### I03 - Bayesian parameter estimation

STAT 587 (Engineering) Iowa State University

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#### Outline

- Bayesian parameter estimation
  - Condition on what is known
  - Describe belief using probability
  - Terminology
    - ullet Prior o posterior
    - Posterior expectation
    - Credible intervals
  - Binomial example
    - Beta distribution

### A Bayesian statistician

#### Let

- y be the data we will collect from an experiment,
- $\bullet$  K be everything we know for certain about the world (aside from y), and
- $\bullet$   $\theta$  be anything we don't know for certain.

My definition of a Bayesian statistician is an individual who makes decisions based on the probability distribution of those things we don't know conditional on what we know, i.e.

$$p(\theta|y,K)$$
.

Typically, the K is dropped from the notation.

### Bayes' Rule

Bayes' Rule applied to a partition  $P = \{A_1, A_2, \ldots\}$ ,

$$P(A_i|B) = \frac{P(B|A_i)P(A_i)}{P(B)} = \frac{P(B|A_i)P(A_i)}{\sum_{i=1}^{\infty} P(B|A_i)P(A_i)}$$

Bayes' Rule also applies to probability density (or mass) functions. e.g.

$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)} = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$$

where the integral plays the role of the sum in the previous statement.

#### Parameter estimation

Let y be data from some model with unknown parameter (vector)  $\theta$ . Then

$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)} = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$$

and we use the following terminology

Terminology	Notation
Posterior	$p(\theta y)$
Prior	p( heta)
Model (likelihood)	$p(y \theta)$
Prior predictive	p(y)
(marginal likelihood)	

Bayesian parameter estimation involves updating your prior belief about  $\theta$ ,  $p(\theta)$ , into a posterior belief about  $\theta$ ,  $p(\theta|y)$ , based on the data observed.

### Bayesian notation

We now have two distributions for our parameter  $\theta$ : prior and posterior. To distinguish these two, we will have no conditioning in the prior and we will condition on y in the posterior. For example,

	Prior	Posterior
Density	$p(\theta)$	$p(\theta y)$
Expectation	$E[\theta]$	$E[\theta y]$
Variance	$Var[\theta]$	$Var[\theta y]$
<b>Probabilities</b>	$P(\theta < c)$	$P(\theta < c y)$

#### Binomial model

Suppose  $Y \sim Bin(n, \theta)$ , then

$$p(y|\theta) = \binom{n}{y} \theta^y (1-\theta)^{n-y}.$$

A reasonable default prior is the uniform distribution on the interval (0,1)

$$p(\theta) = I(0 < \theta < 1).$$

Using Bayes Rule, you can find

$$\theta|y \sim Be(1+y, 1+n-y).$$

#### Beta distribution

The beta distribution defines a distribution for a probability, i.e. a number on the interval (0,1). The probability density function is

$$p(\theta) = \frac{\theta^{a-1} (1-\theta)^{b-1}}{Beta(a,b)} I(0 < \theta < 1)$$

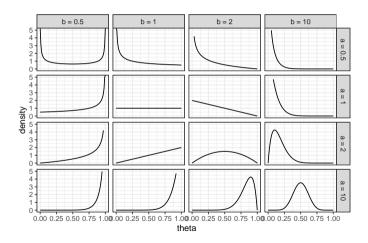
where a, b > 0 and Beta is the beta function, i.e.

$$Beta(a,b) = rac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$$
 and  $\Gamma(a) = \int_0^\infty x^{a-1}e^{-x}dx$ .

The beta distribution has the following properties:

- $\bullet$   $E[\theta] = \frac{a}{a+b}$
- $Var[\theta] = \frac{ab}{(a+b)^2(a+b+1)}$ , and
- $Be(1,1) \stackrel{d}{=} Unif(0,1)$ .

