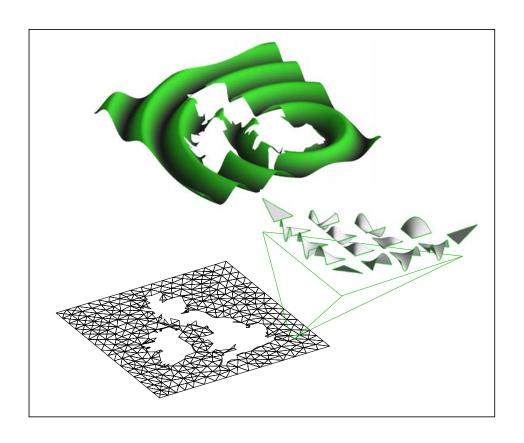
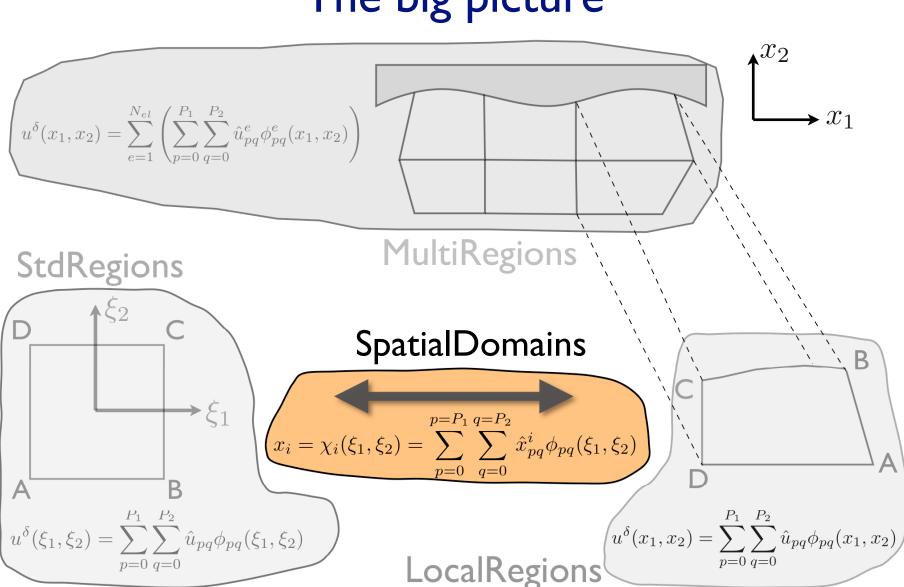
Spatial Construction of Elements





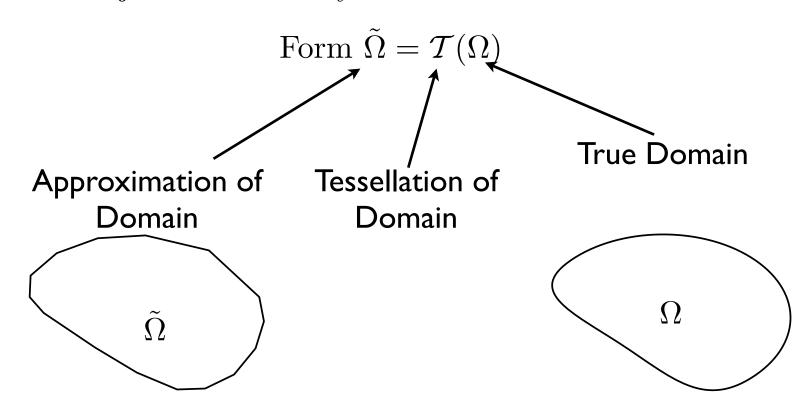


Outline

- I/O Issues
- Geometric Construction of Elements
 - Segment Geometry (SpatialDomains::SegGeom)
 - Quadrilateral Geometry (SpatialDomains::QuadGeom)
 - Triangle Geometry (SpatialDomains::TriGeom)
- Metric Construction

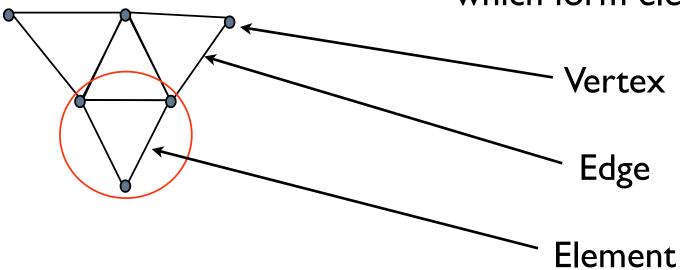
Approximating the Geometry

Find u such that $\mathcal{L}(u) = f$ on Ω subject to boundary and initial conditions



Nomenclature

Mesh - a collection of vertices, edges and faces which form elements



Supported Elements:

