# Approximation algorithms 3 Vertex cover, TSP, k-center

CS240

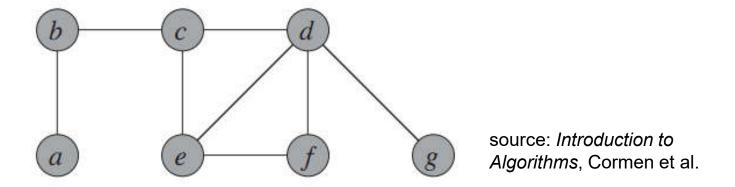
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#### Vertex cover

- Input A graph with vertices V and edges E.
- Output A subset V' of the vertices, so that every edge in E touches some vertex in V'.
- Goal Make |V'| as small as possible.



- Finding the minimum vertex cover is NP-complete.
- Vertex cover is a special case of (unweighted) set cover, where each element (edge) can be covered by at most two sets (vertices).
- We'll see a simple 2 approximation for this problem.

# r,e

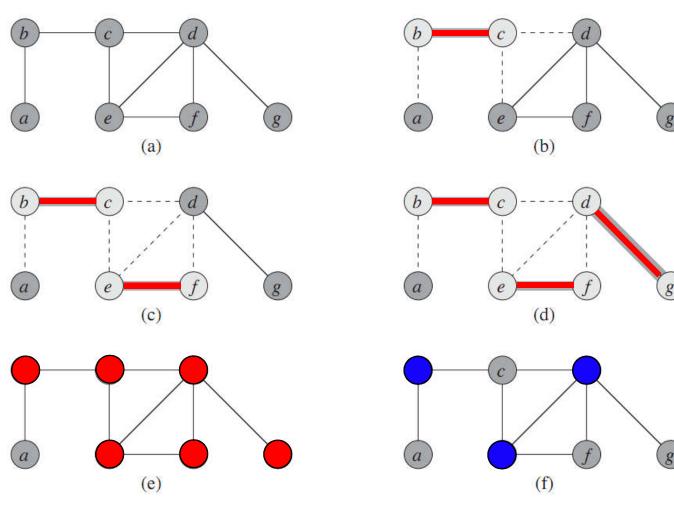
### A vertex cover algorithm

- Initially, let D be all the edges in the graph, and C be the empty set.
  - □ C is our eventual vertex cover.
- Repeat as long as there are edge left in D.
  - □ Take any edge (u,v) in D.
  - $\square$  Add  $\{u,v\}$  to C.
  - □ Remove all the edges adjacent to u or v from D.
- Output C as the vertex cover.



# Example

source: CLRS



Algorithm's vertex cover

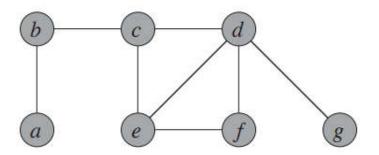
Optimal vertex cover



- The output is certainly a vertex cover.
  - □ In each iteration, we only take out edges that get covered.
  - We keep adding vertices till all edges are covered.
- Now, we show it's a 2 approximation.
- Let C\* be an optimal vertex cover.
- Let A be the set of edges the algorithm picked.

# M

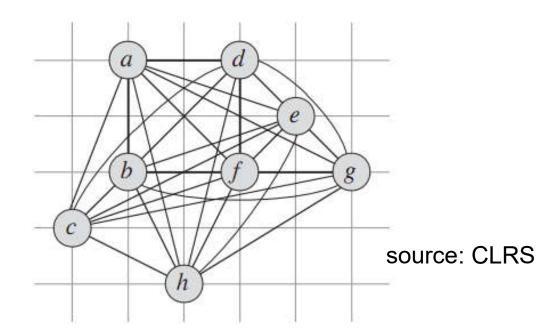
- None of the edges in A touch each other.
  - □ Each time we pick an edge, we remove all adjacent edges.
- So each vertex in C\* covers at most one edge in A.
  - □ The edges covered by a vertex all touch each other.
- Every edge in A is covered by a vertex in C\*.
  - □ Because C\* is a vertex cover.
- So  $|C^*| \ge |A|$ .
- The number of vertices the algorithm uses is 2|A|.
  - □ If alg picks edge (u,v), it uses {u,v} in the cover.
- So (# vertices alg uses) / (# vertices in opt cover) = 2|A| / |C\*| ≤ 2|A| / |A| = 2.





## Traveling Salesman Problem

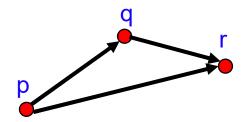
- Input A complete graph with weights on the edges.
- Output A cycle that visits each city once.
- Goal Find a cycle with minimum total weight.



