# Hierarchical models (cont.)

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## Outline

- Theoretical justification for hierarchical models
  - Exchangeability
  - de Finetti's theorem
  - Application to hierarchical models
- Normal hierarchical model
  - Posterior
  - Simulation study
  - Shrinkage

# Exchangeability

#### Definition

The set  $Y_1, Y_2, \ldots, Y_n$  is exchangeable if the joint probability  $p(y_1, \ldots, y_n)$  is invariant to permutation of the indices. That is, for any permutation  $\pi$ ,

$$p(y_1,\ldots,y_n)=p(y_{\pi_1},\ldots,y_{\pi_n}).$$

An exchangeable but not iid example:

- Consider an urn with one red ball and one blue ball with probability 1/2 of drawing either.
- Draw without replacement from the urn.
- Let  $Y_i = 1$  if the *i*th ball is red and otherwise  $Y_i = 0$ .
- Since  $1/2 = P(Y_1 = 1, Y_2 = 0) = P(Y_1 = 0, Y_2 = 1) = 1/2$ ,  $Y_1$  and  $Y_2$  are exchangeable.
- But  $0 = P(Y_2 = 1 | Y_1 = 1) \neq P(Y_2 = 1) = 1/2$  and thus  $Y_1$  and  $Y_2$  are not independent.

# Exchangeability

#### **Theorem**

All independent and identically distributed random variables are exchangeable.

### Proof.

Let  $y_i \stackrel{iid}{\sim} p(y)$ , then

$$p(y_1, \dots, y_n) = \prod_{i=1}^n p(y_i) = \prod_{i=1}^n p(y_{\pi_i}) = p(y_{\pi_1}, \dots, y_{\pi_n})$$

#### Definition

The sequence  $Y_1, Y_2, ...$  is infinitely exchangeable if, for any n,  $Y_1, Y_2, ..., Y_n$  are exchangeable.

## de Finetti's theorem

#### Theorem

A sequence of random variables  $(y_1, y_2, \ldots)$  is infinitely exchangeable iff, for all n,

$$p(y_1, y_2, \dots, y_n) = \int \prod_{i=1}^n p(y_i | \theta) P(d\theta),$$

for some measure P on  $\theta$ .

If the distribution on  $\theta$  has a density, we can replace  $P(d\theta)$  with  $p(\theta)d\theta$ .

This means that there must exist

- $\bullet$  a parameter  $\theta$ ,
- a likelihood  $p(y|\theta)$  such that  $y_i \stackrel{ind}{\sim} p(y|\theta)$ , and
- a distribution P on  $\theta$ .

# Application to hierarchical models

Assume  $(y_1,y_2,\ldots)$  are infinitely exchangeable, then by de Finetti's theorem for the  $(y_1,\ldots,y_n)$  that you actually observed, there exists

- a parameter  $\theta$ ,
- a distribution  $p(y|\theta)$  such that  $y_i \stackrel{ind}{\sim} p(y|\theta)$ , and
- a distribution P on  $\theta$ .

Assume  $\theta=(\theta_1,\theta_2,\ldots)$  with  $\theta_i$  infinitely exchangeable. By de Finetti's theorem for  $(\theta_1,\ldots,\theta_n)$ , there exists

- a parameter  $\phi$ ,
- a distribution  $p(\theta|\phi)$  such that  $\theta_i \overset{ind}{\sim} p(\theta|\phi)$ , and
- a distribution P on  $\phi$ .

Assume  $\phi = \phi$  with  $\phi \sim p(\phi)$ .

# Exchangeability with covariates

Suppose we observe  $y_i$  observations and  $x_i$  covariates for each unit i. Now we assume  $(y_1, y_2, \ldots)$  are infinitely exchangeable given  $x_i$ , then by de Finetti's theorem for the  $(y_1, \ldots, y_n)$ , there exists

- a parameter  $\theta$ ,
- a distribution  $p(y|\theta, \mathbf{x})$  such that  $y_i \stackrel{ind}{\sim} p(y|\theta, \mathbf{x_i})$ , and
- a distribution P on  $\theta$  given x.

Assume  $\theta = (\theta_1, \theta_2, ...)$  with  $\theta_i$  infinitely exchangeable given x. By de Finetti's theorem for  $(\theta_1, ..., \theta_n)$ , there exists

- a parameter  $\phi$ ,
- a distribution  $p(\theta|\phi, \mathbf{x})$  such that  $\theta_i \stackrel{ind}{\sim} p(\theta|\phi, \mathbf{x}_i)$ , and
- a distribution P on  $\phi$  given x.

Assume  $\phi = \phi$  with  $\phi \sim p(\phi|\mathbf{x})$ .

