

STAT 423/523 Statistical Methods for Engineers and Scientists

Lecture 11: Multiple Linear Regression

Chencheng Cai

Washington State University

Multiple Linear Regression

In cases when we have more than one predictor variable, we can extend the simple linear regression model to a **multiple linear regression model**:

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \cdots \beta_p x_{ki} + \epsilon_i,$$

where

- ▶ y_i is the response variable,
- ▶ x_{ji} is the j th predictor variable for the i th observation
- ▶ $\epsilon_i \sim N(0, \sigma^2)$ is the error term.

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- ▶ $\epsilon_i \sim N(0, \sigma^2)$ is the error term.

The predictors could be:

- ▶ additional covariates in the dataset
- ▶ interactions between predictors
- ▶ nonlinear functions of predictors

Ordinary Least Squares

We follow the same principle as in simple linear regression and minimize the residual sum of squares (RSS):

$$\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k = \arg \min_{\beta_0, \beta_1, \dots, \beta_k} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \dots - \beta_k x_{ki})^2$$

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We compute the partial derivatives of the RSS with respect to each β_j :

$$\begin{aligned} \frac{\partial \text{RSS}}{\partial \beta_0} &= -2 \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \dots - \beta_k x_{ki}) \\ \frac{\partial \text{RSS}}{\partial \beta_j} &= -2 \sum_{i=1}^n x_{ji} (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \dots - \beta_k x_{ki}), \quad j = 1, \dots, k \end{aligned}$$

Ordinary Least Squares

The OLS estimators can be obtained by setting the partial derivatives to zero:

$$\sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \cdots - \beta_k x_{ki}) = 0$$

$$\sum_{i=1}^n x_{1i} (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \cdots - \beta_k x_{ki}) = 0$$

$$\sum_{i=1}^n x_{2i} (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \cdots - \beta_k x_{ki}) = 0$$

$$\vdots$$

$$\sum_{i=1}^n x_{ki} (y_i - \beta_0 - \beta_1 x_{1i} - \beta_2 x_{2i} - \cdots - \beta_k x_{ki}) = 0$$

Ordinary Least Squares

This is a linear system of equations in the unknowns $\beta_0, \beta_1, \dots, \beta_k$.

$$\begin{aligned}\sum_{i=1}^n y_i &= n\beta_0 + \beta_1 \sum_{i=1}^n x_{1i} + \beta_2 \sum_{i=1}^n x_{2i} + \cdots + \beta_k \sum_{i=1}^n x_{ki} \\ \sum_{i=1}^n x_{1i}y_i &= \beta_0 \sum_{i=1}^n x_{1i} + \beta_1 \sum_{i=1}^n x_{1i}^2 + \beta_2 \sum_{i=1}^n x_{1i}x_{2i} + \cdots + \beta_k \sum_{i=1}^n x_{1i}x_{ki} \\ \sum_{i=1}^n x_{2i}y_i &= \beta_0 \sum_{i=1}^n x_{2i} + \beta_1 \sum_{i=1}^n x_{2i}x_{1i} + \beta_2 \sum_{i=1}^n x_{2i}^2 + \cdots + \beta_k \sum_{i=1}^n x_{2i}x_{ki} \\ &\vdots \\ \sum_{i=1}^n x_{ki}y_i &= \beta_0 \sum_{i=1}^n x_{ki} + \beta_1 \sum_{i=1}^n x_{ki}x_{1i} + \beta_2 \sum_{i=1}^n x_{ki}x_{2i} + \cdots + \beta_k \sum_{i=1}^n x_{ki}^2\end{aligned}$$

Ordinary Least Squares

We can write it in matrix form:

$$\begin{bmatrix} n & \sum_{i=1}^n x_{1i} & \sum_{i=1}^n x_{2i} & \cdots & \sum_{i=1}^n x_{ki} \\ \sum_{i=1}^n x_{1i} & \sum_{i=1}^n x_{1i}^2 & \sum_{i=1}^n x_{1i}x_{2i} & \cdots & \sum_{i=1}^n x_{1i}x_{ki} \\ \sum_{i=1}^n x_{2i} & \sum_{i=1}^n x_{2i}x_{1i} & \sum_{i=1}^n x_{2i}^2 & \cdots & \sum_{i=1}^n x_{2i}x_{ki} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sum_{i=1}^n x_{ki} & \sum_{i=1}^n x_{ki}x_{1i} & \sum_{i=1}^n x_{ki}x_{2i} & \cdots & \sum_{i=1}^n x_{ki}^2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n y_i \\ \sum_{i=1}^n x_{1i}y_i \\ \sum_{i=1}^n x_{2i}y_i \\ \vdots \\ \sum_{i=1}^n x_{ki}y_i \end{bmatrix}$$