# M

#### Metric TSP

- TSP is NP-hard. In fact, it's even NP-hard to approximate when weights can be arbitrary.
- However, TSP is approximable for special types of weights.
- A weighted graph satisfies the triangle inequality if for any 3 vertices p, q, r, we have d<sub>pq</sub>+d<sub>qr</sub> ≥ d<sub>pr</sub>.
  - □ I.e., direct path is always no worse than a roundabout path.
  - ☐ This is called a metric TSP.
- There is a 1.5-approx algorithm for TSP in graphs with the triangle inequality.
  - □ Let's look at a simpler 2-approx first.



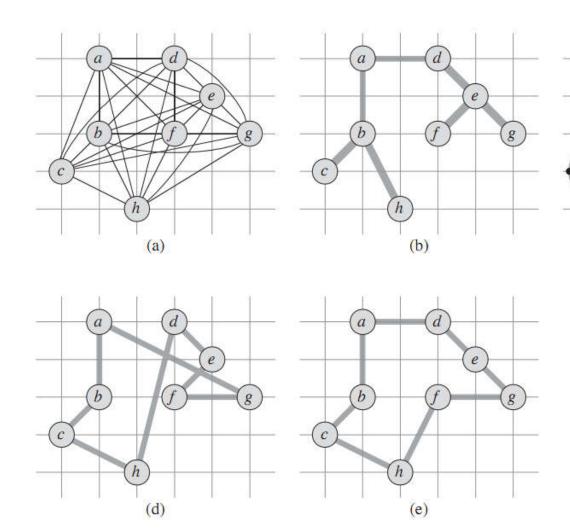


## A 2-approximation for TSP

- Construct a minimum spanning tree T on G.
- Use depth-first traversal to visit all the vertices in T, starting from an arbitrary vertex.
- Convert this depth-first traversal T' to a cycle H that doesn't revisit any vertex.
- Return H as the TSP tour.



# Example



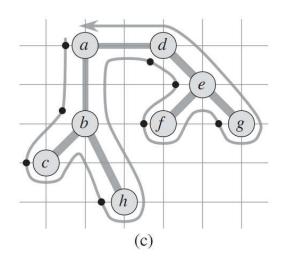
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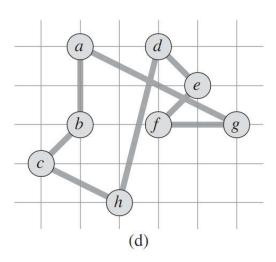
- (b) The MST T.
- (c) visit T in order abcbhbadefegeda.
- (d) converts the tour from
  - (c) to a Hamiltonian cycle, that doesn't revisit any vertices.
- (e) is the optimal TSP.



## Making the tour Hamiltonian

- To go from (c) to (d), we need to make a tour T' that revisits vertices into a cycle H that doesn't revisit vertices.
- We use shortcutting.
  - If we revisit a vertex in T', we directly jump to the next vertex in T' we haven't visited.
    - We allow revisiting the first vertex.
  - □ The sequence of vertices we now visit is H.
  - □ Ex abcbhbadefegeda → abchdefga.





# r,e

## Making the tour Hamiltonian

- Lemma If H is the shortcut of T', then c(H)≤c(T').
- Proof We formed H from T' by skipping over some vertices. E.g. we directly went from c to h, skipping over b.
  - □ But by the triangle inequality,  $d_{cb}+d_{bh} \ge d_{ch}$ .
    - So shortcutting from c to h didn't increase the distance.
  - □ The same thing applies to all our shortcuts.
  - □ So H is no longer than T'.

# re.

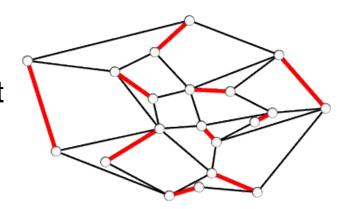
## Proof of 2-approximation

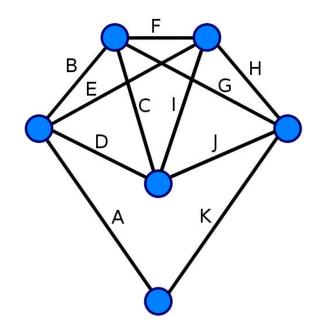
- Let H\* be an optimum TSP.
- If we delete an edge from H\*, we get a spanning tree.
- Since T is an MST,  $c(T) \le c(H^*)$ .
- Call the path from the depth-first traversal T'.
  - □ T' crosses each edge in T twice.
  - $\square$  So c(T') = 2 c(T).
- Let H be the outcome of shortcutting T'.
  - H is a Hamiltonian cycle. It visits all the vertices, and ends where it started.
  - $\Box$  c(H)  $\leq$  c(T'), by the lemma.
  - $\Box$  c(H)  $\leq$  c(T') = 2 c(T)  $\leq$  2 c(H\*).
- So H is a 2-approximation.



