

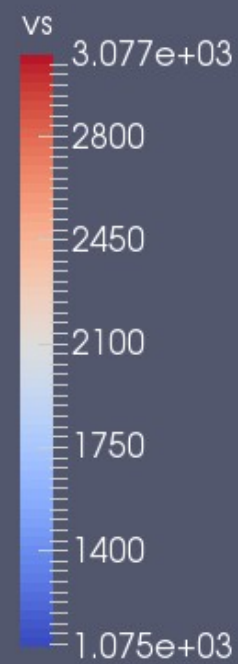
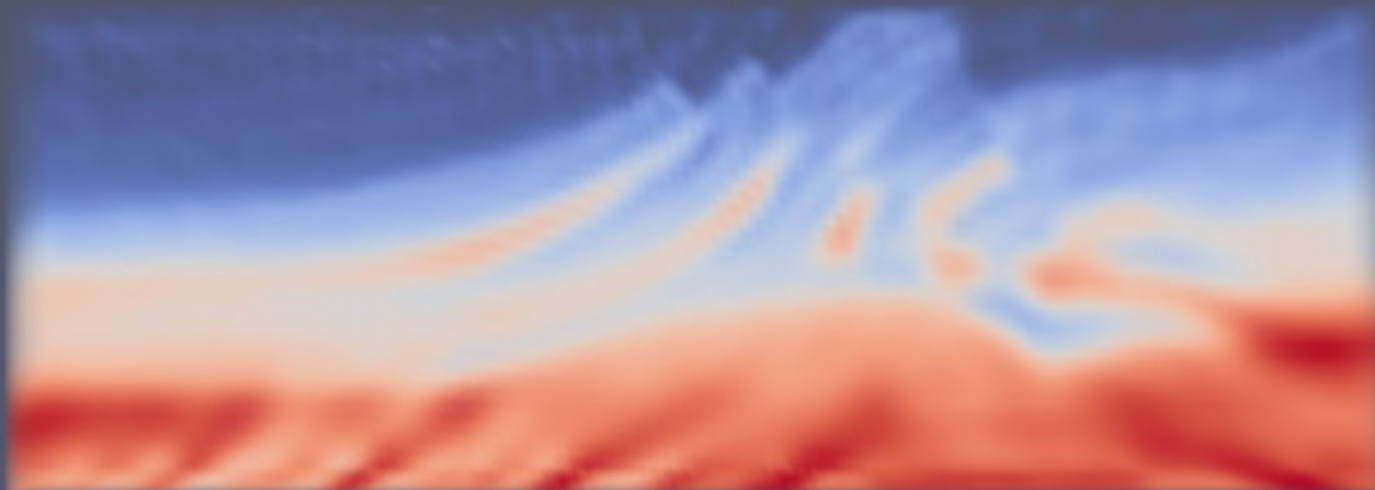
# 3D local-scale SRVM-based Uncertainty Estimation

