

# Chapter 7

# Network Flow



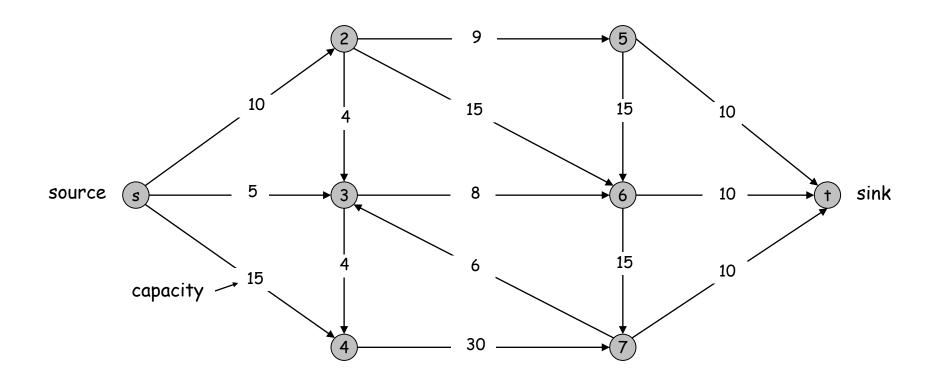
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# 7.1 Max-flow and Ford-Fulkerson Algorithm

#### Flows

#### Flow network.

- Abstraction for material flowing through the edges.
- G = (V, E) = directed graph
- Two distinguished nodes: s = source, t = sink.
- c(e) = nonnegative capacity of edge e.



#### Flows

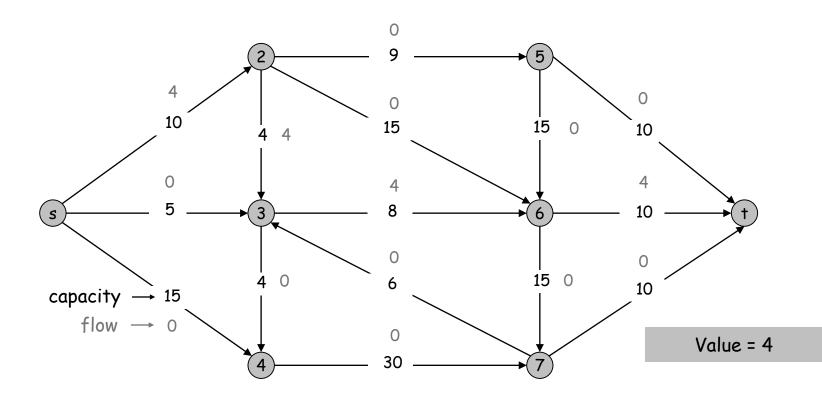
Def. An s-t flow is a function that satisfies:

- For each  $e \in E$ :
  - $0 \le f(e) \le c(e)$

- (capacity)
- For each  $v \in V \{s, t\}$ :  $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$

(conservation)

Def. The value of a flow f is:  $v(f) = \sum_{e \text{ out of } s} f(e)$ .



#### Flows

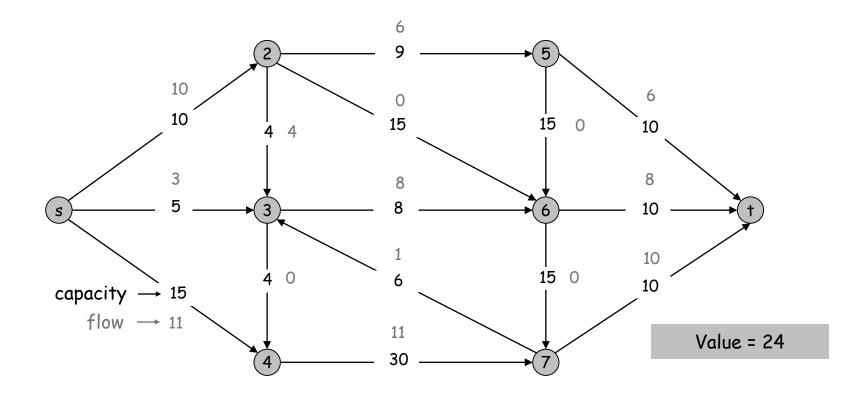
e out of v

Def. An s-t flow is a function that satisfies:

• For each  $e \in E$ :  $0 \le f(e) \le c(e)$  (capacity) • For each  $v \in V - \{s, t\}$ :  $\sum f(e) = \sum f(e)$  (conservation)

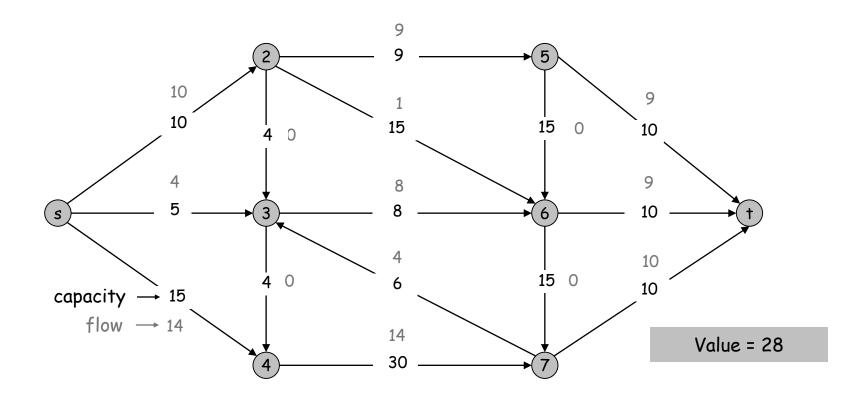
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Def. The value of a flow f is:  $v(f) = \sum_{e \text{ out of } s} f(e)$ .



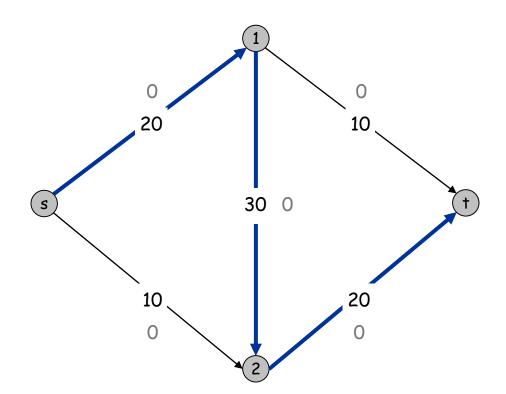
## Maximum Flow Problem

Max flow problem. Find s-t flow of maximum value.



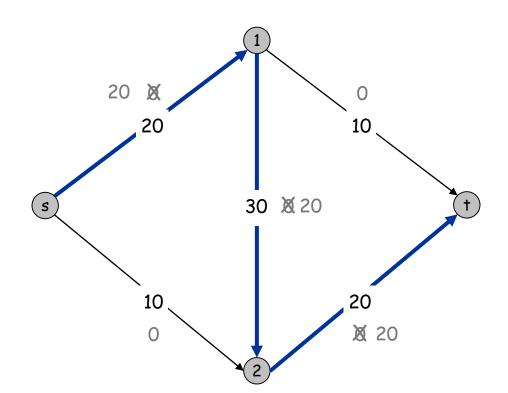
## Greedy algorithm.

- Start with f(e) = 0 for all edge  $e \in E$ .
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.



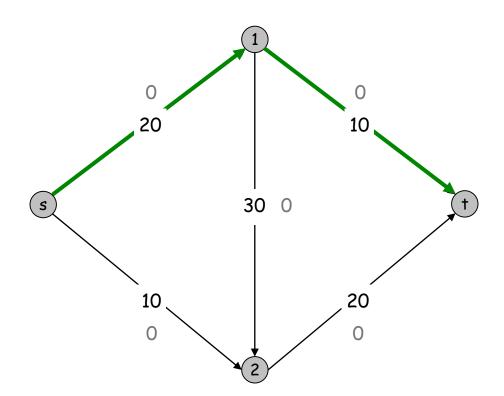
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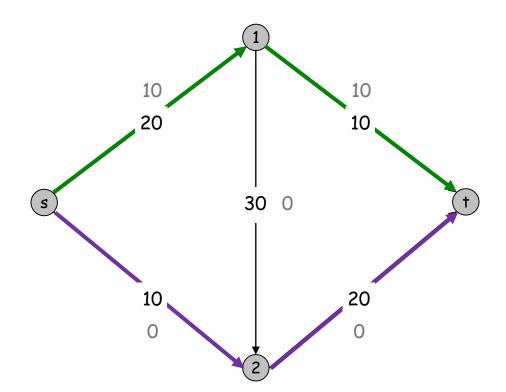
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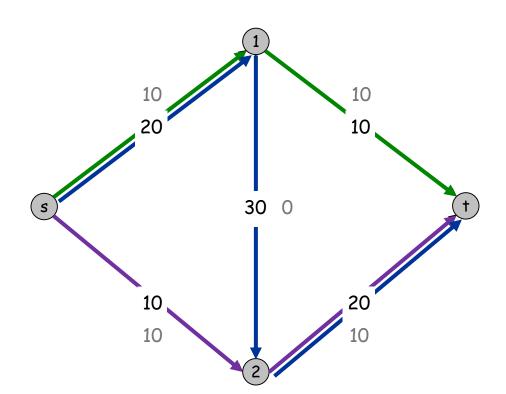
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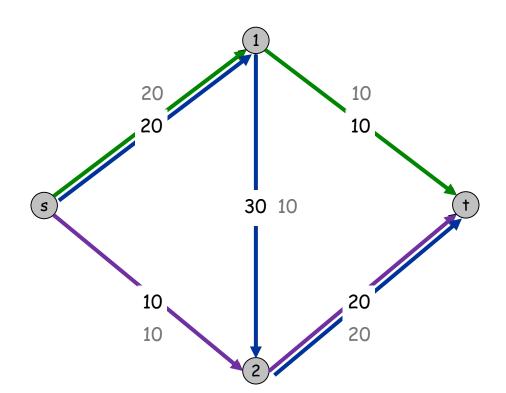
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# Greedy algorithm.

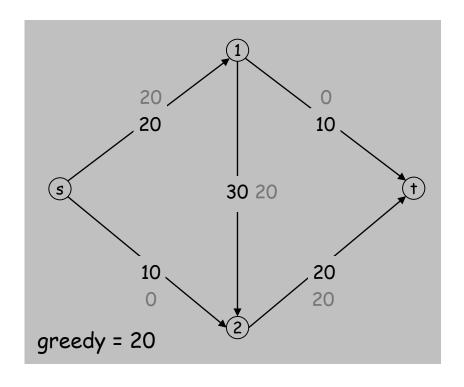
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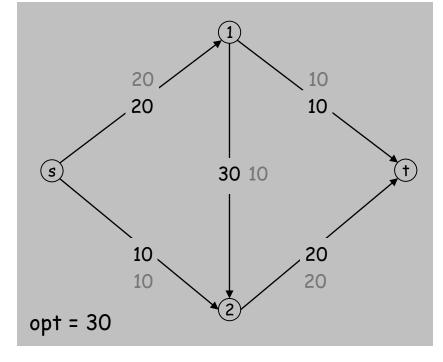


### Greedy algorithm.

- Start with f(e) = 0 for all edge  $e \in E$ .
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.

