

# CS1011: 數位電子導論

## Introduction

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- ▣ Engineering is inherently interdisciplinary
- ▣ Electrical and Electronic Systems represent a major **enabling technology**
  - ◆ Important to all engineers and scientists
- ▣ A **system approach** to engineering combines
  - ◆ A top-down approach
  - ◆ A bottom-up approach

# Systems

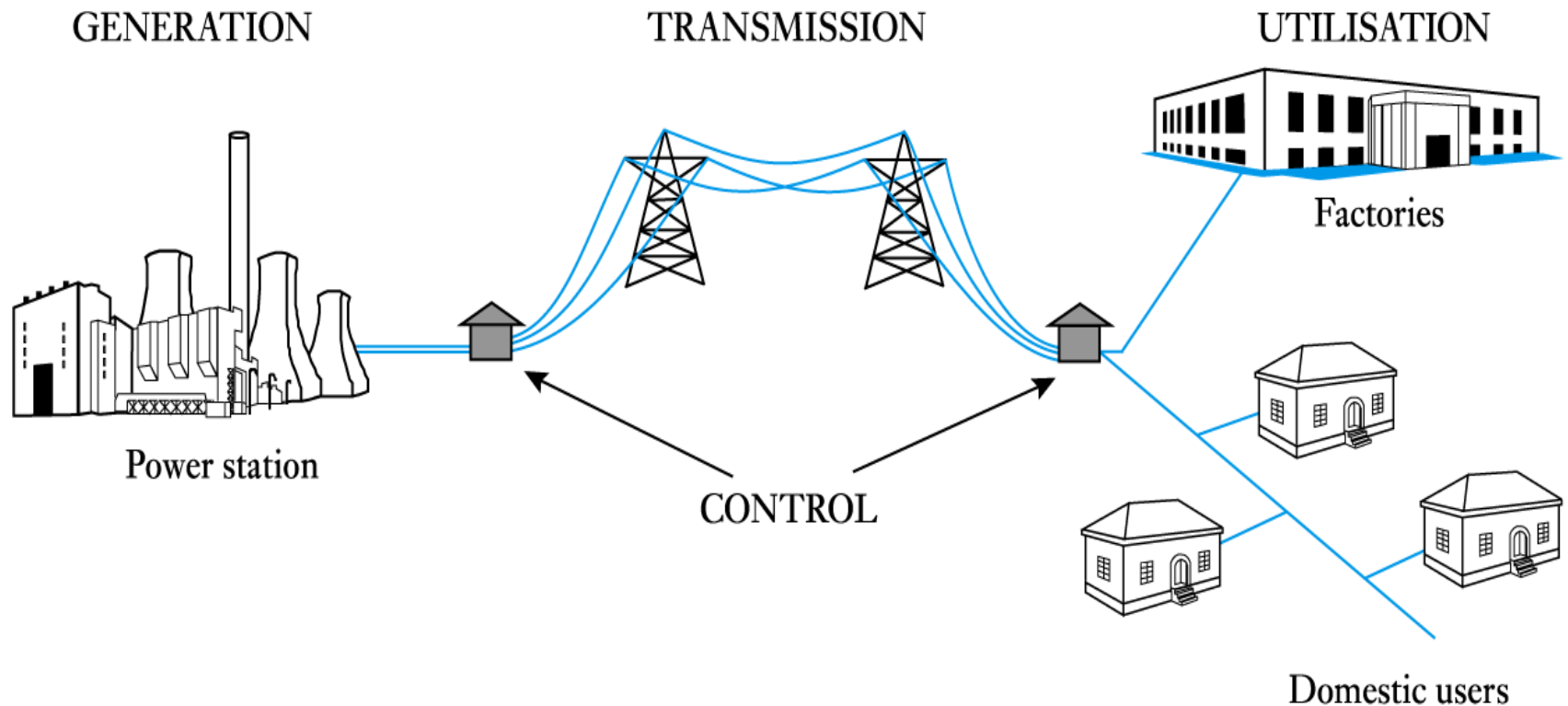
- A system can be defined as
  - Any closed volume for which all the inputs and outputs are known*
- Examples include:
  - ◆ An engine management system
  - ◆ An automotive system
  - ◆ A transportation system
  - ◆ An ecosystem
- Inputs and outputs will reflect the nature of the system

