

# STAT 576 Bayesian Analysis

## Lecture 4: Asymptotic Properties of Bayesian Inference

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# Normal Approximation to the Posterior Distribution

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$$\log p(\boldsymbol{\theta} \mid y) = \log p(\hat{\boldsymbol{\theta}} \mid y) + \frac{1}{2}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}})^T \left[ \frac{d^2}{d\boldsymbol{\theta}^2} \log p(\boldsymbol{\theta} \mid y) \right]_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}} (\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}) + o(\|\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}\|^2)$$

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- ▶ The linear term is omitted because

$$\left[ \frac{d}{d\boldsymbol{\theta}} \log p(\boldsymbol{\theta} \mid y) \right]_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}} = \mathbf{0}$$

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- ▶ we have the normal approximation of the posterior by

$$p(\boldsymbol{\theta} \mid y) \approx \mathcal{N}(\hat{\boldsymbol{\theta}}, \mathbf{J}(\hat{\boldsymbol{\theta}})^{-1})$$

where

$$\mathbf{J}(\boldsymbol{\theta}) = -\frac{d^2}{d\boldsymbol{\theta}^2} \log p(\boldsymbol{\theta} \mid y)$$

is the **observed information matrix**.

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  - ▶  $\mathbf{J}(\hat{\boldsymbol{\theta}})$  is positive-definite / non-singular.
- ▶ Using Bayes' rule, we have

$$\mathbf{J}(\boldsymbol{\theta}) = -\frac{d^2}{d\boldsymbol{\theta}^2} \log p(\boldsymbol{\theta} \mid y) = \underbrace{-\frac{d^2}{d\boldsymbol{\theta}^2} \log p(y \mid \boldsymbol{\theta})}_{\text{info. from observations}} \quad \underbrace{-\frac{d^2}{d\boldsymbol{\theta}^2} \log p(\boldsymbol{\theta})}_{\text{info. from prior}}$$

## Information Matrix

- Suppose we have i.i.d. observations  $y = (y_1, \dots, y_n)$  from a distribution  $F_{\theta}$  from a parametric family  $\{F_{\theta_0} : \theta \in \Theta\}$  with true parameter  $\theta_0$ .

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$$-\frac{1}{n} \sum_{i=1}^n \frac{d^2}{d\boldsymbol{\theta}^2} \log p(y_i \mid \boldsymbol{\theta}) \xrightarrow{F_{\boldsymbol{\theta}_0}} \mathbb{E}_{\boldsymbol{\theta}_0} \left[ -\frac{d^2}{d\boldsymbol{\theta}^2} \log p(y_i \mid \boldsymbol{\theta}) \right]$$

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- ▶ Note: This is **NOT** the Fisher's information matrix because the expectation is taken under the true parameter  $\theta_0$ .

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- ▶ Or the rescaled version:

$$p(\sqrt{n}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}) \mid y) \approx \mathcal{N} \left( \boldsymbol{h} \mid \mathbf{0}, \mathbb{E}_{\boldsymbol{\theta}_0}^{-1} \left[ -\frac{d^2}{d\boldsymbol{\theta}^2} \log p(y_i \mid \boldsymbol{\theta}) \right]_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}} \right)$$

where  $\boldsymbol{h} = \sqrt{n}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}})$  is called the **local parameter** to  $\hat{\boldsymbol{\theta}}$ .



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Therefore, we need first to investigate the asymptotic behavior of  $\hat{\boldsymbol{\theta}}$  itself.

# Asymptotic Equivalence of MAP and MLE

- Maximize-a-posteriori estimator:

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- ▶ A sufficient condition is (1)  $\hat{\boldsymbol{\theta}}_n^{(mle)}$  is consistent for  $\boldsymbol{\theta}_0$ , and (2)  $p(\boldsymbol{\theta})$  is strictly positive in a neighbor of  $\boldsymbol{\theta}_0$ .



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- ▶ The unnormalized version is the distribution that is degenerate at  $\theta_0$ .

$$p(\theta | y) \approx \delta_{\theta_0}$$

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- ▶ The **Bayes estimator** is the estimator  $\hat{\theta}$  that minimizes the Bayes risk:

$$\hat{\theta}_n = \arg \min_{\delta \in \Theta} R(\delta)$$

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  - ▶ under squared loss:  $\hat{\theta}_n$  is the posterior mean.
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**Yes. Doob's Consistency Theorem.**
- ▶ Do we still have the normal approximation for the posterior without utilizing the MAP?