 $\nearrow$  locally optimality  $\Rightarrow$  global optimality

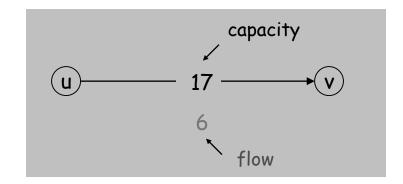




# Residual Graph

## Original edge: $e = (u, v) \in E$ .

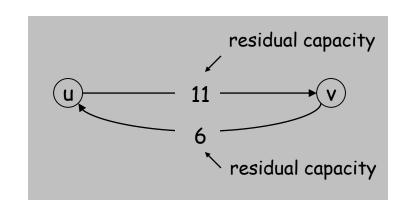
Flow f(e), capacity c(e).



#### Residual edge.

- "Undo" flow sent.
- e = (u, v) and  $e^{R} = (v, u)$ .
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$



### Residual graph: $G_f = (V, E_f)$ .

- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}.$

## Augmenting Path

Augmenting path: a simple s-t path P in the residual graph  $G_f$ 

Bottleneck capacity of an augmenting path P is the minimum residual capacity of any edge in P

```
Augment(f, c, P) {
  b ← bottleneck(P)
  foreach e ∈ P {
    if (e ∈ E) f(e) ← f(e) + b forward edge
    else f(e<sup>R</sup>) ← f(e<sup>R</sup>) - b
  reverse edge
  }
  return f
}
```

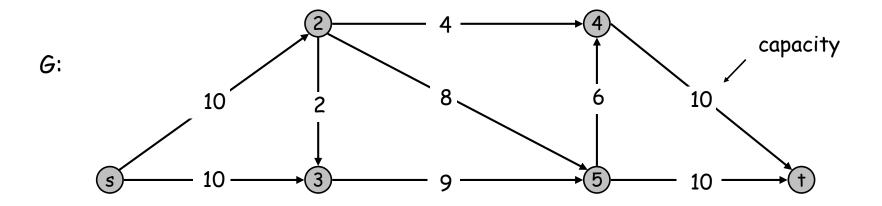
Claim: After augmentation, f is still a flow.

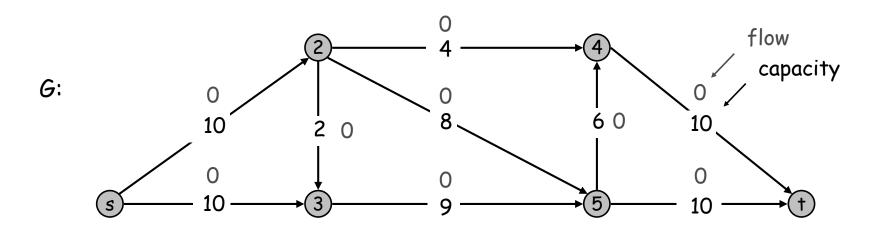
#### Ford-Fulkerson Algorithm

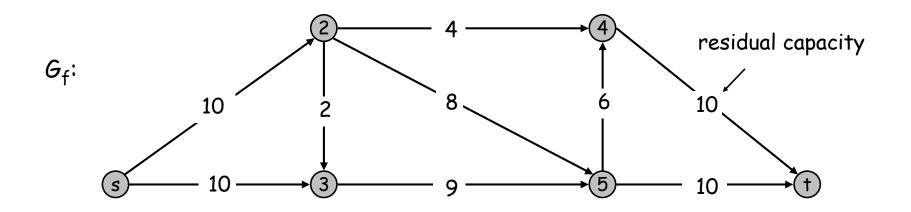
- Start with f(e) = 0 for all edge  $e \in E$ .
- Find an augmenting path P in the residual graph  $G_f$ .
- Augment flow along path P.
- Repeat until you get stuck.

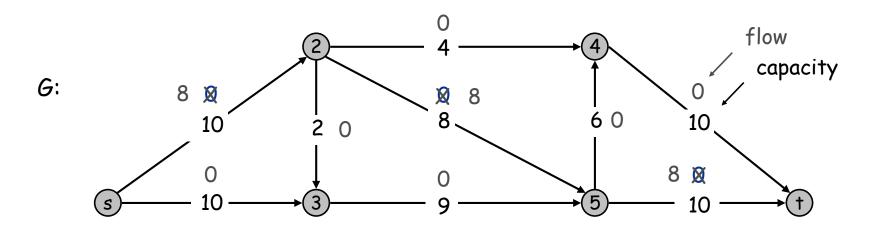
```
Ford-Fulkerson(G, s, t, c) {
   foreach e ∈ E f(e) ← 0
   G<sub>f</sub> ← residual graph

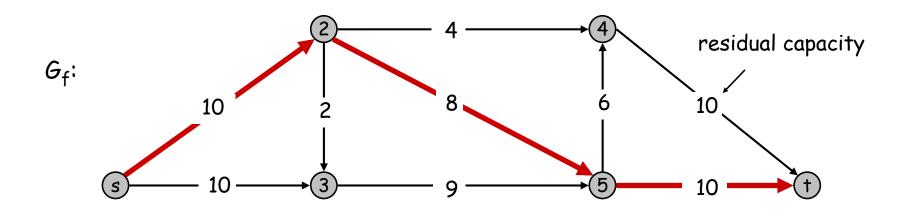
while (there exists augmenting path P) {
   f ← Augment(f, c, P)
     update G<sub>f</sub>
   }
   return f
}
```

