

# Licensed Plate Detection and Recognition

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# 1. 모델 선정

- Problem : 두개의 데이터셋에 대하여 번호판을 탐지하고 인식



- Problem1 : Parking Detection(YOLO V3)
- Problem2 : CCTV Detection(Canny Edge)
- Problem3 : Recognition(CRNN)

## 2. 모델선정 이유와 전략

### ○ 전략 :

- 데이터가 적기 때문에, 학습해서 문제를 해결하려 한다면 Accuracy는 낮을 것이므로, PT가 빠른 모델을 고려하자.
- IoU가 70%만 넘으면 된다는 사실을 이용하자.

### Definition of the Score

$$Score = Score_{park} + Score_{cctv} + 0.1 \times (100 - PT)$$

$$PT = msec./image (average)$$

$$Score_i = Accuracy_{det} + Accuracy_{rec} \quad (i = park \text{ or } cctv)$$

$$Accuracy_{det} = \frac{1}{n} \sum_{i=0}^{n-1} \frac{\#TP_{det} - \#FP_{det}}{\#GT} \times 100\%$$

$$Accuracy_{rec} = \frac{1}{n} \sum_{i=0}^{n-1} \frac{\#TP_{rec}}{\#GT} \times 100\%$$

- PT: average processing time of the model (unit: msec.)

- $\#TP_{det}$ : number of true positive for detection

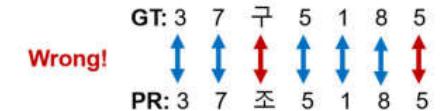
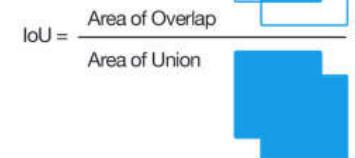
- $\#FP_{det}$ : number of false positive for detection

- $\#TP_{rec}$ : number of true positive for recognition

- $\#GT$ : number of ground-truth

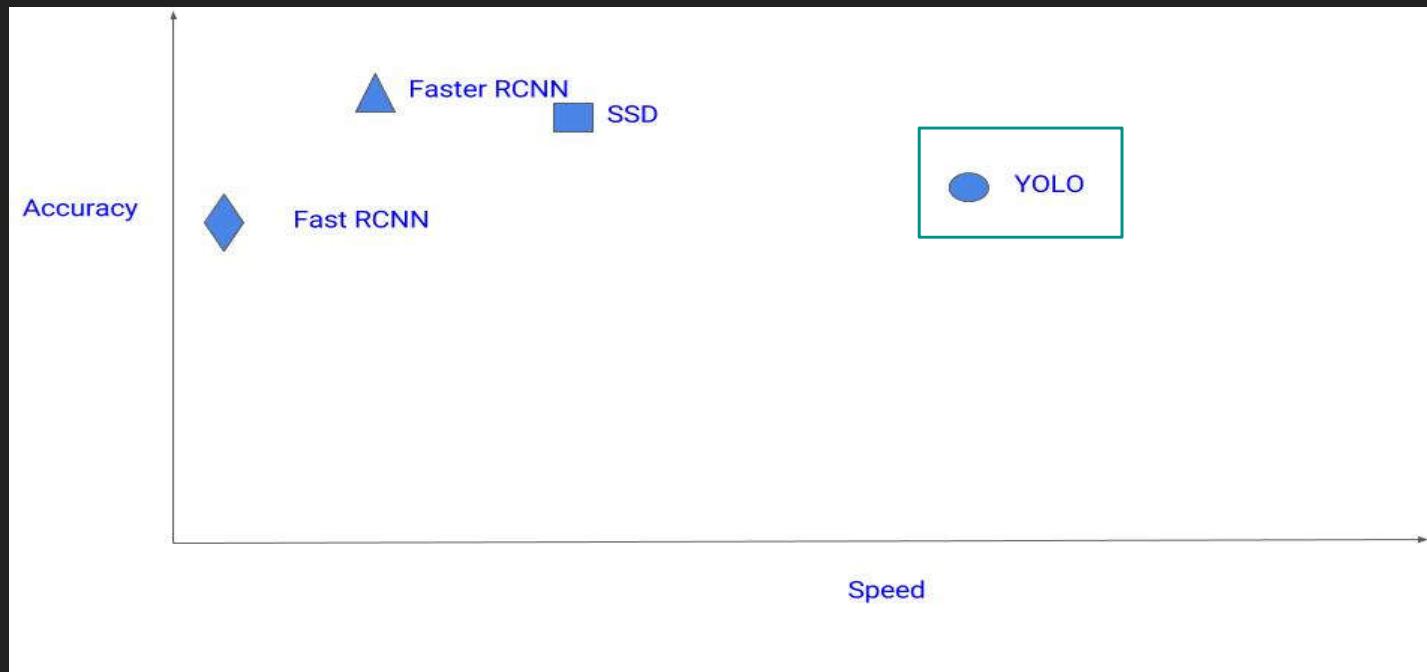
- $TP_{det}: IoU \geq \theta, \theta=0.7$

- $FP_{det}: IoU < \theta$



## 2. 모델선정 이유와 전략(YOLO)

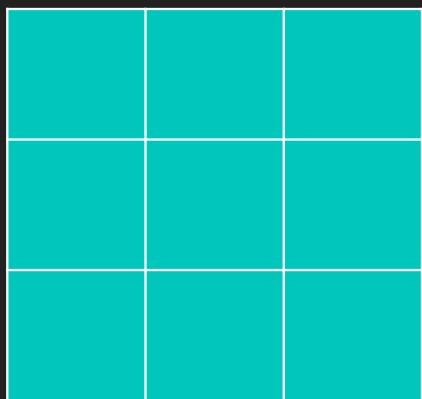
### ○ 모델별 Accuracy 와 speed



## 2. 모델선정 이유와 전략(YOLO)

### ○ Model Concept

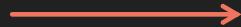
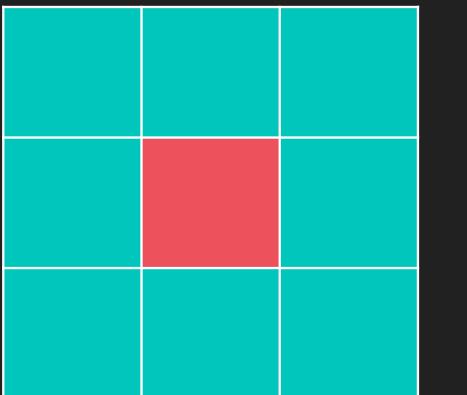
1. Input Image를  $s*s$  grid로 나누어 각 셀에서 확인한다.



## 2. 모델선정 이유와 전략(YOLO)

### ○ Model Concept

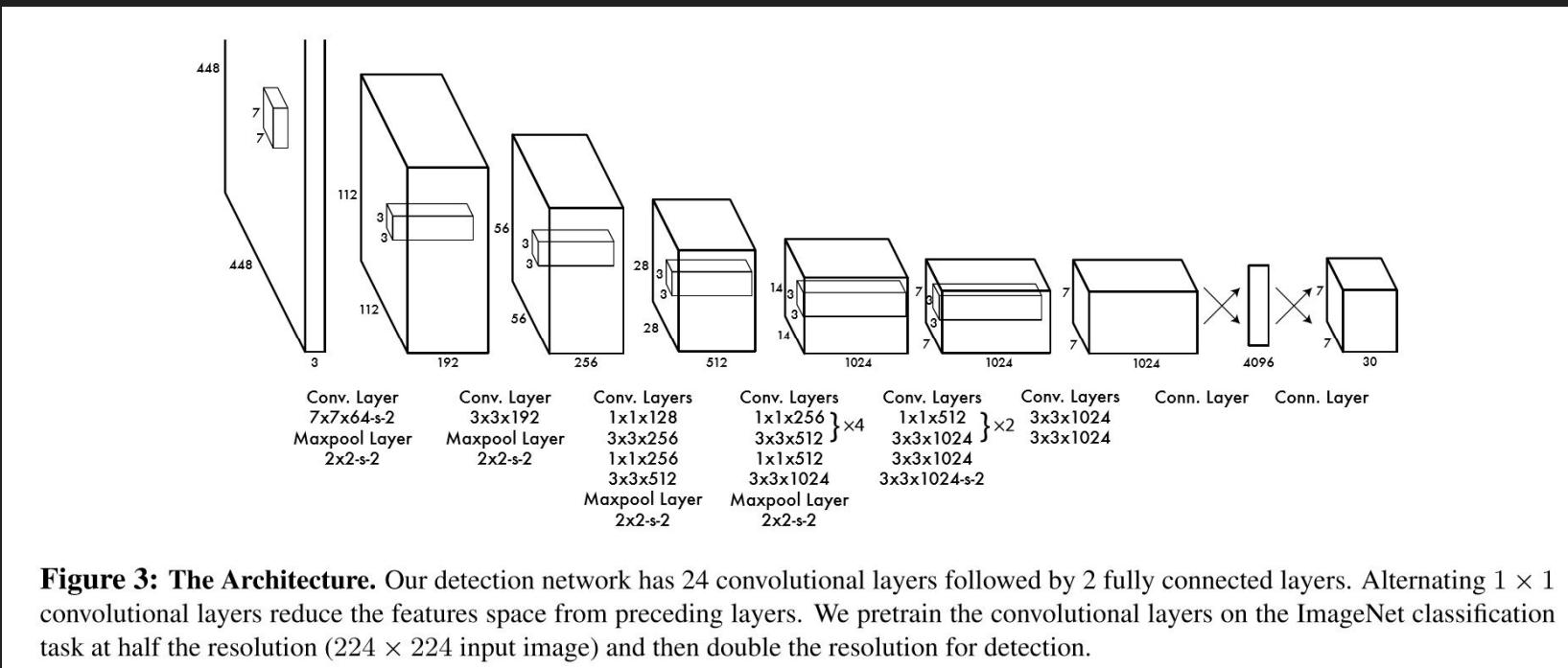
2. Conv layer를 이용하여 각 셀 별로 B개(1, 2, 3, 4)의 바운딩박스에 대한 정보와, confidence score(물체가 존재할 확률), C개의 class probability(어떤 클래스의 물체일지, 4)를 구하여 합친다.



