

Hierarchical models

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Normal hierarchical model

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$$Y_{ig} \stackrel{\text{ind}}{\sim} N(\theta_g, \sigma^2)$$

for $i = 1, \dots, n_g$, $g = 1, \dots, G$, and $\sum_{g=1}^G n_g = n$.

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- $\theta_i \stackrel{ind}{\sim} La(\mu, \tau)$

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To perform a Bayesian analysis, we need a prior on μ , τ^2 , and (in the case of the discrete mixture) π .

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where $i = 1, \dots, n_g$, $g = 1, \dots, G$, and $n = \sum_{g=1}^G n_g$ with prior distribution

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For background on why we are using these priors for the variances, see Gelman (2006) <https://projecteuclid.org/euclid.ba/1340371048>: “Prior distributions for variance parameters in hierarchical models (comment on article by Browne and Draper)”.

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How many steps exist in this Gibbs sampler?

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- Sample $\tau^2 \sim p(\tau^2 | \dots)$.

How many steps exist in this Gibbs sampler? $G+3$? 4?

2-Step Gibbs sampler for normal hierarchical model

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There is stronger theoretical support for 2-step Gibbs sampler, thus, if we can, it is prudent to construct a 2-step Gibbs sampler.

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where $y_g = (y_{1g}, \dots, y_{n_g g})$.

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where $y_g = (y_{1g}, \dots, y_{n_g g})$. We now know that the θ_g are conditionally independent of each other.

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Notice that this does not include $\theta_{g'}$ for any $g' \neq g$.

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Thus

$$\theta_g | \cdots \stackrel{ind}{\sim} N(\mu_g, \tau_g^2)$$

where

$$\begin{aligned} \tau_g^2 &= [\tau^{-2} + n_g \sigma^{-2}]^{-1} \\ \mu_g &= \tau_g^2 [\mu \tau^{-2} + \bar{y}_g n_g \sigma^{-2}] \\ \bar{y}_g &= \frac{1}{n_g} \sum_{i=1}^{n_g} y_{ig}. \end{aligned}$$

Sampling μ, σ^2, τ^2

The full conditional for μ, σ^2, τ^2 is

$$p(\mu, \sigma^2, \tau^2 | \dots) \propto p(y | \theta, \sigma^2) p(\theta | \mu, \tau^2) p(\mu) p(\sigma^2) p(\tau^2)$$

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So we know that σ^2 is independent of μ and τ^2 .

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To derive the full conditional, use

$$\begin{aligned} p(\sigma^2 | \dots) &\propto \prod_{g=1}^G \prod_{i=1}^{n_g} (\sigma^2)^{-1/2} \exp\left(-\frac{1}{2\sigma^2} (y_{ig} - \theta_g)^2\right) \frac{1}{\sigma^2} \\ &= (\sigma^2)^{-n/2-1} \exp\left(-\frac{1}{2} \sum_{g=1}^G \sum_{i=1}^{n_g} (y_{ig} - \theta_g)^2 / \sigma^2\right) \end{aligned}$$

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which is the kernel of a $IG\left(\frac{n}{2}, \frac{1}{2} \sum_{g=1}^G \sum_{i=1}^{n_g} (y_{ig} - \theta_g)^2\right)$.

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Here are some options for sampling from this distribution:

- random-walk Metropolis (in 2 dimensions),
- independent Metropolis-Hastings using posterior from standard non-informative prior as the proposal, or
- rejection sampling using posterior from standard non-informative prior as the proposal

The posterior under the standard non-informative prior is

$$\tau^2 | \dots \sim \text{Inv-}\chi^2(G-1, s_\theta^2) \text{ and } \mu | \tau^2, \dots \sim N(\bar{\theta}, \tau^2/G)$$

where $\bar{\theta} = \frac{1}{G} \sum_{g=1}^G \theta_g$ and $s_\theta^2 = \frac{1}{G-1} (\theta_g - \bar{\theta})^2$.

