CSU44054/CS7GV4: Accordance Reality

Gareth W. Young



Tracking

- Tracking Position and Orientation
- Tracking Attached Bodies
- 3D Scanning of Environments

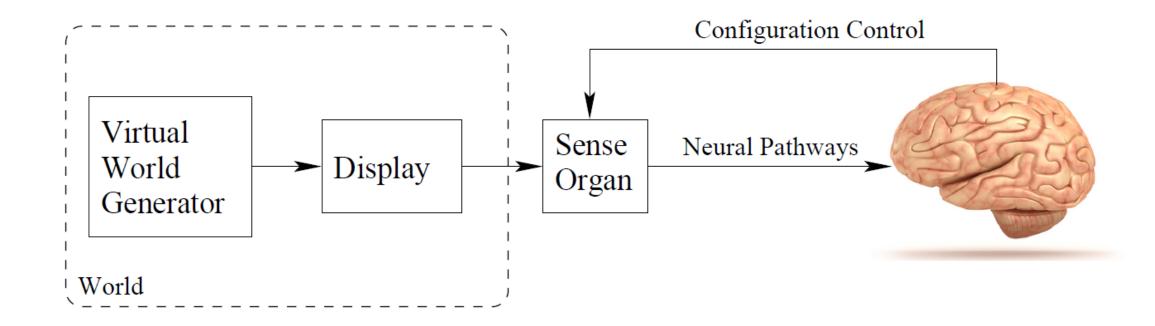
Tracking

The user's sense organs

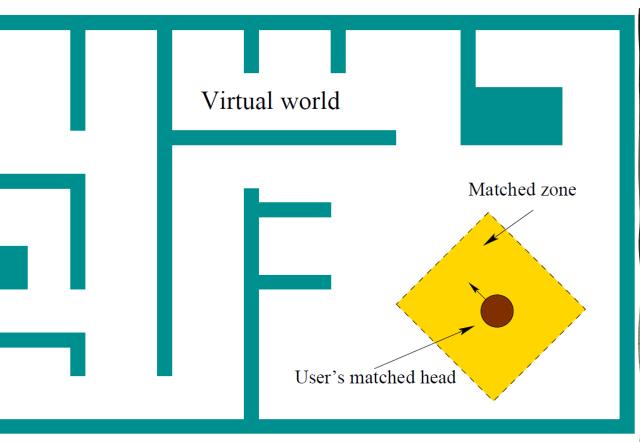
The user's other body parts

The rest of the environment

The user's sense organs



The user's other body parts

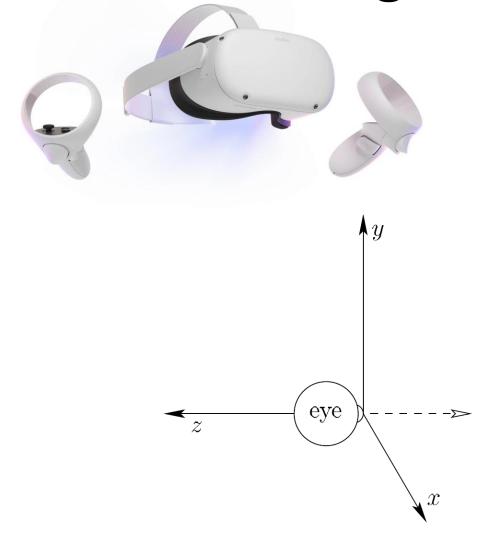