## Matchings and Euler cycles

- A matching in a graph is a set of nonintersecting edges.
  - A perfect matching is a matching that includes every vertex.
- An Euler tour of a graph is a path that starts and ends at the same vertex, and visits every edge once.
  - □ Hamiltonian tour visits every vertex once.
- Thm (Euler) A graph has an Euler tour if and only if all vertices have even degree.
- Note how deciding if graph has Euler tour is trivial, but deciding if it has Hamiltonian tour is NPC!

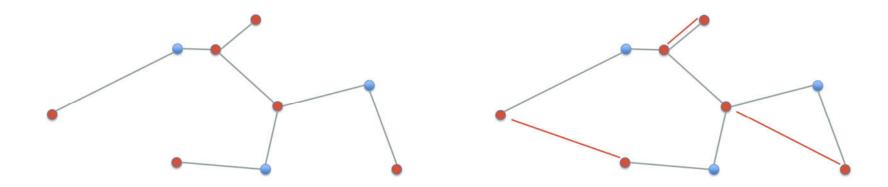






#### Christofides 3/2-approx algorithm

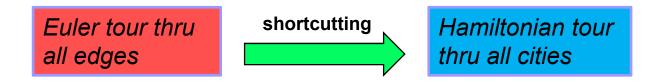
- ❖ A 3/2-approximation for TSP with triangle inequality.
- Construct a minimum spanning tree T on G.
- Find the set V' of odd degree vertices in T.
- Construct a minimum cost perfect matching M on V'.
- Add M to T to obtain T'.
- Find an Euler tour T" in T'.
- Shortcut T" to obtain a Hamiltonian cycle H. Output as the TSP.





## Why Christofides works well

- In the 2-approx, we found a TSP by "doubling" the MST to an Euler tour, then shortcutting.
  - □ We need to start with Euler tour before shortcutting to ensure we visit all cities.



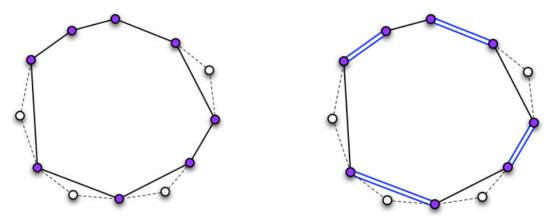
- Key to Christofides is to find a shorter Euler tour, without doubling the MST.
  - □ A graph with only even degree vertices always has Euler tour.
  - So we want to modify the MST to have all even degrees, by adding a matching.



- Lemma T' has an Euler tour.
- Proof There are an even number of vertices in V', because the total degree of T is even.
  - □ Since G is a complete graph and |V'| is even, there's a perfect matching on V'.
    - The min cost perfect matching can be found in O(n²) time using the blossom algorithm.
  - □ The degree of every node in M is odd. Since V' are the odd degree nodes in T, adding M to T makes all nodes in T' have even degree.
  - □ T' has Euler tour by Euler's theorem.



- Lemma Let H\* be an optimal TSP on G, and let m be the cost of M. Then m ≤ c(H\*)/2.
- Proof Let H' be the optimal TSP on V'.
  - □ c(H') ≤ c(H\*) because H' is an optimal TSP on fewer vertices.
  - $\square$  H' is a cycle on V', so it consists of two matchings on V'. The cheaper one has cost m'  $\le$  c(H')/2  $\le$  c(H\*)/2.
  - □ m ≤ m' because M has min cost.





## Proof of 3/2-approximation

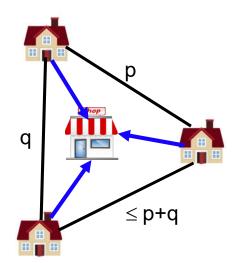
- Thm Let H be the TSP output by Christofides and let H\* be an optimal TSP. Then c(H) ≤ 3/2\*c(H\*).
- Proof
  - □ c(T) ≤ c(H\*) because T is an MST.
  - $\Box$  c(T') = c(M) + c(T) \le c(H\*)/2 + c(H\*) = 3/2\*c(H\*).
  - $\Box$  c(H)  $\leq$  c(T') because H is the shortcut of T'.