1. 이 셀의 물체를 포함하는 바운딩 박스의 Center x, y
2. 이 셀의 물체를 포함하는 바운딩 박스의 w, h
3. 이 바운딩 박스에 물체가 존재할 확률
4. 이 셀에 있는 오브젝트의 class probability

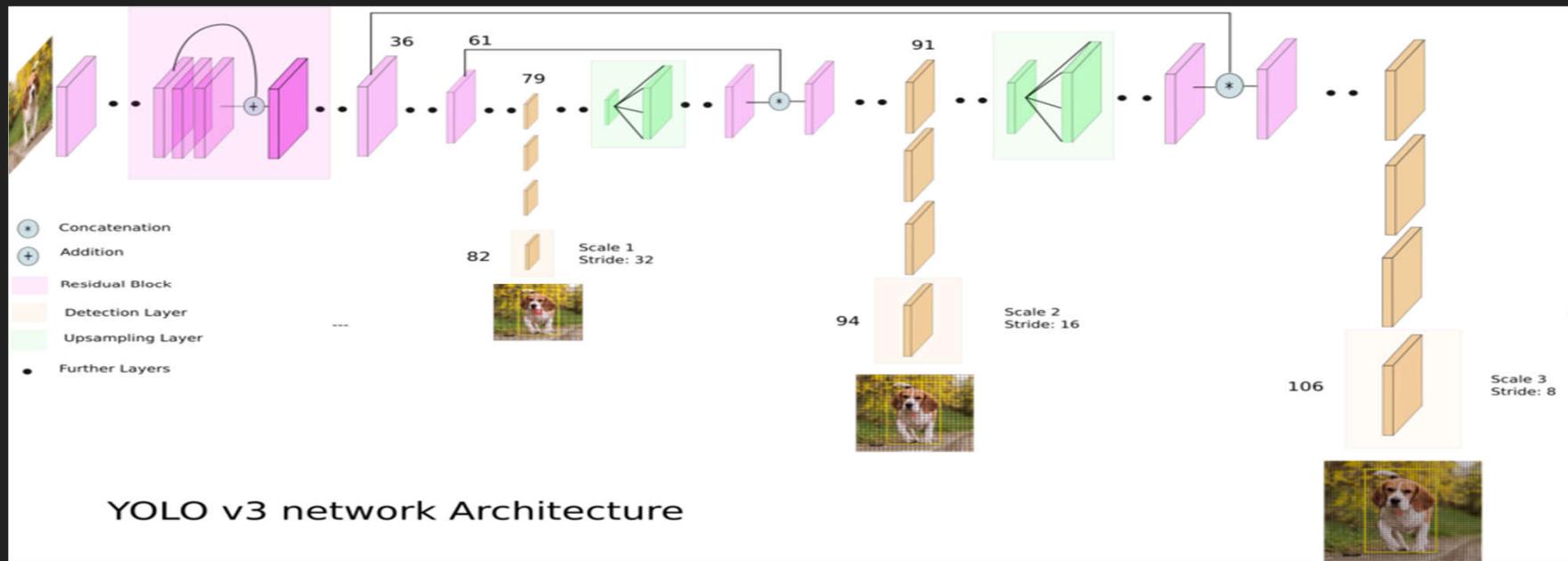
## 2. 모델선정 이유와 전략(YOLO)

### ○ Model Architecture



## 2. 모델선정 이유와 전략(YOLO v3)

- What's new in YOLO v3(Detection at three scales)



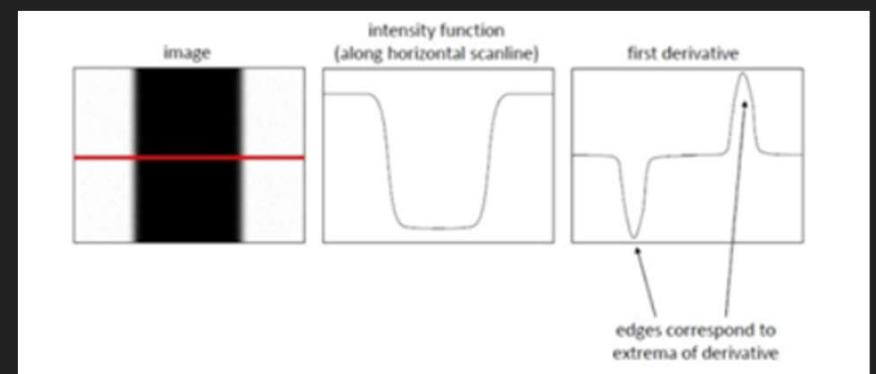
## 2. 모델선정 이유와 전략(YOLO V3)

단점 :

- 1.  $s*s$  그리드로 나누어 각 셀에서 object를 확인하는데, 물체가 작다면 object가 없다고 인식할 수 있어 번호판이 작은 CCTV데이터에선 학습이 안됨.
- 2. 그리드의 사이즈를 작게 해도, 여러 개의 번호판에서 가까운 번호판을 추출하기 어려움.

## 2. 모델선정 이유와 전략(Canny Edge Detection)

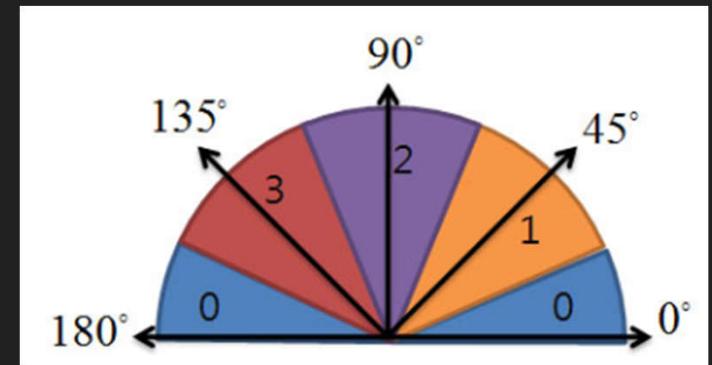
- + 영상의 pixel변화가 급격한곳이 edge이다.
- + 영상의 noise때문에 edge가 아닌데도 기울기가 급격히 변하여 edge라고 할수있기때문에 가우시안필터를 써운 뒤에 sobel 필터로  $dx$ , $dy$ 를 구한다.



# Canny Edge Detection - non maxima Supression

- + 가우시안 필터를 썻음에도 불구하고  $dx, dy$ 값이 edge가 아닌데도 꽤 크게나온다.  
따라서 그 어느정도 크기는 제외시켜야 하는데  
local maxima를 찾고 그 지점만 제외하고  
0으로 만들면 문제를 해결할수있다.

간단 알고리즘 -  $dx, dy$ 로부터 얻은 벡터의 방향의 전후 픽셀과 중심픽셀 3개의 벡터 크기를 비교후  
에 중심이 maxima가 아니라면 0으로 쓴다.



# Canny Edge Detection -double threshold

- + 이제 threshold를 설정하여 edge인부분 edge가 아닌부분을 구분해야하는데 그냥 하나의 threshold만 그어서 판별하기에는 문제가 있다.
- + 조금이나마 해결.. : high threshold 이상이면 무조건 edge low와 high 사이에 있고 edge로 분류된 픽셀과 인접하면 edge

# 번호판찾기 : 외곽선따기

```
cnts,contours,hierarchy = cv2.findContours(canny, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)
```

- + 외곽선따기 알고리즘은 흰픽셀들을 이어주어 그를 물체로 본다는 것이다.
- + APP...SIMPLE : 수평수직 대각성분의 끝점만 저장한다.
- + 번호판에서 SIMPLE인자로 외곽선을 따면 문자당 어떤 외곽선이 추출된다.
- + 찾은 외곽선에서 일정한 특징을 찾으면 그게 번호판이다.  
특징 : 기울기가 비슷한게 나열되어있다. 간격이좁다



## 2. 모델선정 이유와 전략(CRNN)

- 번호판은 모든 글자를 전부 제대로 맞춰야 한다.
- 글자 하나하나의 위치를 찾아 잘라내고(Risk 1)
- 해당 부분을 CNN모델을 이용하여 예측해서 찾는 것은 위험성이 크다.(Risk 2)

## 2. 모델선정 이유와 전략(CRNN)

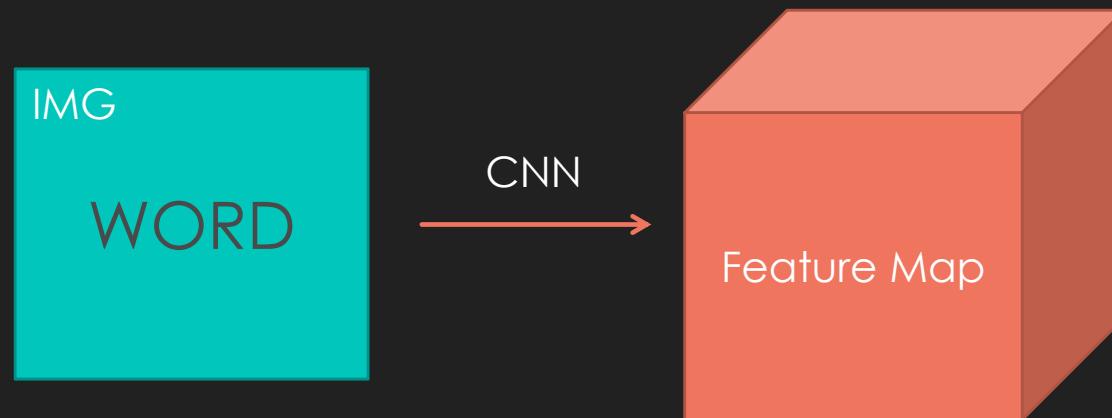
### ○ Model Idea

- 이미지를 Sequential Data로 보아, 각 부분을 RNN을 이용하여 더 정확히 데이터를 처리한다.