ID: Segments

2D:Triangles and Quadrilaterals

3D: Tetrahedra, Hexahedra, Prisms and Pyramids

I/O: Header Information

```
<?xml version="1.0" encoding="utf-8"?>

<NEKTAR>
<!-- Embed a 1-dimensional object in a 2-dimensional space -->
<!-- DIM <= SPACE -->
<!-- This provides a method of optimizing code for a 1-D curve embedded in 3-space.
-->
<GEOMETRY DIM="2" SPACE="2">
```

Example: A oneparameter curve in three dimensions

$$x(t) = f_1(t)$$
$$y(t) = f_2(t)$$

$$z(t) = f_3(t)$$

I/O: Definitions

Example: Setting Boundary Conditions

$$u(x) = Asin(x) + Bcos(x) + Cx$$

I/O:Vertices

```
<VERTEX>
<!-- Always must have four values per entry. -->
< VID="0"> -1.00000000000000 3.500000000000000
                                         0.0 < V >
0.0 < V >
< VID="2"> -1.00000000000000 2.500000000000000
                                         0.0 < V >
0.0 < V >
<V ID="4">
         3.80000000000000 4.500000000000000
                                         0.0 < V >
                                         0.0 < V >
<V ID="5">
         0.0 < V >
<V ID="6"> 2.90000000000000 4.50000000000000
<VID="7"> 2.0000000000000 4.50000000000000
                                         0.0 < V >
<V ID="8"> 1.1000000000000 4.50000000000000
                                         0.0 < V >
<V ID="9"> 5.0000000000000 0.500000000000000
                                         0.0 < V >
<V ID="10"> 5.00000000000000 3.50000000000000
                                         0.0 < V >
                                          0.0 < V >
<V ID="11"> 5.00000000000000 1.50000000000000
                                          0.0 < V >
<V ID="12"> 5.00000000000000 2.50000000000000
                                          0.0 < /V >
<V ID="13"> 0.20000000000000 -0.500000000000000
                                          0.0 < V >
<V ID="14"> 3.80000000000000 -0.500000000000000
                                          0.0 < /V >
<V ID="15"> 1.10000000000000 -0.500000000000000
<V ID="16"> 2.00000000000000 -0.500000000000000
                                          0.0 < V >
0.0 < V >
0.0 < V >
<V ID="19"> 4.40000000000000  4.000000000000000
                                          0.0 < V >
```

I/O: Edges

```
<EDGE NUMBER="96">
                             Edge 0 consists of (Vertex=0, Vertex=21)
 <E ID="0"> 1 21 </E>
 <E ID="1"> 13 21 </E>
 <E ID="2"> 13 15 </E>
 <E ID="3"> 15 16 </E>
 <E ID="4"> 16 17 </E>
 <E ID="5"> 14 17 </E>
 <E ID="6"> 1 3 </E>
 <E ID="7"> 1 29 </E>
 <E ID="8"> 21 29 </E>
 <E ID="9"> 21 30 </E>
                           Edge 10 consists of (Vertex=13, Vertex=30)
 <E ID="10"> 13 30 </E>
 <E ID="11"> 15 30 </E>
 <E ID="12"> 15 27 </E>
 <E ID="13"> 16 27 </E>
 <E ID="14"> 16 25 </E>
 <E ID="15"> 17 25 </E>
 <E ID="16"> 3 29 </E>
 <E ID="17"> 29 30 </E>
 <E ID="18"> 27 30 </E>
 <E ID="19"> 25 27 </E>
 <E ID="20"> 2 3 </E>
```

I/O: Elements

```
<!-- Q - quads, T - triangles, S - segments, E - tet, P - pyramid, R - prism, H - hex -->
 <!-- Only certain element types are appropriate for the given dimension (dim on
mesh) -->
 <!-- Can also use faces to define 3-D elements. Specify with F[1] for face 1, for
example. -->
  <ELEMENT>
                                      Element 3 is a Triangle
   <T ID="0"> 6 7 16 </T>
   <T ID="1"> 0 8 7 </T>
                                              consists of
   <T ID="2"> 9 17 8 </T>
                                  Edge = I (vertex 13 and 21)
   <T ID="3"> 1 10 9 </T>
   <T ID="4"> 2 11 10 </T>
                                 Edge = 10 (vertex 13 and 30)
   <T ID="5"> 11 12 18 </T>
                                  Edge = 9 (vertex 21 and 30)
   <T ID="6"> 3 13 12 </T>
   <T ID="7"> 14 19 13 </T>
   <T ID="8"> 4 15 14 </T>
                                               edge 10
                                                        VI3
   <T ID="9"> 5 39 15 </T>
                                        V30
```

edge 9

edge

I/O: Composite and Domain

I/O: Parameters and Boundaries

<CONDITIONS>

```
<!-- Removed redundancy since we can specify any level of granularity
                                                                     Parameters
in the ExpansionTypes section below.-->
<PARAMETERS>
 <P> Lambda = 1 </P>
</PARAMETERS>
<!--One of these for each dimension. These are the vector
                                                                 Solution Variable
components, say, s = (u,v); comprised of two components in
this example for a 2D dimension.-->
<VARIABLES>
 <V ID="0"> u </V>
</VARIABLES>
<!--These composites must be defined in the geometry file.-->
                                                                Boundary Regions
<BOUNDARYREGIONS>
                                                                (where boundary
 <B ID = "0" > C[2] < /B >
 <B ID="1">C[3]</B>
                                                              conditions are to be
 <B ID = "2" > C[4] < /B >
 <B ID="3">C[5]</B>
                                                                       applied)
 <B ID = "4" > C[6] < /B >
```