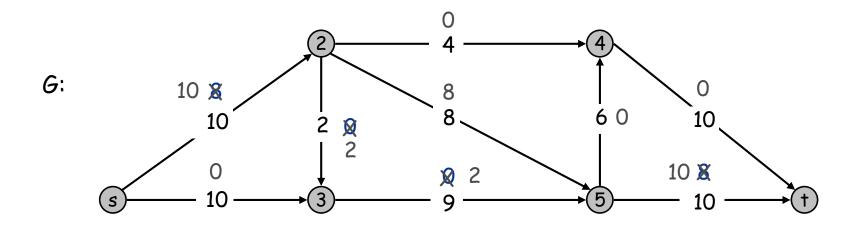


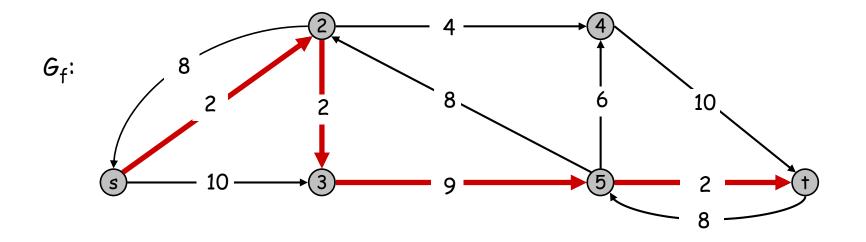


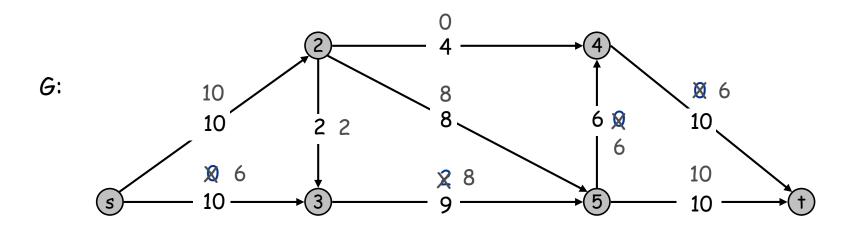


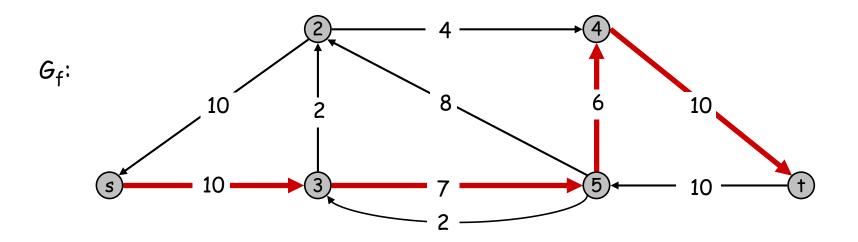


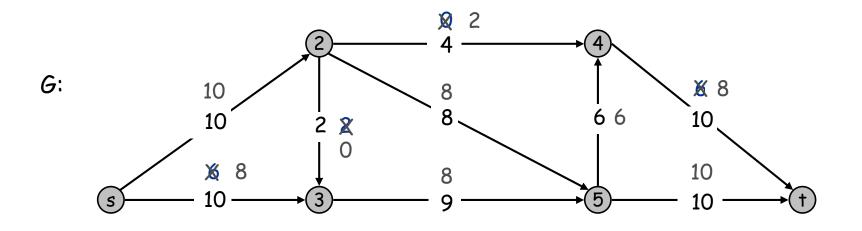


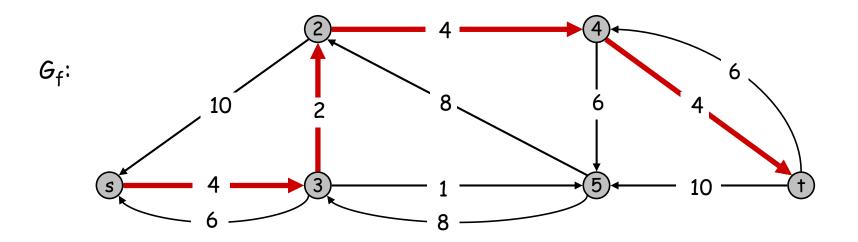


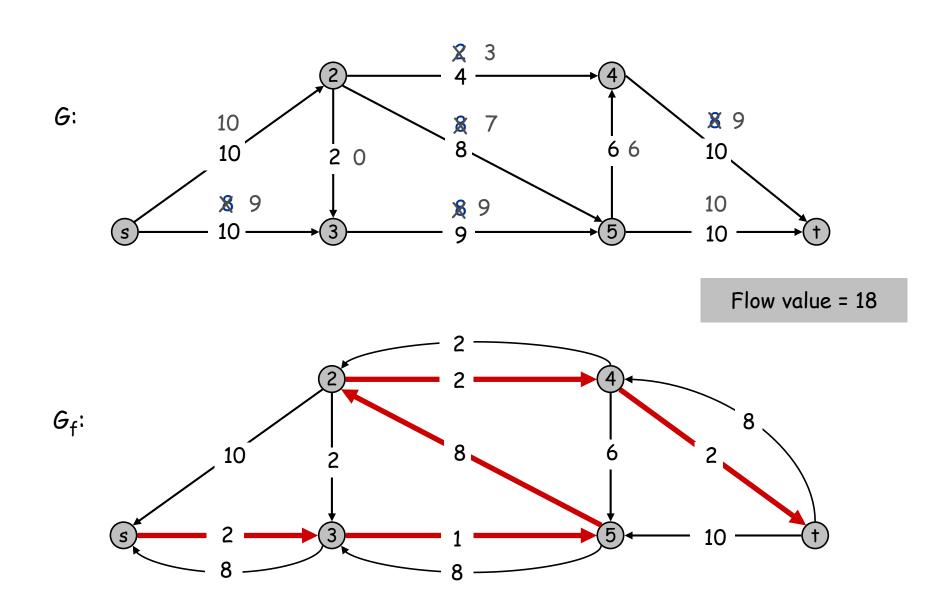


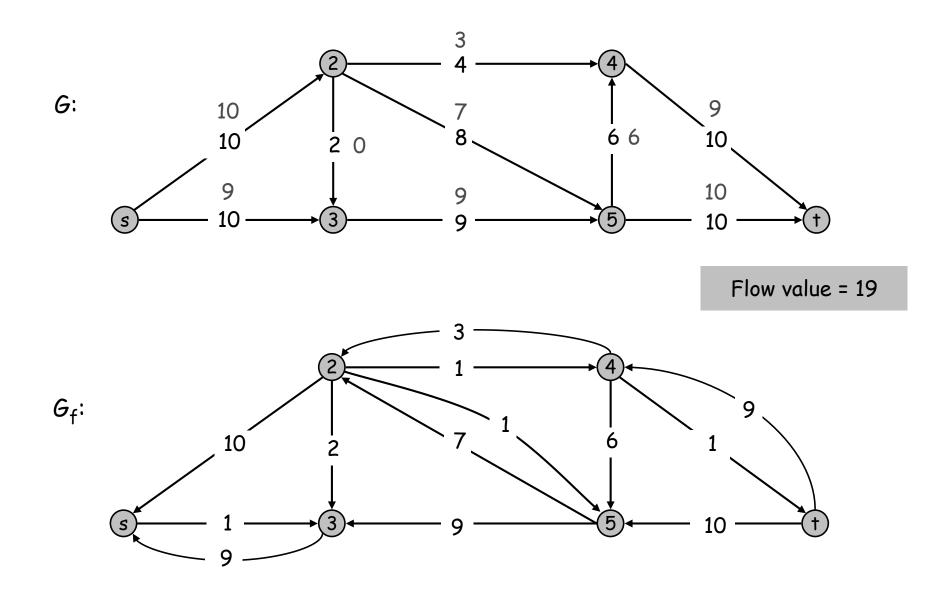










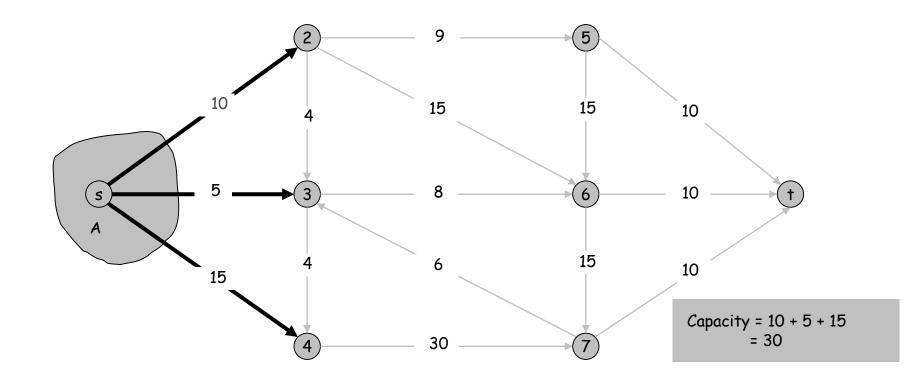


# 7.2 Max-flow and Min-cut

#### Cuts

Def. An s-t cut is a partition (A, B) of V with  $s \in A$  and  $t \in B$ .

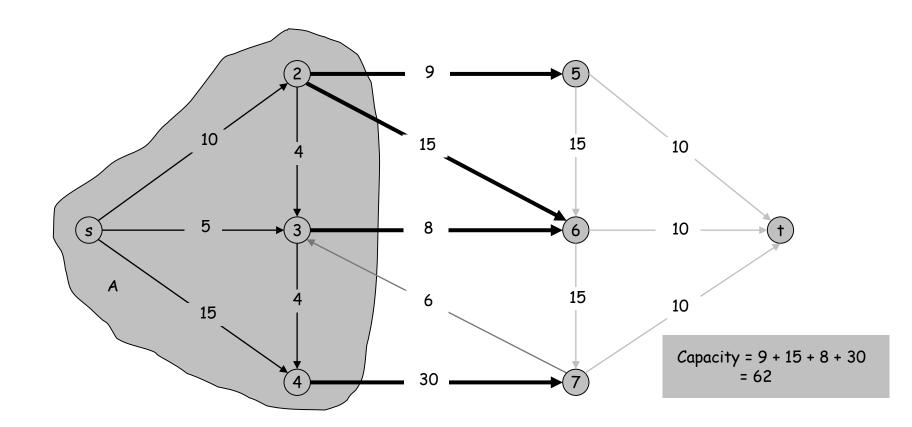
Def. The capacity of a cut (A, B) is:  $cap(A, B) = \sum_{e \text{ out of } A} c(e)$ 



#### Cuts

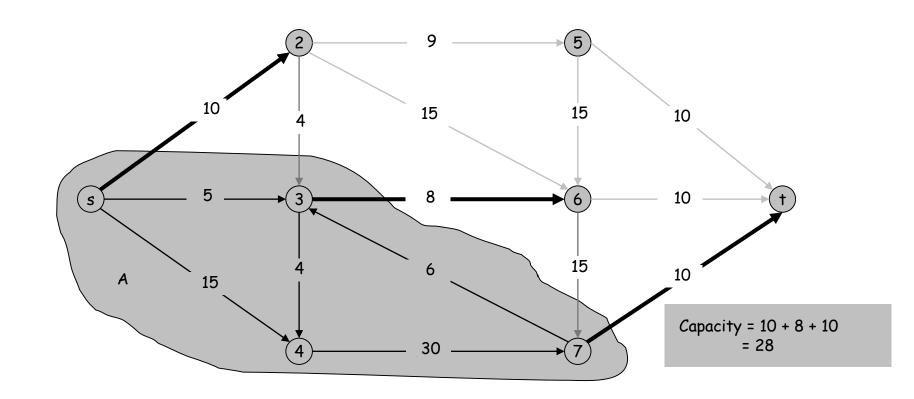
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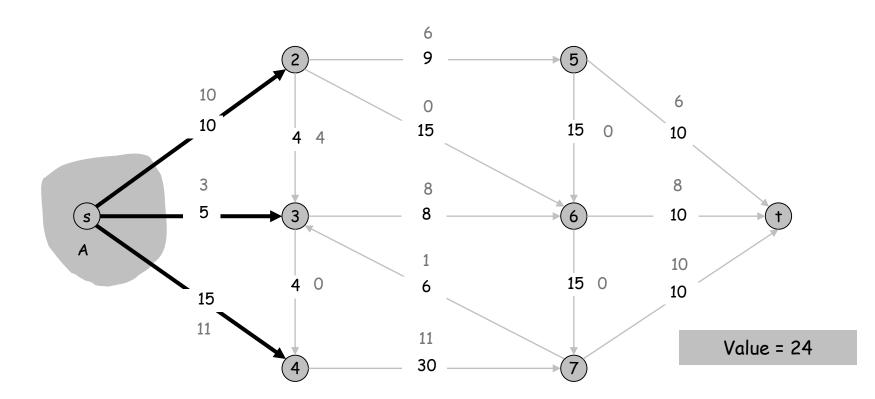
## Minimum Cut Problem

Min s-t cut problem. Find an s-t cut of minimum capacity.



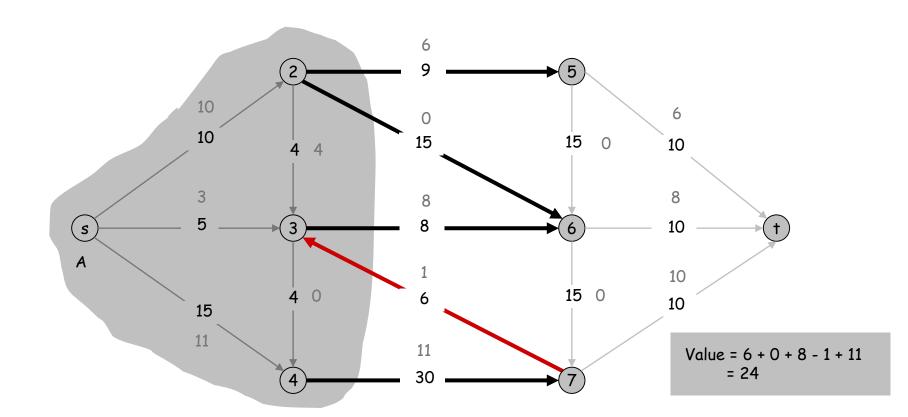
Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$$



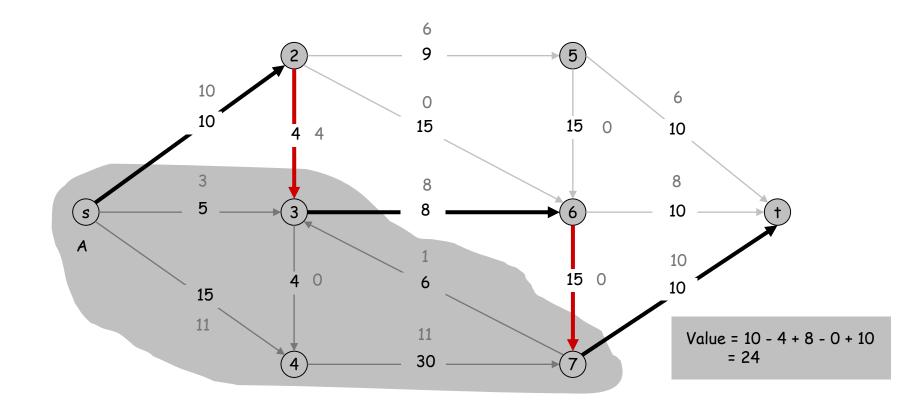
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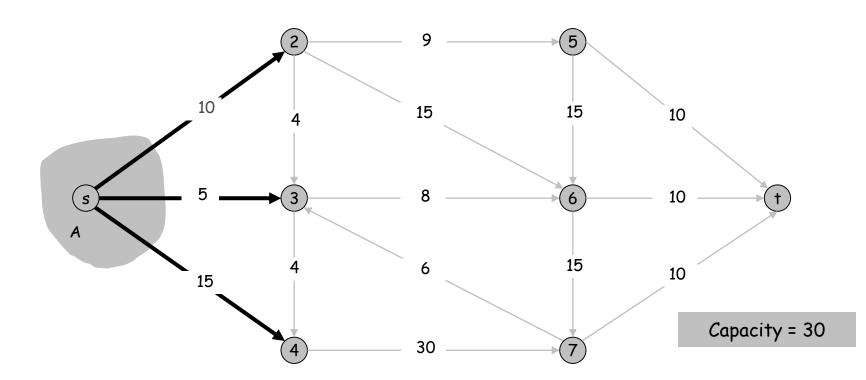
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

Pf. 
$$v(f) = \sum_{e \text{ out of } s} f(e)$$
by flow conservation, all terms 
$$= \sum_{v \in A} \left( \sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$$

$$= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e).$$

Weak duality. Let f be any flow, and let (A, B) be any s-t cut. Then the value of the flow is at most the capacity of the cut.

Cut capacity =  $30 \Rightarrow \text{Flow value} \leq 30$ 



Weak duality. Let f be any flow. Then, for any s-t cut (A, B) we have  $v(f) \le cap(A, B)$ .

Pf.

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} c(e)$$

$$\leq cap(A, B)$$

#### Max-Flow Min-Cut Theorem

Augmenting path theorem. Flow f is a max flow iff there are no augmenting paths.

Max-flow min-cut theorem. [Ford-Fulkerson 1956] The value of the max flow is equal to the value of the min cut.