## 2. 모델선정 이유와 전략(CRNN)

### ○ Model Concept

1. Convolutional Layer을 이용하여, 이미지를 Feature Map으로 바꾼다



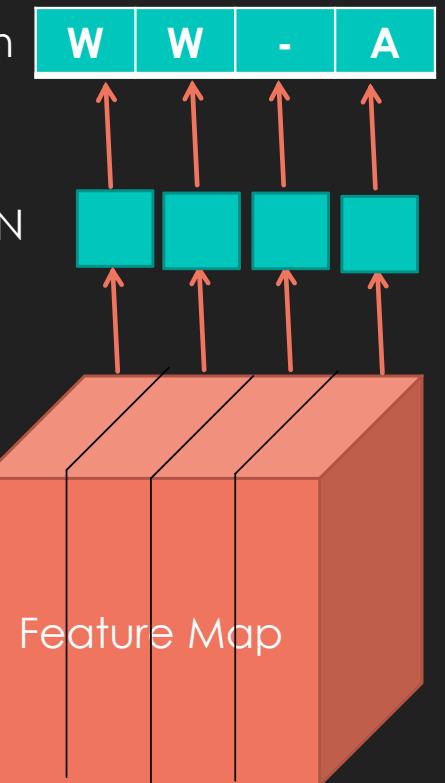
## 2. 모델선정 이유와 전략(CRNN)

### ○ Model Concept

#### 2. Recurrent Layer frame별로 예측

이때, 각각의 부분들의 크기를 같게 맞춰주고 RNN에 넣는다.

Per-frame prediction



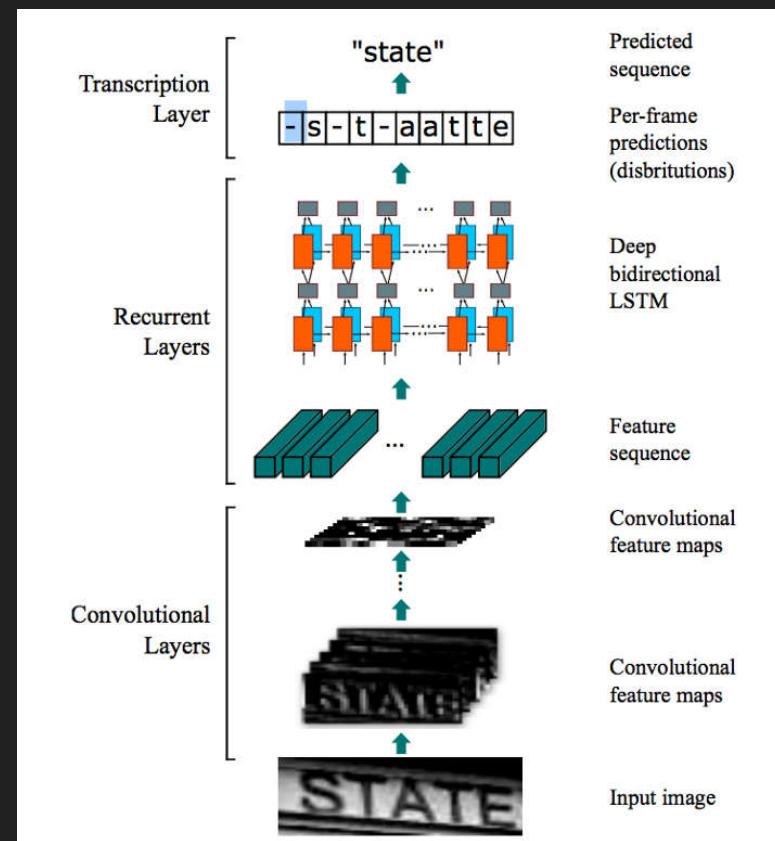
## 2. 모델선정 이유와 전략(CRNN)

- Model Concept
- 3. Transcription Layer



## 2. 모델선정 이유와 전략(CRNN)

### ○ Model Architecture



### 3. 데이터 준비 및 개발과정

# CRNN을 위한 데이터 : 한줄 번호판



- + Sequence로 해석되어야한다.
- + 라벨링은 한글자체를 하나의 라벨로 ( 번호판은 규격에따라 정해진 한글만 있어서  
괜찮음)  
초성,중성나누기는 ? : 밑으로 받침이 들어가면 문제가 생김  
바 ([ㅂ][ㅏ]) 벼([ㅂ][ㅓ]) 보([ㅗ][ㅗ])

# CRNN을 위한 데이터 : 두줄 번호판은 제외하자

+ Sequence로 해석되어야한다.



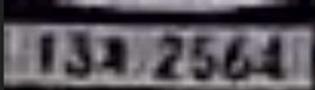
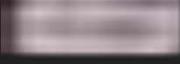
+ 두줄인 번호판을 트레이닝 하려면... :

1. 그냥 이미지를 왼쪽에서 오른쪽으로 스캔 : 같은 시퀀스 스캔 상태에서 (서3)이 같은 스캔범위내에서 classification되기때문에 set으로 묶어 서3을 하나의 class로 구분하여야한다.

2. 빨간색위로 스캔한번 아래로 스캔한번 트레이닝 되어야 한다.

따라서 한줄인 번호판만 하기로했고 그중에서도 일단 P1만 트레이닝 해보았다.

# 지도학습의 문제점 : Trainning data set 검증

- + 정확한 라벨의 이미지로 Trainning 시켜야한다.
- + 깨끗한 이미지만 쓰면 안된다. blurring되거나 변형된 데이터도 라벨을 확인할수 있다면 Trainning 해야한다. - 오버피팅방지
- + 이정도는 되야...  
- + 형체를 알아볼수없는, 라벨을 확인할수없는 너무 작은 바운딩 박스, 글자가 아예가려진 데이터는 안된다. 이런데이터는 라벨이 없는 데이터인데 학습시키면 안된다는 것  

# 지도학습의 문제점 : 잘못된 데이터에 취약

```
</object>
<object>
  <name>P1_23구6044</name>
  <pose>Unspecified</pose>
  <truncated>0</truncated>
  <difficult>0</difficult>
  - <bndbox>
    <xmin>720</xmin>
    <ymin>211</ymin>
    <xmax>728</xmax>
    <ymax>211</ymax>
  </bndbox>
```

error name  
P!\_10리0284\_27.png P!\_10리0284

+ !로 라벨링한 분들...

+ '투'라는 번호판은 없는데 잘못 읽으신 분들...

+ 바운딩 박스를 잘못그리신 분들...

error name  
P1\_28투0145\_90.png P1\_28투0145

```
<path>C:\Users\daegeun\Desktop\08_12121609\24_24917_0290550.png</path>
<source>
  <database>Unknown</database>
</source>
<size>
  <width>1920</width>
  <height>1080</height>
  <depth>3</depth>
</size>
<segmented>0</segmented>
<object>
  <name>P1_51라9883</name>
  <pose>Unspecified</pose>
  <truncated>0</truncated>
  <difficult>0</difficult>
  - <bndbox>
    <xmin>710</xmin>
    <ymin>211</ymin>
    <xmax>725</xmax>
    <ymax>211</ymax>
  </bndbox>
```

# 데이터 모으기...

+ P1만

```
    continue  
if plateKind != "P1":
```

+ 번호판 규격 데이터만

```
if de_En_codeSystem.isContainHangulKey(hangul)==False:#번호판 mapping 없으면 데이터제외
```

+ 번호판 이상하게 쓰신분들...데이터제외

```
#박스의 x,y좌표가 같은사람들....
```

```
if boxes[sub_idx][1]==boxes[sub_idx][3] or boxes[sub_idx][0]==boxes[sub_idx][2]:  
    continue
```