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Markov chain Monte Carlo for normal hierarchical model

1. Sample $\theta \sim p(\theta | \dots)$:
 - a. For $g = 1, \dots, G$, sample $\theta_g \sim N(\mu_g, \tau_g^2)$.
2. Sample μ, σ^2, τ^2 :
 - a. Sample $\sigma^2 \sim IG(n/2, SSE)$.
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What happens if $\theta_g \stackrel{ind}{\sim} La(\mu, \tau)$ or $\theta_g \stackrel{ind}{\sim} t_\nu(\mu, \tau^2)$?

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This is called a location mixture.

Now, if

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and we assume a mixing distribution for ϕ , we have a scale mixture. Since the top level distributional assumption is normal, we refer to this as a **scale mixture of normals**.

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Notice that the parameterization has a redundancy between C and a/b , i.e. we could have chosen $C = \tau^2$, $a = \nu/2$, and $b = \nu/2$ and we would have obtained the same marginal distribution for θ .

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Recall our hierarchical model

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For simplicity, let's assume $\sigma^2 \sim \text{IG}(a, b)$, $\mu \sim N(m, C)$, and $\tau \sim \text{Ca}^+(0, c)$ and that σ^2 , μ , and τ are *a priori* independent.

Gibbs sampling

The following Gibbs sampler will converge to the posterior $p(\theta, \sigma, \mu, \phi, \tau|y)$:

1. Sample $\mu \sim p(\mu|\cdots)$.
2. Independently, sample $\theta_i \sim p(\theta_i|\cdots)$.
3. Sample $\sigma \sim p(\sigma|\cdots)$.
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The first three steps will be common to all models while the last two steps will be unique to each model (without a point mass).

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$$\mu | \cdots \sim N(m', C')$$

with

$$\begin{aligned} C' &= \left(\frac{1}{C} + \sum_{i=1}^I \frac{1}{\phi_i} \right)^{-1} \\ m' &= C' \left(\frac{m}{C} + \sum_{i=1}^I \frac{\theta_i}{\phi_i} \right) \end{aligned}$$

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$$\theta_i | \dots \sim N \left(\left[\frac{\mu}{\phi_i} + \frac{n_i}{\sigma^2} \bar{y}_i \right], \left[\frac{1}{\phi_i} + \frac{n_i}{\sigma^2} \right]^{-1} \right)$$

where $\bar{y}_i = \sum_{j=1}^{n_i} y_{ij} / n_i$.

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$$\sigma^2 | \dots \sim IG(a', b')$$

where

$$\begin{aligned} a' &= a + \sum_{i=1}^I n_i / 2 = a + n / 2 \\ b' &= b + \sum_{i=1}^I \sum_{j=1}^{n_i} (y_{ij} - \theta_i)^2 / 2. \end{aligned}$$

Distributional assumption for θ_i

$$Y_{ij} \stackrel{\text{ind}}{\sim} N(\theta_i, \sigma^2) \text{ and } \theta_i \stackrel{\text{ind}}{\sim} N(\mu, \phi_i)$$

$$\phi_i = \tau$$

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The steps that are left are 1) sample ϕ and 2) sample τ^2 ,

Sample ϕ for normal model

For normal model, $\phi_i = \tau$, so we will address this when we sample τ .

Sample ϕ for Laplace model

For Laplace model,

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So the individual ϕ_i are conditionally independent

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$$p(\phi | \dots) \propto \left[\prod_{i=1}^I N(\theta_i; \mu, \phi_i) \text{Exp}(\phi_i; 1/2\tau^2) \right].$$

So the individual ϕ_i are conditionally independent with

$$p(\phi_i | \dots) \propto N(\theta_i; \mu, \phi_i) \text{Exp}(\phi_i; 1/2\tau^2) \propto \phi_i^{-1/2} e^{-(\theta_i - \mu)^2 / 2\phi_i} e^{-\phi_i / 2\tau^2}$$

Sample ϕ for Laplace model

For Laplace model,

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which is the kernel of an inverse Gaussian distribution with mean $\sqrt{1/\tau^2(\theta_i - \mu)^2}$ and scale $1/\tau^2$ where the parameterization is such that the variance is μ^3/λ (different from the `mgcv::rig` parameterization).