Liu & Peter

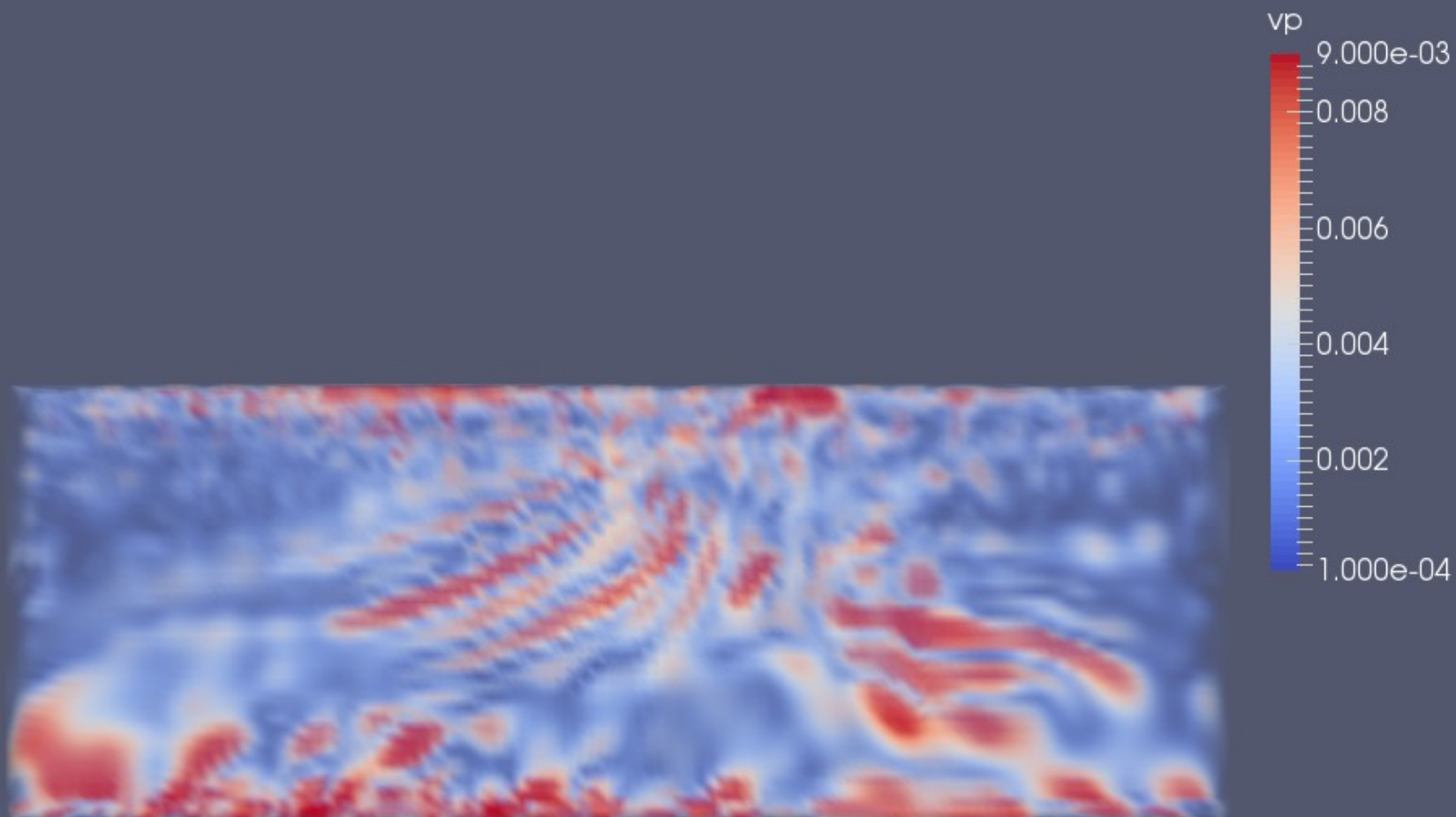
Nov 4<sup>th</sup>, 2018

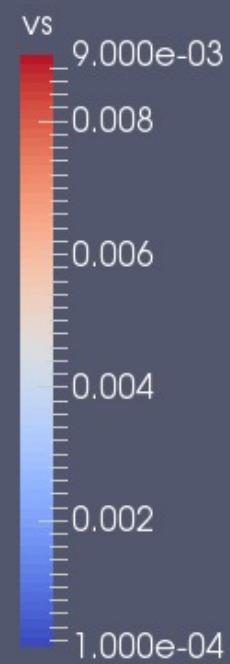
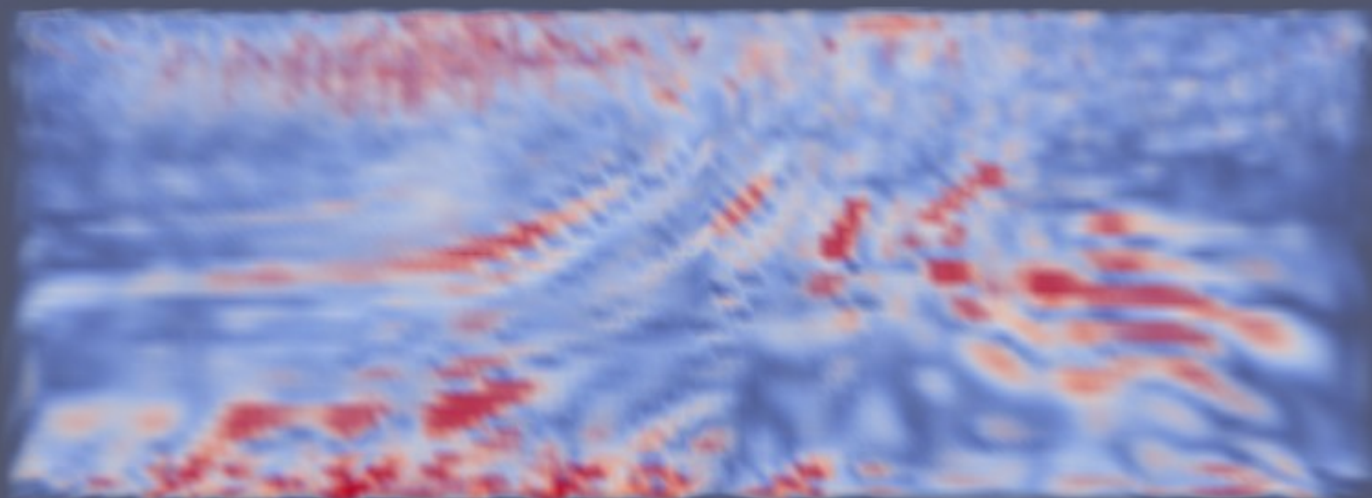
Inverted results





