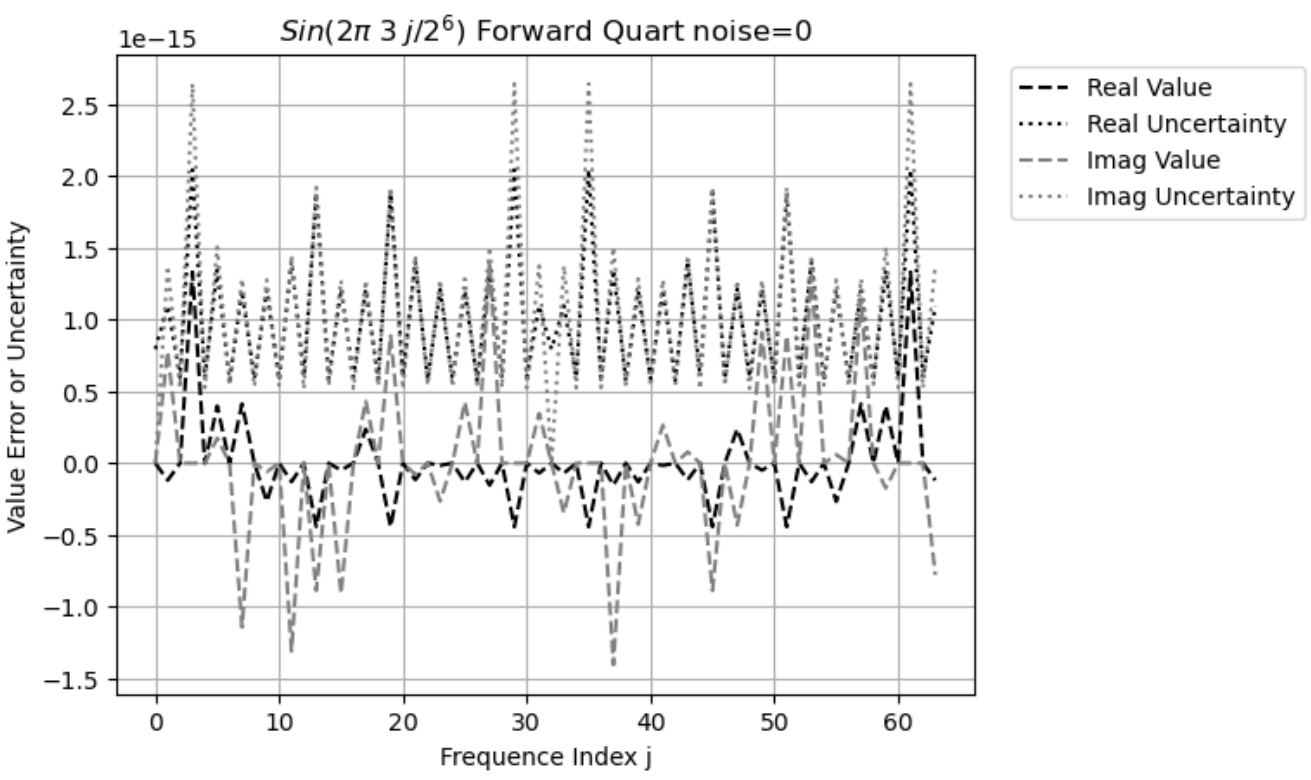
$Sin(2\pi\ 3\ j/2^6)$ Forward Quart noise=0
1e−15
2.5
2.0
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
Value Error or Uncertainty
0
10
20
30
40
50
60
Frequence Index j
Real Value
Real Uncertainty
Imag Value
Imag Uncertainty