+ 좀 큰(식별되는) 번호판만

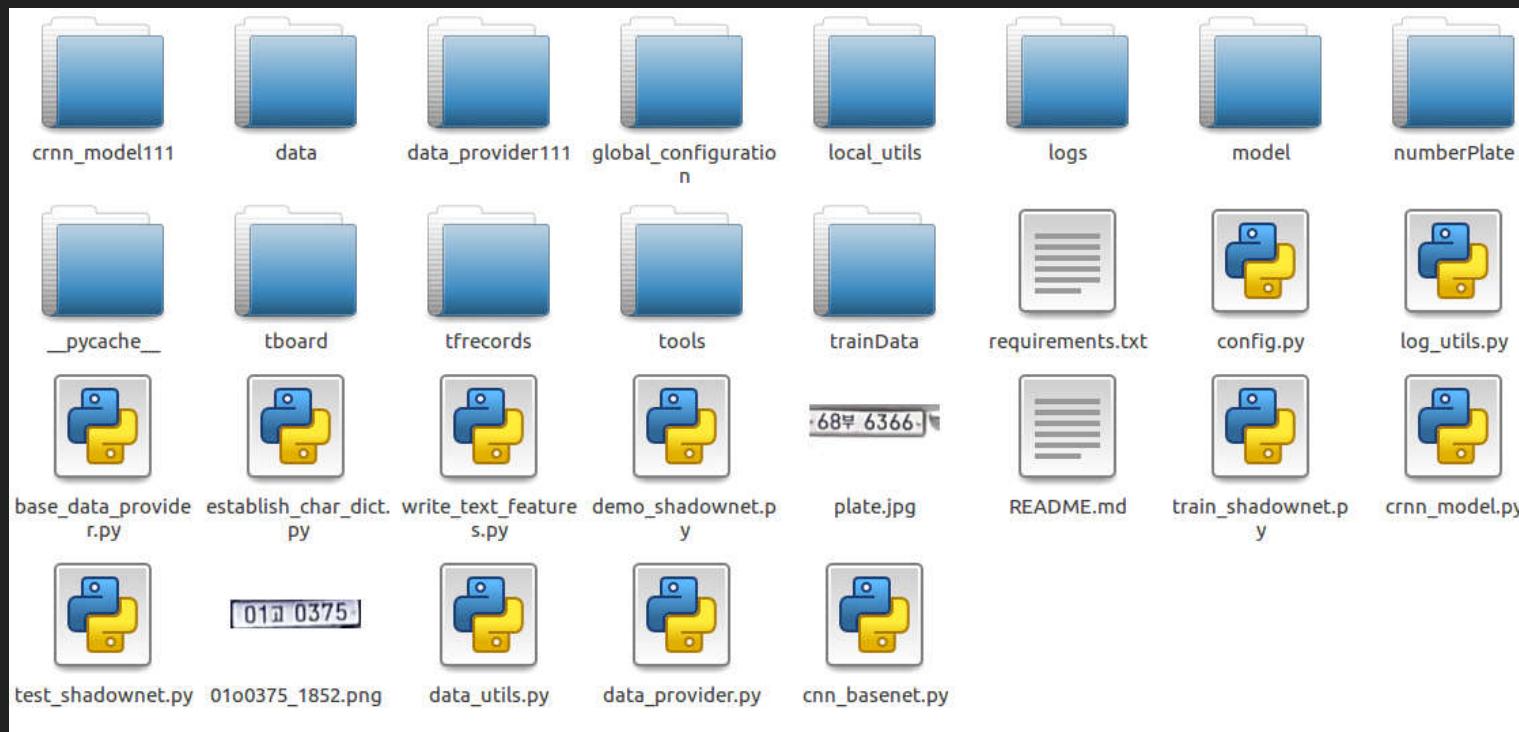
```
boxSquare=(boxes[sub_idx][3]-boxes[sub_idx][1]) * (boxes[sub_idx][2]-boxes[sub_idx][0])  
if boxSquare<2300:  
    continue
```

+ 숫자아닌 이상한거 쓴분들...데이터제외

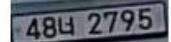
```
#숫자아닌걸로 써는사람들...
```

```
if char4<'0' or '9'<char4:
```

# 개발과정\_CRNN



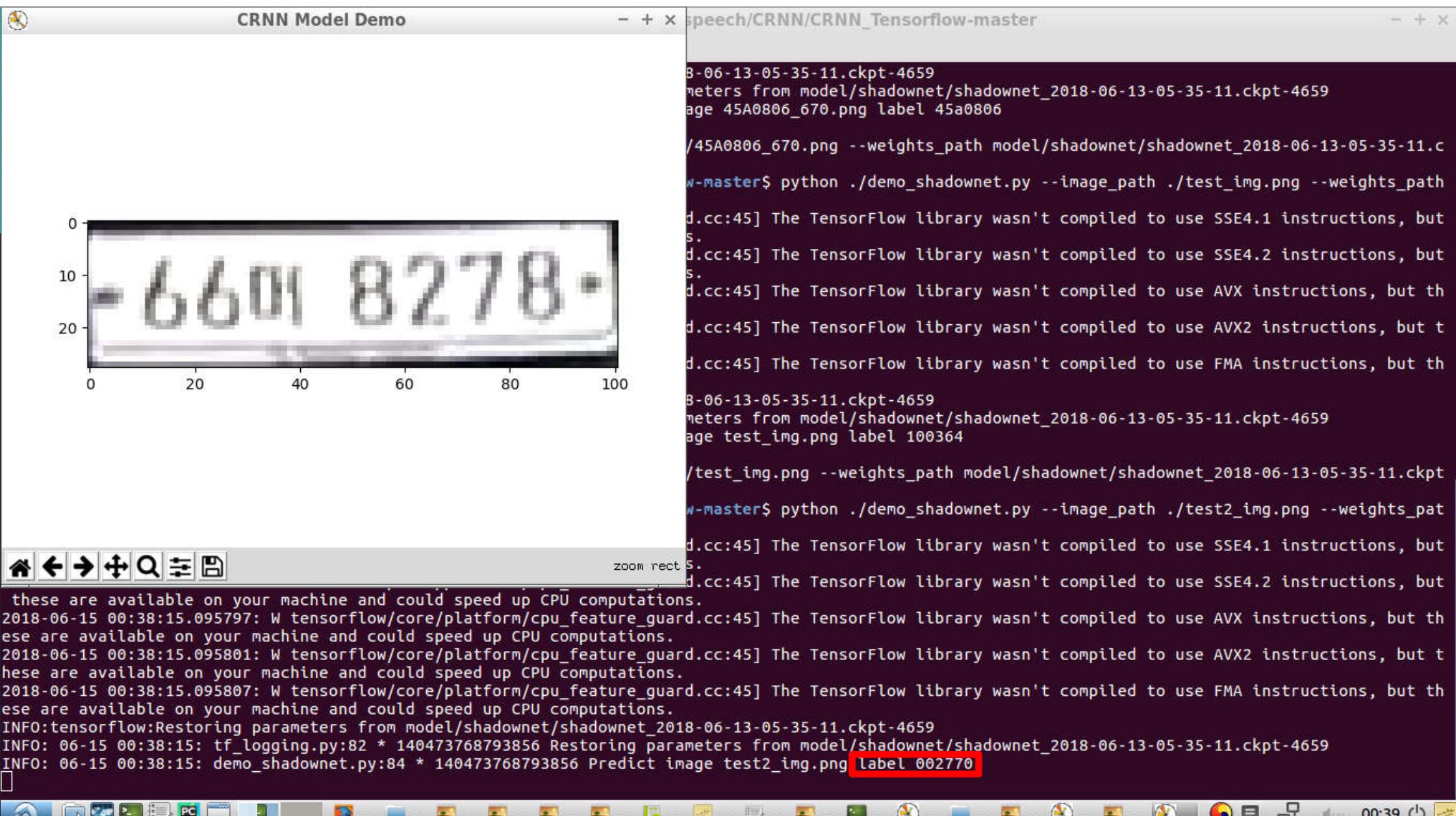
○ CRNN 폴더의 첫 모습

	sample.txt	58o8884_494.png	29i7287_336.png	15w9635_433.png	53w7774_487.png	03o0825_340.png	60j4815_516.png	92z0341_460.png	53j2500_606.png
	57g5981_521.png	63A6141_470.png	23r2012_495.png	61d5278_476.png	52m2707_395.png	12f0515_510.png	04n0467_431.png	63c2297_473.png	14m2346_505.png
	48u2795_466.png	42F8807_411.png	45A0806_670.png	49x9922_246.png	41k8346_467.png	33B6226_279.png	60d6386_558.png	87l7576_330.png	95i1973_546.png
	43n6070_444.png	15n5186_320.png	82D7146_235.png	79D3156_504.png	50g4452_38.png	11b1675_439.png	89h3409_217.png	84l7626_251.png	10K8259_436.png
	53p4403_410.png	22B7853_459.png	56r6846_316.png	92r4080_920.png	19u9106_455.png	31l6722_536.png	11J9821_842.png	45r6978_449.png	77z9735_858.png

# 개발과정\_CRNN

```
(AT_project) yun@itlab-server98:~/AI_project_speech/CRNN/CRNN_Tensorflow-master$ python ./write_text_features --dataset_dir ./numberPlate --save_dir ./tfrecords
```

- Tensorflow로 실행시키기 전, data 전처리



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```
#!/usr/bin/env python
# -*- coding: utf-8 -*-
# @Time    : 17-9-22 下午3:25
# @Author  : Luo Yao
# @Site   : http://github.com/TJCVRS
# @File    : config.py
# @IDE: PyCharm Community Edition
"""
Set some global configuration
"""
from easydict import EasyDict as edict