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more compactly, we can write it as:

$$\begin{bmatrix} S_{x_0x_0} & S_{x_0x_1} & S_{x_0x_2} & \cdots & S_{x_0x_k} \\ S_{x_1x_0} & S_{x_1x_1} & S_{x_1x_2} & \cdots & S_{x_1x_k} \\ S_{x_2x_0} & S_{x_2x_1} & S_{x_2x_2} & \cdots & S_{x_2x_k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ S_{x_kx_0} & S_{x_kx_1} & S_{x_kx_2} & \cdots & S_{x_kx_k} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} = \begin{bmatrix} S_{x_0y} \\ S_{x_1y} \\ S_{x_2y} \\ \vdots \\ S_{x_ky} \end{bmatrix}$$

where $S_{x_jx_l} = \sum_{i=1}^n x_{ji}x_{li}$ and $S_{x_jy} = \sum_{i=1}^n x_{ji}y_i$ with $x_{0i} = 1$.

Ordinary Least Squares

The OLS estimators can be computed using matrix algebra:

$$\begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \\ \hat{\beta}_2 \\ \vdots \\ \hat{\beta}_k \end{bmatrix} = \begin{bmatrix} S_{x_0x_0} & S_{x_0x_1} & S_{x_0x_2} & \cdots & S_{x_0x_k} \\ S_{x_1x_0} & S_{x_1x_1} & S_{x_1x_2} & \cdots & S_{x_1x_k} \\ S_{x_2x_0} & S_{x_2x_1} & S_{x_2x_2} & \cdots & S_{x_2x_k} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ S_{x_kx_0} & S_{x_kx_1} & S_{x_kx_2} & \cdots & S_{x_kx_k} \end{bmatrix}^{-1} \begin{bmatrix} S_{x_0y} \\ S_{x_1y} \\ S_{x_2y} \\ \vdots \\ S_{x_ky} \end{bmatrix}$$

Ordinary Least Squares

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When $k = 1$, we have:

$$\begin{aligned}\begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix} &= \begin{bmatrix} S_{x_0x_0} & S_{x_0x_1} \\ S_{x_1x_0} & S_{x_1x_1} \end{bmatrix}^{-1} \begin{bmatrix} S_{x_0y} \\ S_{x_1y} \end{bmatrix} \\ &= \begin{bmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{bmatrix}^{-1} \begin{bmatrix} \sum y_i \\ \sum x_i y_i \end{bmatrix} \\ &= \frac{1}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix} \begin{bmatrix} \sum y_i \\ \sum x_i y_i \end{bmatrix} \\ &= \frac{1}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum x_i^2 \sum y_i - \sum x_i \sum x_i y_i \\ n \sum x_i y_i - \sum x_i \sum y_i \end{bmatrix} \\ &= S_{xx}^{-1} \begin{bmatrix} \bar{y} S_{xx} - \bar{x} S_{xy} \\ S_{xy} \end{bmatrix}\end{aligned}$$

Ordinary Least Squares

For the variance component, we have:

$$\hat{\sigma}^2 = \text{MSE} = \frac{\text{RSS}(\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_k)}{n - k - 1} = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n - k - 1}$$

where

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where

- ▶ $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_{1i} + \hat{\beta}_2 x_{2i} + \dots + \hat{\beta}_k x_{ki}$ is the **predicted** or **fitted** value of y_i
- ▶ The degrees of freedom is $n - k - 1$ because we have estimated $k + 1$ parameters $(\beta_0, \beta_1, \dots, \beta_k)$ from the data.

Ordinary Least Squares

The OLS estimators are **unbiased**:

$$\mathbb{E}[\hat{\beta}_j] = \beta_j, \quad j = 0, 1, \dots, k$$

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Let $s_{\hat{\beta}_j}$ be the estimated standard error of $\hat{\beta}_j$. Then

$$\frac{\hat{\beta}_j}{s_{\hat{\beta}_j}} \sim t_{n-k-1}$$

which is a t -distribution with $n - k - 1$ degrees of freedom.

Confidence interval and t-test

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$$\hat{\beta}_j \pm t_{\alpha/2, n-k-1} s_{\hat{\beta}_j}.$$

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Consider the hypothesis test:

$$H_0 : \beta_j = 0 \text{ vs. } H_a : \beta_j \neq 0$$

We reject H_0 if:

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We reject H_0 if:

- ▶ The CI does not contain 0.
- ▶ The t-statistic

$$t = \frac{\hat{\beta}_j}{s_{\hat{\beta}_j}}$$

has absolute value greater than $t_{\alpha/2, n-k-1}$.

