

Simplex Integration

By Domain Subdivision

Inhaltsverzeichnis

I. Theory	3
1. Problem	3
1.1. Ansatz functions	3
2. Element Description	4
3. Simplex Integration in $n = 2$	5
3.1. Simplex Integration	5
3.2. Integraltransformation	5
3.3. Simplex Subdivision	6

Teil I. Theory

1. Problem

Total Energy in the System:

$$\Pi = \int_{\Omega} g(\phi)\psi(\mathbf{u}) \, d\Omega + \frac{G_c}{2l} \int_{\Omega} \phi^2 + l^2 \nabla \phi \cdot \nabla \phi \, d\Omega \rightarrow \min \quad [1.1]$$

Degradation Function

$$g(\phi) = \left(1 - \phi^2\right)^2 + k \quad [1.2]$$

mit

- k ... being a small but finite scalar such as 10^{-6}
- G_c ... critical energy release rate, material parameter
- l ... *width* of phase field
- $\psi(\mathbf{u})$... strain energy density function
- \mathbf{u} ... displacement function
- ϕ ... phase field parameter, ansatz function discussed below
- $\nabla \phi$... gradient of phase field parameter

$$\delta_{\mathbf{u}} \Pi = \int_{\Omega} g(\phi) \sigma(\mathbf{u}) \frac{\partial \varepsilon}{\partial \mathbf{u}} \delta \mathbf{u} \, d\Omega = 0 \quad [1.3]$$

$$\delta_{\phi} \Pi = \int_{\Omega} 2(\phi - 1) \delta \phi \psi(\mathbf{u}) \, d\Omega + \frac{G_c}{l} \int_{\Omega} \phi \delta \phi + l^2 \nabla \phi \cdot \nabla \delta \phi \, d\Omega = 0 \quad [1.4]$$

1.1. Ansatz functions

$$\mathbf{u} = \sum_i N_i \mathbf{u}_i + \sum_i N_i F \mathbf{a}_i \quad [1.5]$$

mit

- N_i ... are quadratic lagrange (standard) shape functions for tetrahedrons
- $\mathbf{u}_i = \mathbf{u}_i, \mathbf{a}_i$... are nodal degrees of freedom for displacement function
- F ... is an enrichment function (sigmoid like, depends on ϕ , later)

$$f_{\text{base}} = \sum_i N_i \phi_i \quad [1.6]$$

$$\zeta = \frac{f_{\text{base}}}{\sqrt[4]{f_{\text{base}}^2 + k_{\text{res}}}} \quad [1.7]$$

mit

$k_{\text{reg}} \dots$ small but finite parameter

$$\phi = \exp(-\varsigma) \quad [1.8]$$

$$\phi = \exp\left(-\frac{\varsigma}{l}\right) \quad [1.9]$$

we need to be able to integrate the residual vectors and the stiffness matrices efficiently and accurately

$$\delta_{\mathbf{u}_i} \Pi = \int_{\Omega} g(\phi) \sigma(\mathbf{u}) \frac{\partial \varepsilon}{\partial \mathbf{u}} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{U}} d\Omega \cdot \delta \mathbf{U}_i \quad [1.10]$$

$$\delta_{\phi_i} \Pi = \int_{\Omega} 2(\phi - 1) \frac{\partial \phi}{\partial \phi_i} \psi(\mathbf{u}) d\Omega \delta \phi_i + \frac{G_c}{l} \int_{\Omega} \phi \frac{\partial \phi}{\partial \phi_i} + l^2 \nabla \phi \cdot \frac{\partial \nabla \phi}{\partial \phi_i} d\Omega \delta \phi_i = 0 \quad [1.11]$$

$$\Delta_{\mathbf{u}_i} \delta_{\mathbf{u}_i} \Pi = \mathbf{U}_i \cdot \int_{\Omega} g(\phi) \frac{\partial \varepsilon}{\partial \mathbf{U}_i} \cdot \mathbb{C} \cdot \frac{\partial \varepsilon}{\partial \mathbf{U}_i} d\Omega \cdot \delta \mathbf{U}_i \quad [1.12]$$

$$\Delta_{\phi_j} \delta_{\phi_i} \Pi = \phi_j \int_{\Omega} 2 \left(\frac{\partial \phi}{\partial \phi_i} \right)^2 \psi(\mathbf{u}) d\Omega \delta \phi_i + \phi_j \int_{\Omega} 2(\phi - 1) \frac{\partial^2 \phi}{\partial \phi_i^2} \phi(\mathbf{u}) d\Omega \delta \phi_i \quad [1.13]$$

$$+ \phi_j \frac{G_c}{l} \int_{\Omega} \frac{\partial \phi}{\partial \phi_i} + \frac{\partial^2 \phi}{\partial \phi_i^2} + l^2 \frac{\partial \nabla \phi}{\partial \phi_j} \cdot \frac{\partial \nabla \phi}{\partial \phi_i} + l^2 \nabla \phi \cdot \frac{\partial^2 \nabla \phi}{\partial \phi_i^2} d\Omega \delta \phi_i \quad [1.14]$$

