

COMPUTACIONAL HW 2 MATH 33B

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Execute to install dependencies.

```
In [ ]: !pip install numpy
!pip install pandas
!pip install scipy
!pip install matplotlib
```

Libraries to use

```
In [ ]: import numpy as np
from scipy.integrate import odeint
import matplotlib.pyplot as plt
```

PROBLEM 1

Consider a damped forced system

$$y'' + \frac{\mu}{m}y' + \frac{k}{m}y = \frac{F_0}{m}\cos(\omega t)$$

where ω is the forcing frequency. Using analytical methods, we find the sketchy state response (particular solutions).

$$y_s(t) = \frac{F_0}{m\sqrt{(2\omega p)^2 + (\omega_0^2 - \omega^2)^2}}\cos(\omega y - \gamma)$$

where

$$p = \frac{\mu}{2m}, \omega_0 = \sqrt{\frac{k}{m}}, \gamma = \arctan\left(\frac{2\omega p}{\omega_0^2 - \omega^2}\right)$$

(a) Let $m = 4, \mu = 1, k = 8$ and $F_0 = 8$. Plot the amplitud A of the steady state response versus ω for $0 \leq \omega \leq 5$

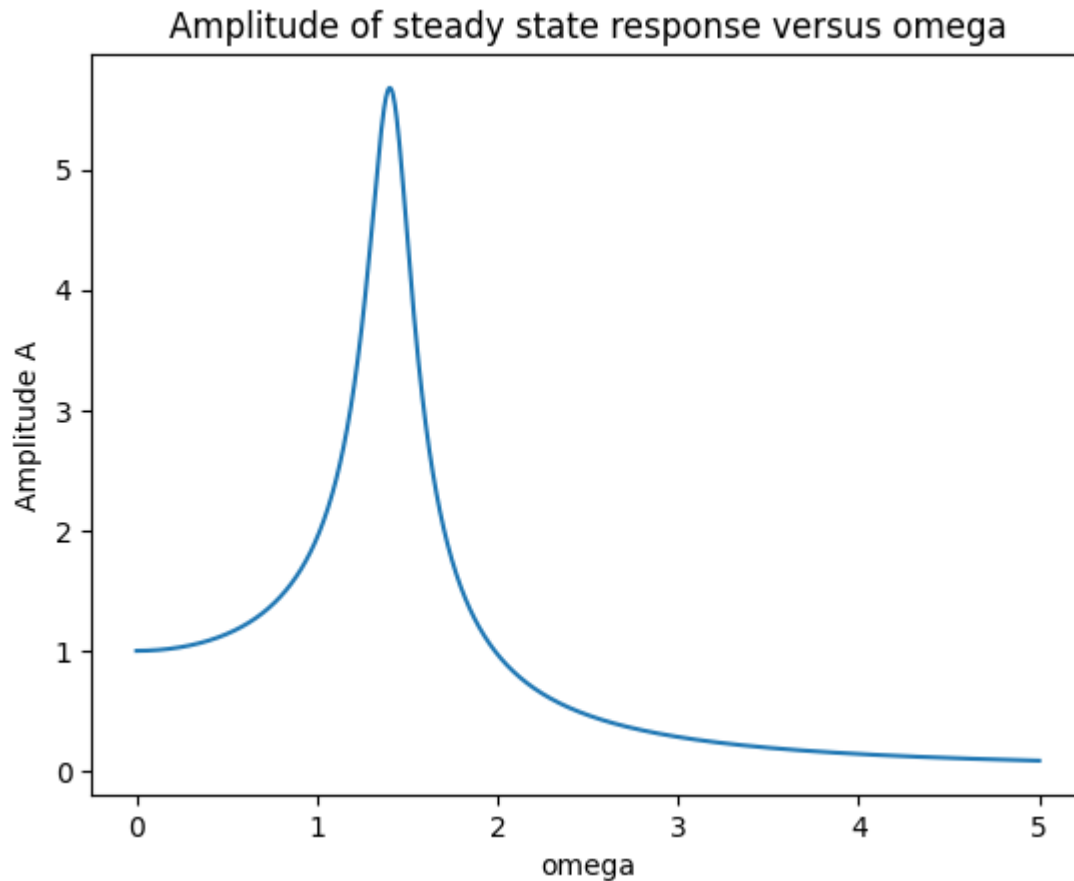
```
In [ ]: # Define the given parameters
m = 4
mu = 1
k = 8
F_0 = 8

# Define the range of omega values to plot
omega_vals = np.linspace(0, 5, 1000)

# Calculate the amplitude A for each value of omega
p = mu / (2 * m)
omega_0 = np.sqrt(k / m)
gamma = np.arctan(2 * omega_vals * p / (omega_0**2 - omega_vals**2))
A = F_0 / (m * np.sqrt((2 * omega_vals * p)**2 + (omega_0**2 - omega_vals**2)**2))

# Plot the amplitude A versus omega
plt.plot(omega_vals, A)
plt.xlabel('omega')
```

```
plt.ylabel('Amplitude A')
plt.title('Amplitude of steady state response versus omega')
plt.show()
```