- ▶ The p-value

$$p = 2(1 - F_{t, n-k-1}(|t|))$$

is less than α .

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- ▶ The standard error of $\hat{\beta}_j$ can be read from the output of the regression models in R and Python.
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- ▶ A covariate $x_{ji}, i = 1, \dots, n$ is **significant** if the null hypothesis $H_0 : \beta_j = 0$ is rejected.
- ▶ A covariate $x_{ji}, i = 1, \dots, n$ is **insignificant** if the null hypothesis $H_0 : \beta_j = 0$ is not rejected.

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- ▶ Insignificant covariates can be removed from the model to simplify the model.

Example

We consider the **mtcars** dataset in R and run a linear regression model of mpg (miles per gallon) on disp (displacement), hp (gross horsepower), and wt (weight of car).

Call:

```
lm(formula = mpg ~ disp + hp + wt, data = mtcars)
```

Residuals:

Min	1Q	Median	3Q	Max
-3.891	-1.640	-0.172	1.061	5.861

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	37.105505	2.110815	17.579	< 2e-16 ***
disp	-0.000937	0.010350	-0.091	0.92851
hp	-0.031157	0.011436	-2.724	0.01097 *
wt	-3.800891	1.066191	-3.565	0.00133 **

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 2.639 on 28 degrees of freedom

Multiple R-squared: 0.8268, Adjusted R-squared: 0.8083

F-statistic: 44.57 on 3 and 28 DF, p-value: 8.65e-11

Example

- ▶ The estimated intercept is $\hat{\beta}_0 = 37.11$.
- ▶ The estimated slope for `disp` is $\hat{\beta}_1 = -0.000937$.
- ▶ The estimated slope for `hp` is $\hat{\beta}_2 = -0.03116$.
- ▶ The estimated slope for `wt` is $\hat{\beta}_3 = -3.8009$.

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- ▶ The intercept, `hp`, and `wt` are significant at $\alpha = 0.05$ level.
- ▶ The `disp` is insignificant at $\alpha = 0.05$ level.

Example

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- ▶ The estimated slope for `hp` is $\hat{\beta}_2 = -0.03116$.
- ▶ The estimated slope for `wt` is $\hat{\beta}_3 = -3.8009$.
- ▶ The intercept, `hp`, and `wt` are significant at $\alpha = 0.05$ level.
- ▶ The `disp` is insignificant at $\alpha = 0.05$ level.
- ▶ fitted model is

$$\text{mpg} = 37.11 - 0.0009 \times \text{disp} - 0.0312 \times \text{hp} - 3.801 \times \text{wt} + \epsilon \quad \text{with } \epsilon \sim N(0, 2.639^2)$$

Example

A direct improvement of the model is to remove `disp` from the model and refit the model:

Call:

```
lm(formula = mpg ~ hp + wt, data = mtcars)
```

Residuals:

Min	1Q	Median	3Q	Max
-3.941	-1.600	-0.182	1.050	5.854

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	37.22727	1.59879	23.285	< 2e-16 ***
hp	-0.03177	0.00903	-3.519	0.00145 **
wt	-3.87783	0.63273	-6.129	1.12e-06 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 2.593 on 29 degrees of freedom

Multiple R-squared: 0.8268, Adjusted R-squared: 0.8148

F-statistic: 69.21 on 2 and 29 DF, p-value: 9.109e-12

Model Comparison

Consider two **nested** models:

- ▶ The **full model**: (all subscript i are removed for simplicity)

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \cdots + \beta_q x_q + \beta_{q+1} x_{q+1} + \cdots + \beta_k x_k + \epsilon$$

- ▶ The **reduced model**: (all subscript i are removed for simplicity)

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- ▶ The **reduced model**: (all subscript i are removed for simplicity)

$$y = \beta_0 + \beta_1 x_1 + \cdots + \beta_q x_q + \epsilon$$

- ▶ The reduced model is a special case of the full model with $\beta_{q+1} = \cdots = \beta_k = 0$.
- ▶ Comparing the two models is equivalent to testing the null hypothesis:

$$H_0 : \beta_{q+1} = \cdots = \beta_k = 0$$

Model Comparison

$$H_0 : \beta_{q+1} = \cdots = \beta_k = 0$$

In order to compare the nested models, we can use the **F-test**:

$$F = \frac{(SSE_{reduced} - SSE_{full})/(k - q)}{SSE_{full}/(n - k - 1)}$$

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In order to compare the nested models, we can use the **F-test**:

$$F = \frac{(SSE_{reduced} - SSE_{full})/(k - q)}{SSE_{full}/(n - k - 1)}$$

reject null if

- ▶ $F > F_{\alpha, k-q, n-k-1}$
- ▶ The p-value:

$$1 - F_{F, k-q, n-k-1}(F)$$

is less than α .