Proof strategy. We prove both simultaneously by showing the equivalence of the following three conditions for any flow f:

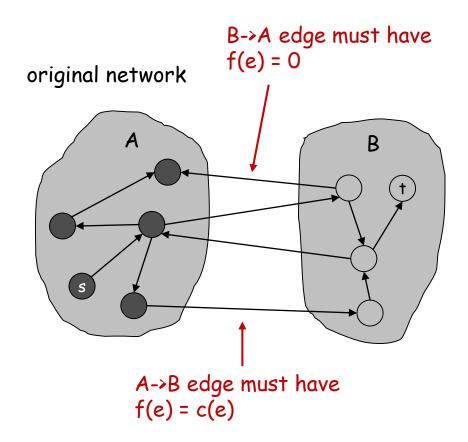
- (i) There exists a cut (A, B) such that v(f) = cap(A, B).
- (ii) Flow f is a max flow.
- (iii) There is no augmenting path relative to f.
- (i)  $\Rightarrow$  (ii) This was the corollary to weak duality lemma.
- (ii)  $\Rightarrow$  (iii) We show contrapositive.
- If there exists an augmenting path, then we can improve f by sending flow along path.

#### Proof of Max-Flow Min-Cut Theorem

#### (iii) $\Rightarrow$ (i)

- Let f be a flow with no augmenting paths.
- Let A be set of vertices reachable from s in residual graph.
- By definition of  $A, s \in A$ .
- By definition of  $f, t \notin A$ .

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$
$$= \sum_{e \text{ out of } A} c(e)$$
$$= cap(A, B) \quad \blacksquare$$



## 7.3 Choosing Good Augmenting Paths

## Running Time

Assumption. All capacities are integers between 1 and C.

Invariant. Every flow value f(e) and every residual capacities  $c_f(e)$  remains an integer throughout the algorithm.

Integrality theorem. If all capacities are integers, then there exists a max flow f for which every flow value f(e) is an integer.

Pf. Since algorithm terminates, theorem follows from invariant.

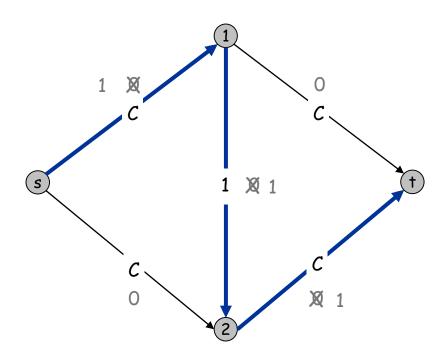
Theorem. The algorithm terminates in at most  $v(f^*) \le nC$  iterations. Pf. Each augmentation increase value by at least 1.

Corollary. Running time of Ford-Fulkerson is  $O(mnC) \leftarrow Polynomial$ ?

## Ford-Fulkerson: Exponential Number of Augmentations

Generic Ford-Fulkerson algorithm is not polynomial in input size?

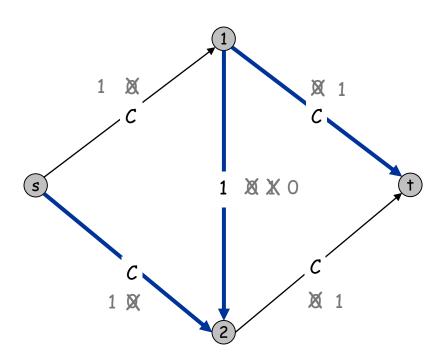
An example: If max capacity is C, then the algorithm can take  $\geq C$  iterations.



## Ford-Fulkerson: Exponential Number of Augmentations

Generic Ford-Fulkerson algorithm is not polynomial in input size?

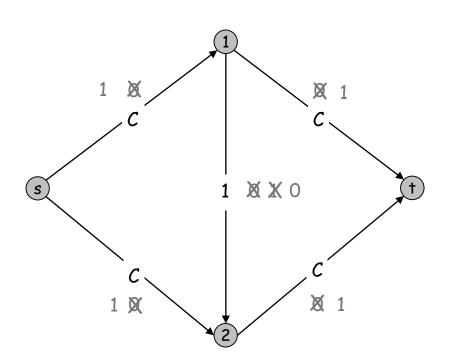
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## Ford-Fulkerson: Exponential Number of Augmentations

Generic Ford-Fulkerson algorithm is not polynomial in input size?

An example: If max capacity is C, then the algorithm can take  $\geq C$  iterations.



each augmenting path sends only 1 unit of flow (# augmenting paths = 2C)

## Choosing Good Augmenting Paths

### Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- (If capacities are irrational, algorithm not guaranteed to terminate!)

### Goal: choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

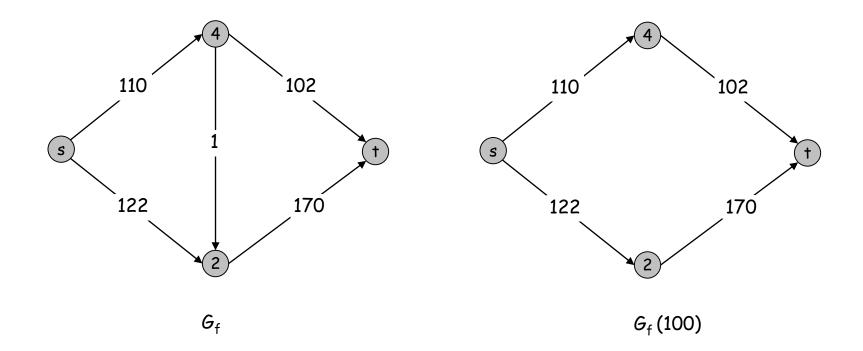
#### Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]

- Max bottleneck capacity.
- Fewest number of edges.
- Sufficiently large bottleneck capacity.

## Capacity Scaling

Intuition. Choosing path with high bottleneck capacity

- Maintain scaling parameter  $\Delta$ .
- Let the  $\Delta$ -residual graph  $G_f(\Delta)$  be the subgraph of the residual graph consisting of only arcs with capacity at least  $\Delta$ .



## Capacity Scaling

```
Scaling-Max-Flow(G, s, t, c) {
    foreach e \in E f(e) \leftarrow 0
    \Delta \leftarrow largest power of 2 \leq C
    while (\Delta \ge 1) {
        G_f(\Delta) \leftarrow \Delta-residual graph
        while (there exists augmenting path P in G_f(\Delta)) {
            f \leftarrow augment(f, c, P)
           update G_f(\Delta)
       \Delta \leftarrow \Delta / 2
    return f
```

## Capacity Scaling: Correctness

Assumption. All edge capacities are integers between 1 and C.

Integrality invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then f is a max flow. Pf.

- By integrality invariant, when  $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$ .
- Upon termination of  $\Delta$  = 1 phase, there are no augmenting paths. •

## Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats  $1 + \lfloor \log_2 C \rfloor$  times. Pf. Initially  $C/2 < \Delta \le C$ .  $\Delta$  decreases by a factor of 2 each iteration.

Lemma 2. Let f be the flow at the end of a  $\Delta$ -scaling phase. Then the value of the maximum flow is at most  $v(f) + m \Delta$ .  $\leftarrow$  proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase.

- Let f be the flow at the end of the previous scaling phase.
- L2  $\Rightarrow$  v(f\*)  $\leq$  v(f) + m (2 $\Delta$ ).
- Each augmentation in a  $\Delta$ -phase increases v(f) by at least  $\Delta$ . •

Theorem. The scaling max-flow algorithm finds a max flow in  $O(m \log C)$  augmentations. It can be implemented to run in  $O(m^2 \log C)$  time.

## Capacity Scaling: Running Time

Lemma 2. Let f be the flow at the end of a  $\Delta$ -scaling phase. Then value of the maximum flow is at most  $v(f) + m \Delta$ .

Pf. (almost identical to proof of max-flow min-cut theorem)

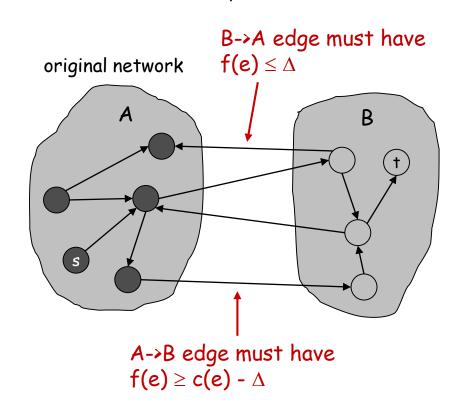
- We show that at the end of a  $\Delta$ -phase, there exists a cut (A, B) such that  $cap(A, B) \leq v(f) + m \Delta$ .
- Choose A to be the set of nodes reachable from s in  $G_f(\Delta)$ .
- By definition of  $A, s \in A$ .
- By definition of  $f, t \notin A$ .

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e)$$

$$\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta$$

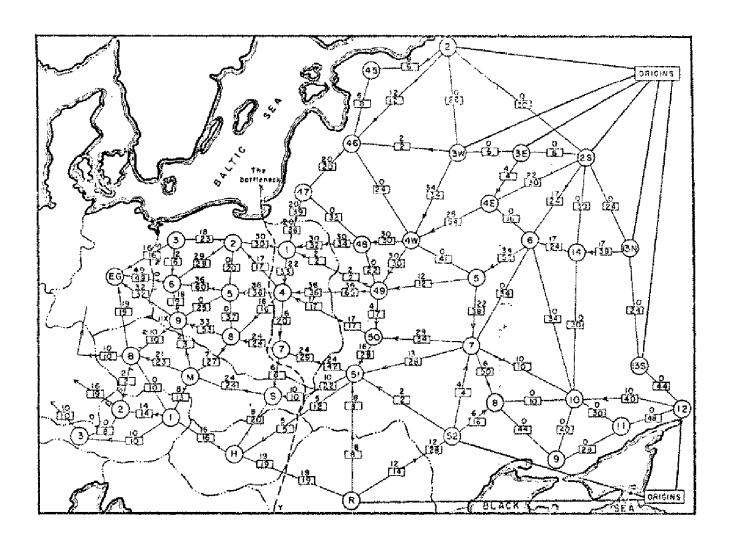
$$= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta$$

$$\geq cap(A, B) - m\Delta$$



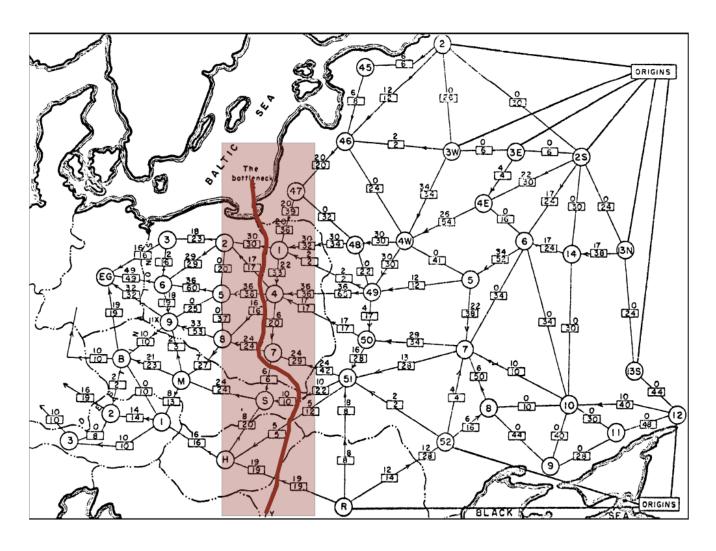
## Applications of max-flow

## Soviet Rail Network, 1955



Reference: On the history of the transportation and maximum flow problems. Alexander Schrijver in Math Programming, 91: 3, 2002.