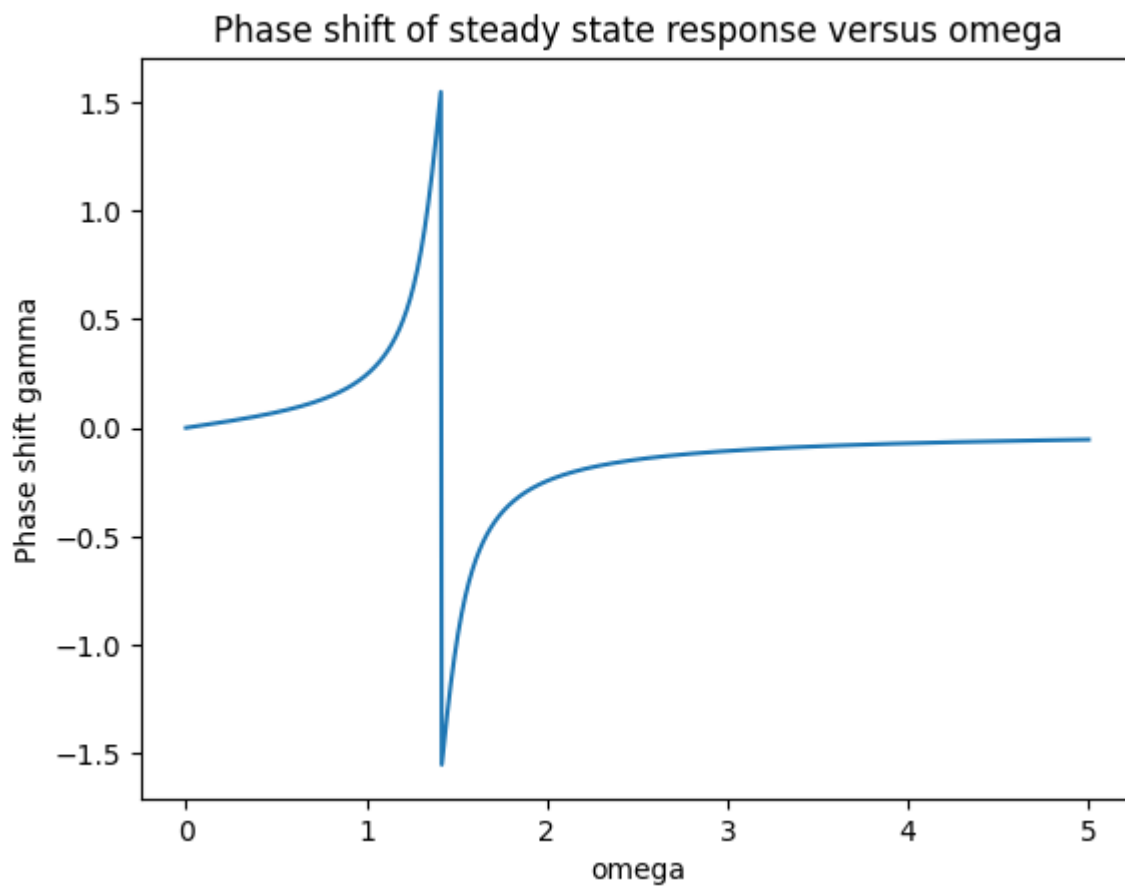
(b) With the same parameters, plot the phase shift γ of the steady state response versus ω for $0 \leq \omega \leq 5$

```
In [ ]: # Define the given parameters
m = 4
mu = 1
k = 8
F_0 = 8

# Define the range of omega values to plot
omega_vals = np.linspace(0, 5, 1000)

# Calculate the phase shift gamma for each value of omega
p = mu / (2 * m)
omega_0 = np.sqrt(k / m)
gamma = np.arctan(2 * omega_vals * p / (omega_0**2 - omega_vals**2))

# Plot the phase shift gamma versus omega
plt.plot(omega_vals, gamma)
plt.xlabel('omega')
plt.ylabel('Phase shift gamma')
plt.title('Phase shift of steady state response versus omega')
plt.show()
```



