.linalg.pinv(sigma)).dot(mean2.T)+np.log(1.0*len(trainx2)/len(trainx))
beta2 = np.linalg.pinv(sigma).dot(mean2.T)
trainp1 =
np.exp((trainx.dot(beta1)+gamma1))/(np.exp((trainx.dot(beta1)+gamma1))+np.exp((trainx.dot(beta2)+gamma2)))
trainp2 =
np.exp((trainx.dot(beta2)+gamma2))/(np.exp((trainx.dot(beta1)+gamma1))+np.exp((trainx.dot(beta2)+gamma2)))
trainyfit=np.zeros((1000))
for i in range(1000):
    if trainp1[i]>=trainp2[i]:
        trainyfit[i]=-1
    else:
        trainyfit[i]=1
goal=np.sum(trainyfit==trainy)/1000

testp1 =
np.exp((testx.dot(beta1)+gamma1))/(np.exp((testx.dot(beta1)+gamma1))+np.exp((testx.dot(beta2)+gamma2)))
testp2 =
np.exp((testx.dot(beta2)+gamma2))/(np.exp((testx.dot(beta1)+gamma1))+np.exp((testx.dot(beta2)+gamma2)))
testyfit=np.zeros((500))
for i in range(500):
    if testp1[i]>=testp2[i]:
        testyfit[i]=-1
    else:
        testyfit[i]=1
goal1=np.sum(testyfit==testy)/500
m=np.zeros((500))
for i in range(500):

```

```

        if testyfit[i]*testy[i]<0:
            m[i]=i
k=m[m>0]
import matplotlib.cm as cm
from matplotlib import pyplot as plt
for i in range(5):
    plt.figure()
    plt.imshow(testx[k[i],:].reshape((26,26)), interpolation="nearest", cmap=cm.Greys_r)

```

(2)

```

import numpy as np
from sklearn import svm
trainy = np.loadtxt('trainingLabels.gz', dtype=np.uint8, delimiter=',')
trainx = np.loadtxt('trainingData.gz', dtype=np.uint8, delimiter=',')
testx = np.loadtxt('testData.gz', dtype=np.uint8, delimiter=',')
from __future__ import division
clf = svm.SVC(kernel='rbf',gamma=10**(-8), C=10)
clf.fit(trainx, trainy)
z=clf.predict(testx)

```

(4b)

```

import numpy as np
train      =      np.loadtxt("steel_composition_train.csv",      delimiter=",",      skiprows=1,
usecols=(1,2,3,4,5,6,7,8,9))
x1=train[:,0:8]
y1=train[:,8]
x1 = (x1-np.mean(x1,0))/np.std(x1,0)
y1 = np.reshape(y1,((len(y1),1)))

```

```

K1 = (x1.dot(x1.T)+1)**2
a1 = np.linalg.inv(np.identity(len(x1))+K1).dot(y1)
Err1 = a1.T.dot(K1).dot(K1).dot(a1)-2*y1.T.dot(K1).dot(a1)+y1.T.dot(y1)+a1.T.dot(K1).dot(a1)
rmse1 = np.sqrt(Err1/len(x1))

```

```

K2 = (x1.dot(x1.T)+1)**3
a2 = np.linalg.inv(np.identity(len(x1))+K2).dot(y1)
Err2= a2.T.dot(K2).dot(K2).dot(a2)-2*y1.T.dot(K2).dot(a2)+y1.T.dot(y1)+a2.T.dot(K2).dot(a2)
rmse2 = np.sqrt(Err2/len(x1))

```

```

K3 = (x1.dot(x1.T)+1)**4
a3 = np.linalg.inv(np.identity(len(x1))+K3).dot(y1)
Err3= a3.T.dot(K3).dot(K3).dot(a3)-2*y1.T.dot(K3).dot(a3)+y1.T.dot(y1)+a3.T.dot(K3).dot(a3)

```

```
rmse3 = np.sqrt(Err3/len(x1))
```

```
from numpy.linalg import norm
```

```
K4 = []
```

```
for i in range(0,len(x1)):
```

```
    K4.append(np.exp(-0.5*norm(x1[i]-x1,axis=1)**2))
```

```
K4 = np.array(K4)
```

```
a4 = np.linalg.inv(np.identity(len(x1))+K4).dot(y1)
```

```
Err4 = a4.T.dot(K4).dot(K4).dot(a4)-2*y1.T.dot(K4).dot(a4)+y1.T.dot(y1)+a4.T.dot(K4).dot(a4)
```

```
rmse4 = np.sqrt(Err4/len(x1))
```