Example

Recall the **mtcars** dataset, we compare the following two models:

```
> model1 = lm(mpg~disp+hp+wt, mtcars)
> model2 = lm(mpg~disp, mtcars)
```


Example

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```

The F-test result can be read from anova function:

```
> anova(model2, model1)
Analysis of Variance Table

Model 1: mpg ~ disp
Model 2: mpg ~ disp + hp + wt
Res.Df    RSS Df Sum of Sq    F    Pr(>F)
1      30 317.16
2      28 194.99  2    122.17 8.7715 0.001102 **
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Model Comparison

- ▶ R^2 is a metric for the goodness of fit of the model.
- ▶ But we **cannot** use R^2 to compare two models with different number of predictors, because **adding more predictors will always increase R^2** .

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- ▶ We can use the **adjusted R^2** :

$$R_{adj}^2 = 1 - \frac{n-1}{n-k-1} \frac{\text{SSE}}{\text{SST}}$$

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- ▶ We can use the **adjusted R^2** :

$$R_{adj}^2 = 1 - \frac{n-1}{n-k-1} \frac{\text{SSE}}{\text{SST}}$$

- ▶ The adjusted R^2 adds a penalty for the number of predictors in the model.
- ▶ The adjusted R^2 is always less than or equal to R^2 .

Example

Recall part of the output of the `mtcars` example:

```
Residual standard error: 2.639 on 28 degrees of freedom  
Multiple R-squared:  0.8268, Adjusted R-squared:  0.8083  
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- ▶ The R^2 is 0.8268, which means 82.68% of the variability in `mpg` can be explained by the model.
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- ▶ The R^2 is 0.8268, which means 82.68% of the variability in `mpg` can be explained by the model.
- ▶ The adjusted R^2 is 0.8083.
- ▶ The F-statistic and the p-value are for the following hypothesis test:

$$H_0 : \beta_1 = \beta_2 = \cdots = \beta_k = 0.$$

- ▶ The p-value is very small, which means at least one of the predictors is significant in the model or the model is significant.

Example

However, if we consider a linear regression model of mpg on disp, hp, and cyl.

Call:

```
lm(formula = mpg ~ disp + hp + cyl, data = mtcars)
```

Residuals:

Min	1Q	Median	3Q	Max
-4.0889	-2.0845	-0.7745	1.3972	6.9183

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	34.18492	2.59078	13.195	1.54e-13 ***
disp	-0.01884	0.01040	-1.811	0.0809 .
hp	-0.01468	0.01465	-1.002	0.3250
cyl	-1.22742	0.79728	-1.540	0.1349

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 3.055 on 28 degrees of freedom

Multiple R-squared: 0.7679, Adjusted R-squared: 0.743

F-statistic: 30.88 on 3 and 28 DF, p-value: 5.054e-09

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Residual standard error: 3.055 on 28 degrees of freedom

Multiple R-squared: 0.7679, Adjusted R-squared: 0.743

F-statistic: 30.88 on 3 and 28 DF, p-value: 5.054e-09

None of the covariates are significant at $\alpha = 0.05$ level. But they are jointly significant.

Multicollinearity

The **multicollinearity** is a problem when two or more predictors are highly correlated with each other.

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To verify it, we can check the correlation matrix of the predictors in previous example:

```
> cor(mtcars[,c("disp", "hp", 'cyl')])
      disp      hp      cyl
disp 1.0000000 0.7909486 0.9020329
hp   0.7909486 1.0000000 0.8324475
cyl  0.9020329 0.8324475 1.0000000
```

Multicollinearity

To measure the multicollinearity, we can use the **variance inflation factor** (VIF):

$$VIF_j = \frac{1}{1 - R_j^2}$$

where R_j^2 is the R^2 of the regression of x_j on all other predictors.

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- ▶ If $VIF_j > 10$, we consider x_j is highly correlated with other predictors.
- ▶ If $5 < VIF_j < 10$, we consider x_j is correlated with other predictors.
- ▶ If $1 < VIF_j < 5$, we consider x_j is lightly correlated with other predictors.
- ▶ If $VIF_j = 1$, we consider x_j is not correlated with other predictors.

Example

We can use the `vif` function in R to compute the VIF for each predictor:

```
> library(car)
> model = lm(mpg~disp+hp+cyl, mtcars)
> vif(model)
disp      hp      cyl
5.521460 3.350964 6.732984
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We should consider removing `cyl` from the model.