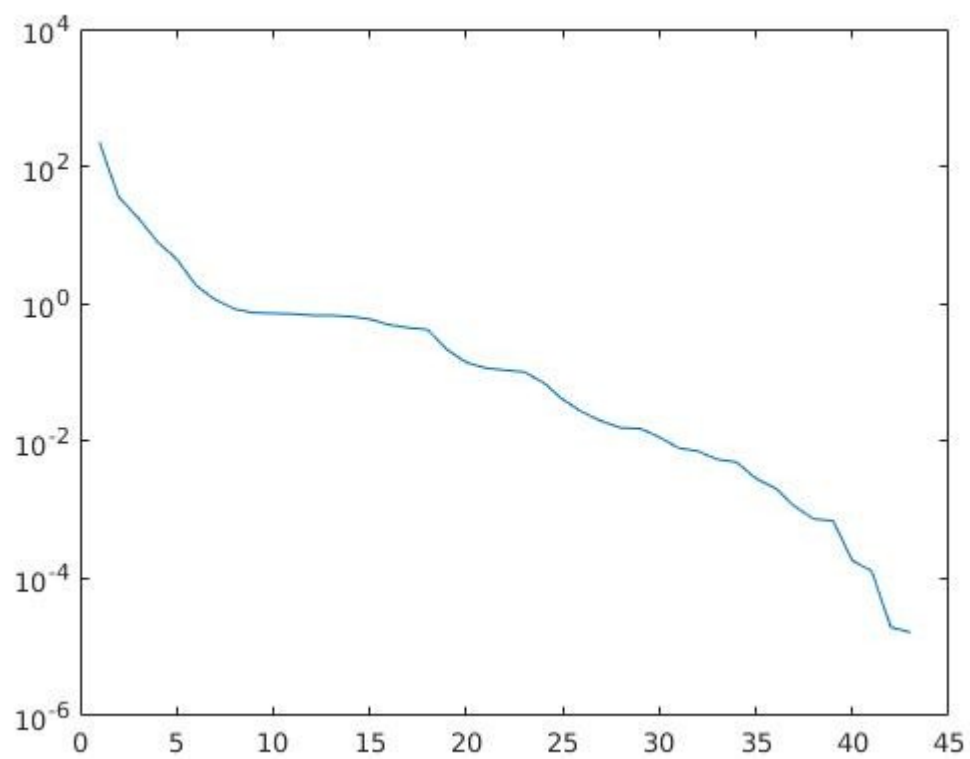
Uncertainty map



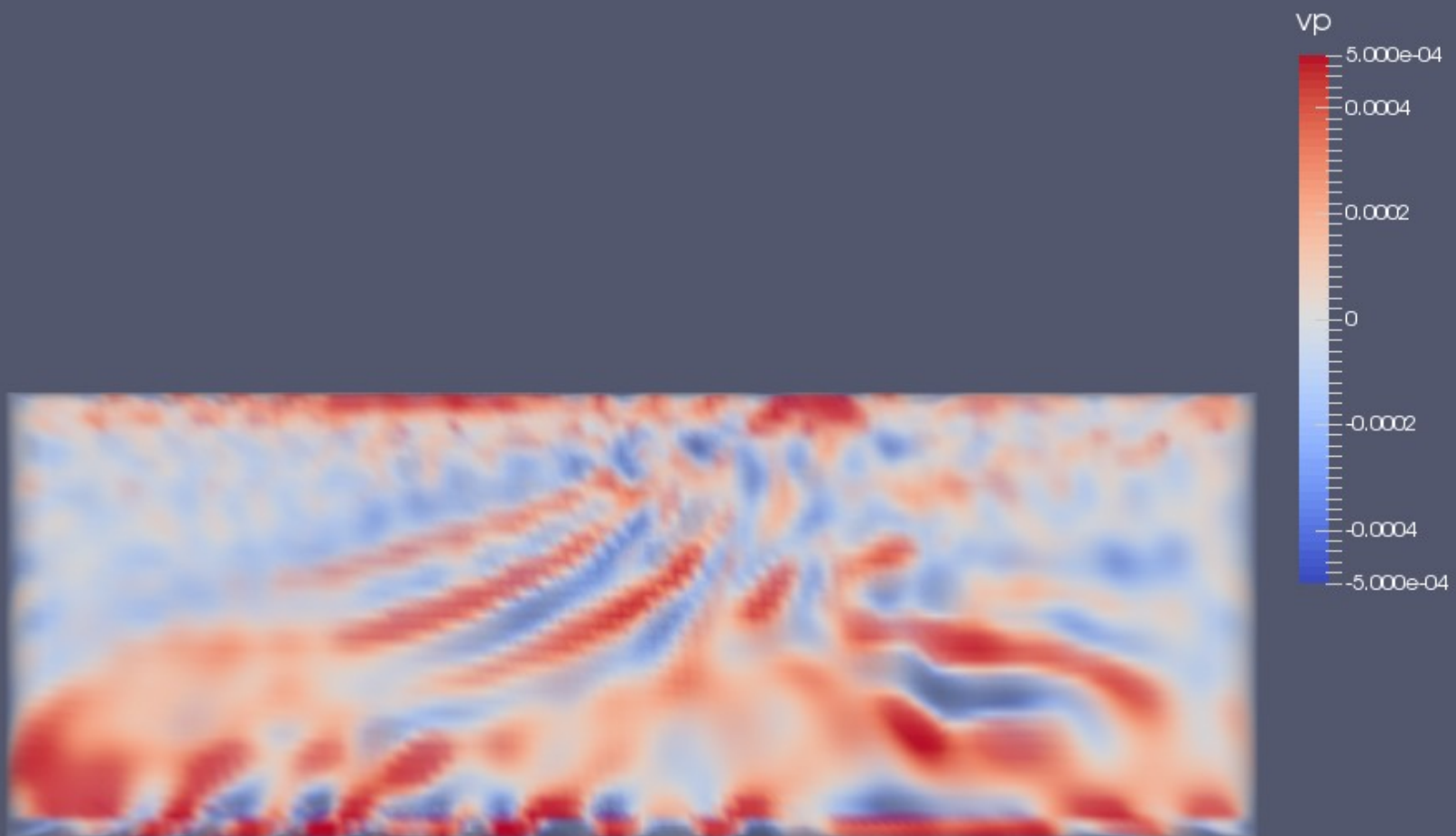