# Electrical and Electronic Systems

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- Basic functions include elements concerned with the manipulation of electrical energy
- Common functions are:
  - ◆ Generation
  - ◆ Transmission of communication
  - ◆ Control or processing
  - ◆ Utilization
  - ◆ Storage

# A Power Distribution System Example

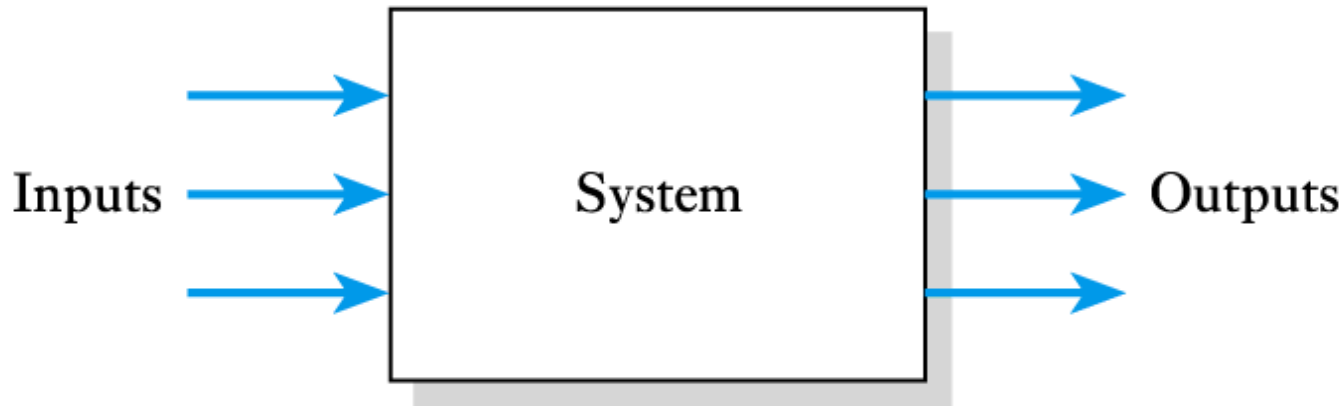


# More System Examples

- **Electrical and electronic systems often fall within a range of categories, such as those responsible for:**
  - ◆ **Power generation and distribution**
  - ◆ **Monitoring of some equipment or process**
  - ◆ **Control of some equipment or process**
  - ◆ **Signal processing**
  - ◆ **Communications**
  - ◆ **...**