(c) Estimate the maximum value of A and the frequency ω for which occurs.

```
In [ ]: # Define the given parameters
m = 4
mu = 1
k = 8
F_0 = 8

# Define the range of omega values to plot
omega_vals = np.linspace(0, 5, 10000)

# Calculate the amplitude A for each value of omega
p = mu / (2 * m)
omega_0 = np.sqrt(k / m)
gamma = np.arctan(2 * omega_vals * p / (omega_0**2 - omega_vals**2))
A = F_0 / (m * np.sqrt((2 * omega_vals * p)**2 + (omega_0**2 - omega_vals**2)**2))

# Find the maximum value of A and its index
max_A_index = np.argmax(A)
max_A = A[max_A_index]

# Find the corresponding value of omega
max_omega = omega_vals[max_A_index]

# Print the results
print(f"The maximum value of A is {max_A:.2f} and it occurs at omega = {max_omega:.2f}")
```

The maximum value of A is 5.68 and it occurs at $\omega = 1.40$

PROBLEM 2

Consider an undamped mass-spring system where $m = 2$, $k = 10$ and $\mu = 0$ and with forcing function $F(t) = \cos(\omega t)$

$$2y''(t) + 10y(t) = \cos(\omega t), y(0) = y'(0) = 0$$

(a) Plot the solution $y(t)$ with $\omega = 2.5$ for $0 \leq t \leq 100$

```
In [ ]: # Define the system of ODEs
def system(y, t, w):
    y1, y2 = y
    dydt = [y2, (np.cos(w*t) - 10*y1) / 2]
    return dydt

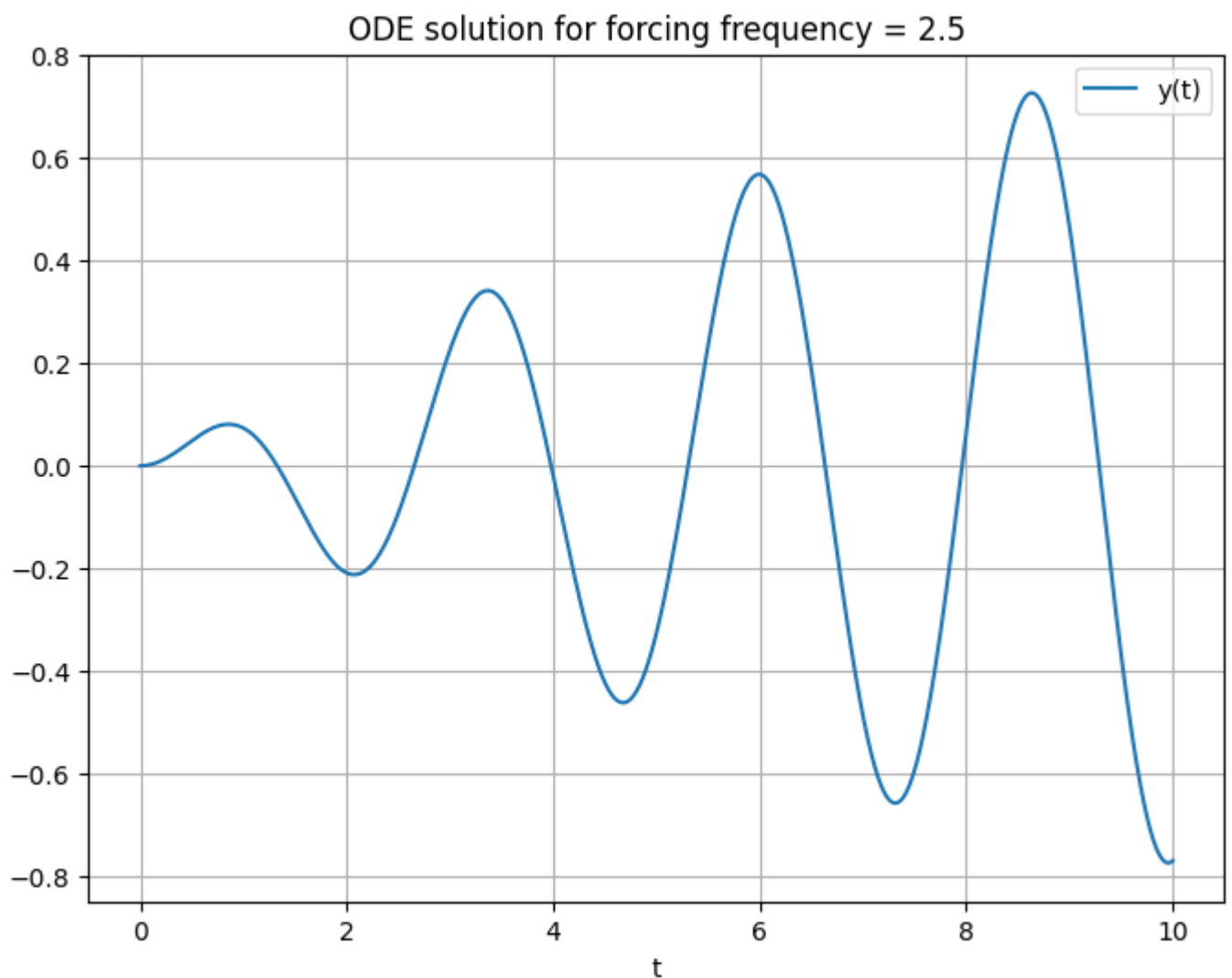
# Initial conditions
y0 = [0, 0]

# Time array
t = np.linspace(0, 10, 1000)