2. Element Description

Shape Functions in barycentric coordinates

$$N_1(\xi_1, \xi_2, \xi_3) = \xi_1 \quad [2.1]$$

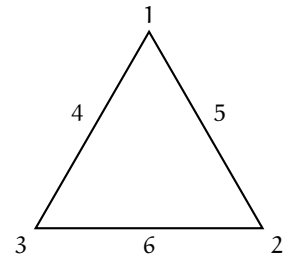
$$N_2(\xi_1, \xi_2, \xi_3) = \xi_2 \quad [2.2]$$

$$N_3(\xi_1, \xi_2, \xi_3) = \xi_3 \quad [2.3]$$

$$N_4(\xi_1, \xi_2, \xi_3) = 4\xi_1 \xi_3 \quad [2.4]$$

$$N_5(\xi_1, \xi_2, \xi_3) = 4\xi_1 \xi_2 \quad [2.5]$$

$$N_6(\xi_1, \xi_2, \xi_3) = 4\xi_2 \xi_3 \quad [2.6]$$



Barycentric Interpolation Formula $P : \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$P(\xi_1, \xi_2, \xi_3) = p_1 \xi_1 + p_2 \xi_2 + p_3 \xi_3 \quad [2.7]$$

mit $p_i \in \mathbb{R}^2$, $\xi_i \in [0, 1]$

ξ - η -Transformation

$$\xi_1 := 1 - \xi - \eta \quad [2.8]$$

$$\xi_2 := \xi \quad [2.9]$$

$$\xi_3 := \eta \quad [2.10]$$

mit $\xi \in [0, 1]$, $\eta \in [0, 1]$

Es gilt:

$$T(\xi, \eta) = \begin{bmatrix} 1 - \xi - \eta \\ \xi \\ \eta \end{bmatrix} \quad [2.11]$$

$$T^{-1}(\xi_1, \xi_2, \xi_3) = \xi_1 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \xi_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \xi_3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad [2.12]$$

3. Simplex Integration in $n = 2$

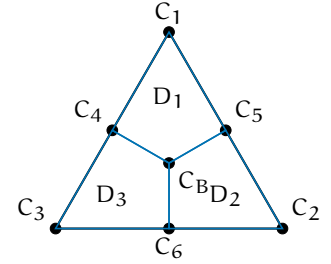
3.1. Simplex Integration

Characteristic points in barycentric coordinates

$$C_B = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \quad [3.1]$$

$$C_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad C_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad C_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad [3.2]$$

$$C_4 = \begin{bmatrix} 0.5 \\ 0 \\ 0.5 \end{bmatrix} \quad C_5 = \begin{bmatrix} 0.5 \\ 0.5 \\ 0 \end{bmatrix} \quad C_6 = \begin{bmatrix} 0 \\ 0.5 \\ 0.5 \end{bmatrix} \quad [3.3]$$



Domain of a Simplex Δ can be decomposed into three disjunct subdomains:

$$\Delta = D_1 \cup D_2 \cup D_3 \quad [3.4]$$

Therefore the double-Integral

$$\iint_{\Delta} F d\Delta = \iint_{D_1} F dD_1 + \iint_{D_2} F dD_2 + \iint_{D_3} F dD_3 \quad [3.5]$$

Mapping functions from the $[-1, 1] \times [-1, 1]$ X-Y-Unit Square

$$g_1(X) = \frac{X}{2} + \frac{1}{2} \quad g_2(X) = -\frac{X}{2} + \frac{1}{2} \quad [3.6]$$

$$\frac{\partial g_1}{\partial X} = \frac{1}{2} \quad \frac{\partial g_2}{\partial X} = -\frac{1}{2} \quad [3.7]$$

$$g_1(Y) = \frac{Y}{2} + \frac{1}{2} \quad g_2(Y) = -\frac{Y}{2} + \frac{1}{2} \quad [3.8]$$

$$\frac{\partial g_1}{\partial Y} = \frac{1}{2} \quad \frac{\partial g_2}{\partial Y} = -\frac{1}{2} \quad [3.9]$$

to barycentric coordinates of the D_1, D_2, D_3 Quadrilaterals

$$C_{D_1}(X, Y) = C_1 \cdot g_1(X)g_1(Y) + C_5 \cdot g_1(X)g_2(Y) + C_B \cdot g_2(X)g_2(Y) + C_4 \cdot g_2(X)g_1(Y) \quad [3.10]$$

$$C_{D_2}(X, Y) = C_2 \cdot g_1(X)g_1(Y) + C_6 \cdot g_1(X)g_2(Y) + C_B \cdot g_2(X)g_2(Y) + C_5 \cdot g_2(X)g_1(Y) \quad [3.11]$$

$$C_{D_3}(X, Y) = C_3 \cdot g_1(X)g_1(Y) + C_4 \cdot g_1(X)g_2(Y) + C_B \cdot g_2(X)g_2(Y) + C_6 \cdot g_2(X)g_1(Y) \quad [3.12]$$

3.2. Integraltransformation

3.3. Simplex Subdivision

The Integral over a parent Simplex Δ_p , can be expressed as an Integral over 4 Child Simplexes Δ_i :

$$\iint_{\Delta_p} F d\Delta_p = \iint_{\Delta_1} F d\Delta_1 + \iint_{\Delta_2} F d\Delta_2 + \iint_{\Delta_3} F d\Delta_3 + \iint_{\Delta_4} F d\Delta_4 \quad [3.13]$$

The Coordinates of a Child Δ_i can be expressed in local-barycentric coordinates $\xi'_{i,1}, \xi'_{i,2}, \xi'_{i,3}$

The corresponding Transformation from the local coordinate System into the global is given by

$$T_{lg}(\xi'_{i,1}, \xi'_{i,2}, \xi'_{i,3}) = C_{i,1}\xi'_{i,1} + C_{i,2}\xi'_{i,2} + C_{i,3}\xi'_{i,3} \quad [3.14]$$

where $C_{i,j}$ are the coordinates of the Verteces of the Child Simplex Δ_i .