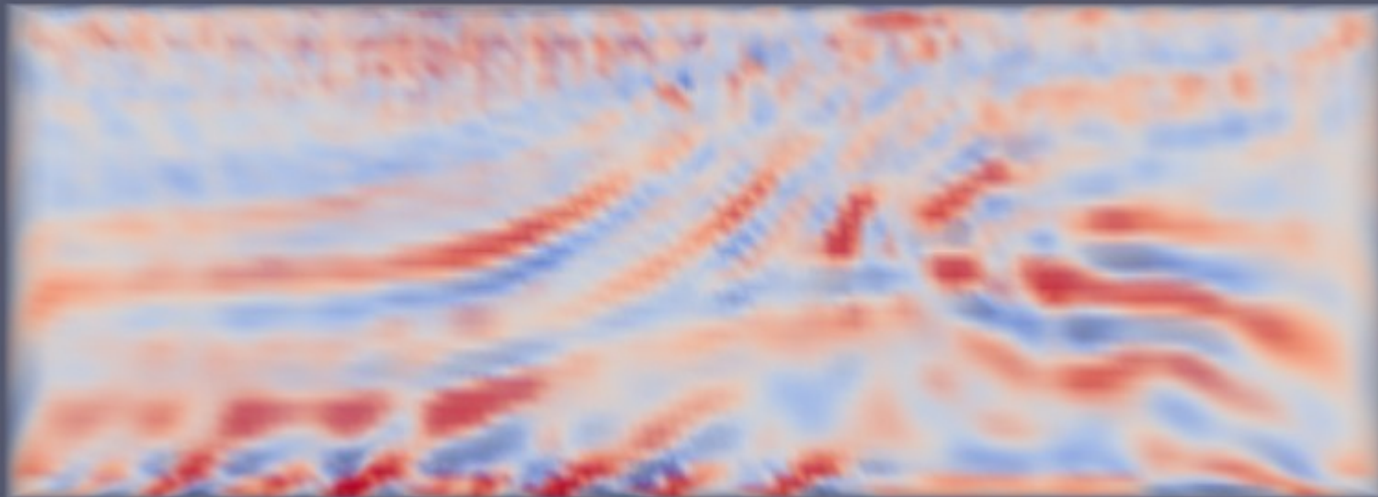
# Eigenvalues



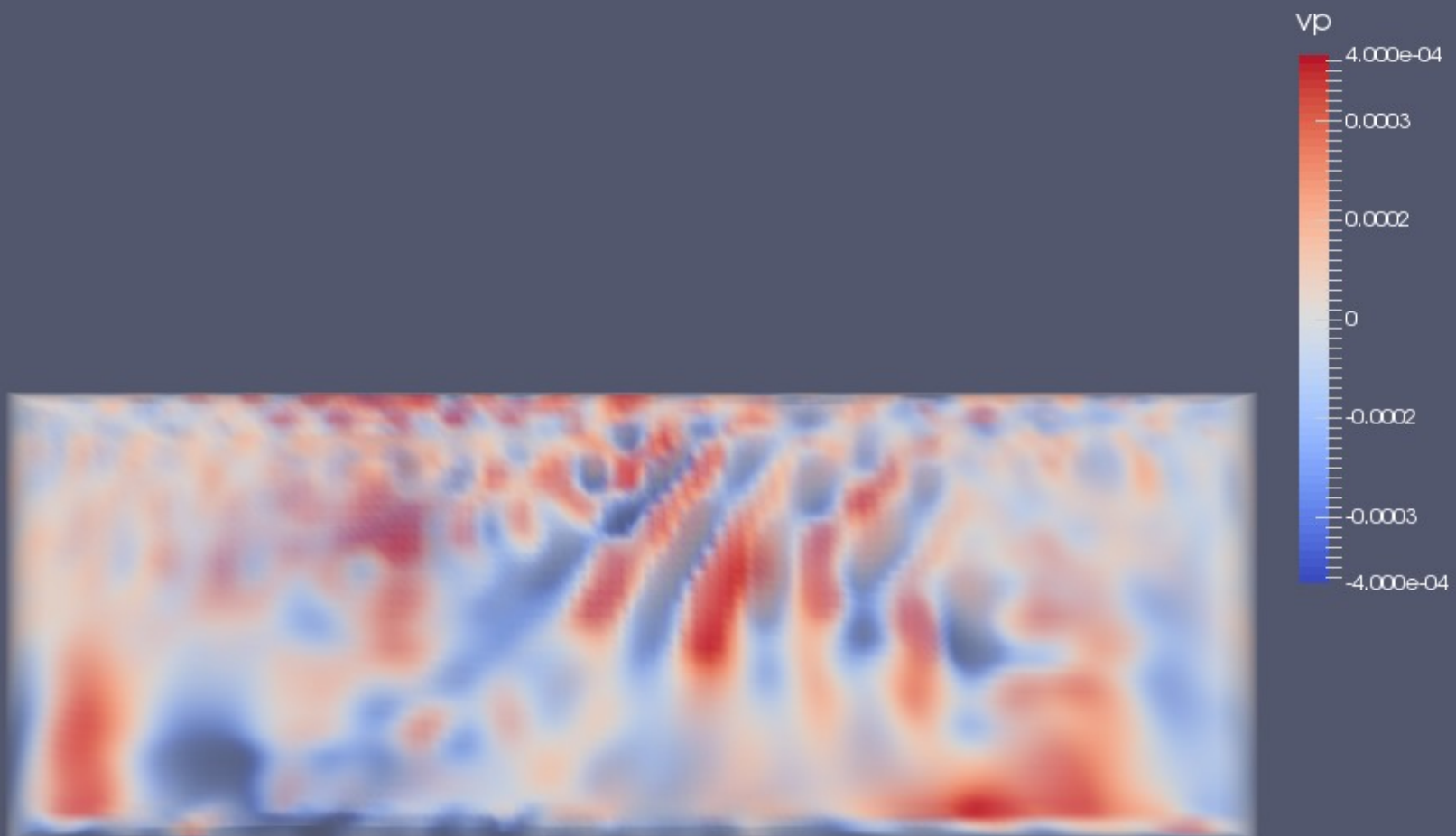