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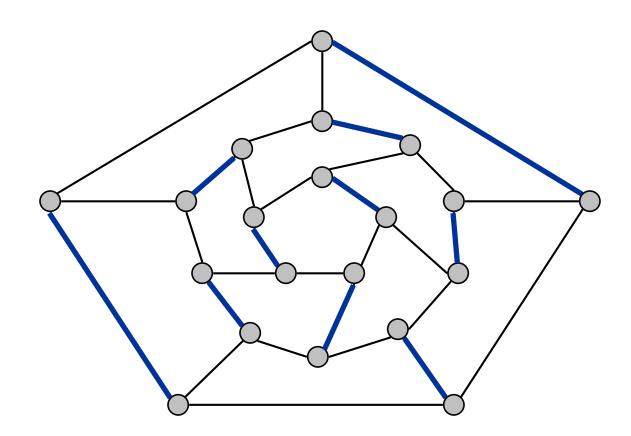
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## 7.5 Bipartite Matching

## Matching

## Matching.

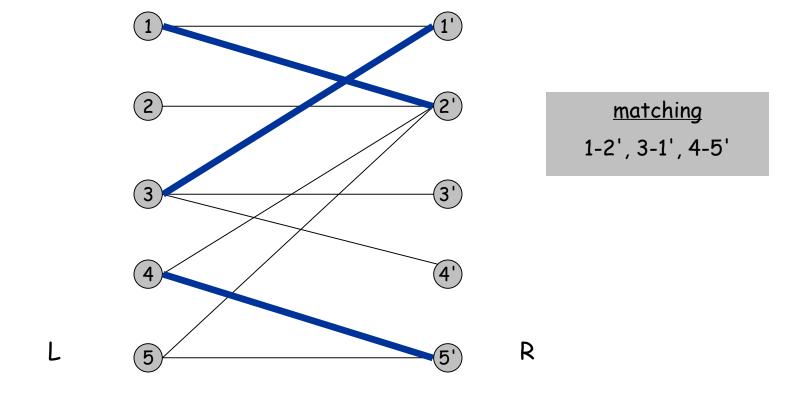
- Input: undirected graph G = (V, E).
- $M \subseteq E$  is a matching if each node appears in at most one edge in M.
- Max matching: find a max cardinality matching.



## Bipartite Matching

### Bipartite matching.

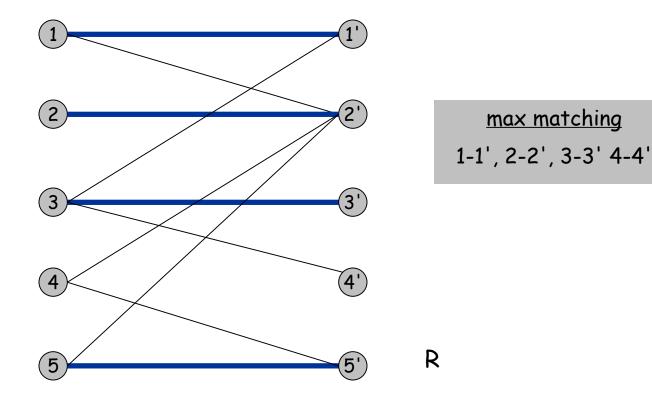
- Input: undirected, bipartite graph  $G = (L \cup R, E)$ .
- $M \subseteq E$  is a matching if each node appears in at most one edge in M.
- Max matching: find a max cardinality matching.



## Bipartite Matching

### Bipartite matching.

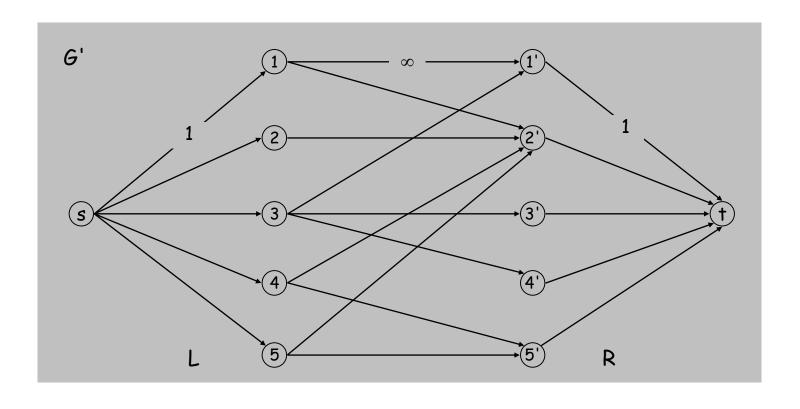
- Input: undirected, bipartite graph  $G = (L \cup R, E)$ .
- $M \subseteq E$  is a matching if each node appears in at most one edge in M.
- Max matching: find a max cardinality matching.



## Bipartite Matching

#### Max flow formulation.

- Create digraph  $G' = (L \cup R \cup \{s, t\}, E')$ .
- Direct all edges from L to R, and assign infinite (or unit) capacity.
- Add source s, and unit capacity edges from s to each node in L.
- Add sink t, and unit capacity edges from each node in R to t.

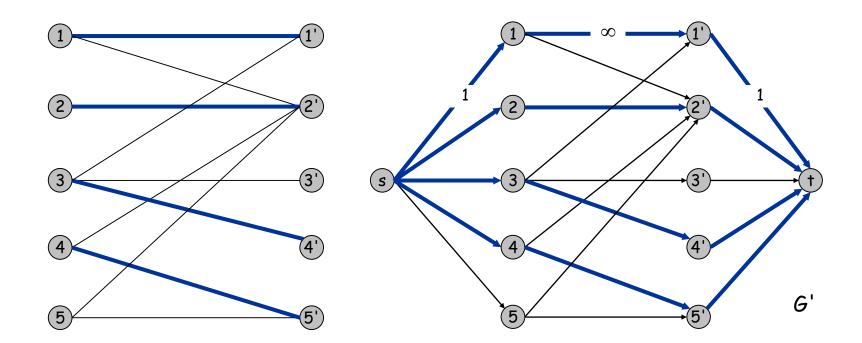


## Bipartite Matching: Proof of Correctness

Theorem. Max cardinality matching in G = value of max flow in G'. Pf.  $\leq$ 

- Given max matching M of cardinality k.
- Consider flow f that sends 1 unit along each of k paths.
- f is a flow, and has cardinality k.

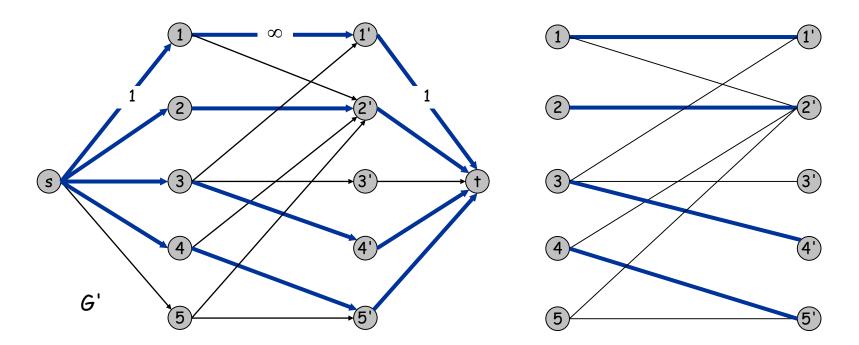
G



## Bipartite Matching: Proof of Correctness

Theorem. Max cardinality matching in G = value of max flow in G'. Pf.  $\geq$ 

- Let f be a max flow in G' of value k.
- Integrality theorem  $\Rightarrow$  k is integral and can assume f is 0-1.
- Consider M = set of edges from L to R with f(e) = 1.
  - each node in L and R participates in at most one edge in M
  - |M| = k: consider cut  $(L \cup s, R \cup t)$  -



## Perfect Matching

Def. A matching  $M \subseteq E$  is perfect if each node appears in exactly one edge in M.

Q. When does a bipartite graph have a perfect matching?

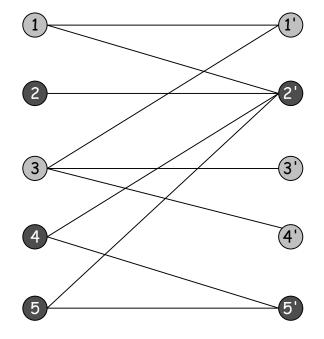
Structure of bipartite graphs with perfect matchings.

- Clearly we must have |L| = |R|.
- What other conditions are necessary?
- What conditions are sufficient?

## Perfect Matching

Notation. Let S be a subset of nodes, and let N(S) be the set of nodes adjacent to nodes in S.

Observation. If a bipartite graph  $G = (L \cup R, E)$ , has a perfect matching, then  $|N(S)| \ge |S|$  for all subsets  $S \subseteq L$ . Pf. Each node in S has to be matched to a different node in N(S).



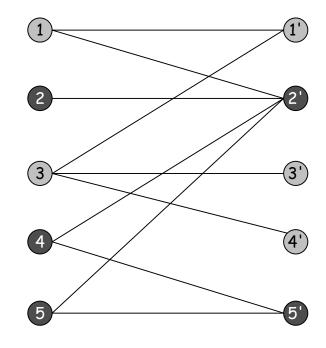
No perfect matching:

$$N(S) = \{ 2', 5' \}.$$

## Marriage Theorem

Marriage Theorem. [Frobenius 1917, Hall 1935] Let  $G = (L \cup R, E)$  be a bipartite graph with |L| = |R|. Then, G has a perfect matching iff  $|N(S)| \ge |S|$  for all subsets  $S \subseteq L$ .

Pf.  $\Rightarrow$  This was the previous observation.



No perfect matching:

R

$$N(S) = \{ 2', 5' \}.$$

## Proof of Marriage Theorem

Marriage Theorem. G has a perfect matching iff  $|N(S)| \ge |S|$  for all subsets  $S \subseteq L$ .

Pf.  $\leftarrow$  Suppose G does not have a perfect matching.

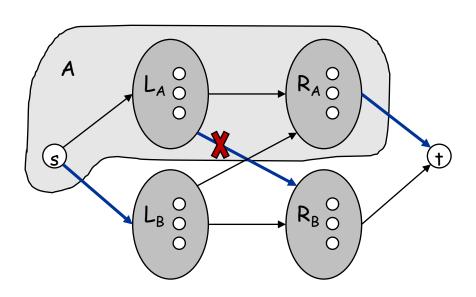
- Formulate as a max flow problem and let (A, B) be min cut in G'.
- Define  $L_A = L \cap A$ ,  $L_B = L \cap B$ ,  $R_A = R \cap A$ ,  $R_B = R \cap B$ .
- $cap(A, B) = v(f^*) = |M| < |L| ("<": because no perfect matching)$
- Since min cut can't use  $\infty$  edges, no edge between  $L_A$  and  $R_B$

$$- cap(A, B) = |L_B| + |R_A|$$

- 
$$N(L_A) \subseteq R_A$$
.

■ 
$$|N(L_A)| \le |R_A|$$
  
=  $cap(A, B) - |L_B|$   
<  $|L| - |L_B|$   
=  $|L_A|$ .