#### Beta densities

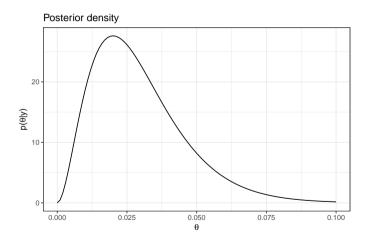


### Beta posterior

Suppose we have made 100 sensors according to a particular protocol and 2 have a sensitivity below a pre-determined threshold. Let Y be the number below the threshold. Assume  $Y \sim Bin(n,\theta)$  with n=100 and  $\theta \sim Be(1,1)$ , then

$$\theta | y \sim Be(1+y, 1+n-y) \stackrel{d}{=} Be(3,99).$$

# Posterior density



## Posterior expectation

Often times it is inconvenient to provide a full posterior and so we often summarize using a point estimate from the posterior. For a point estimate, we can use the posterior expectation:

$$\hat{\theta}_{Bayes} = E[\theta|y] = \frac{1+y}{(1+y)+(1+n-y)} = \frac{1+y}{2+n}$$

Note that this is close, but not exactly equal to  $\hat{\theta}_{MLE} = y/n$ . Since the MLE is unbiased, this posterior expectation will generally be biased but it is still consistent since  $\hat{\theta}_{Bayes} \rightarrow \hat{\theta}_{MLE}$ .

#### Credible intervals

A 100(1-a)% credible interval is any interval (L,U) such that

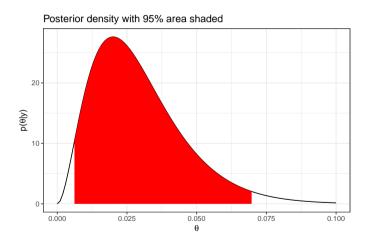
$$1 - a = \int_{L}^{U} p(\theta|y) d\theta.$$

An equal-tail 100(1-a)% credible interval is the interval L, U) such that

$$a/2 = \int_{-\infty}^{L} p(\theta|y)d\theta = \int_{U}^{\infty} p(\theta|y)d\theta.$$

```
# 95% credible interval is
ci = qbeta(c(.025,.975), 1+y, 1+n-y)
round(ci, 3)
Γ17 0.006 0.070
```

## Equal-tail 95% credible interval



### Summary

#### Bayesian parameter estimation involves

- 1. Specifying a model  $p(y|\theta)$  for your data.
- 2. Specifying a prior  $p(\theta)$  for the parameter.
- 3. Deriving the posterior

$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)} \propto p(y|\theta)p(\theta).$$

This equation updates your prior belief,  $p(\theta)$ , about the unknown parameter  $\theta$  into your posterior belief,  $p(\theta|y)$ , about  $\theta$ .

- 4. Calculating quantities of interest, e.g.
  - Posterior expectation,  $E[\theta|y]$
  - Credible interval

## Bayesian analysis for binomial model summary

Let  $Y \sim Bin(n, \theta)$  and assume  $\theta \sim Be(a, b)$ . Then

$$\theta|y \sim Be(a+y, b+n-y).$$

A default prior is  $\theta \sim Be(1,1) \stackrel{d}{=} Unif(0,1)$ .

#### R code for binomial analysis:

```
a <- 1: b <- 1
                                # default uniform prior
v <- 3: n <- 10
                                # data
curve(dbeta(x,ay,b+n-y))
                                # posterior (pdf)
(a+v)/(a+b+n)
                              # posterior mean
                              # posterior median
qbeta(.5, a+v, b+n-v)
gbeta(c(.025..975), a+v, b+n-v) # 95% equal tail credible interval
# Probabilities
pbeta(0.5, a+v, b+n-v)
                                \# P(theta < 0.5/y)
# Special cases
                              # if y=0, use a lower one-sided CI
gbeta(c(0,.95), a+v, b+n-v)
qbeta(c(.05,1), a+y, b+n-y)
                                # if y=n, use a upper one-sided CI
```