# Bayes Estimator

- ▶ Note that  $R(\delta) = \mathbb{E}[\mathbb{E}_{p(\theta|y)}[L(\theta, \delta) \mid y]]$
- ▶ The Bayes estimator turns out to be the conditional optimizer:

$$\hat{\theta}_n(y) = \arg \min_{\delta \in \Theta} \mathbb{E}_{p(\theta|y)}[L(\theta, \delta) \mid y] = \arg \min_{\delta \in \Theta} \int L(\theta, \delta) p(\theta \mid y) d\mu$$

- ▶ Examples:
  - ▶ under squared loss:  $\hat{\theta}_n$  is the posterior mean.
  - ▶ under absolute loss:  $\hat{\theta}_n$  is the posterior median.
  - ▶ under cross entropy loss:  $\hat{\theta}_n$  is the one with minimum Kullback-Leibler divergence.
- ▶ Do we still have the consistency result for Bayes estimators other than the MAP?  
**Yes. Doob's Consistency Theorem.**
- ▶ Do we still have the normal approximation for the posterior without utilizing the MAP?  
**Yes. Bernstein-Von Mises Theorem.**



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- ▶ Zero prior density at  $\theta_0$ .

- ▶ Converge to the edge of the parameter space.

# Notation

- ▶ Distribution family  $\{P_\theta : \theta \in \Theta\}$
- ▶ For any measurable function  $f : \mathcal{X} \rightarrow \mathbb{R}$ ,

$$P_\theta f := \mathbb{E}_\theta[f(X)]$$

is the expectation of  $f$  under probability measure  $P_\theta$ .

- ▶  $P_\theta^n$  is the joint probability measure for  $n$  independent copies.
- ▶  $P_{\theta|y_1, y_2, \dots, y_n}$  is the posterior probability measure given observations  $y_1, \dots, y_n$ .

# Doob's Consistency Theorem

## Definition (Consistency)

A sequence of posterior measures  $P_{\theta|y_1, y_2, \dots, y_n}$  is called consistent under  $\theta_0$  if under  $P_{\theta_0}^\infty$ -probability it converges in distribution to the measure  $\delta_{\theta_0}$  that is degenerate at  $\theta_0$ , in probability. It is strongly consistent if this happens for almost every sequence  $X_1, X_2, \dots$ .

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Main result for the consistency of the posterior measure:

## Theorem (Doob's Consistency Theorem)

*Suppose that the sample space  $(\mathcal{X}, \mathcal{A})$  is a subset of Euclidean space with its Borel  $\sigma$ -field. Suppose that  $P_\theta \neq P_{\theta'}$  whenever  $\theta \neq \theta'$ . Then for every prior probability measure  $\Pi$  on  $\Theta$  the sequence of posterior measures is consistent for  $\Pi$ -almost every  $\theta$ .*

## Doob's Consistency Theorem — Proof

- ▶ The probability space we are working with:  $\theta \sim \Pi$  and  $y_1, y_2, \dots \mid \theta \sim P_\theta$  i.i.d..
- ▶ Let  $Q$  be the joint probability measure on  $\mathcal{X}^\infty \times \Theta$  such that the joint distribution  $(y_1, \dots, y_n, \theta)$  is a cylinder of the space.



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- ▶ **Step 1:** Claim: there exists a measurable function  $h : \mathcal{X}^\infty \rightarrow \Theta$  such that

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- ▶ **Step 2:** Then, for any bounded, measurable function  $f : \Theta \rightarrow \mathbb{R}$ , we construct a sequence  $\eta_1, \eta_2, \dots$  by

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$$\eta_n = \mathbb{E}[f(\theta) \mid y_1, \dots, y_n].$$

- ▶  $\eta_n$  is a martingale. By Doob's martingale convergence theorem, we have

$$\eta_n \rightarrow \eta_\infty := \mathbb{E}[f(\theta) \mid y_1, y_2, \dots] = f(h(y_1, y_2, \dots)), \quad Q - a.s.$$

## Theorem (Doob's Martingale Convergence Theorem)

Suppose  $X_n$  is a super-martingale that satisfies  $\sup_n \mathbb{E}[|X_n|] < +\infty$ . Then

$X_\infty = \lim_{n \rightarrow \infty} X_n$  exists almost surely, and  $X_n \rightarrow X_\infty$  a.s.