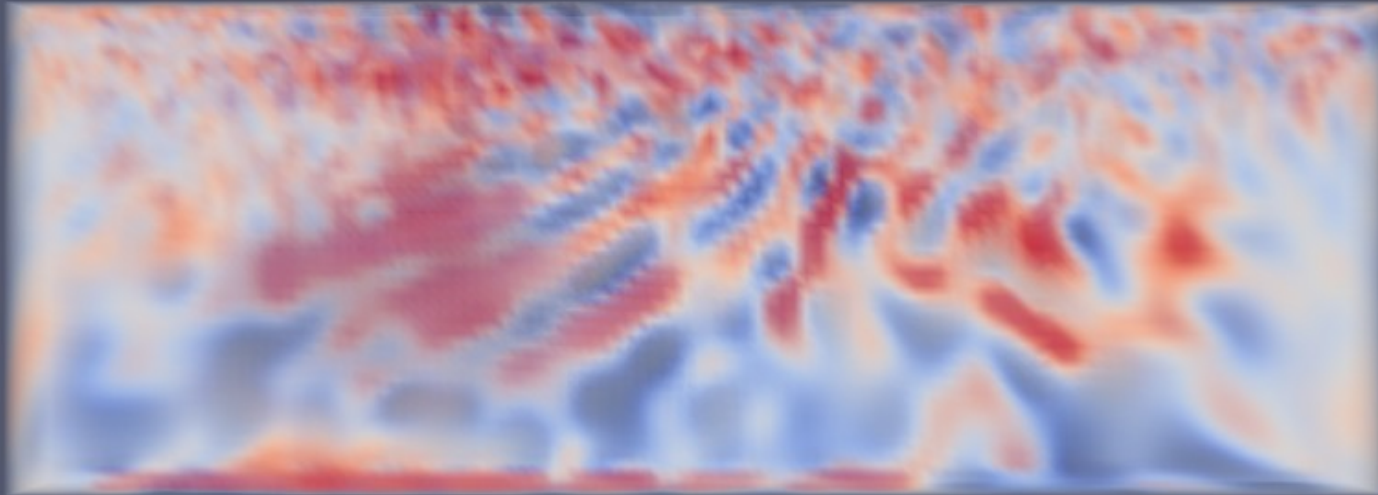
1<sup>st</sup> eigenvector





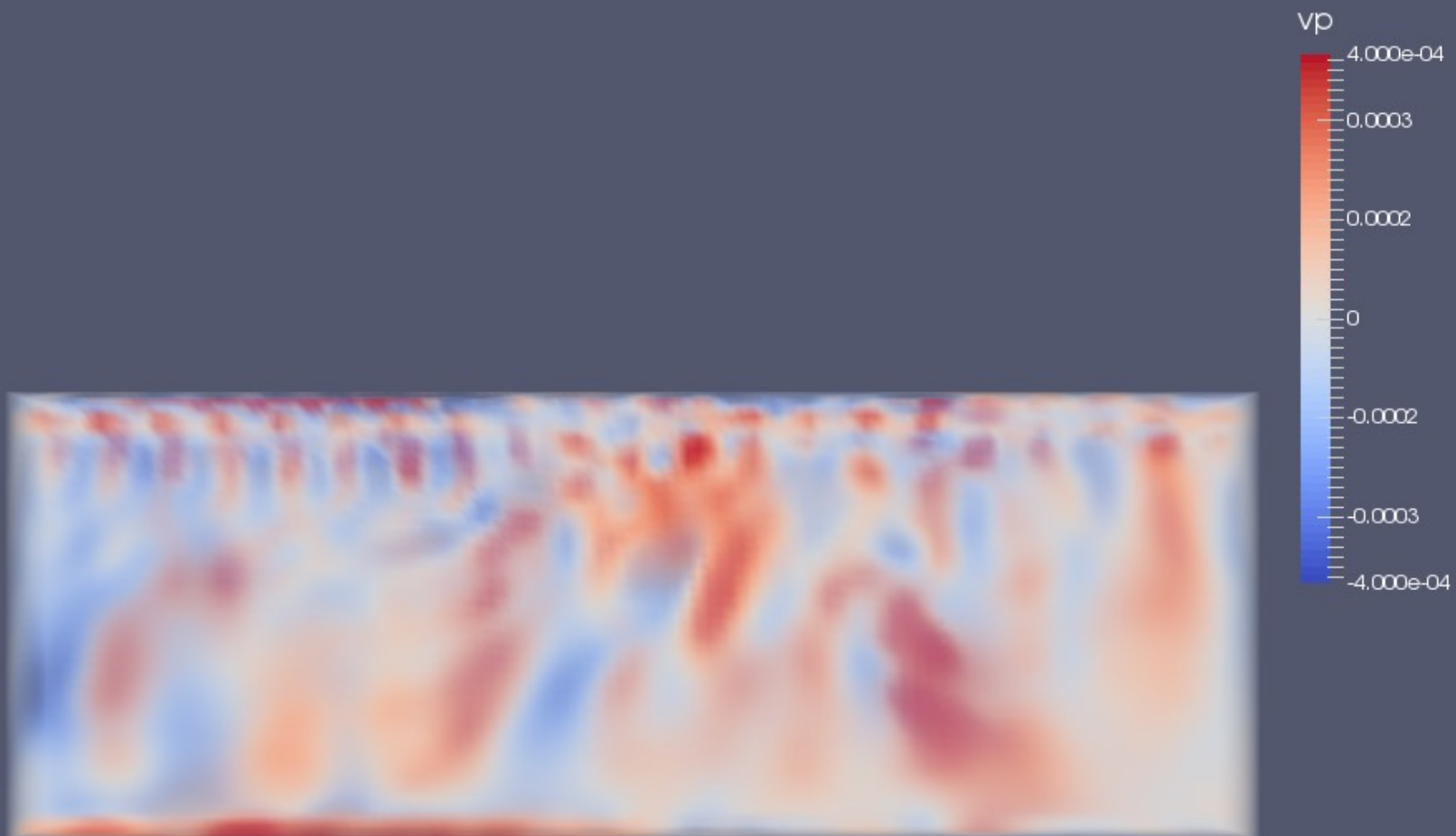