__C = edict()
# Consumers can get config by: from config import cfg

cfg = __C

# Train options
__C.TRAIN = edict()

# Set the shadownet training epochs
__C.TRAIN.EPOCHS = 40000
# Set the display step
__C.TRAIN.DISPLAY_STEP = 1
# Set the test display step during training process
__C.TRAIN.TEST_DISPLAY_STEP = 100
# Set the momentum parameter of the optimizer
__C.TRAIN.MOMENTUM = 0.9
# Set the initial learning rate
__C.TRAIN.LEARNING_RATE = 0.1
# Set the GPU resource used during training process
__C.TRAIN.GPU_MEMORY_FRACTION = 0.85
# Set the GPU allow growth parameter during tensorflow training process
__C.TRAIN.TF_ALLOW_GROWTH = True
# Set the shadownet training batch size
__C.TRAIN.BATCH_SIZE = 32
# Set the shadownet validation batch size
```

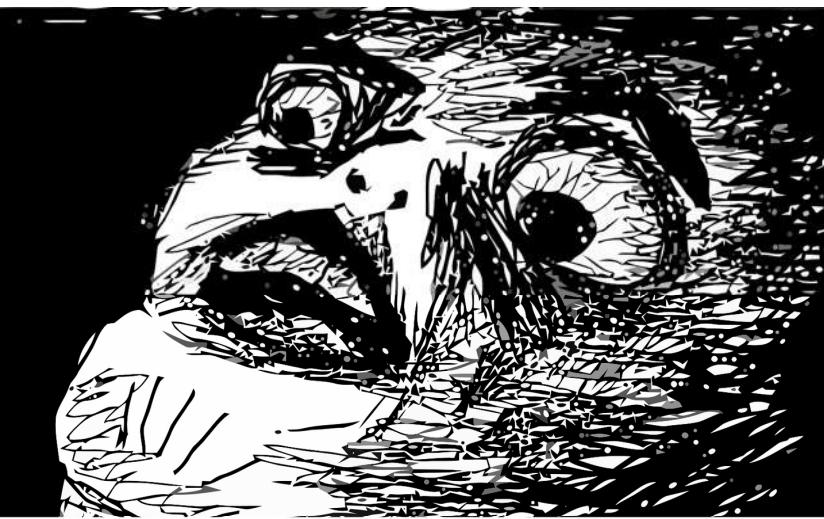
 GitHub - Maybe... [1. crnn -> 과정 ...] [yu]

○ 'Config' 파일을 통해 EPOCHS 값 수정

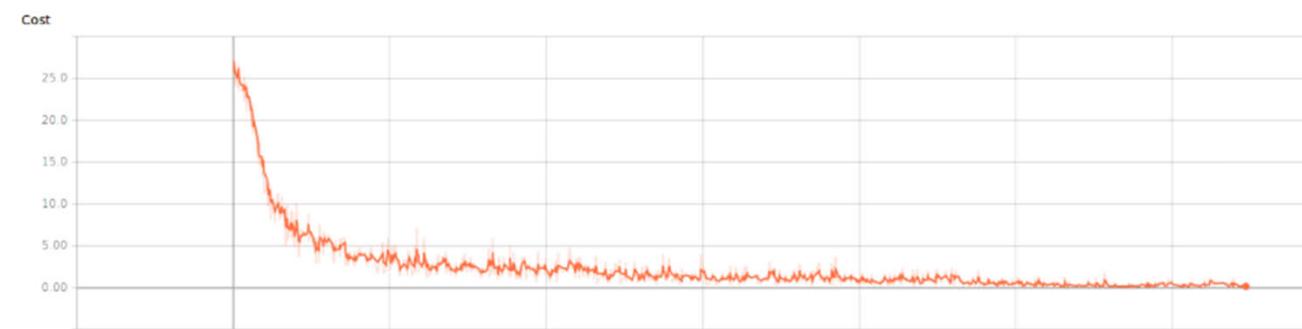
yun@itlab-server98: ~/AI\_project\_speech/CRNN/CRNN\_Tensorflow-master

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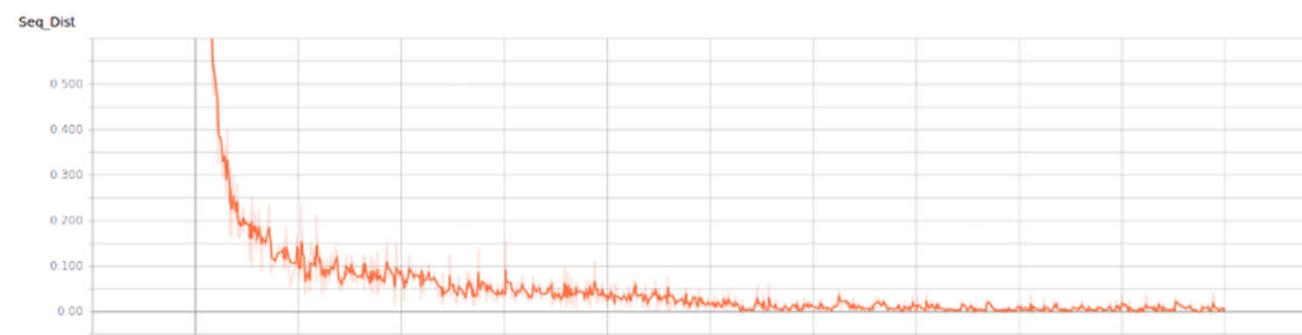
```
INFO: 06-14 22:46:48: train_shadownet.py:152 * 139659819460352 Epoch: 2 cost= 56.126884 seq distance= 1.214286 train accuracy= 0.053571
INFO: 06-14 22:46:50: train_shadownet.py:152 * 139659819460352 Epoch: 3 cost= 39.882992 seq distance= 0.879464 train accuracy= 0.044643
INFO: 06-14 22:46:52: train_shadownet.py:152 * 139659819460352 Epoch: 4 cost= 30.298731 seq distance= 0.915179 train accuracy= 0.013393
INFO: 06-14 22:46:55: train_shadownet.py:152 * 139659819460352 Epoch: 5 cost= 27.258877 seq distance= 0.897321 train accuracy= 0.008929
INFO: 06-14 22:46:57: train_shadownet.py:152 * 139659819460352 Epoch: 6 cost= 26.220751 seq distance= 0.955357 train accuracy= 0.004464
INFO: 06-14 22:46:59: train_shadownet.py:152 * 139659819460352 Epoch: 7 cost= 25.592739 seq distance= 0.964286 train accuracy= 0.008929
INFO: 06-14 22:47:02: train_shadownet.py:152 * 139659819460352 Epoch: 8 cost= 25.110500 seq distance= 0.950893 train accuracy= 0.004464
INFO: 06-14 22:47:04: train_shadownet.py:152 * 139659819460352 Epoch: 9 cost= 24.964756 seq distance= 0.955357 train accuracy= 0.017857
INFO: 06-14 22:47:06: train_shadownet.py:152 * 139659819460352 Epoch: 10 cost= 24.979609 seq distance= 0.959821 train accuracy= 0.013393
INFO: 06-14 22:47:09: train_shadownet.py:152 * 139659819460352 Epoch: 11 cost= 24.594109 seq distance= 0.919643 train accuracy= 0.008929
INFO: 06-14 22:47:11: train_shadownet.py:152 * 139659819460352 Epoch: 12 cost= 24.212904 seq distance= 0.946429 train accuracy= 0.013393
INFO: 06-14 22:47:13: train_shadownet.py:152 * 139659819460352 Epoch: 13 cost= 24.158167 seq distance= 0.933036 train accuracy= 0.000000
INFO: 06-14 22:47:16: train_shadownet.py:152 * 139659819460352 Epoch: 14 cost= 23.773846 seq distance= 0.928571 train accuracy= 0.017857
INFO: 06-14 22:47:18: train_shadownet.py:152 * 139659819460352 Epoch: 15 cost= 23.592751 seq distance= 0.946429 train accuracy= 0.017857
INFO: 06-14 22:47:20: train_shadownet.py:152 * 139659819460352 Epoch: 16 cost= 23.745987 seq distance= 0.941964 train accuracy= 0.008929
INFO: 06-14 22:47:23: train_shadownet.py:152 * 139659819460352 Epoch: 17 cost= 23.574177 seq distance= 0.950893 train accuracy= 0.017857
INFO: 06-14 22:47:25: train_shadownet.py:152 * 139659819460352 Epoch: 18 cost= 23.406982 seq distance= 0.950893 train accuracy= 0.000000
INFO: 06-14 22:47:27: train_shadownet.py:152 * 139659819460352 Epoch: 19 cost= 22.933498 seq distance= 0.941964 train accuracy= 0.013393
INFO: 06-14 22:47:30: train_shadownet.py:152 * 139659819460352 Epoch: 20 cost= 23.201078 seq distance= 0.933036 train accuracy= 0.031250
INFO: 06-14 22:47:32: train_shadownet.py:152 * 139659819460352 Epoch: 21 cost= 23.232277 seq distance= 0.950893 train accuracy= 0.004464
INFO: 06-14 22:47:35: train_shadownet.py:152 * 139659819460352 Epoch: 22 cost= 23.004635 seq distance= 0.946429 train accuracy= 0.013393
INFO: 06-14 22:47:37: train_shadownet.py:152 * 139659819460352 Epoch: 23 cost= 23.311407 seq distance= 0.933036 train accuracy= 0.031250
INFO: 06-14 22:47:39: train_shadownet.py:152 * 139659819460352 Epoch: 24 cost= 23.026693 seq distance= 0.955357 train accuracy= 0.000000
INFO: 06-14 22:47:42: train_shadownet.py:152 * 139659819460352 Epoch: 25 cost= 23.105705 seq distance= 0.946429 train accuracy= 0.008929
INFO: 06-14 22:47:44: train_shadownet.py:152 * 139659819460352 Epoch: 26 cost= 22.804663 seq distance= 0.950893 train accuracy= 0.022321
INFO: 06-14 22:47:46: train_shadownet.py:152 * 139659819460352 Epoch: 27 cost= 22.860863 seq distance= 0.928571 train accuracy= 0.008929
INFO: 06-14 22:47:49: train_shadownet.py:152 * 139659819460352 Epoch: 28 cost= 22.625650 seq distance= 0.924107 train accuracy= 0.031250
INFO: 06-14 22:47:51: train_shadownet.py:152 * 139659819460352 Epoch: 29 cost= 22.853930 seq distance= 0.933036 train accuracy= 0.022321
INFO: 06-14 22:47:53: train_shadownet.py:152 * 139659819460352 Epoch: 30 cost= 22.558969 seq distance= 0.928571 train accuracy= 0.004464
INFO: 06-14 22:47:56: train_shadownet.py:152 * 139659819460352 Epoch: 31 cost= 22.747505 seq distance= 0.941964 train accuracy= 0.017857
INFO: 06-14 22:47:58: train_shadownet.py:152 * 139659819460352 Epoch: 32 cost= 22.340515 seq distance= 0.915179 train accuracy= 0.013393
INFO: 06-14 22:48:00: train_shadownet.py:152 * 139659819460352 Epoch: 33 cost= 22.484076 seq distance= 0.950893 train accuracy= 0.013393