World Space versus Reference Space

World Space

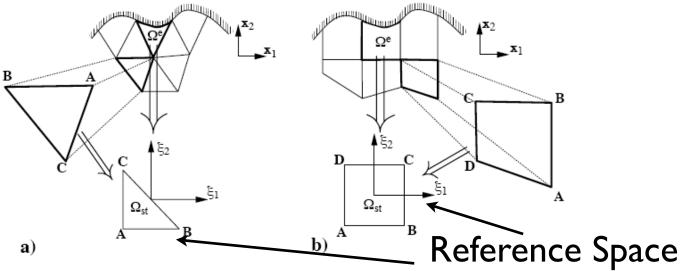


Figure 3.2 To construct a C^0 expansion from multiple elements of specified shapes (for example, triangles or rectangles), each elemental region Ω^e is mapped to a standard region Ω_{st} in which all local operations are evaluated.

Course Notes: Section 3.1.3.1

Mapping from reference space to world space

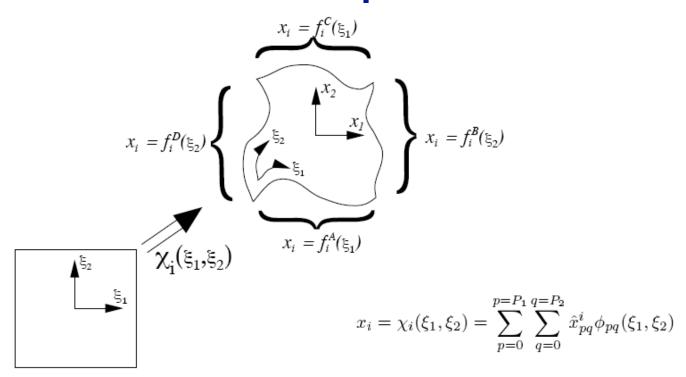


Figure 3.4 A general curved element can be described in terms of a series of parametric functions $f^A(\xi_1), f^B(\xi_2), f^C(\xi_1)$, and $f^D(\xi_2)$. Representing these functions as a discrete expansion we can construct an iso-parametric mapping $\chi_i(\xi_1, \xi_2)$ relating the standard region (ξ_1, ξ_2) to the deformed region (x_1, x_2) .

Course Notes: Section 3.1.3.2

Metric Terms

Recall from Calculus:

$$\int_{a}^{b} f(x)dx \longleftrightarrow \int_{-1}^{1} f(\psi^{-1}(\xi)) \left| \frac{(b-a)}{2} \right| d\xi$$

$$x = \psi(\xi) = \frac{(b-a)}{2} (\xi+1) + a$$
Jacobian of the mapping

Chain Rule:

Given
$$f(x) = H(\psi^{-1}(x))$$

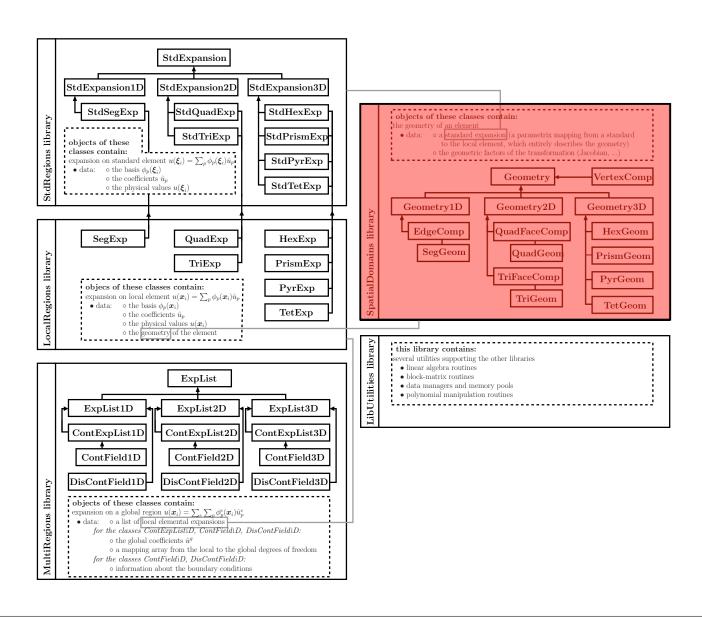
$$\frac{d}{dx}f(x) = \frac{d}{dx}H(\psi^{-1}(x))$$

$$= \left[\frac{d}{dx}\psi^{-1}(x)\right]\frac{dH(\xi)}{d\xi}$$

Course Notes: Section 3.1

Impact of the mapping

Nektar++ code



Nektar++ code