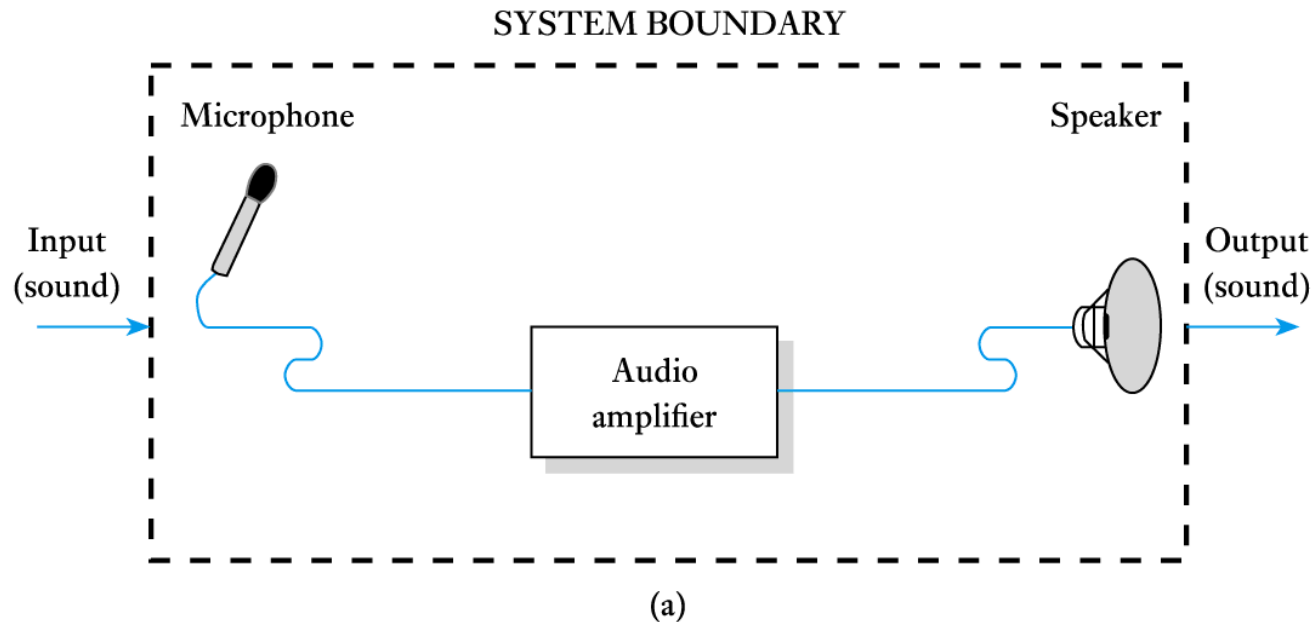
# System Inputs and Outputs

- Systems may often be described simply by their inputs, their output and the relationship between them



# Input/Output Example

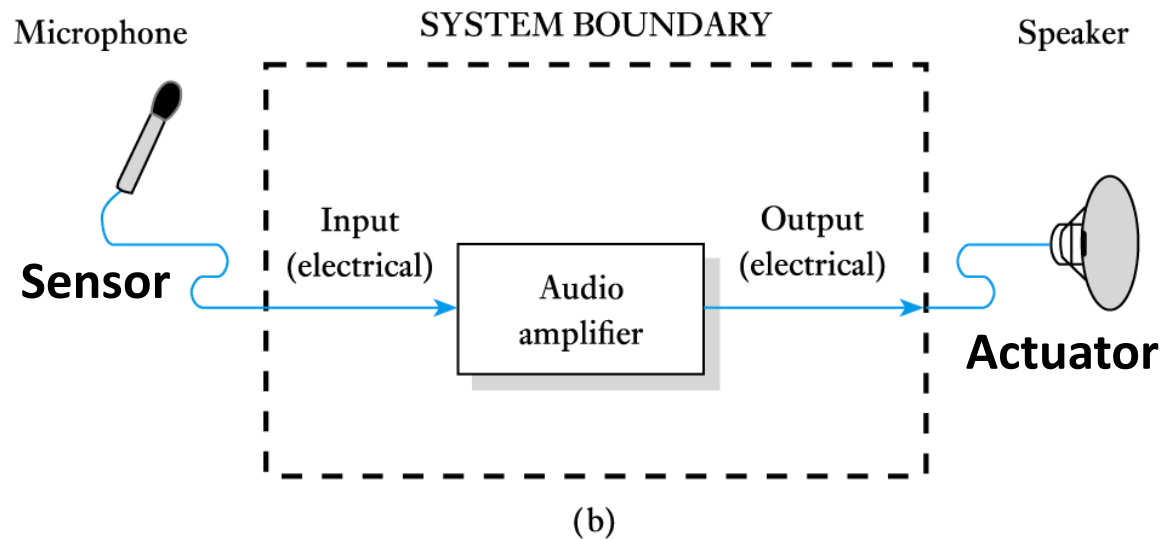
- Nature of inputs/outputs will depend on where we draw our system boundaries. For example:





# System Boundary Could be Changed

- By changing the system boundary we change the nature of the inputs and outputs



# Sensors and Actuators

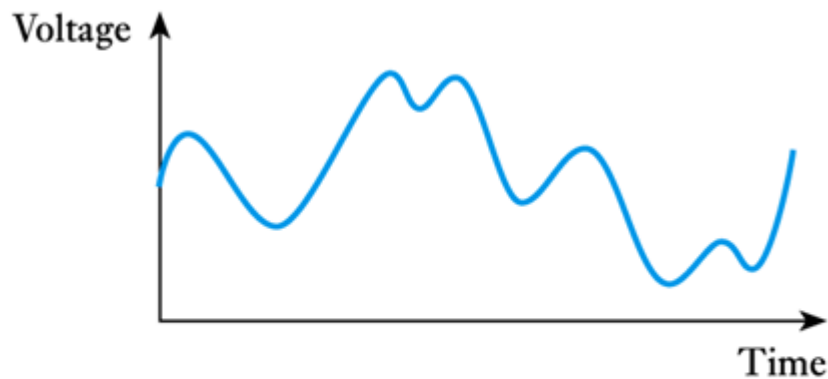
- Components that interact with the outside world are termed **sensors** and **actuators**
  - ◆ In the previous example, the **microphone** represents a sensor
  - ◆ In the previous example, the **loudspeaker** represents an actuator
- We will look at sensors and actuators in more detail in later lectures

# Physical Quantities & Electrical Signals

- The world about us is characterized by a number of **physical properties** or **quantities**
  - ◆ E.g., temperature, pressure, humidity, etc.
- Physical quantities may be **continuous** or **discrete**
- **Continuous quantities** change smoothly and can take an infinite number of values
  - ◆ Most real-world quantities are continuous
- **Discrete quantities** change abruptly from one value to another
  - ◆ Many man-made quantities are discrete

# Analog Signals

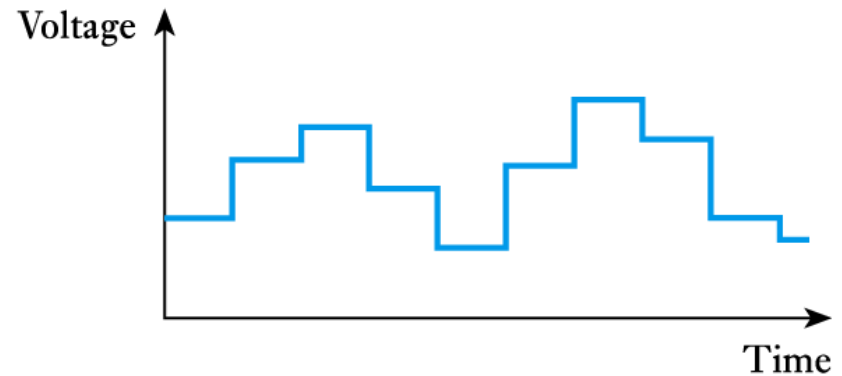
- It is often convenient to represent physical quantities by electrical signals (could be continuous or discrete)
- Continuous signals are often described as **analog signals**



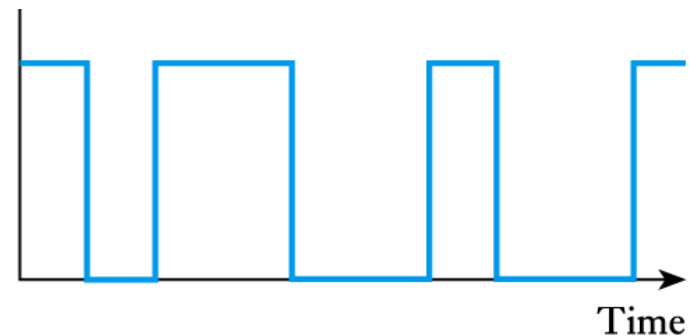
(a) An analog signal

# Digital and Binary Signals

- Discrete signals are often described as **digital signals**
- Many digital signals take only two values and are referred to as **binary signals**