This contradicts the condition

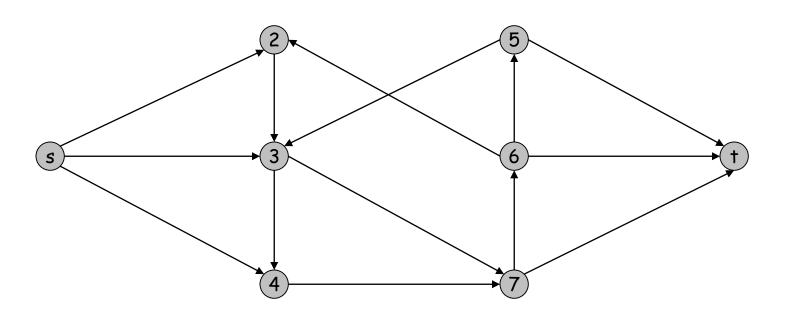


# 7.6 Disjoint Paths

Disjoint path problem. Given a digraph G = (V, E) and two nodes s and t, find the max number of edge-disjoint s-t paths.

Def. Two paths are edge-disjoint if they have no edge in common.

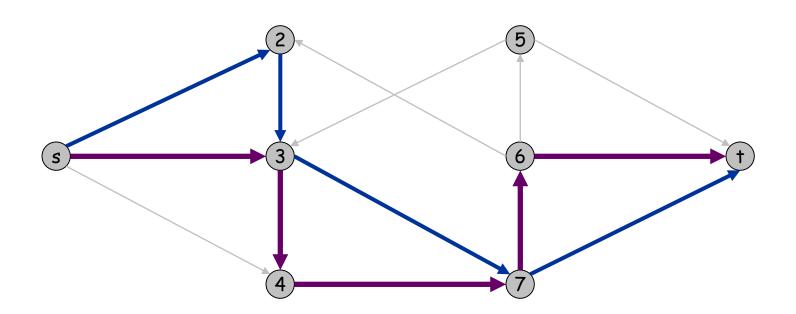
Ex: communication networks.



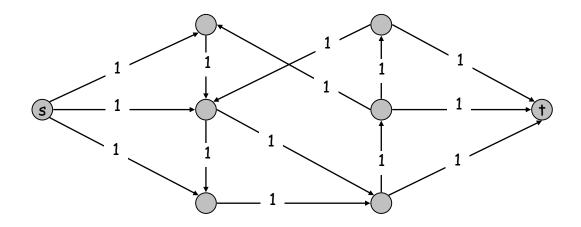
Disjoint path problem. Given a digraph G = (V, E) and two nodes s and t, find the max number of edge-disjoint s-t paths.

Def. Two paths are edge-disjoint if they have no edge in common.

Ex: communication networks.



Max flow formulation: assign unit capacity to every edge.



Theorem. Max number edge-disjoint s-t paths equals max flow value.

Theorem. Max number edge-disjoint s-t paths equals max flow value. Pf.  $\leq$ 

- Suppose there are k edge-disjoint paths  $P_1, \ldots, P_k$ .
- Set f(e) = 1 if e participates in some path  $P_i$ ; else set f(e) = 0.
- Since paths are edge-disjoint, f is a flow of value k.

Theorem. Max number edge-disjoint s-t paths equals max flow value. Pf.  $\geq$ 

- Suppose max flow value is k.
- Integrality theorem  $\Rightarrow$  there exists 0-1 flow f of value k.
- Consider edge (s, u) with f(s, u) = 1.
  - by conservation, there exists an edge (u, v) with f(u, v) = 1
  - continue until reach t, always choosing a new edge
  - So we get a s-t path
- Reduce the flow to 0 along the path, so we get a flow of value k-1
- Repeat the process for k times, then we get k (not necessarily simple) edge-disjoint paths.

can eliminate cycles to get simple paths if desired

## 7.7 Extensions to Max Flow

#### Circulation with demands.

- Directed graph G = (V, E).
- Edge capacities c(e),  $e \in E$ .
- Node supply and demands d(v),  $v \in V$ .

demand if d(v) > 0; supply if d(v) < 0; transshipment if d(v) = 0

#### Def. A circulation is a function that satisfies:

■ For each  $e \in E$ :  $0 \le f(e) \le c(e)$  (capacity)

For each  $e \in V$ :  $\nabla f(e) = d(v)$  (conservation)

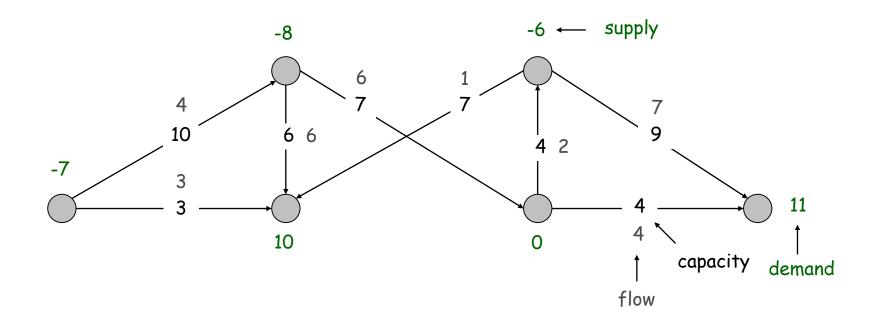
■ For each  $v \in V$ :  $\sum_{e \text{ in to } v} f(e) - \sum_{e \text{ out of } v} f(e) = d(v) \qquad \text{(conservation)}$ 

Circulation problem: given (V, E, c, d), does there exist a circulation?

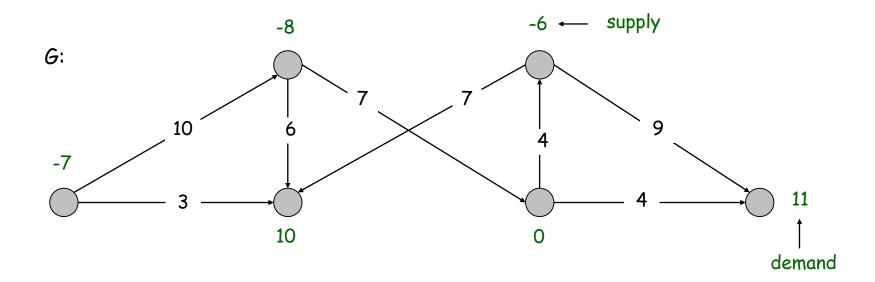
Necessary condition: sum of supplies = sum of demands.

$$\sum_{v:d(v)>0} d(v) = \sum_{v:d(v)<0} -d(v) =: D$$

Pf. Sum conservation constraints for every demand node v.

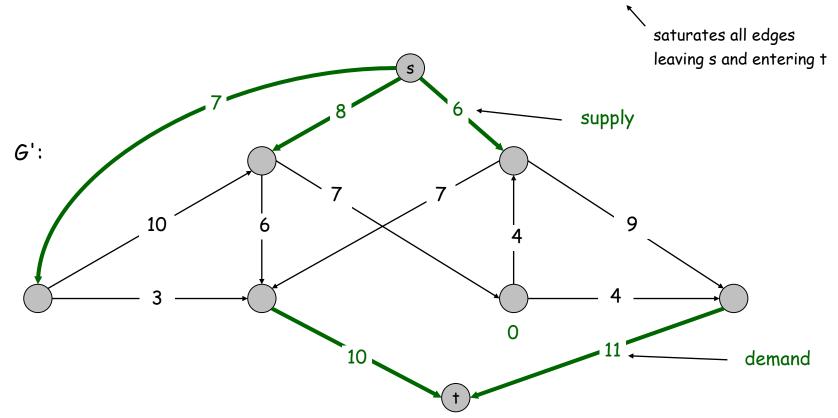


Max flow formulation.



#### Max flow formulation.

- Add new source s and sink t.
- For each v with d(v) < 0, add edge (s, v) with capacity -d(v).
- For each v with d(v) > 0, add edge (v, t) with capacity d(v).
- Claim: G has circulation iff G' has max flow of value D.



### Circulation with Demands

Integrality theorem. If all capacities and demands are integers, and there exists a circulation, then there exists one that is integer-valued.

Pf. Follows from max flow formulation and integrality theorem for max flow.

Characterization. Given (V, E, c, d), there does not exists a circulation iff there exists a node partition (A, B) such that  $\Sigma_{v \in B} d_v > \text{cap}(A, B)$ 

Pf idea. Look at max flow and min cut in G'.

demand by nodes in B exceeds supply of nodes in B plus max capacity of edges going from A to B

### Circulation with Demands and Lower Bounds

#### Feasible circulation.

- Directed graph G = (V, E).
- Edge capacities c(e) and lower bounds  $\ell$  (e),  $e \in E$ .
- Node supply and demands d(v),  $v \in V$ .

### Def. A circulation is a function that satisfies:

• For each 
$$e \in E$$
:  $\ell$  (e)  $\leq$   $r$ (e) (capacity)

■ For each 
$$v \in V$$
: 
$$\sum_{e \text{ in to } v} f(e) - \sum_{e \text{ out of } v} f(e) = d(v) \qquad \text{(conservation)}$$

Circulation problem with lower bounds. Given  $(V, E, \ell, c, d)$ , does there exists a circulation?

### Circulation with Demands and Lower Bounds

Idea. Model lower bounds with demands.

- Send  $\ell(e)$  units of flow along edge e.
- Update demands of both endpoints.



Theorem. There exists a circulation in G iff there exists a circulation in G'. If all demands, capacities, and lower bounds in G are integers, then there is a circulation in G that is integer-valued.

Pf sketch. f(e) is a circulation in G iff  $f'(e) = f(e) - \ell(e)$  is a circulation in G'.

# 7.8 Survey Design

## Survey Design

### Survey design.

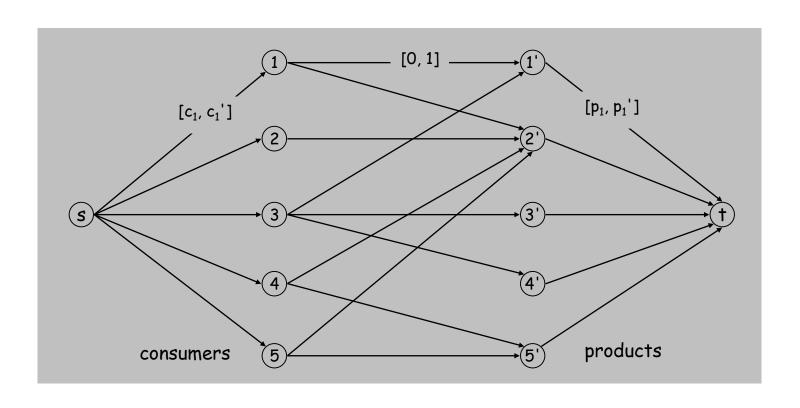
- Design survey asking  $n_1$  consumers about  $n_2$  products.
- Can only survey consumer i about a product j if they own it.
- Ask consumer i between c<sub>i</sub> and c<sub>i</sub> questions.
- Ask between  $p_i$  and  $p_j$  consumers about product j.

Goal. Design a survey that meets these specs, if possible.