3<sup>rd</sup> eigenvector

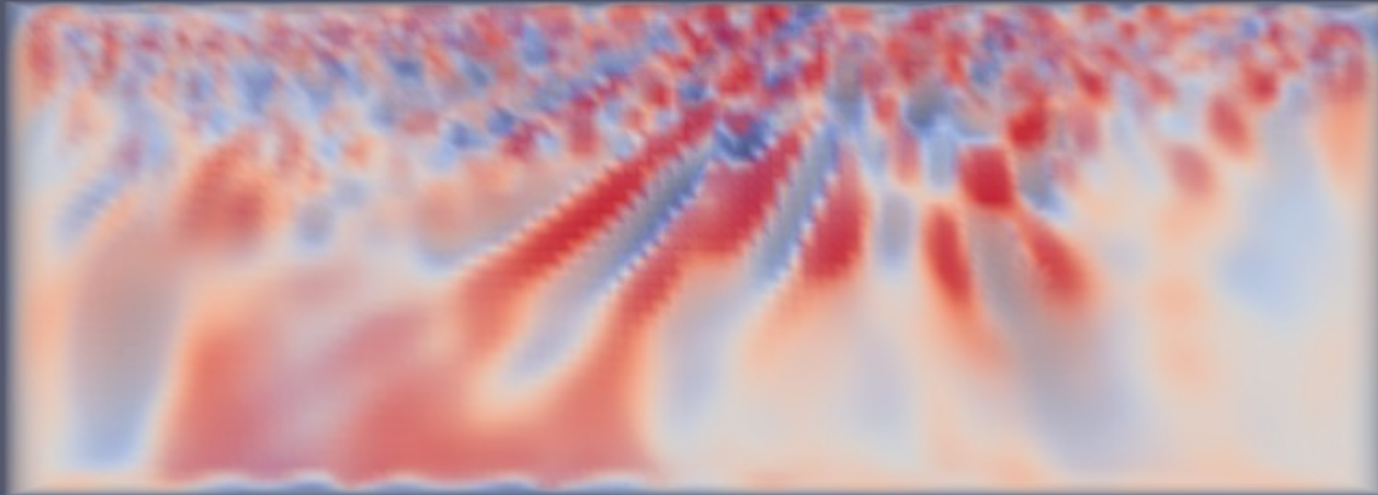




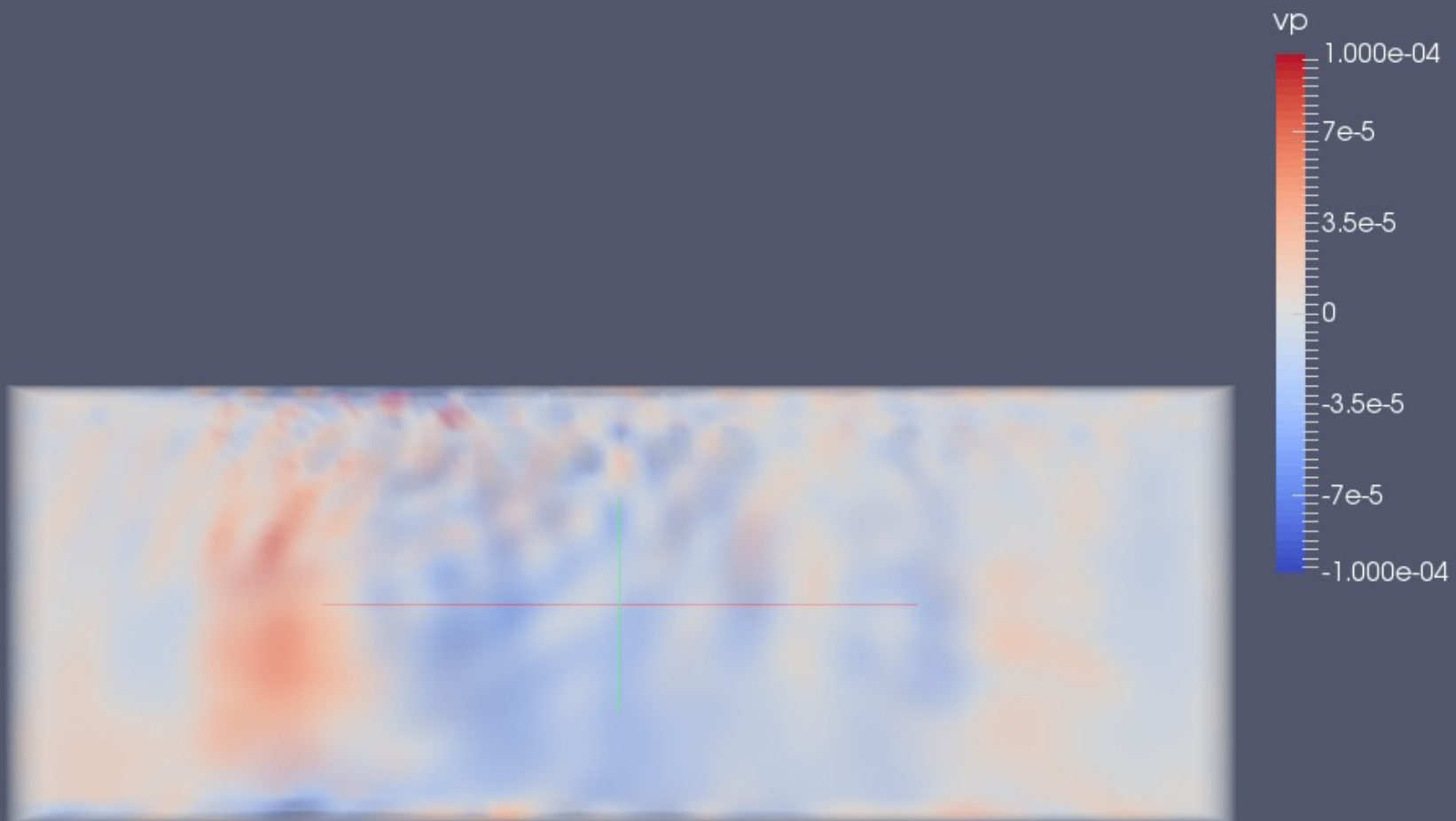