# Doob's Consistency Theorem — Proof

- Recall: for any bounded, measurable function  $f$ , we have

$$\mathbb{E}[f(\theta) \mid y_1, \dots, y_n] \rightarrow f(h(y_1, y_2, \dots)), \quad Q - a.s.$$

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## Lemma (Convergence-Determining Class)

*There exists a countable set of continuous functions  $f : \mathbb{R}^k \rightarrow [0, 1]$  that  $X_n \xrightarrow{\mathcal{D}} X$  if and only if  $\mathbb{E}[X_n] \rightarrow \mathbb{E}[X]$  uniformly in  $f \in \mathcal{F}$ .*

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- With the countable convergence-determining class, we have

$$P_{\theta|y_1, \dots, y_n} \xrightarrow{\mathcal{D}} \delta_{h(y_1, y_2, \dots)}, \quad Q - a.s.$$

**End of Step 2.**

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- Now we need to translate the right-hand side to  $\delta_{\theta_0}$ .

## Doob's Consistency Theorem — Proof

- ▶ **Step 3:** Let  $C \subset \mathcal{X}^\infty \times \Theta$  be the subset that all current results hold,
- ▶ that is the intersection of all  $Q$  – *a.s.* sets so far.



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- ▶ By Fubini's Theorem, we have

$$1 = Q(C) = \iint \mathbb{I}\{(y, \theta) \in C\} dP_\theta^\infty(y) d\Pi(\theta) = \int P_\theta^\infty(C_\theta) d\Pi(\theta),$$

where  $C_\theta = \{y : (y, \theta) \in C\}$ .

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- ▶ For those  $\theta_0$  that  $P_{\theta_0}^\infty(C_{\theta_0}) = 1$ , we have  $(y, \theta_0) \in C$  for  $P_{\theta_0}^\infty$ -almost every sequence  $y_1, y_2, \dots$ , then

$$P_{\theta|y_1, \dots, y_n} \xrightarrow{\mathcal{D}} \delta_{h(y_1, y_2, \dots)} = \delta_{\theta_0}$$

- ▶ **Now the theorem is proved.**

# Doob's Consistency Theorem — Proof of Step 1

Claim: there exists a measurable function  $h : \mathcal{X}^\infty \rightarrow \Theta$  such that

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## Definition (Accessibility)

A measurable function  $f : \Theta \rightarrow \mathbb{R}$  is called accessible if there exists a sequence of measurable functions  $h_n : \mathcal{X}^n \rightarrow \mathbb{R}$  such that

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- ▶ The claim is equivalent to say all  $f(\theta) = \theta_0$  is accessible.
- ▶ We can show: every Borel measurable function is accessible.

# Doob's Consistency Theorem — Proof of Step 1

Want to show: every Borel measurable function is accessible.

- ▶ **Step 1.1:**  $f(\theta) = P_\theta(A)$  for any measurable set  $A$  is accessible.
- ▶ We can choose  $h_n(y) = n^{-1} \sum_{i=1}^n \mathbb{I}\{y_i \in A\}$  and by LLN.

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- ▶ **Step 1.3:** Since  $(\mathcal{X}, \mathcal{A})$  is Euclidean, there exists a countable measure determining subcollection  $\mathcal{A}_0 \subset \mathcal{A}$ .
- ▶ For  $A$  ranging over  $\mathcal{A}_0$ , the function  $P_\theta(A)$  separates the points of  $\Theta$  because of the identifiability. These functions generate the Borel  $\sigma$ -field on  $\Theta$ .

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- ▶ **Step 1.4:** Therefore all Borel measurable functions are accessible.