## Survey Design

### Algorithm. Formulate as a flow-network?

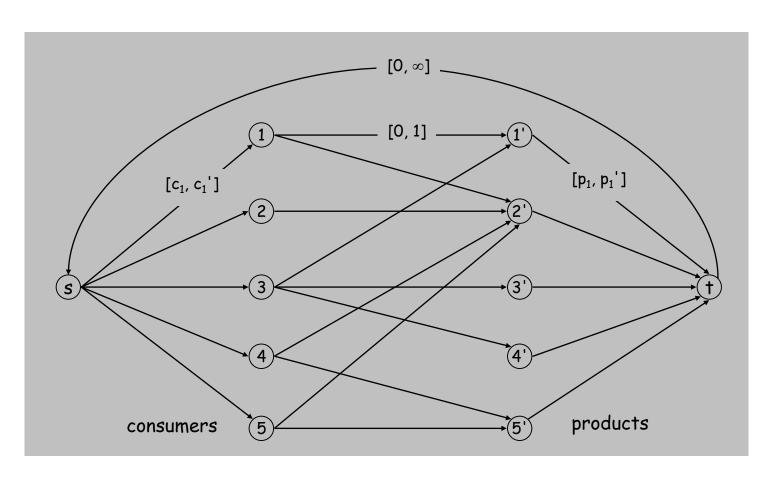
- Include an edge (i, j) if customer own product i.
- Goal: find a flow that satisfies edge upper lower bounds. How?



## Survey Design

Algorithm. Formulate as a circulation problem with lower bounds.

- Include an edge (i, j) if customer own product i.
- Integer circulation  $\Leftrightarrow$  feasible survey design.



# 7.10 Image Segmentation

### Image segmentation.

- Central problem in image processing.
- Divide image into coherent regions.

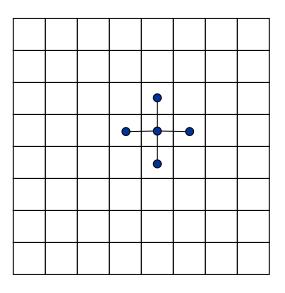
Ex: Two people standing in front of complex background scene. Identify each person as a coherent object.





### Foreground / background segmentation.

- Label each pixel in picture as belonging to foreground or background.
- V = set of pixels, E = pairs of neighboring pixels.
- $a_i \ge 0$  is likelihood pixel i in foreground.
- $b_i \ge 0$  is likelihood pixel i in background.
- $p_{ij} \ge 0$  is separation penalty for labeling one of i and j as foreground, and the other as background.



### Goals.

- Accuracy: if  $a_i > b_i$  in isolation, prefer to label i in foreground.
- Smoothness: if many neighbors of i are labeled foreground, we should be inclined to label i as foreground.

$$\begin{array}{c|c} \textbf{Find partition (A, B) that maximizes:} & \sum\limits_{i \in A} a_i + \sum\limits_{j \in B} b_j & -\sum\limits_{(i,j) \in E} p_{ij} \\ \text{foreground background} & |A \cap \{i,j\}| = 1 \end{array}$$

### Formulate as min cut problem.

- Maximization.
- No source or sink.
- Undirected graph.

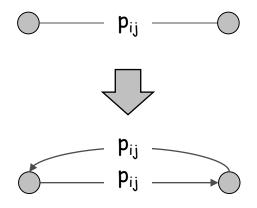
### Turn into minimization problem.

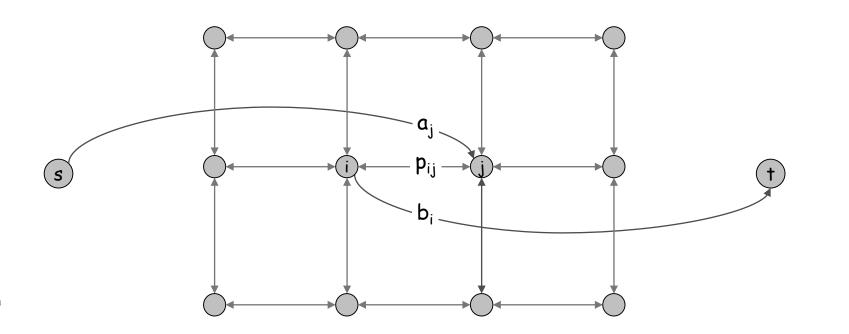
is equivalent to minimizing 
$$\underbrace{\left(\sum_{i\in V}a_i + \sum_{j\in V}b_j\right)}_{\text{a constant}} - \underbrace{\sum_{i\in A}a_i - \sum_{j\in B}b_j}_{i\in A} + \underbrace{\sum_{(i,j)\in E}p_{ij}}_{|A\cap\{i,j\}|=1}$$

• or alternatively 
$$\sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{(i,j) \in E} p_{ij}$$

### Formulate as min cut problem.

- G' = (V', E').
- Add source to correspond to foreground;
   add sink to correspond to background
- Use two anti-parallel edges instead of undirected edge.



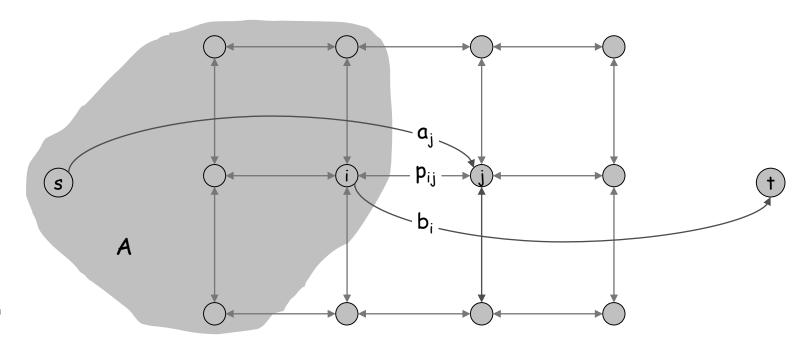


### Consider min cut (A, B) in G'.

A =foreground.

$$cap(A,B) = \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, \ j \in B}} p_{ij} \qquad \text{if i and j on different sides,}$$

Precisely the quantity we want to minimize.



# 7.11 Project Selection

## Project Selection

can be positive or negative

### Projects with prerequisites.

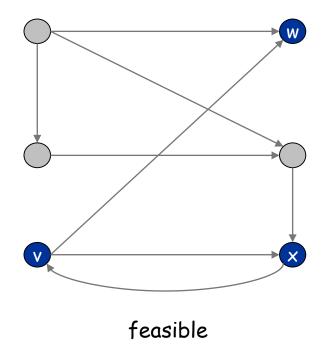
- Set P of possible projects. Project v has associated revenue  $p_v$ .
  - some projects generate money: create e-commerce interface, design web page
  - others cost money: upgrade computers, get site license
- Set of prerequisites E. If  $(v, w) \in E$ , can't do project v unless also do project w.
- A subset of projects  $A \subseteq P$  is feasible if the prerequisite of every project in A also belongs to A.

Project selection. Choose a feasible subset of projects to maximize revenue.

## Project Selection: Prerequisite Graph

### Prerequisite graph.

- Include an edge from v to w if can't do v without also doing w.
- $\{v, w, x\}$  is feasible subset of projects.
- $\{v, x\}$  is infeasible subset of projects.



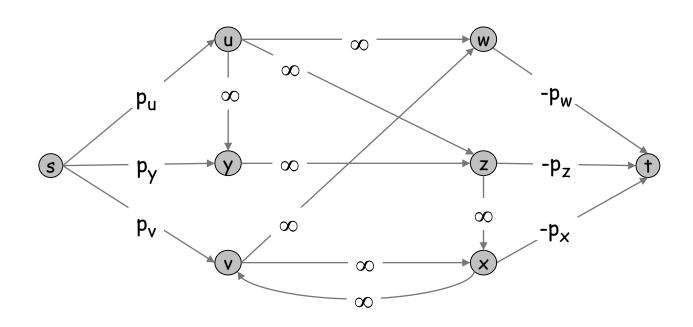
V X

infeasible

## Project Selection: Min Cut Formulation

### Min cut formulation.

- Assign capacity  $\infty$  to all prerequisite edges.
- Add edge (s, v) with capacity  $p_v$  if  $p_v > 0$ .
- Add edge (v, t) with capacity  $-p_v$  if  $p_v < 0$ .
- For notational convenience, define  $p_s = p_t = 0$ .

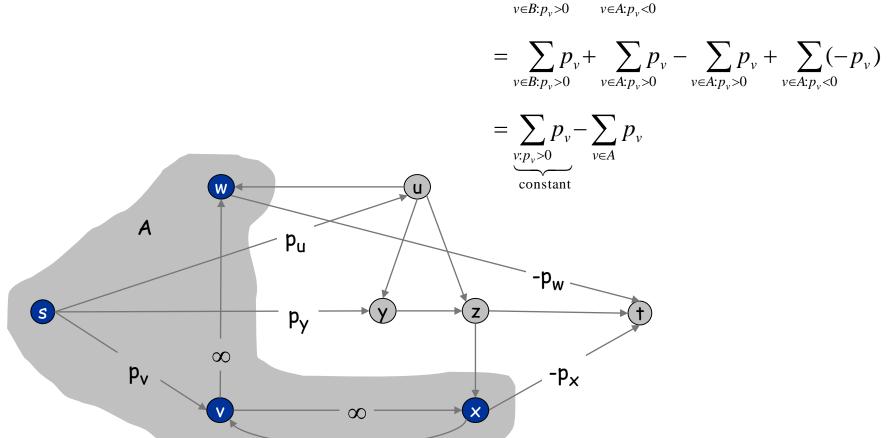


## Project Selection: Min Cut Formulation

Claim. (A, B) is min cut iff  $A - \{s\}$  is optimal set of projects.

- Infinite capacity edges ensure  $A \{s\}$  is feasible.
- Max revenue because:  $cap(A,B) = \sum p_v + \sum (-p_v)$

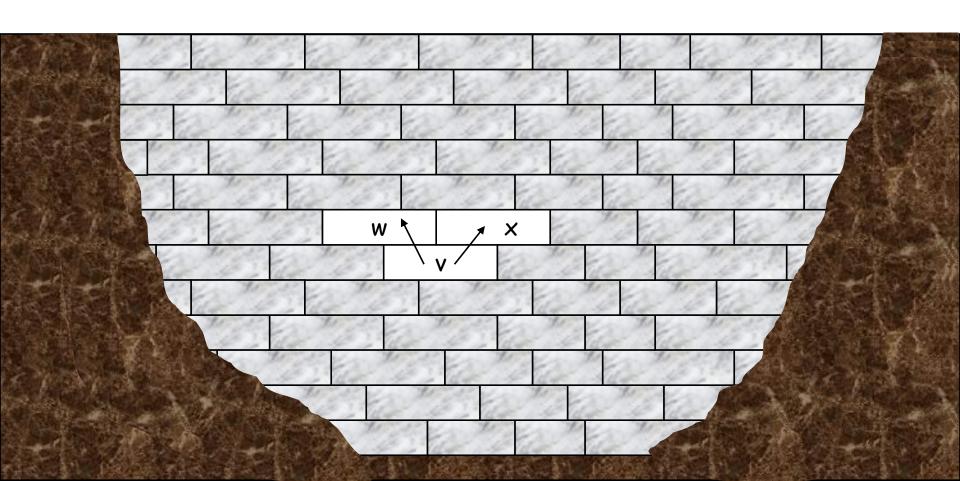
 $\infty$ 



## Open Pit Mining

## Open-pit mining. (studied since early 1960s)

- Blocks of earth are extracted from surface to retrieve ore.
- Each block v has net value  $p_v$  = value of ore processing cost.
- Can't remove block v before w or x.