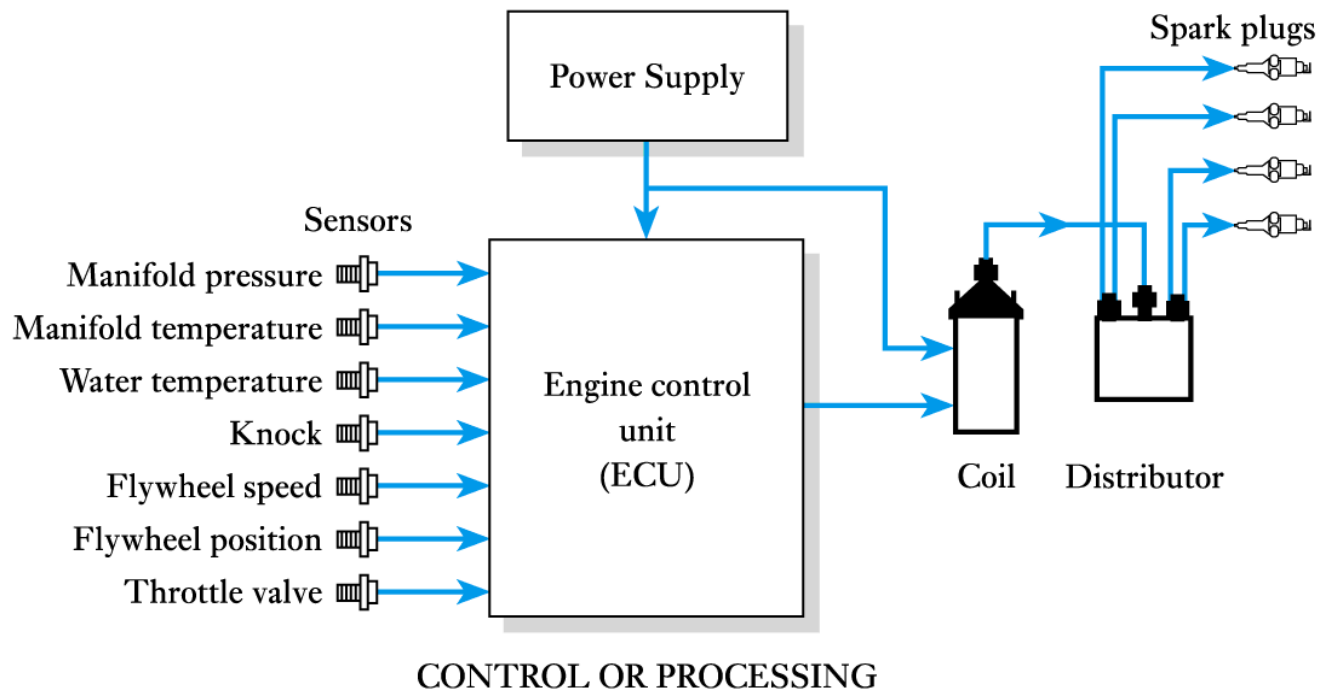
(b) A multi-valued digital signal



(c) A binary signal

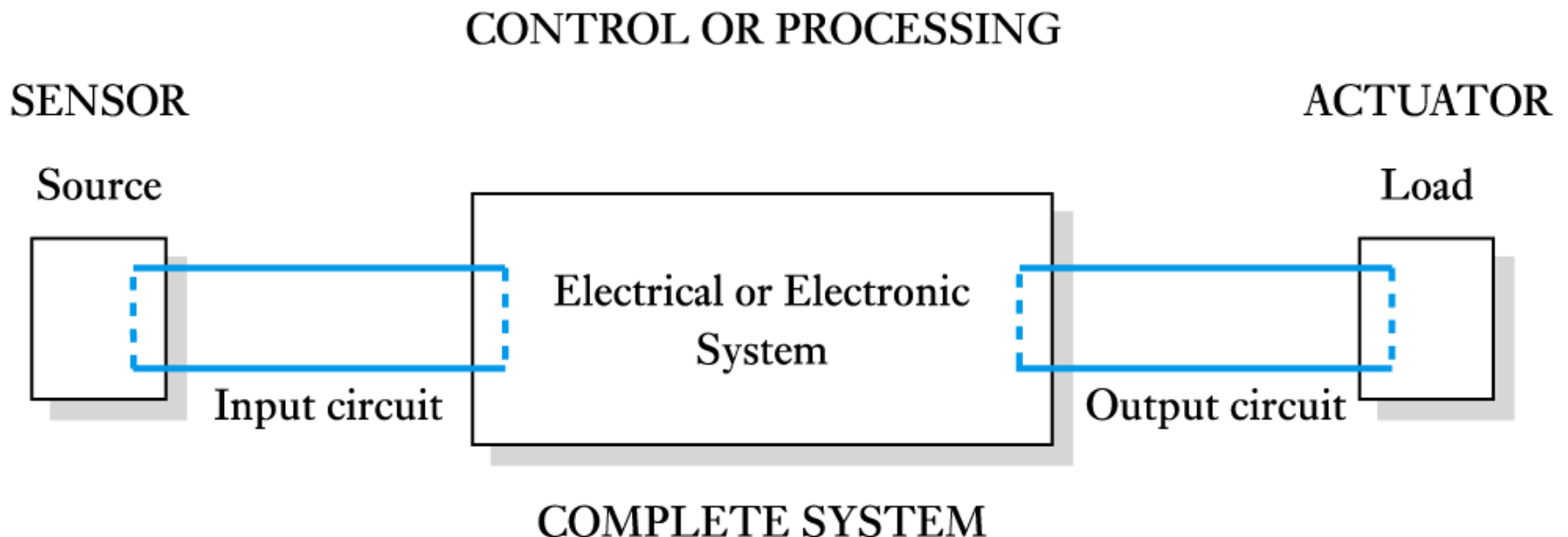
# System Block Diagrams

- It is often convenient to represent complex arrangements by a simplified block diagram



# Source/Load for a Complete System

- In an electrical system, a flow of energy requires a **circuit** - a system with a single input and a single output is shown below
  - ◆ this shows the **input circuit** and the **output circuit**
  - ◆ the sensor represents the **source**
  - ◆ the actuator represents the **load**



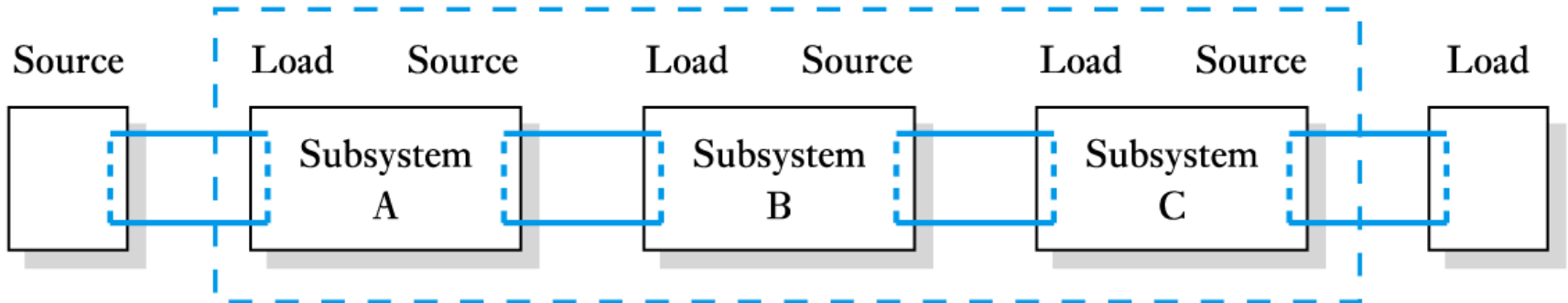
# System Partition for a Complex System

- We often divide complex circuits into subsystems or modules – as shown below
  - ◆ The **output** of each module represents a **source** for the following section
  - ◆ The **input** of each module represents a **load** to the previous section

## COMPLETE SYSTEM

SENSOR

ACTUATOR





# Key Points

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- Engineering is inherently interdisciplinary
- Engineers often adopt a 'systems approach'
- Systems may be defined by their inputs, their outputs and the relationship between them
- Systems interact with the world using sensors and actuators
- Physical quantities can be either continuous or discrete
- Physical quantities are often represented by signals
- Complex systems are often represented by block diagrams