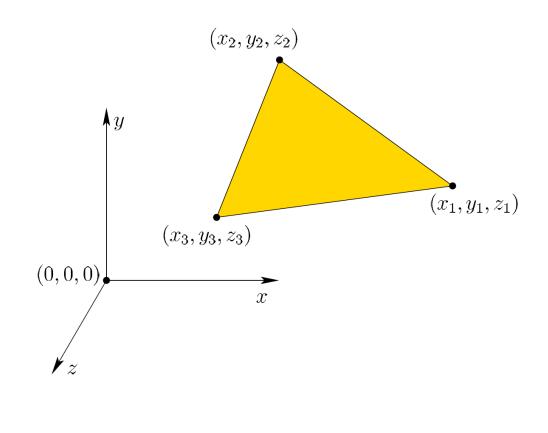




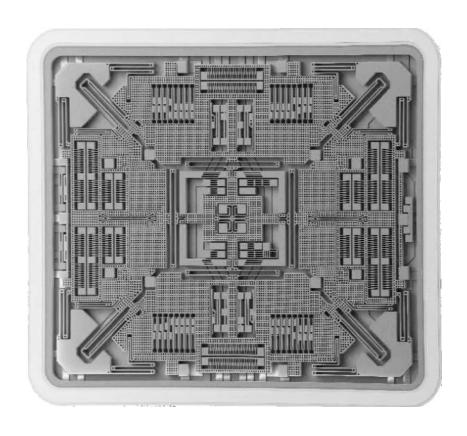
The rest of the environment

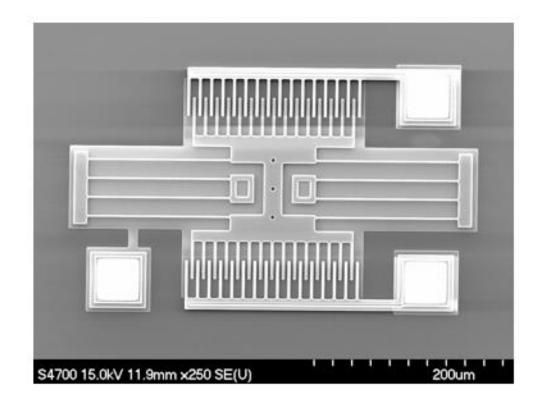




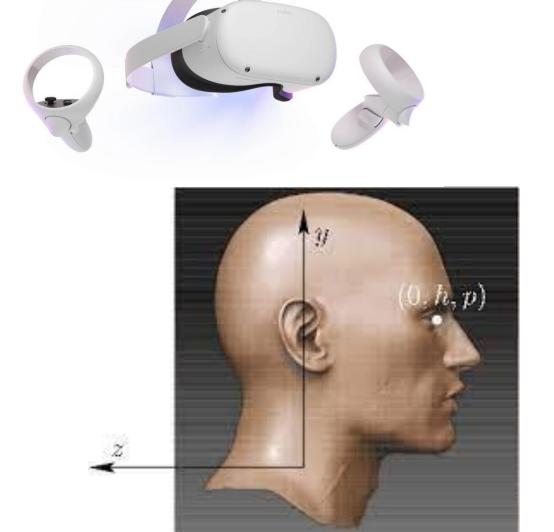


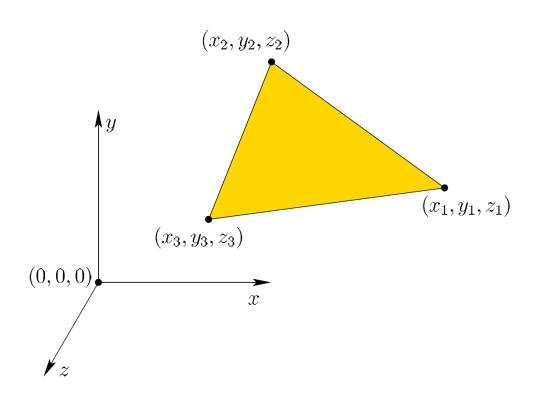
IMUs



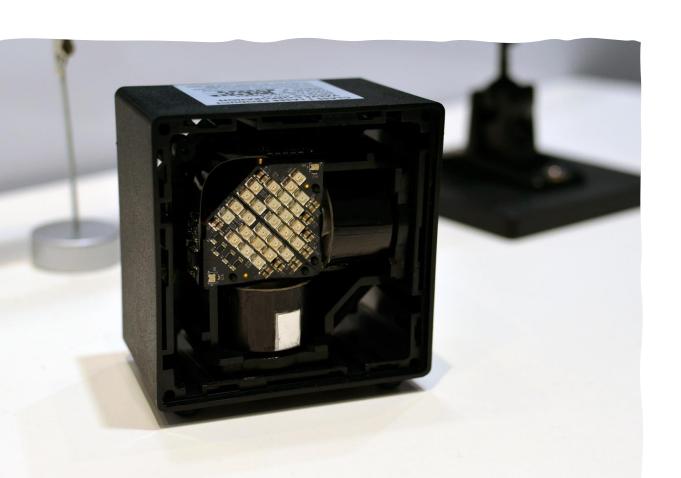


Head Model Translation







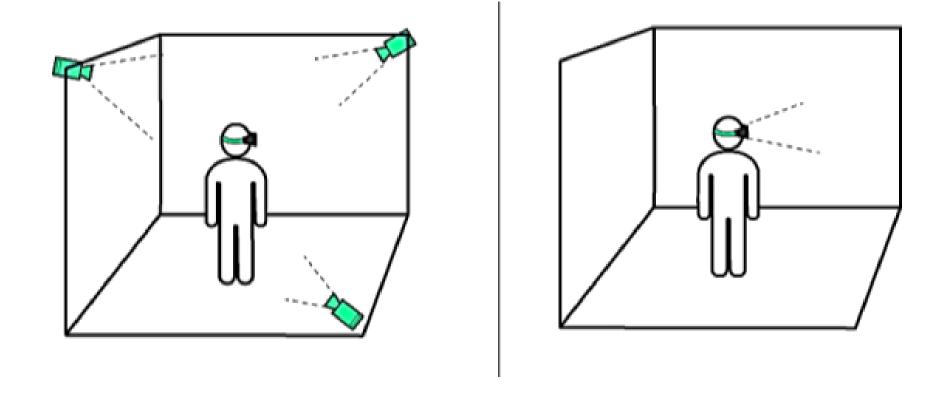




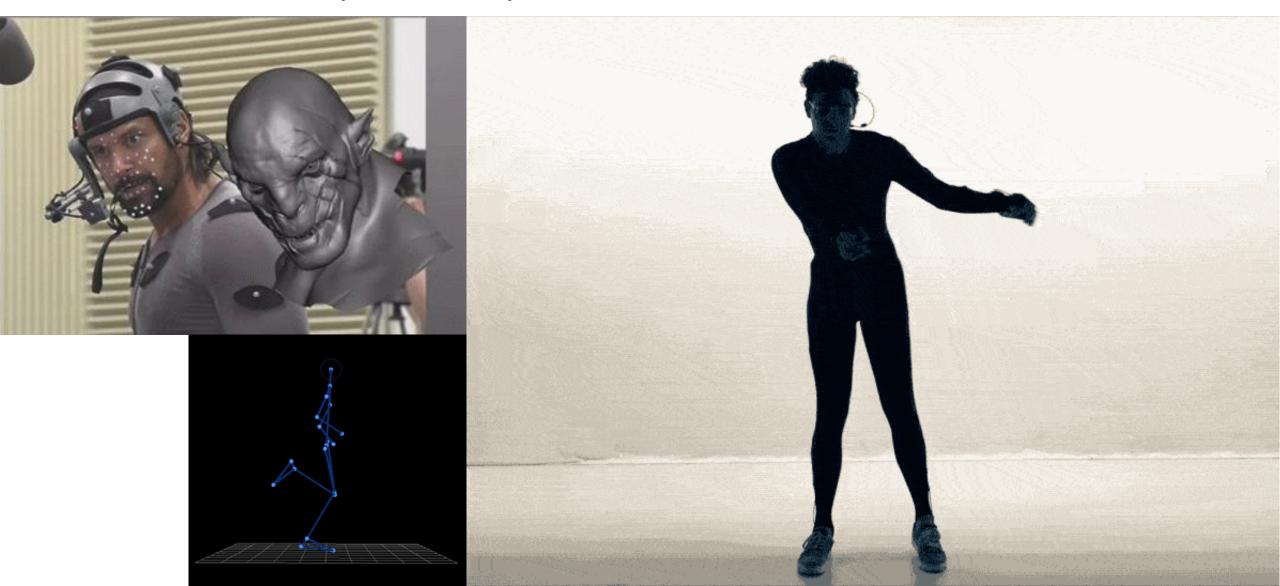




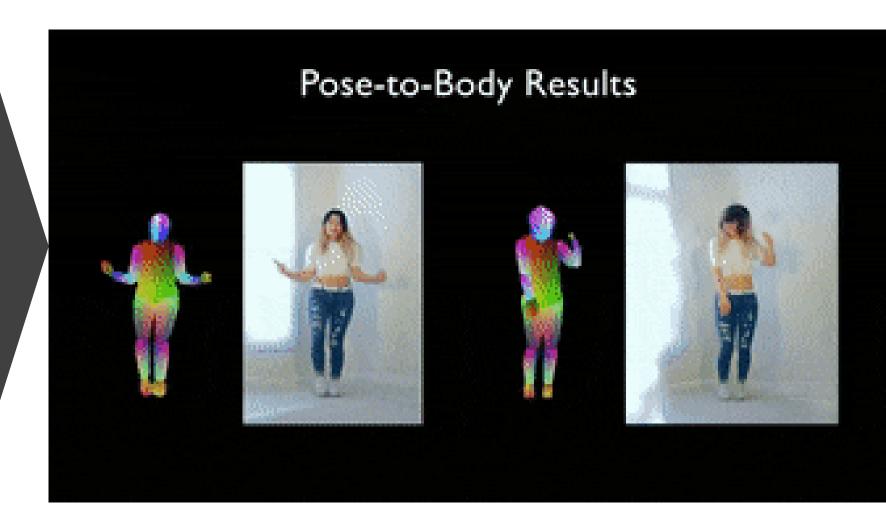
Outside in & Inside Out Tracking