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so we have

$$\phi_i | \dots \stackrel{\text{ind}}{\sim} IG([v+1]/2, [v\tau^2 + (\theta_i - \mu)^2]/2).$$

Since this is just I independent normal data models with a known mean and independent conjugate inverse gamma priors on the variance.

Sample τ for normal model

Let

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$$p(\eta | \dots) \propto \eta^{-I/2} e^{-\sum_{i=1}^I (\theta_i - \mu)^2 / 2\eta} (1 + \eta/c^2)^{-1} \eta^{-1/2}$$

where we performed the transformation $\eta = \tau^2$ on the prior.

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Let's use Metropolis-Hastings with proposal distribution

$$IG\left(\frac{I-1}{2}, \sum_{i=1}^I \frac{(\theta_i - \mu)^2}{2}\right)$$

and acceptance probability $\min\{1, \rho\}$ where

$$\rho = \frac{(1 + \eta^*/c^2)^{-1}}{(1 + \eta^{(i)}/c^2)^{-1}} = \frac{1 + \eta^{(i)}/c^2}{1 + \eta^*/c^2}$$

where $\eta^{(i)}$ and η^* are the current and proposed value respective.

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Then we calculate $\tau = \sqrt{\eta}$.

Sample τ for t model

Let

$$\phi_i \sim IG(v/2, v\tau^2/2) \text{ and } \tau \sim Ca^+(0, c)$$

so the full conditional is

$$p(\eta | \dots) \propto \eta^{Iv/2} e^{-\frac{\eta}{2} \sum_{i=1}^I \frac{1}{\phi_i}} (1 + \eta/c^2)^{-1} \eta^{-1/2}.$$

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Sample τ for t model

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Dealing with point-mass distributions

We would also like to consider models with

$$\theta_i \overset{\text{ind}}{\sim} \pi\delta_0 + (1 - \pi)N(\mu, \phi_i)$$

where $\phi_i = \tau^2$ corresponds to a normal and

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corresponds to a t distribution for the non-zero θ_i .

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corresponds to a t distribution for the non-zero θ_i .

Similar to the previous, the θ_i are conditionally independent. To sample θ_i , we calculate

$$\begin{aligned} \pi' &= \frac{\pi \prod_{j=1}^{n_i} N(y_{ij}; 0, \sigma^2)}{\pi \prod_{j=1}^{n_i} N(y_{ij}; 0, \sigma^2) + (1 - \pi) \prod_{j=1}^{n_i} N(y_{ij}; \mu, \phi_i + \sigma^2)} \\ \phi'_i &= \left(\frac{1}{\phi_i} + \frac{n_i}{\sigma^2} \right)^{-1} \\ \mu'_i &= \phi'_i \left(\frac{\mu}{\phi_i} + \frac{n_i}{\sigma^2} \bar{y}_i \right) \end{aligned}$$

Dealing with point-mass distributions (cont.)

Let

$$\theta_i \overset{\text{ind}}{\sim} \pi\delta_0 + (1 - \pi)N(\mu, \phi_i)$$

and independently $\pi \sim \text{Beta}(s, f)$, $\mu \sim N(m, C)$, and $\phi_i = \tau^2$ for normal model or $\phi_i \overset{\text{ind}}{\sim} \text{IG}(\nu/2, \nu\tau^2/2)$ for the t model.

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The full conditional for π is

$$\pi | \dots \sim \text{Beta} \left(s + \sum_{i=1}^I \text{I}(\theta_i = 0), f + \sum_{i=1}^I \text{I}(\theta_i \neq 0) \right)$$

and μ and ϕ_i get updated using only those θ_i that are non-zero.