5<sup>th</sup> eigenvector

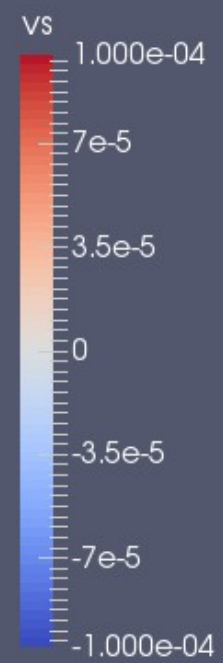
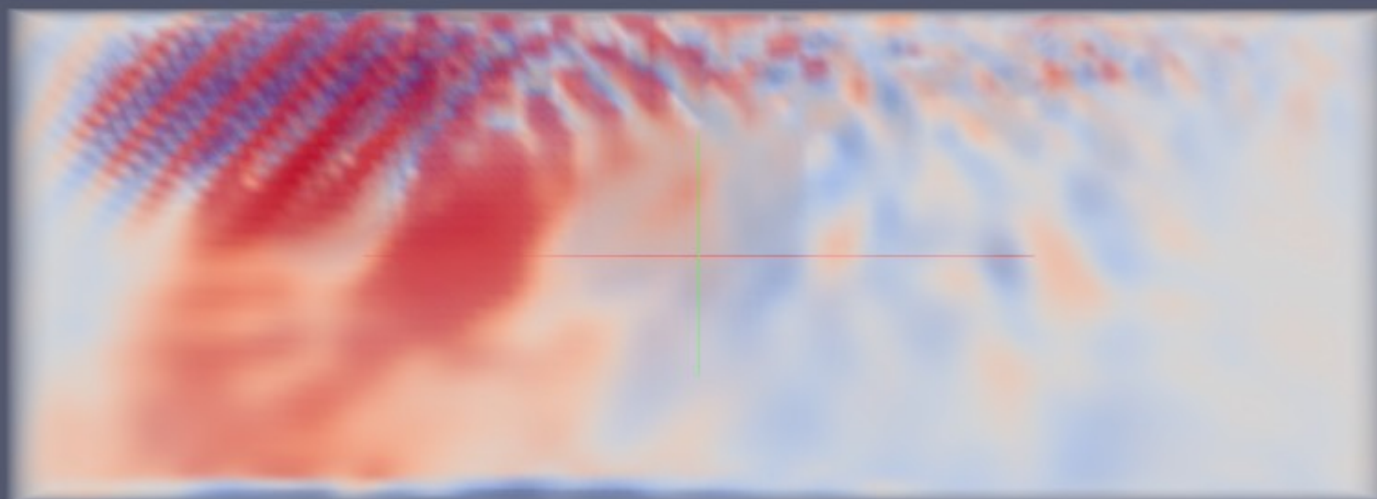