# Summary

Hierarchical model:

$$y_i \stackrel{ind}{\sim} p(y|\theta_i), \qquad \theta_i \stackrel{ind}{\sim} p(\theta|\phi), \qquad \phi \sim p(\phi)$$

Hierarchical linear model:

$$y_i \stackrel{ind}{\sim} p(y|\theta_i, x_i), \qquad \theta_i \stackrel{ind}{\sim} p(\theta|\phi, x_i), \qquad \phi \sim p(\phi|x)$$

Although hierarchical models are typically written using the conditional independence notation above, the assumptions underlying the model are exchangeability and functional forms for the priors.

## Normal hierarchical models

Suppose we have the following model

$$y_{ij} \stackrel{ind}{\sim} N(\theta_i, \sigma^2)$$
  
 $\theta_i \stackrel{iid}{\sim} N(\mu, \tau^2)$ 

with  $j=1,\ldots,n_i$ ,  $i=1,\ldots,I$ , and  $n=\sum_{i=1}^J n_i$ . This is a normal hierarchical model.

Make the following assumptions for computational reasons:

- Let  $\sigma^2 = s^2$  be known.
- Assume  $p(\mu,\tau) \propto p(\mu|\tau)p(\tau) \propto p(\tau)$ , i.e. assume an improper uniform prior on  $\mu$ .

## Posterior distribution

The posterior is

$$p(\theta, \mu, \tau | y) \propto p(y|\theta)p(\theta|\mu, \tau)p(\mu|\tau)p(\tau)$$

but the decomposition

$$p(\theta, \mu, \tau | y) = p(\theta | \mu, \tau, y) p(\mu | \tau, y) p(\tau | y)$$

where

$$\begin{array}{ll} p(\theta|\mu,\tau,y) & \propto p(y|\theta)p(\theta|\mu,\tau) \\ p(\mu|\tau,y) & \propto \int p(y|\theta)p(\theta|\mu,\tau)d\theta\,p(\mu|\tau) \\ p(\tau|y) & \propto \int p(y|\theta)p(\theta|\mu,\tau)p(\mu|\tau)d\theta d\mu\,p(\tau) \end{array}$$

will aide computation via

- 1.  $\tau^{(k)} \sim p(\tau|y)$
- 2.  $\mu^{(k)} \sim p(\mu | \tau^{(k)}, y)$
- 3.  $\theta_i^{(k)} \sim p(\theta | \mu^{(k)}, \tau^{(k)}, y)$  for i = 1, ..., I.

## Posterior distributions

The necessary conditional and marginal posteriors are presented in section 5.4 of BDA. Let

$$\overline{y}_{i\cdot} = \frac{1}{n_i} \sum_{j=1}^{n_i} y_{ij} \quad \text{and} \quad s_i^2 = s^2/n_i$$

Then

$$p(\tau|y) \propto p(\tau)V_{\mu}^{1/2} \prod_{i=1}^{I} (s_{i}^{2} + \tau^{2})^{-1/2} \exp\left(-\frac{(\overline{y}_{i} - \hat{\mu})^{2}}{2(s_{i}^{2} + \tau^{2})}\right)$$

$$\mu|\tau, y \sim N(\hat{\mu}, V_{\mu})$$

$$\theta_{i}|\mu, \tau, y \sim N(\hat{\theta}_{i}, V_{i})$$

$$\begin{array}{lll} V_{\mu}^{-1} & = \sum_{j=1}^{J} \frac{1}{s_{i}^{2} + \tau^{2}} & \hat{\mu} & = V_{\mu} \left( \sum_{i=1}^{\mathrm{I}} \frac{\overline{y}_{\cdot i}}{s_{i}^{2} + \tau^{2}} \right) \\ V_{i}^{-1} & = \frac{1}{s_{i}^{2}} + \frac{1}{\tau^{2}} & \hat{\theta}_{i} & = V_{i} \left( \frac{\overline{y}_{i \cdot}}{s_{i}^{2}} + \frac{\mu}{\tau^{2}} \right) \end{array}$$

## Simulation study

### Simulation

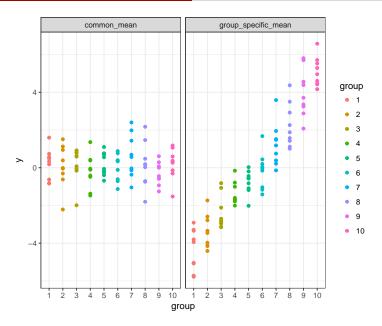
- 1.  $\theta_i = 0$  for all i
- 2.  $\theta_i = i (I/2 + .5)$

#### Common to both simulations

- I = 10
- $n_i = 9$  for all i
- s=1 thus  $s_i=1/3$  for all i

Use  $\tau \sim Ca^+(0,1)$ .