## 7.12 Baseball Elimination

### Baseball Elimination

Team	Wins	Losses	To play	Against = r <sub>ij</sub>				
i	W <sub>i</sub>	l <sub>i</sub>	r <sub>i</sub>	Atl	Phi	NY	Mon	
Atlanta	83	71	8	-	1	6	1	
Philly	80	79	3	1	-	0	2	
New York	78	78	6	6	0	-	0	
Montreal	77	82	3	1	2	0	-	

## Which teams have a chance of finishing the season with most wins?

- Montreal eliminated since it can finish with at most 80 wins, but Atlanta already has 83.
- $w_i + r_i < w_j \Rightarrow$  team i eliminated.
- Sufficient, but not necessary!

### Baseball Elimination

Team	Wins	Losses	To play	Against = r <sub>ij</sub>				
i	W <sub>i</sub>	l <sub>i</sub>	r <sub>i</sub>	Atl	Phi	NY	Mon	
Atlanta	83	71	8	-	1	6	1	
Philly	80	79	3	1	-	0	2	
New York	78	78	6	6	0	-	0	
Montreal	77	82	3	1	2	0	-	

## Which teams have a chance of finishing the season with most wins?

- Philly can win 83, but still eliminated . . .
  - If Atlanta loses all games, then New York wins 84 . . .

### Baseball Elimination

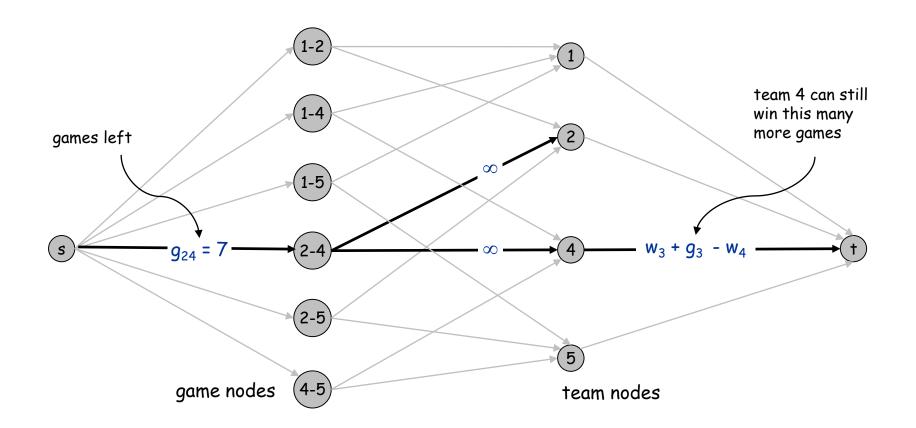
### Baseball elimination problem.

- Set of teams S.
- Distinguished team  $z \in S$ .
- Team x has won  $w_x$  games already.
- ${\bf .}$  Teams  ${\bf x}$  and  ${\bf y}$  play each other  $g_{{\bf x}{\bf y}}$  additional times.
- Is there any outcome of the remaining games in which team z finishes with the most (or tied for the most) wins?

### Baseball Elimination: Max Flow Formulation

### Can team 3 finish with most wins?

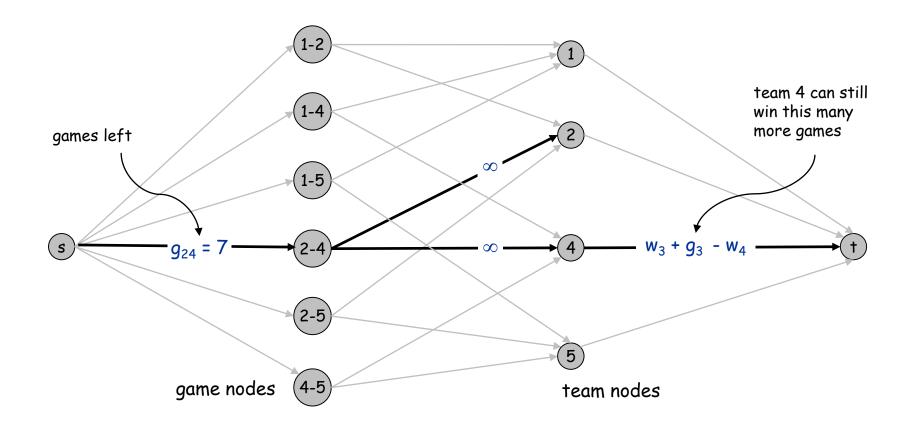
- Assume team 3 wins all remaining games  $\Rightarrow$  w<sub>3</sub> + g<sub>3</sub> wins.
- Divvy remaining games so that all teams have  $\leq w_3 + g_3$  wins.



### Baseball Elimination: Max Flow Formulation

Theorem. Team 3 is not eliminated iff max flow saturates all edges leaving source.

- Integrality theorem  $\Rightarrow$  each remaining game between x and y added to number of wins for team x or team y.
- Capacity on (x, t) edges ensure no team wins too many games.



Team	Wins	Losses	To play	Against = r <sub>ij</sub>				
i	w <sub>i</sub>	l <sub>i</sub>	r <sub>i</sub>	NY	Bal	Bos	Tor	Det
NY	75	59	28	-	3	8	7	3
Baltimore	71	63	28	3	-	2	7	4
Boston	69	66	27	8	2	-	0	0
Toronto	63	72	27	7	7	0	-	-
Detroit	49	86	27	3	4	0	0	-

AL East: August 30, 1996

## Which teams have a chance of finishing the season with most wins?

Detroit could finish season with 49 + 27 = 76 wins.

Team	Wins	Losses	To play	Against = r <sub>ij</sub>				
i	w <sub>i</sub>	l <sub>i</sub>	r <sub>i</sub>	NY	Bal	Bos	Tor	Det
NY	75	59	28	-	3	8	7	3
Baltimore	71	63	28	3	-	2	7	4
Boston	69	66	27	8	2	-	0	0
Toronto	63	72	27	7	7	0	-	-
Detroit	49	86	27	3	4	0	0	-

AL East: August 30, 1996

### Which teams have a chance of finishing the season with most wins?

Detroit could finish season with 49 + 27 = 76 wins.

### Certificate of elimination. R = {NY, Bal, Bos, Tor}

- Have already won w(R) = 278 games.
- Remaining games among R is r(R) = 3+8+7+2+7 = 27
- Average team in R wins at least (278+27)/4 > 76 games.

Certificate of elimination.

$$T \subseteq S$$
,  $w(T) \coloneqq \sum_{i \in T}^{\# \text{ wins}} w_i$ ,  $g(T) \coloneqq \sum_{\{x,y\} \subseteq T}^{\# \text{ remaining games}} g_{xy}$ ,

Theorem. [Hoffman-Rivlin 1967] Team z is eliminated iff there exists a subset T\* such that

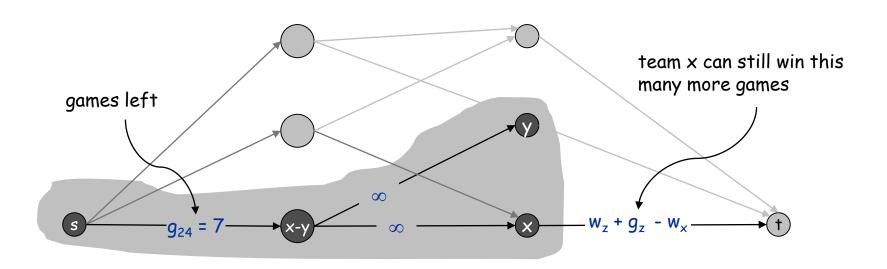
LB on avg# games won
$$\frac{w(T^*) + g(T^*)}{|T^*|} > w_z + g_z$$

### Proof. ←

 The average number of wins of teams in T\* is larger than the maximum number of wins of z

### Proof. $\Rightarrow$

- Use max flow formulation, and consider min cut (A, B).
- Define T\* = team nodes on source side of min cut.
- Observe  $x-y \in A$  iff both  $x \in T^*$  and  $y \in T^*$ .
  - infinite capacity edges ensure if  $x-y \in A$  then  $x \in A$  and  $y \in A$
  - if  $x \in A$  and  $y \in A$  but  $x-y \in B$ , then adding x-y to A decreases capacity of cut



### Proof. $\Rightarrow$

- Use max flow formulation, and consider min cut (A, B).
- Define T\* = team nodes on source side of min cut.
- Observe  $x-y \in A$  iff both  $x \in T^*$  and  $y \in T^*$ .
- Since z is eliminated, by max-flow min-cut theorem:

$$g(S - \{z\}) > cap(A,B)$$

$$= g(S - \{z\}) - g(T^*) + \sum_{x \in T^*}^{\text{capacityof team edges entering t}} (w_z + g_z - w_x)$$

$$= g(S - \{z\}) - g(T^*) - w(T^*) + |T^*| (w_z + g_z)$$

Rearranging terms:  $w_z + g_z < \frac{w(T^*) + g(T^*)}{|T^*|}$ 

# Chapter Summary

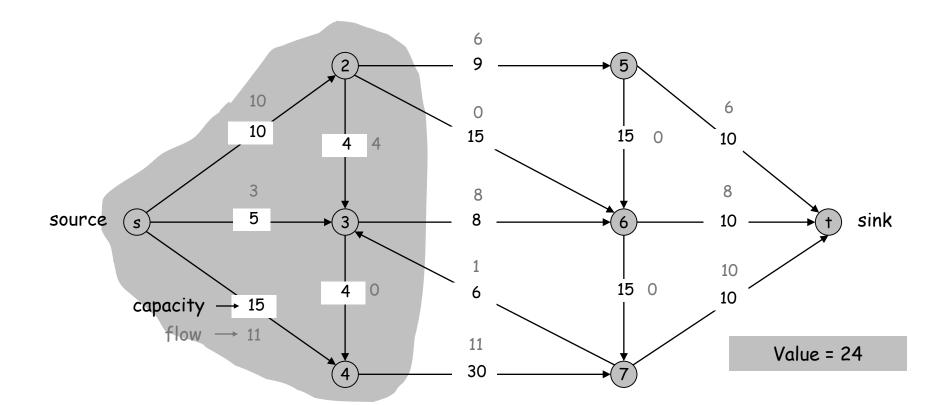
### Flows

## Concepts

- s-t flow
- Max-flow
- s-t cut
- Min-cut

### Max-flow min-cut theorem.

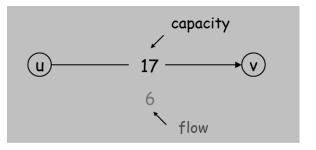
The value of the max flow is equal to the value of the min cut.

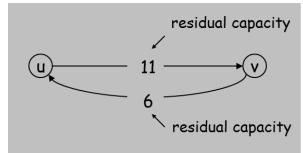


## Ford-Fulkerson Algorithm

### Ford-Fulkerson Algorithm

- Start with f(e) = 0 for all edge  $e \in E$ .
- Find an augmenting path P in the residual graph  $G_f$ .
  - Can be chosen using capacity scaling
- Augment flow along path P.
- Repeat until you get stuck.





```
Ford-Fulkerson(G, s, t, c) {
   foreach e ∈ E f(e) ← 0
   G<sub>f</sub> ← residual graph

while (there exists augmenting path P) {
   f ← Augment(f, c, P)
      update G<sub>f</sub>
   }
   return f
}
```

## **Applications**

### Problems covered in class

- Bipartite Matching
- Disjoint Paths
- Circulation with Demands (+ edge lower bounds)
- Survey Design
- Image Segmentation
- Project Selection
- Baseball Elimination