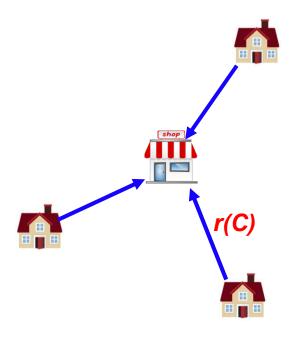
- □Construct a minimum spanning tree T on G.
- □ Find set V' of odd-degree vertices in T.
- □ Construct a minimum cost perfect matching M on V'.
- $\square$  Add M to T to obtain T'.
- ☐ Shortcut T' to obtain a Hamiltonian cycle. Output as the TSP.



### k-Center problem

- Given a city with n sites, we want to build k centers to serve them.
  - □ Let S be set of sites, C be set of centers.
- Each site uses the center closest to it.
  - □ Distance of site s from the nearest center is  $d(s,C) = \min_{c \in C} d(s,c)$ .
- Goal is to make sure no site is too far from its center.
  - We want to minimize the max distance that any site is from its closest center.
    - Minimize r(C)=max<sub>s∈S</sub> min<sub>c∈C</sub> d(s,c).
  - □ C is called a cover of S, and r is called
    C's radius.
  - Where should we put centers to minimize the radius?
- Assume distances satisfy triangle inequality.





# Gonzalez's algorithm

- k-Center is NP-complete.
- We'll give a simple 2-approximation for it.
- Idea Say there's one site that's farthest away from all centers. Then it makes the radius large. We'll put a center at that site, to reduce the radius.
  - □ Note we allow putting center at same location as site.



## Gonzalez's algorithm

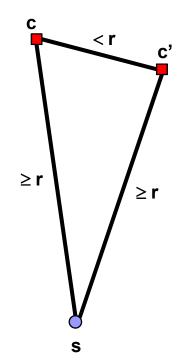
C is set of centers, initially empty.

- □ repeat k times
  - □choose site s with maximum d(s,C)
  - □add s to C
- □ return C

■ Note The centers are located at the sites.



- Let C be the algorithm's output, and r be C's radius.
  - $\Box$  r = max<sub>s∈S</sub> min<sub>c∈C</sub> d(s,c)
- Lemma 1 For any c,c'∈C, d(c,c')≥r.
- Proof Since r is the radius, there exists a point s∈S at distance ≥ r from all the centers.
  - □ If there's no such s, then C's radius < r.
  - $\square$  So s is distance  $\ge$  r from c and c'.
  - □ Suppose WLOG c' is added to C after c.
  - □ If d(c,c')<r, then algorithm would add s to C instead of c', since s is farther.

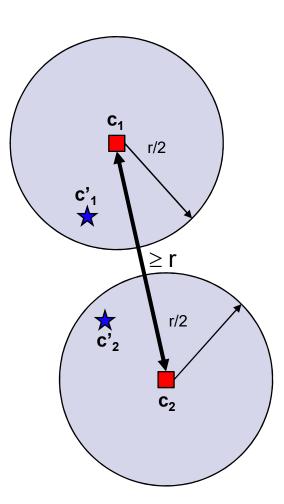


# r,e

- Cor There exist k+1 points mutually at distance ≥ r from each other.
  - □ By the lemma, the k centers are mutually ≥ r distance apart.
  - □ Also, there's an s∈S at distance ≥ r from all the centers.
    - Otherwise C's covering radius is < r.
  - ☐ So the k centers plus s are the k+1 points.
- Call these k+1 points D.



- Let C\* be an optimal cover with radius r\*.
- Lemma 2 Suppose r > 2r\*. Then for every c∈D, there exists a corresponding c'∈C\*. Furthermore, all these c' are unique.
- Proof Draw a circle of radius r/2 around each c∈D.
  - □ There must be a c'∈C\* inside the circle, because
    - c is at most distance r\* away from its nearest center, since r\* is C\*'s radius.
    - r/2>r\*.
  - □ Given  $c_1, c_2 \in D$ , let  $c'_1, c'_2 \in C^*$  be inside  $c_1$  and  $c_2$ 's circle, resp.
  - $\Box$  c<sub>1</sub> and c<sub>2</sub>'s circles don't touch, because d(c<sub>1</sub>,c<sub>2</sub>)  $\geq$  r.
  - □ So  $c'_1 \neq c'_2$ .





- Thm Let C be the output of Gonzalez's algorithm, and let C\* be an optimal kcenter. Then r(C) ≤ 2r(C\*).
- Proof By Lemma 2, if r(C)>2r(C\*), then for every c∈D, there is a unique c'∈C\*.
  - □ But there are k+1 points in D, by the corollary.
  - □ So there are k+1 points in C\*. This is a contradiction because C\* is a k-center.