# Simulation study



# Summary statistics

	simulation	group	n	mean	sd
1	common_mean	1	9	0.18	0.81
2	common_mean	2	9	0.09	1.11
3	common_mean	3	9	0.18	0.91
4	common_mean	4	9	-0.19	0.89
5	common_mean	5	9	0.17	0.62
6	common_mean	6	9	0.02	0.70
7	common_mean	7	9	0.61	1.14
8	common_mean	8	9	0.14	1.19
9	common_mean	9	9	-0.31	0.60
10	common_mean	10	9	0.20	0.81
11	group_specific_mean	1	9	-4.32	1.10
12	group_specific_mean	2	9	-3.40	0.88
13	group_specific_mean	3	9	-2.41	0.89
14	group_specific_mean	4	9	-1.38	0.60
15	group_specific_mean	5	9	-0.76	0.61
16	group_specific_mean	6	9	-0.16	0.95
17	group_specific_mean	7	9	1.21	1.12
18	group_specific_mean	8	9	2.23	1.15
19	group_specific_mean	9	9	3.97	1.26
20	group_specific_mean	10	9	5.08	0.77

# Sampling on a grid

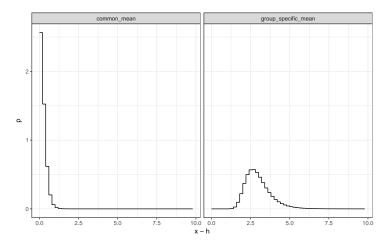
Consider samping from an arbitrary unnormalized density  $f(\tau) \propto p(\tau|y)$  using the following approach

- 1. Construct a step-function approximation to this density:
  - a. Determine an interval [L,U] such that outside this interval  $f(\tau)$  is small.
  - b. Set an interval half-width h to generate a grid of M points  $(x_1,\ldots,x_M)$  in this interval, i.e.

$$x_1 = L + h \text{ and } x_m = x_{m-1} + 2h \quad \forall 1 < m \le M.$$

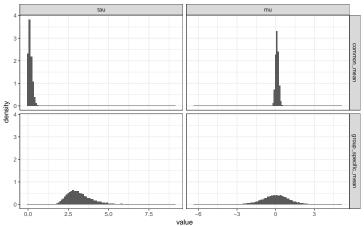
- c. Evaluate the density on this grid, i.e.  $f(x_m)$ .
- d. Normalize interval weights, i.e.  $w_m = f(x_m) \left/ \sum_{i=1}^M f(x_i) \right.$  (to constructed a normalized density, divide each  $w_m$  by 2h.).
- 2. Sampling from this approximation:
  - a. Sample an interval m with probability  $w_m$ .
  - b. Sample uniformly within this interval, i.e.  $\tau \sim \text{Unif}(x_m h, x_m + h)$ .

# Approximation to $p(\tau|y)$ when $\tau \sim Ca^+(0,1)$



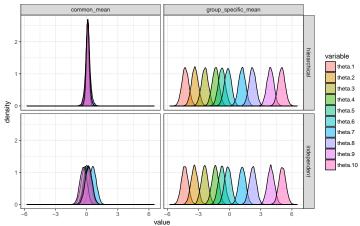
# Hyperparameters: group-to-group mean variability

Recall  $\theta_i \stackrel{ind}{\sim} N(\mu, \tau^2)$ :



# Group-specific means

# Recall $\theta_i \stackrel{ind}{\sim} N(\mu, \tau^2)$ :



## Extensions

Unknown data variance:

$$y_{ij} \sim N(\theta_i, \sigma^2), \, \theta_i \sim N(\mu, \tau^2)$$

or

$$y_{ij} \sim N(\theta_i, \sigma^2), \ \theta_i \sim N(\mu, \sigma^2 \tau^2)$$

- Alternative distributions:
  - Heavy-tailed:

$$y_{ij} \sim N(\theta_i, \sigma^2), \ \theta_i \sim t_{\nu}(\mu, \tau^2)$$

• Peak at zero:

$$y_{ij} \sim N(\theta_i, \sigma^2), \, \theta_i \sim \mathsf{Laplace}(\mu, \tau^2)$$

Point mass at zero:

$$y_{ij} \sim N(\theta_i, \sigma^2), \ \theta_i \sim \pi \delta_0 + (1 - \pi) N(\mu, \tau^2)$$

## Summary

#### Hierarchical models

- allow the data to inform us about similarities across groups
- provide data driven shrinkage toward a grand mean
  - lots of shrinkage when means are similar
  - little shrinkage when means are different

Computation used the decomposition

$$p(\theta, \mu, \tau | y) = p(\theta | \mu, \tau, y) p(\mu | \tau, y) p(\tau | y)$$

which allowed for simulation from  $\tau$  then  $\mu$  and then  $\theta$  to obtain samples from the posterior.