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### Lemma

*Let  $\mathcal{F}$  be a linear subspace of  $\mathcal{L}^1(\Pi)$  with the properties:*

- 1. if  $f, g \in \mathcal{F}$ , then  $f \wedge g \in \mathcal{F}$ ;*
- 2. if  $0 \leq f_1 \leq f_2 \leq \cdots \in \mathcal{F}$ , and  $f_n \uparrow f \in \mathcal{L}^1(\Pi)$ , then  $f \in \mathcal{F}$ ;*
- 3.  $1 \in \mathcal{F}$ .*

*Then  $\mathcal{F}$  contains every  $\sigma(\mathcal{F})$ -measurable function in  $\mathcal{L}^1(\Pi)$ .*

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Proof:

- ▶ Let  $\mathcal{A}_0 = \{A : \mathbf{1}_A \in \mathcal{F}\}$
- ▶  $\mathcal{A}_0$  is a  $\pi$ -system and a  $\lambda$ -system. By Dynkin Theorem,  $\mathcal{A}_0$  is a  $\sigma$ -field.
- ▶ For any  $f \in \mathcal{F}$ , the function  $n(f - \alpha)_+ \wedge 1$  is in  $\mathcal{F}$  and converges to  $\mathbb{I}\{f > \alpha\}$ .  
So  $\{f > \alpha\} \in \mathcal{A}_0$ .
- ▶ So  $\sigma(\mathcal{F}) \subset \mathcal{A}_0$ .

# Doob's Consistency Theorem — Proof of Step 1.3

## Lemma

*Let  $\mathcal{F}$  be a countable collection of measurable functions  $f : \Theta \subset \mathbb{R}^k \rightarrow \mathbb{R}$  that separates the points of  $\Theta$ . Then the Borel  $\sigma$ -field and the  $\sigma$ -field generated by  $\mathcal{F}$  on  $\Theta$  coincide.*

## Quadratic Mean Differentiability (QMD)

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- ▶ Taylor expansion:

$$\log \prod_{i=1}^n p(y_i \mid \theta_0 + h/\sqrt{n}) = \log \prod_{i=1}^n p(y_i \mid \theta_0) + \frac{h}{\sqrt{n}} \sum_{i=1}^n \dot{\ell}(\theta_0; y_i) + \frac{h^2}{2n} \sum_{i=1}^n \ddot{\ell}(\theta_0; y_i) + o(h^2/n)$$



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- ▶ By Law of Large Numbers, we have

$$\log \prod_{i=1}^n \frac{p(y_i \mid \theta_0 + h/\sqrt{n})}{p(y_i \mid \theta_0)} = h\Delta_{n,\theta_0} - \frac{1}{2}h^2\mathcal{I}(\theta_0) + o_P(1),$$

where  $\Delta_{n,\theta_0} = n^{-1/2} \sum_{i=1}^n \dot{\ell}(\theta_0; y_i)$  and  $\mathcal{I}(\theta_0) = -P_{\theta_0} \ddot{\ell}(\theta_0; y_i)$ .

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- ▶ Do we require the second-order Differentiability of  $\ell$  to have this result?

# Quadratic Mean Differentiability (QMD)

## Definition (Quadratic Mean Differentiability)

The probability family  $\{P_\theta : \theta \in \Theta\}$  is called differentiable in quadratic mean at  $\theta_0$  if there exists a measurable vector function  $\dot{\ell}(\theta)$  such that

$$\int \left[ \sqrt{p_{\theta_0+h}} - \sqrt{p_{\theta_0}} - \frac{1}{2} h^T \dot{\ell}(\theta_0) \right]^2 d\mu = o(\|h\|^2), \quad h \rightarrow 0.$$

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- ▶ QMD does not require the existence of  $\dot{\ell}$  everywhere.
- ▶ Instead, it finds a proxy function that works as  $\dot{\ell}$  as long as the **overall** error is controlled.

# Quadratic Mean Differentiability (QMD)

## Theorem

*Suppose that  $\Theta$  is an open subset of  $\mathbb{R}^k$ , and the probability family  $\{P_\theta : \theta \in \Theta\}$  is differentiable in quadratic mean at  $\theta_0$ . Then  $P_{\theta_0}\dot{\ell}(\theta_0) = 0$  and the Fisher information matrix  $\mathcal{I}(\theta_0) = P_{\theta_0}\dot{\ell}(\theta_0)\dot{\ell}(\theta_0)^T$  exists. Furthermore, for every converging sequence  $h_n \rightarrow h$  as  $n \rightarrow \infty$ ,*

$$\log \prod_{i=1}^n \frac{p(y_i \mid \theta_0 + h/\sqrt{n})}{p(y_i \mid \theta_0)} = \frac{1}{\sqrt{n}} \sum_{i=1}^n h^T \dot{\ell}(\theta_0) - \frac{1}{2} h^T \mathcal{I}(\theta_0) h + o_P(1).$$