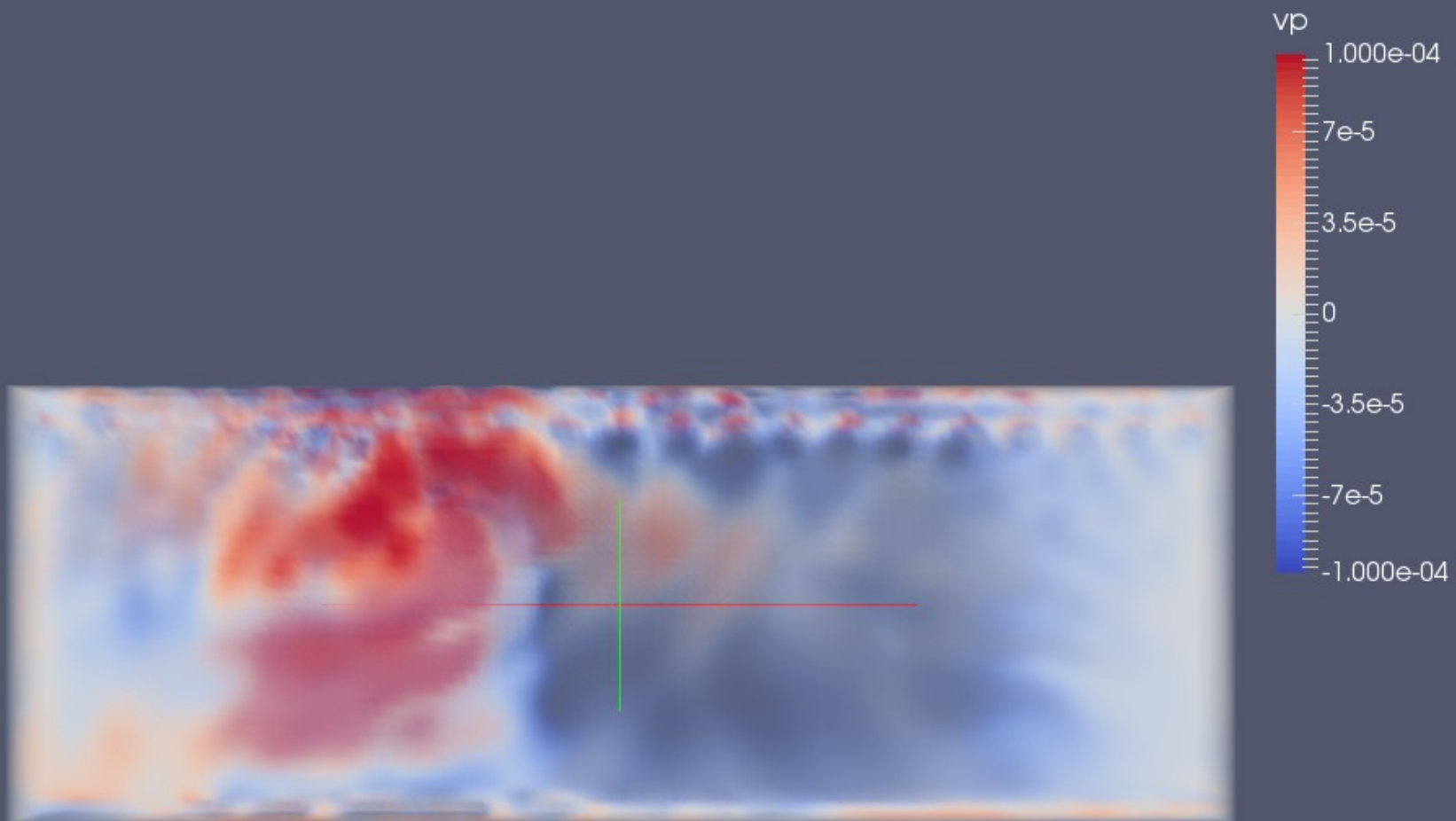


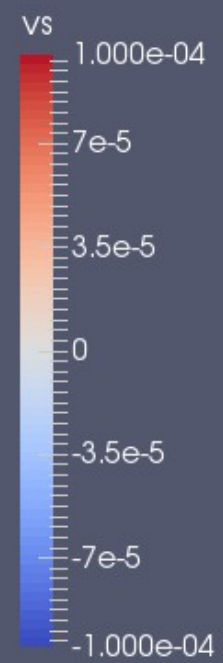
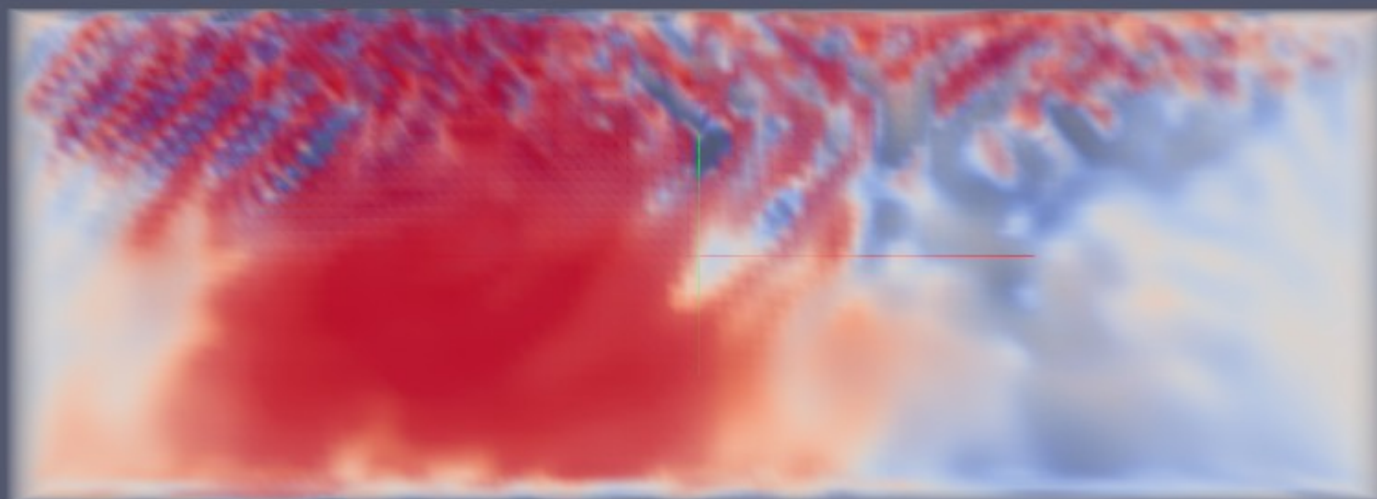
10<sup>th</sup> eigenvector





20<sup>th</sup> eigenvector







40<sup>th</sup> eigenvector