INFO: 06-14 22:48:03: train_shadownet.py:152 * 139659819460352 Epoch: 34 cost= 22.440865 seq distance= 0.924107 train accuracy= 0.017857
INFO: 06-14 22:48:05: train_shadownet.py:152 * 139659819460352 Epoch: 35 cost= 22.427692 seq distance= 0.928571 train accuracy= 0.026786
INFO: 06-14 22:48:07: train_shadownet.py:152 * 139659819460352 Epoch: 36 cost= 22.171822 seq distance= 0.933036 train accuracy= 0.017857
INFO: 06-14 22:48:10: train_shadownet.py:152 * 139659819460352 Epoch: 37 cost= 22.364008 seq distance= 0.937500 train accuracy= 0.022321
INFO: 06-14 22:48:12: train_shadownet.py:152 * 139659819460352 Epoch: 38 cost= 22.343708 seq distance= 0.937500 train accuracy= 0.004464
INFO: 06-14 22:48:15: train_shadownet.py:152 * 139659819460352 Epoch: 39 cost= 22.284977 seq distance= 0.906250 train accuracy= 0.026786
INFO: 06-14 22:48:17: train_shadownet.py:152 * 139659819460352 Epoch: 40 cost= 22.412735 seq distance= 0.950893 train accuracy= 0.017857
```



During my experiment the loss drops as follows



The distance between the ground truth and the prediction drops as follows



~/AI\_project\_speech/CRNN/CRNN\_Tensorflow-master

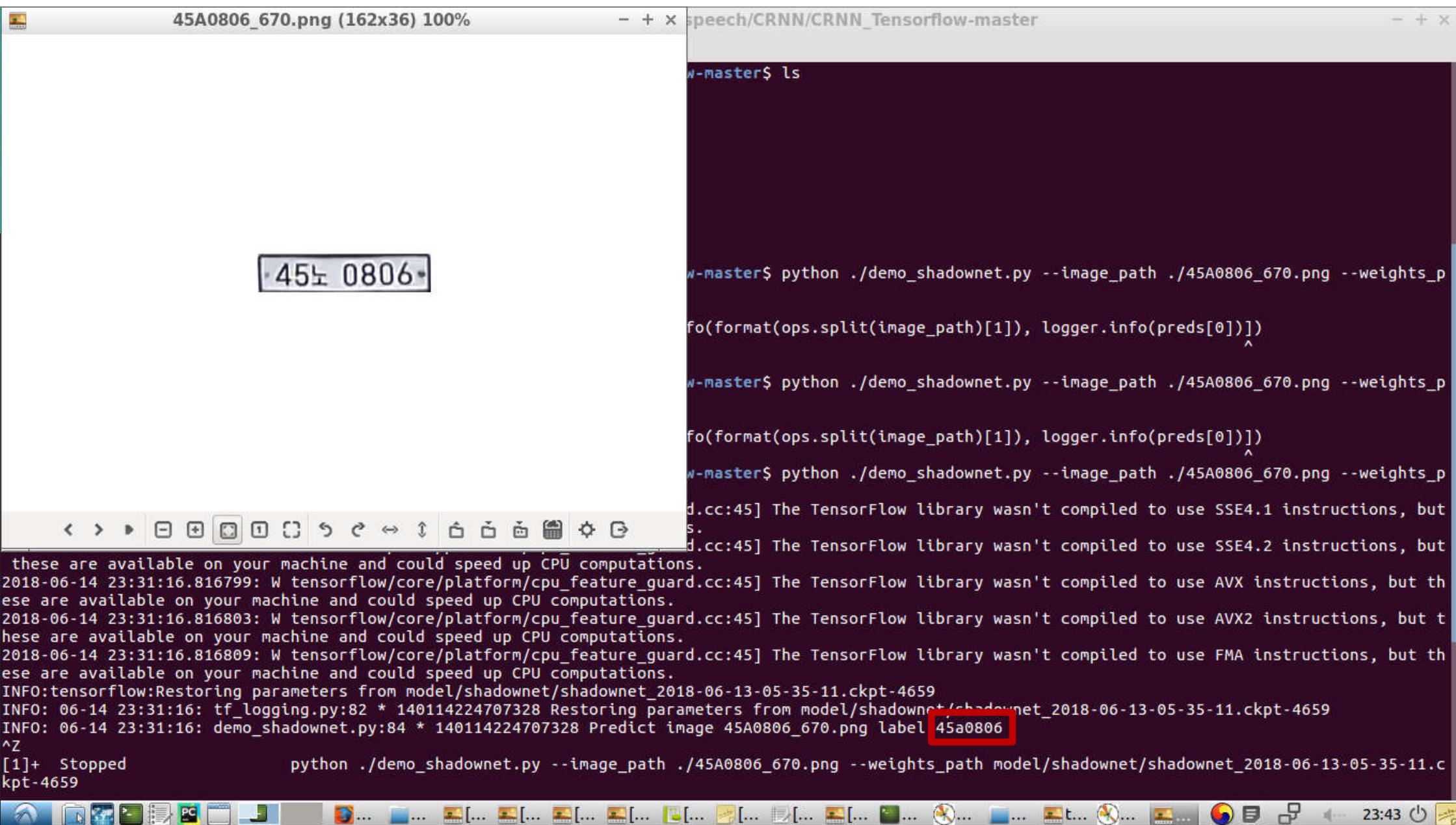
```
5616 Epoch: 2 cost= 0.558493 seq distance= 0.026786 train accuracy= 0.897321
5616 Epoch: 3 cost= 0.478799 seq distance= 0.008929 train accuracy= 0.991071
5616 Epoch: 4 cost= 0.341261 seq distance= 0.008929 train accuracy= 0.977679
5616 Epoch: 5 cost= 0.661102 seq distance= 0.022321 train accuracy= 0.937500
5616 Epoch: 6 cost= 0.490162 seq distance= 0.026786 train accuracy= 0.924107
5616 Epoch: 7 cost= 0.526102 seq distance= 0.013393 train accuracy= 0.950893
5616 Epoch: 8 cost= 0.576091 seq distance= 0.013393 train accuracy= 0.973214
5616 Epoch: 9 cost= 0.403551 seq distance= 0.008929 train accuracy= 0.955357
5616 Epoch: 10 cost= 0.403516 seq distance= 0.008929 train accuracy= 0.991071
5616 Epoch: 11 cost= 0.429775 seq distance= 0.013393 train accuracy= 0.986607
5616 Epoch: 12 cost= 0.432648 seq distance= 0.008929 train accuracy= 0.968750
5616 Epoch: 13 cost= 0.446549 seq distance= 0.013393 train accuracy= 0.986607
5616 Epoch: 14 cost= 0.500075 seq distance= 0.008929 train accuracy= 0.991071
5616 Epoch: 15 cost= 0.451168 seq distance= 0.004464 train accuracy= 0.995536
5616 Epoch: 16 cost= 0.477360 seq distance= 0.008929 train accuracy= 0.991071
      seq distance= 0.008929 train accuracy= 0.991071
      seq distance= 0.004464 train accuracy= 0.977679
      seq distance= 0.013393 train accuracy= 0.973214
      seq distance= 0.004464 train accuracy= 0.995536
      seq distance= 0.022321 train accuracy= 0.928571
      seq distance= 0.008929 train accuracy= 0.968750
      seq distance= 0.004464 train accuracy= 0.977679
      seq distance= 0.008929 train accuracy= 0.973214
      seq distance= 0.008929 train accuracy= 0.973214
      seq distance= 0.004464 train accuracy= 0.991071
      seq distance= 0.008929 train accuracy= 0.977679
      seq distance= 0.004464 train accuracy= 0.973214
      seq distance= 0.017857 train accuracy= 0.946429
      seq distance= 0.022321 train accuracy= 0.941964
      seq distance= 0.017857 train accuracy= 0.982143
      seq distance= 0.004464 train accuracy= 0.995536
      seq distance= 0.008929 train accuracy= 0.968750
      seq distance= 0.008929 train accuracy= 0.991071
      seq distance= 0.008929 train accuracy= 0.991071
      seq distance= 0.017857 train accuracy= 0.982143
      seq distance= 0.004464 train accuracy= 0.995536
      seq distance= 0.004464 train accuracy= 0.973214
      seq distance= 0.017857 train accuracy= 0.964286
      seq distance= 0.008929 train accuracy= 0.991071
      seq distance= 0.000000 train accuracy= 1.000000
```

(~/... yun@itlab-se... checkpoint 22:54)

# 개발과정\_CRNN

shadownet_2018-06 -13-05-35-11.ckpt-46 59.data-00000-of...	shadownet_2018-06 -13-05-35-11.ckpt-46 58.data-00000-of...	shadownet_2018-06 -13-05-35-11.ckpt-46 57.data-00000-of...	shadownet_2018-06 -13-05-35-11.ckpt-46 56.data-00000-of...	shadownet_2018-06 -13-05-35-11.ckpt-46 55.data-00000-of...	shadownet_2018-06 -13-05-35-11.ckpt-46 59.meta	shadownet_2018-06 -13-05-35-11.ckpt-46 58.meta	shadownet_2018-06 -13-05-35-11.ckpt-46 57.meta	
								checkpoint
shadownet_2018-06 -13-05-35-11.ckpt-46 56.meta	shadownet_2018-06 -13-05-35-11.ckpt-46 55.meta	shadownet_2018-06 -13-05-35-11.ckpt-46 59.index	shadownet_2018-06 -13-05-35-11.ckpt-46 58.index	shadownet_2018-06 -13-05-35-11.ckpt-46 57.index	shadownet_2018-06 -13-05-35-11.ckpt-46 56.index	shadownet_2018-06 -13-05-35-11.ckpt-46 55.index		

○ Model 생성 후 모습

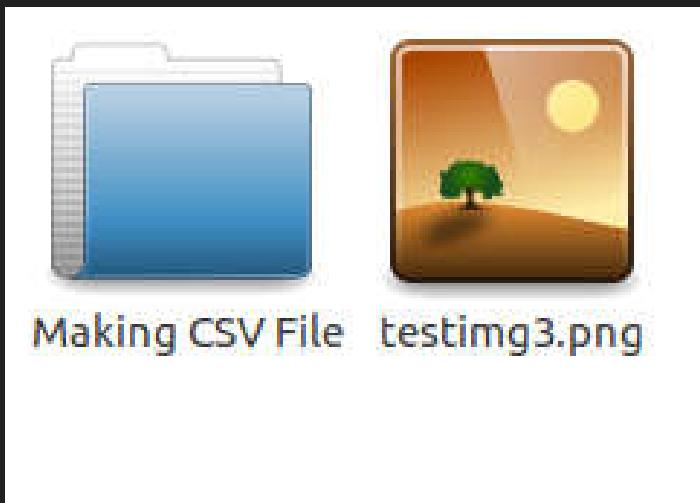


# 개발과정\_CRFNN

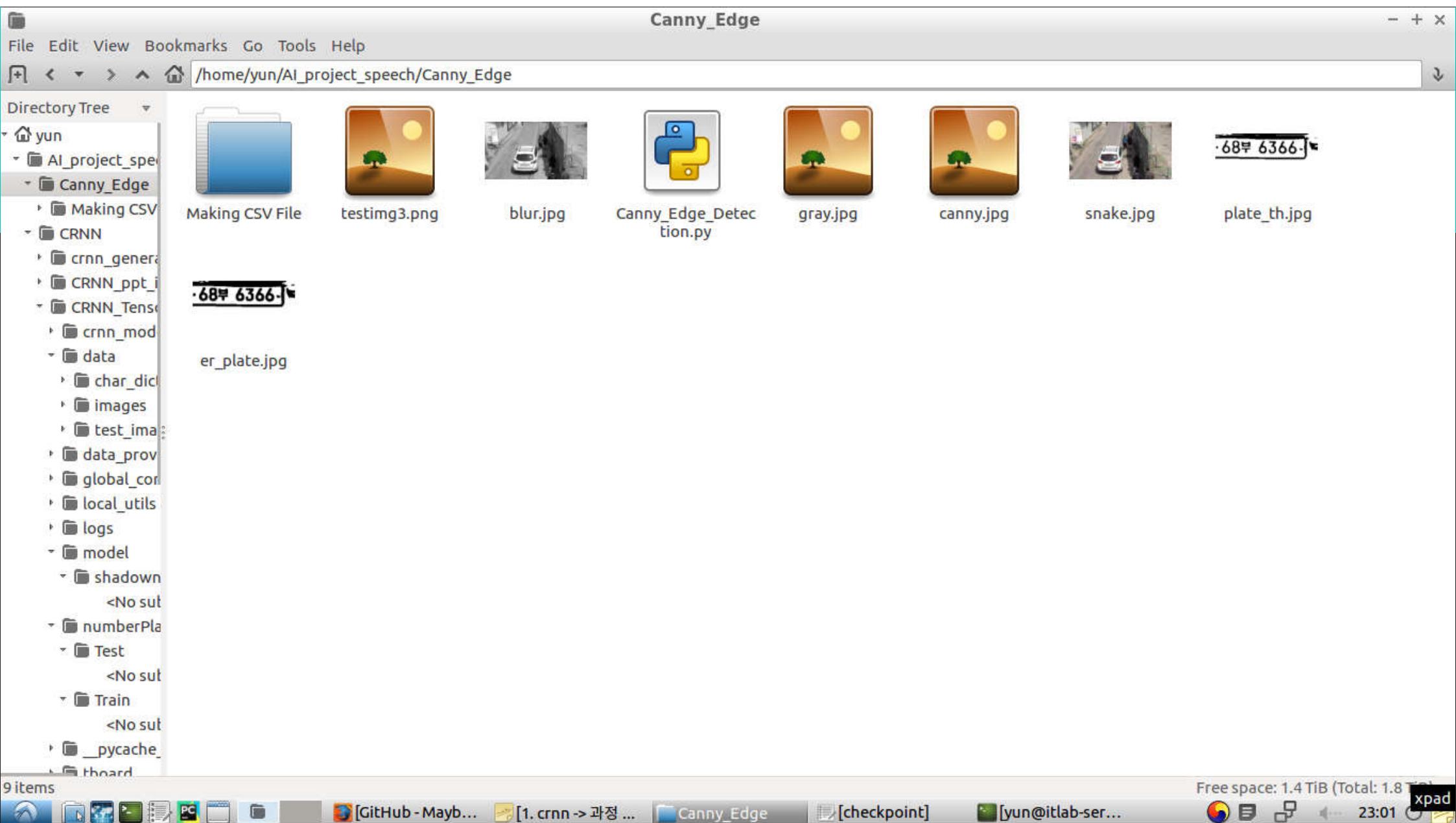
```
{"아": "a", "어": "b", "오": "c", "우": "d", "바": "e", "벼": "f", "보": "g", "부": "h",  
"다": "i", "더": "j", "도": "k", "두": "l", "가": "m", "거": "n", "고": "o", "구": "p",  
"자": "q", "저": "r", "조": "s", "주": "t", "마": "u", "머": "v", "모": "w", "무": "x",  
"나": "y", "너": "z", "노": "A", "누": "B", "라": "C", "러": "D", "로": "E", "루": "F",  
"사": "G", "서": "H", "소": "I", "수": "J", "허": "K"}  
#"ㅓ" : "-","ㅗ" : "-","ㅡ" : "-","ㅣ" : "-","ㅓ" : "-","ㅏ" : "-"
```

- ## ○ 한글-영어 Matching

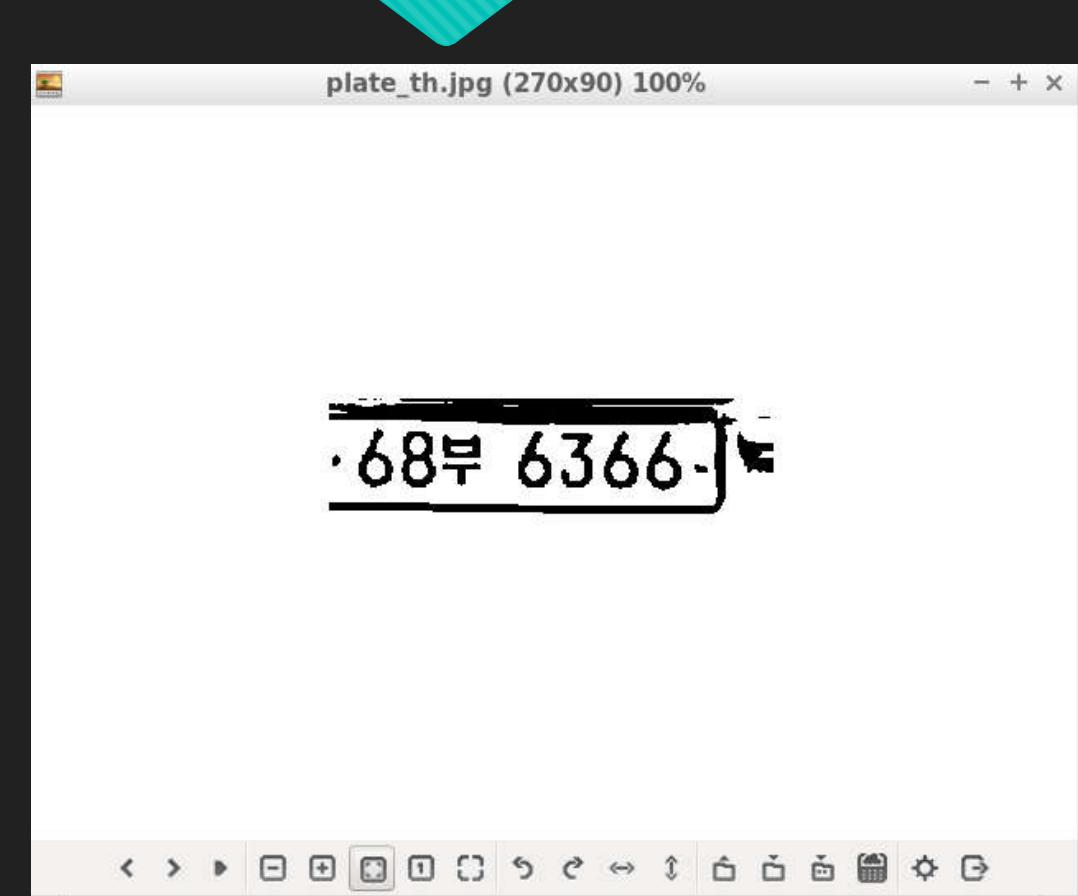
# 개발과정\_Canny Edge



- Canny Edge 폴더의 첫 모습



# 개발과정\_Canny Edge



- Output File의 모습

edit View Search Tools Documents Help

config.py Canny\_Edge\_Detection.py