# Bernstein-Von Mises Theorem

## Theorem (Bernstein-Von Mises)

*Suppose the probability family  $\{P_\theta : \theta \in \Theta\}$  is differentiable in quadratic mean at  $\theta_0$  with nonsingular Fisher information matrix  $\mathcal{I}(\theta_0)$ , and suppose that for any  $\epsilon > 0$  there exists a sequence of tests  $\phi_n$  such that*

$$P_{\theta_0}^n \phi_n \rightarrow 0, \quad \sup_{\|\theta - \theta_0\| > \epsilon} P_\theta^n (1 - \phi_n) \rightarrow 0.$$

*Futhermore, let the prior measure be absolutely continuous in a neighborhood of  $\theta_0$  with a continuous density function at  $\theta_0$ . Then the corresponding posterior distribution satisfy*

$$\left\| P_{\sqrt{n}(\theta - \theta_0) | y_1, \dots, y_n} - \mathcal{N}(\Delta_{n, \theta_0}, \mathcal{I}(\theta_0)^{-1}) \right\|_{TV} \xrightarrow{P_{\theta_0}^n} 0$$

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- ▶  $\phi_n : \mathcal{X}^n \rightarrow \{0, 1\}$  is a test with  $\phi_n(y_1, \dots, y_n) = 1$  meaning “reject”.
- ▶ The assumption

$$P_{\theta_0}^n \phi_n \rightarrow 0, \quad \sup_{\|\theta - \theta_0\| > \epsilon} P_{\theta}^n (1 - \phi_n) \rightarrow 0.$$

means there exists a sequence of tests that distinguishes  $\theta_0$  from any other points.

# Bernstein-Von Mises Theorem

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- ▶  $\phi_n : \mathcal{X}^n \rightarrow \{0, 1\}$  is a test with  $\phi_n(y_1, \dots, y_n) = 1$  meaning “reject”.
- ▶ The assumption

$$P_{\theta_0}^n \phi_n \rightarrow 0, \quad \sup_{\|\theta - \theta_0\| > \epsilon} P_{\theta}^n (1 - \phi_n) \rightarrow 0.$$

means there exists a sequence of tests that distinguishes  $\theta_0$  from any other points.

- ▶ The **total variation** distance between two distributions  $F_1$  and  $F_2$  is defined as

$$\|F_1 - F_2\|_{TV} = \sup_{A \in \mathcal{F}} |F_1(A) - F_2(A)| = \frac{1}{2} \int |f_1(x) - f_2(x)| d\mu(x)$$

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- ▶ The in probability convergence is w.r.t.  $P_{\theta_0}^n$ , because the randomness of the left-hand side is the observations  $y_1, \dots, y_n$ .

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- ▶ For a given set  $C$ , let  $\Pi_n^C$  be the probability measure by restricting  $\Pi_n$  to  $C$  and then renormalizing.
- ▶ We write  $P_{n,h}$  as the distribution of  $y_1, \dots, y_n \mid \theta_0 + h/\sqrt{n}$ .
- ▶ Let  $P_{n,C} = \int P_{n,h} d\Pi_n^C(h)$  be the average probability measure on  $C$ .

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- ▶ The posterior distributions with priors  $\Pi_n$  and  $\Pi_n^C$  are  $P_{h|y_1, \dots, y_n}$  and  $P_{h|y_1, \dots, y_n}^C$ .