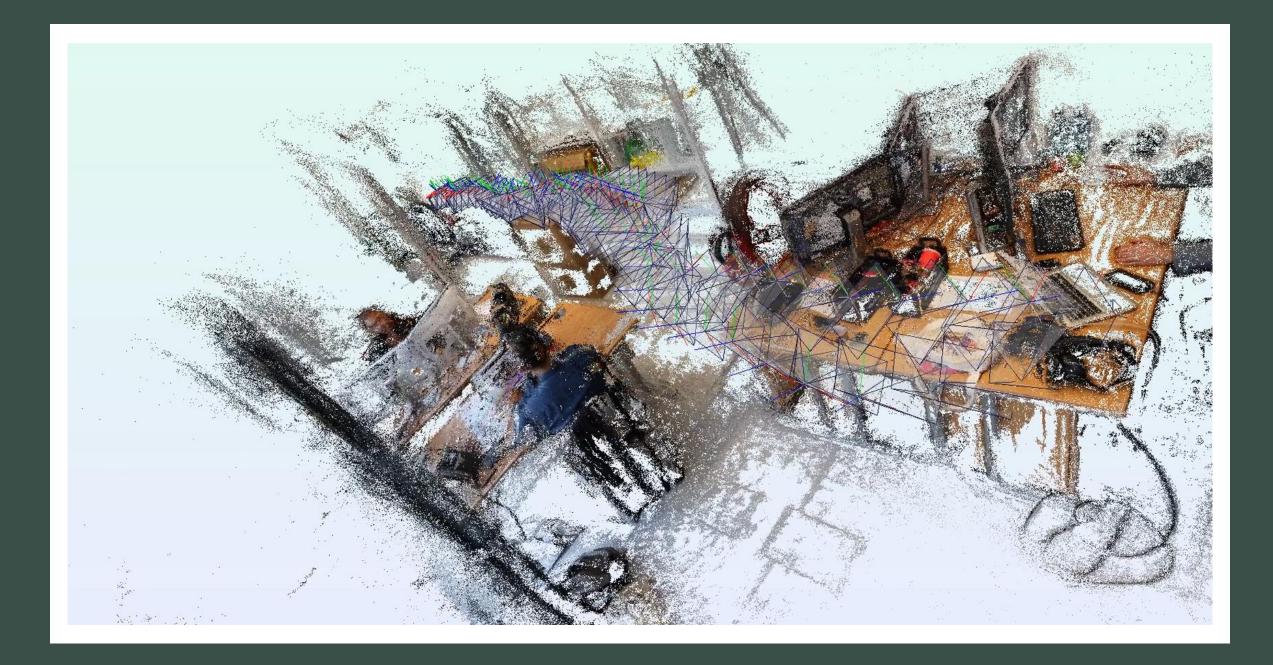
Motion capture systems



Motion capture systems







FOV (Persp): 40.2047 Viewport (5123 x 2881) Focal Length 3935.8501 PxSize (1.0000 x 1.0000) 103



Jonathan Swift

Virtual Reality



Further Reading

- W. T. Fong, S. K. Ong, and A. Y. C. Nee. Methods for in-field user calibration of an inertial measurement unit without external equipment. Measurement Science and Technology, 19(8), 2008.
- G. Welch and E. Foxlin. Motion tracking: no silver bullet, but a respectable arsenal. IEEE Computer Graphics and Applications, 22(6):24–28, 2002.
- H. Zhou and H. Hu. Human motion tracking for rehabilitation A survey. Biomedical Signal Processing and Control, 3(1):1–18, 2007.
- J. Fuentes-Pacheco, J. Ruiz-Ascencio, and J. M. Rendon-Mancha. Visual simultaneous localization and mapping: a survey. Journal Artificial Intelligence Review, 43(1):55–81, 2015.