```
-/bin/etc python

# cv2
# numpy as np
# pytesseract
# PIL import Image

Recognition:
def ExtractNumber(self):
    Number = 'testing3.png'
    img = cv2.imread(Number, cv2.IMREAD_COLOR)
    copy_img = img.copy()
    img2 = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
    cv2.imwrite('gray.jpg', img2)
    blur = cv2.GaussianBlur(img2, (3, 3), 0)
    cv2.imwrite('blur.jpg', blur)
    canny = cv2.Canny(blur, 100, 200)
    cv2.imwrite('canny.jpg', canny)
    cnts, contours, hierarchy = cv2.findContours(canny, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)

    box1 = []
    f_count = 0
    select = 0
    plate_width = 0

    for i in range(len(contours)):
        cnt = contours[i]
        area = cv2.contourArea(cnt)
        x, y, w, h = cv2.boundingRect(cnt)
        rect_area = w * h # area size
        aspect_ratio = float(w) / h # ratio = width/height

        if (aspect_ratio >= 0.2) and (aspect_ratio <= 1.0) and (rect_area >= 100) and (rect_area <= 700):
            cv2.rectangle(img, (x, y), (x + w, y + h), (0, 255, 0), 1)
            box1.append(cv2.boundingRect(cnt))

    return box1
```

○ 하나의 Input File

Python Tab Width: 8 Ln 1, Col 1 22:57 INS

[GitHub - Mayb... [1. crnn->과정 ... Canny Edge Canny\_Edge\_D... [checkpoint]

File Search Tools Documents Help

config.py Canny\_Edge\_Detection.py

```
gradient = float(delta_y) / float(delta_x)
if gradient < 0.25:
    count = count + 1
# measure number plate size
if count > f_count:
    select = m
    f_count = count;
    plate_width = delta_x
    .imwrite('snake.jpg', img)

number_plate = copy_img[box1[select][1] - 10:box1[select][3] + box1[select][1] + 20,
                      box1[select][0] - 10:140 + box1[select][0]]

y_min = box1[select][1] - 10
y_max = box1[select][3] + box1[select][1] + 20
x_min = box1[select][0] - 10
x_max = 140 + box1[select][0]

print(y_min, y_max, x_min, x_max)
```

○ PRINT 추가!