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- ▶ For any measurable set  $B$ , (let  $y = (y_1, \dots, y_n)$ )

$$\begin{aligned} P_{h|y}(B) - P_{h|y}^{C_n}(B) &= P_{h|y}(B \cap C_n^c) + P_{h|y}(B \cap C_n) - P_{h|y}^{C_n}(B \cap C_n) - P_{h|y}^{C_n}(B \cap C_n^c) \\ &= P_{h|y}(B \cap C_n^c) + P_{h|y}(B \cap C_n) - P_{h|y}^{C_n}(B \cap C_n) \\ &= P_{h|y}(B \cap C_n^c) + P_{h|y}(C_n)P_{h|y}^{C_n}(B \cap C_n) - P_{h|y}^{C_n}(B \cap C_n) \\ &= P_{h|y}(B \cap C_n^c) - P_{h|y}(C_n^c)P_{h|y}^{C_n}(B \cap C_n) \\ &= P_{h|y}(B \cap C_n^c) - P_{h|y}(C_n^c)P_{h|y}^{C_n}(B) \\ &\leq 2P_{h|y}(C_n^c) \end{aligned}$$

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- ▶ Therefore,

$$\left\| P_{h|y} - P_{h|y}^{C_n} \right\|_{TV} \leq 2P_{h|y}(C_n^c)$$

# Bernstein-Von Mises Theorem — Proof

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- ▶ Let  $U$  be a ball around zero with fixed radius.
- ▶ Then

$$\begin{aligned} P_{n,U} P_{h|y}(C_n^c)(1 - \phi_n) &= P_{n,U} \int_{C_n^c} \frac{p_{n,h}(y)(1 - \phi_n)}{\int p_{n,\tilde{h}}(y) d\Pi_n(\tilde{h})} d\Pi_n(h) \\ &= \int_U \left[ \int_{\mathcal{X}^n} p_{n,h'}(y) \int_{C_n^c} \frac{p_{n,h}(y)(1 - \phi_n)}{\int p_{n,\tilde{h}}(y) d\Pi_n(\tilde{h})} d\Pi_n(h) dy \right] d\Pi_n^U(h') \\ &= \frac{1}{\Pi_n(U)} \int_U \int_{\mathcal{X}^n} \int_{C_n^c} \frac{p_{n,h}(y) p_{n,h'}(y)(1 - \phi_n)}{\int p_{n,\tilde{h}}(y) d\Pi_n(\tilde{h})} d\Pi_n(h) dy d\Pi_n(h') \\ &= \frac{\Pi_n(C_n^c)}{\Pi_n(U)} P_{n,C_n^c} P_{h|y}(U)(1 - \phi_n) \\ &\leq \frac{1}{\Pi_n(U)} \int_{C_n^c} P_{n,h}(1 - \phi_n) d\Pi_n(h) \end{aligned}$$

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- ▶ The integrand converges pointwise to 0. But that's not enough.

# Bernstein-Von Mises Theorem — Proof

## Lemma

*There exists a sequence of tests  $\phi_n$  and a constant  $c$  such that for every sufficiently large  $n$  and every  $\|\theta - \theta_0\| \geq M_n/\sqrt{n}$ ,*

$$P_{\theta_0}^n \phi_n \rightarrow 0, \quad P_{\theta}^n(1 - \phi_n) \leq \exp \{ -cn(\|\theta - \theta_0\|^2 \wedge 1) \}$$



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## proof sketch:

- ▶ For  $M_n/\sqrt{n} \leq \|\theta - \theta_0\| \leq \epsilon$ , we set  $\phi_n = \mathbb{I}\{(\mathbb{P}_n - P_{\theta_0})\dot{\ell}^L(\theta_0) \geq \sqrt{M_n/n}\}$
- ▶ For  $\|\theta - \theta_0\| > \epsilon$ , we first choose  $k$  such that  $P_{\theta_0}^k \phi_k < 1/4$  and  $P_{\theta}^k(1 - \phi_k) < 1/4$  as the assumption in the BVM theorem. For  $n = mk$ , let  $\psi_1, \dots, \psi_m$  be  $\phi_k$  applied to  $(y_1, \dots, y_k), \dots, (y_{(m-1)k+1}, \dots, y_{mk})$ . Let  $\phi_n = \mathbb{I}\{\bar{\psi} \geq 1/2\}$ .

## Bernstein-Von Mises Theorem — Proof

Return to our Step 1 of the main proof.

- ▶ Let  $D \leq 1$  be sufficiently small such that  $\pi(\theta)$  is uniformly bounded on  $\|\theta - \theta_0\| \leq D$ .