# Forcing frequency
w = 2.5

# Solve the ODE
sol = odeint(system, y0, t, args=(w,))

# Plot the solution
plt.figure(figsize=(8, 6))
plt.title("ODE solution for forcing frequency = 2.5")
plt.plot(t, sol[:, 0], label='y(t)')
plt.legend(loc='best')
plt.xlabel('t')
plt.grid()
plt.show()
```



(b) Experiment with different values for the forcing frequency ω in $F(t) = \cos(\omega t)$. Find the maximum range of values (to 2 decimal places) such that the maximum amplitude $|y(t)|$ exceeds 1. (Note. It may be helpful to use a for loop and max function)

```

In [ ]: # Define the system of ODEs
def system(y, t, w):
    y1, y2 = y
    dydt = [y2, (np.cos(w*t) - 10*y1) / 2]
    return dydt

# Initial conditions
y0 = [0, 0]

# Time array
t = np.linspace(0, 10, 1000)

# Forcing frequency range
w_range = np.linspace(0, 10, 1000)

# Store w values that result in max amplitude > 1
w_values = []

for w in w_range:
    # Solve the ODE
    sol = odeint(system, y0, t, args=(w,))

    # Find max amplitude
    max_amplitude = np.max(np.abs(sol[:, 0]))

    # Check if max amplitude > 1
    if max_amplitude > 1:
        w_values.append(w)

# Print the range of w values
print(f"The range of w values for which the maximum amplitude exceeds 1 is from {min(w_values)} to {max(w_values)}")

```

The range of w values for which the maximum amplitude exceeds 1 is from 2.08 to 2.27.