```
size_plate = cv2.resize(number_plate, None, fx=1.8, fy=1.8, interpolation=cv2.INTER_CUBIC + cv2.INTER_LINEAR)
plate_gray = cv2.cvtColor(resize_plate, cv2.COLOR_BGR2GRAY)
_, th_plate = cv2.threshold(plate_gray, 150, 255, cv2.THRESH_BINARY)

.imwrite('plate_th.jpg', th_plate)
kernel = np.ones((3, 3), np.uint8)
plate = cv2.erode(th_plate, kernel, iterations=1)
invplate = er_plate
.imwrite('er_plate.jpg', er_invplate)
result = pytesseract.image_to_string(Image.open('er_plate.jpg'), lang='kor')
return (result.replace(" ", ""))

# Recognition()
# recogtest.ExtractNumber()
# t)
```

Python Tab Width: 8 Ln 1, Col 1 INS

[GitHub - Mayb... [1. crnn -> 과정 ... Canny Edge Canny\_Edge\_D... [checkpoint]

22:58

```
dit View Search Tools Documents Help
y_max = box1[select][1] + box1[select][3] + 20
x_min = box1[select][0] - 10
x_max = 140 + box1[select][0]

#ADDED LINE
output=[x_min, y_min, x_max, y_max]
output_total.append(output)

LINE
print(output_total)
f = open('output.csv', 'w', encoding='utf-8', newline='')
wr = csv.writer(f)
for i in range(0, len(input_list)):
    wr.writerow([input_list[i], output_total[i][0], output_total[i][1], output_total[i][2], output_total[i][3]])
f.close()

resize_plate = cv2.resize(number_plate, None, fx=1.8, fy=1.8, interpolation=cv2.INTER_CUBIC + cv2.INTER_LINEAR)
plate_gray = cv2.cvtColor(resize_plate, cv2.COLOR_BGR2GRAY)
ret, th_plate = cv2.threshold(plate_gray, 150, 255, cv2.THRESH_BINARY)

cv2.imwrite('plate_th.jpg', th_plate)
kernel = np.ones((3, 3), np.uint8)
er_plate = cv2.erode(th_plate, kernel, iterations=1)
er_invplate = er_plate
cv2.imwrite('er_plate.jpg', er_invplate)
result = pytesseract.image_to_string(Image.open('er_plate.jpg'), lang='kor')
return (result.replace(" ", ""))

os.path.dirname(os.path.realpath(__file__))
path = os.listdir(path)
files_png = [i for i in files if i.endswith('.png')]

test = Recognition()
t = recogtest.ExtractNumber(files_png)
t(result)
```

○ 경로 안에 있는 모든 png파일 선택

```

dit View Search Tools Documents Help
select = m
f_count = count;
plate_width = delta_x
cv2.imwrite('snake.jpg', img)

number_plate = copy_img[box1[select][1] - 10:box1[select][3] + box1[select][1] + 20,
                      box1[select][0] - 10:140 + box1[select][0]]

y_min = box1[select][1] - 10
y_max = box1[select][3] + box1[select][1] + 20
x_min = box1[select][0] - 10
x_max = 140 + box1[select][0]

#ADDED LINE
output=[x_min, y_min, x_max, y_max]
output_total.append(output)

```

## ○ 모든 파일에 대해 CSV 기록 및 출력

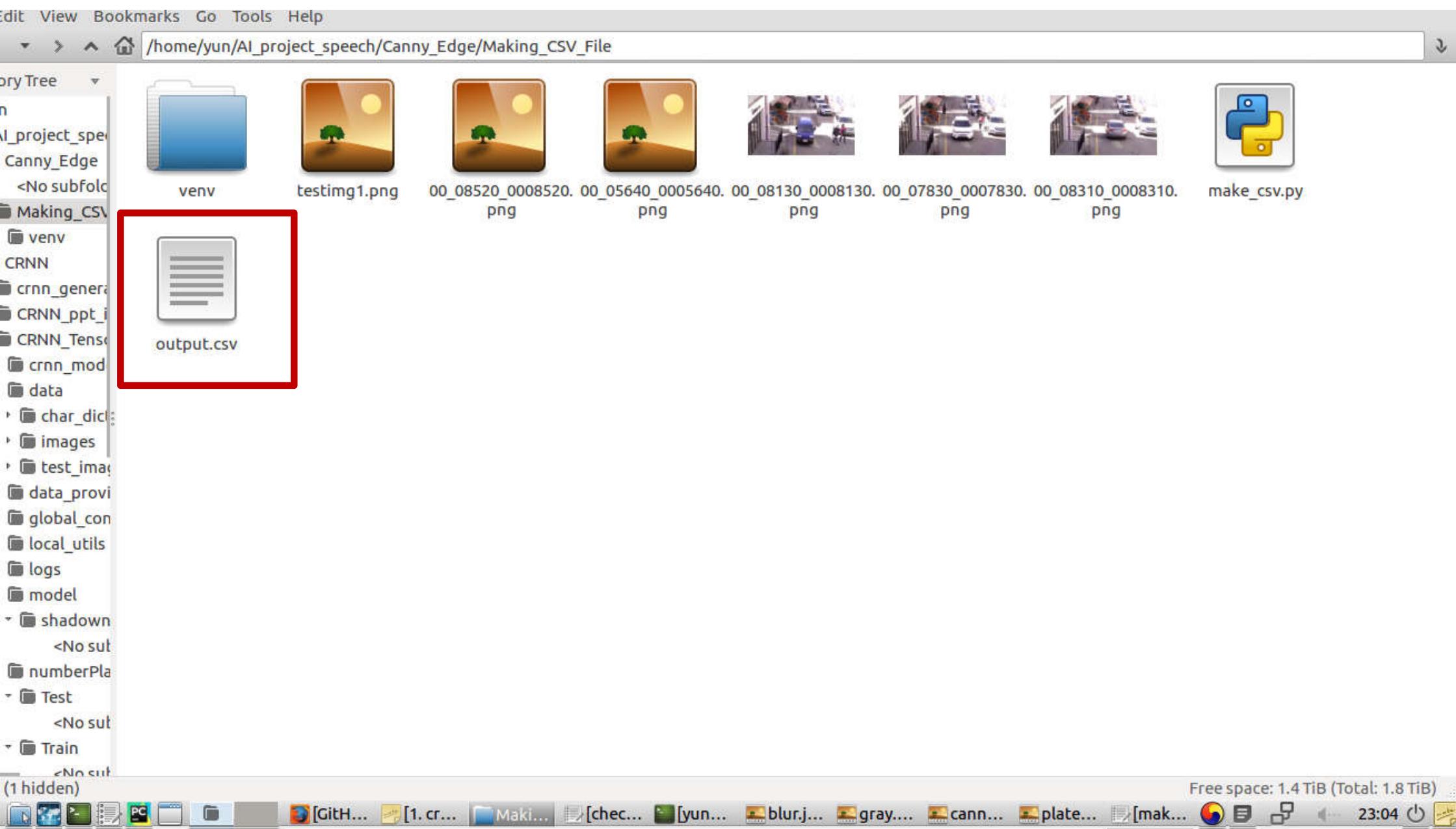
```

print(output_total)
f = open('output.csv', 'w', encoding='utf-8', newline='')
wr = csv.writer(f)
for i in range(0, len(input_list)):
    wr.writerow([input_list[i], output_total[i][0], output_total[i][1], output_total[i][2], output_total[i][3]])
f.close()

resize_plate = cv2.resize(number_plate, None, fx=1.8, fy=1.8, interpolation=cv2.INTER_CUBIC + cv2.INTER_LINEAR)
plate_gray = cv2.cvtColor(resize_plate, cv2.COLOR_BGR2GRAY)
ret, th_plate = cv2.threshold(plate_gray, 150, 255, cv2.THRESH_BINARY)

cv2.imwrite('plate_th.jpg', th_plate)
kernel = np.ones((3, 3), np.uint8)
er_plate = cv2.erode(th_plate, kernel, iterations=1)
er_invplate = er_plate
cv2.imwrite('er_plate.jpg', er_invplate)
result = pytesseract.image_to_string(Image.open('er_plate.jpg'), lang='kor')
return (result.replace(" ", ""))

```



t.csv

$$\text{Sum} = 0$$

## 4. 성능평가

	YOLO v3	canny Edge
fps	11fps	20fps
accuracy	<u>약 50%</u>	약 14%
학습	8시간이상	0시간
필요한메모리	weight의량	이미지한장에서 계산 다소적음
필요한메타데이터	weight의량	없음

## 5. 향후 개선 방향

- 1. Training epoch 증가
- 2. 데이터셋의 증가
- 3. 어두운 데이터 밝기 변화
- 4. 유니코드 맵핑

## 6. QnA