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- ▶ Then

$$\begin{aligned} P_{n,U} P_{h|y}(C_n^c)(1 - \phi_n) &\leq \frac{1}{\Pi_n(U)} \int_{C_n^c} P_{n,h}(1 - \phi_n) d\Pi_n(h) \\ &\leq \frac{1}{\Pi_n(U)} \int_{\|h\| \geq M_n} e^{-c(\|h\|^2 \wedge n)} d\Pi_n(h) \\ &= \frac{1}{\Pi_n(U)} \left( \int_{M_n \leq \|h\| \leq D\sqrt{n}} + \int_{\|h\| \geq D\sqrt{n}} \right) e^{-c(\|h\|^2 \wedge n)} d\Pi_n(h) \\ &\leq K \left( \int_{\|h\| \geq M_n} e^{-c\|h\|^2} dh + \sqrt{n^k} e^{-cD^2n} \right) \rightarrow 0 \end{aligned}$$

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- ▶ Therefore  $P_{h|y}(C_n^c) \xrightarrow{P_{\theta_0}^n} 0$ .

# Bernstein-Von Mises Theorem — Proof

**Step 2: show that  $\mathcal{N}(\Delta_{n,\theta_0}, \mathcal{I}(\theta_0)^{-1})$  and  $P_{h|y}^{C_n}$  are close.**

- ▶ Now let  $C$  be the ball with fixed radius  $M$  around 0. Let  $\mathcal{N}^C(\mu, \Sigma)$  be the normal distribution restricted to  $C$ .

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$$\begin{aligned} & \|\mathcal{N}^C(\Delta_{n,\theta_0}, \mathcal{I}(\theta_0)^{-1}) - P_{h|y}^C\|_{TV} \\ &= \int \left(1 - \frac{d\mathcal{N}^C}{dP_{h|y}^C}\right)_+ dP_{h|y}^C = \int \left(1 - \frac{d\mathcal{N}^C(h) \int_C p_{n,g}(y) d\Pi_n(g)}{\mathbb{I}\{h \in C\} p_{n,h}(y) d\Pi_n(h)}\right)_+ dP_{h|y}^C(h) \\ &\leq \iint \left(1 - \frac{p_{n,g}(y) d\Pi_n(g) d\mathcal{N}^C(h)}{p_{n,h}(y) d\Pi_n(h) d\mathcal{N}^C(g)}\right)_+ d\mathcal{N}^C(g) dP_{h|y}^C(h) \end{aligned}$$

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- ▶ It follows from the expansion theorem of QMD family.

# Summary

- ▶ Both Doob's Consistency Theorem and Bernstein-Von Mises Theorem requires QMD.

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- ▶ Both Doob's Consistency Theorem and Bernstein-Von Mises Theorem requires QMD.
- ▶ Some sufficient condition for QMD:

## Lemma

*For every  $\theta$  in an open subset of  $\mathbb{R}^k$ , let  $p_\theta$  be a  $\mu$ -probability density. Assume the map  $\theta \mapsto \sqrt{p_\theta(x)}$  is continuously differentiable for every  $x$ . If the elements of the matrix*

$$\mathcal{I}(\theta) = \int \frac{\dot{p}_\theta}{p_\theta} \frac{\dot{p}_\theta^T}{p_\theta} p_\theta d\mu$$

*are well defined and continuous in  $\theta$ . Then the map  $\theta \mapsto \sqrt{p_\theta(x)}$  is QMD with  $\dot{\ell}(\theta) = \dot{p}_\theta/p_\theta$ .*

# Summary

- ▶ Under regularity conditions, the Doob's consistency theorem gives

$$p(\theta \mid y) \xrightarrow{\mathcal{D}} \delta_{\theta_0}$$

- ▶ Under regularity conditions, the Bernstein-Von Mises Theorem gives

$$\|p(\sqrt{n}(\theta - \theta_0) \mid y) - \mathcal{N}(\Delta_{n,\theta_0}, \mathcal{I}(\theta_0)^{-1})\|_{TV} \xrightarrow{P} 0$$

or the rescaled version

$$\left\| p(\theta \mid y) - \mathcal{N}\left(\theta_0 + \frac{1}{n} \sum_{i=1}^n \dot{\ell}(\theta_0 \mid y_i), \frac{1}{n} \mathcal{I}(\theta_0)^{-1}\right) \right\|_{TV} \xrightarrow{P} 0$$