

AIAA 5047  
Responsible AI  
2025 Fall

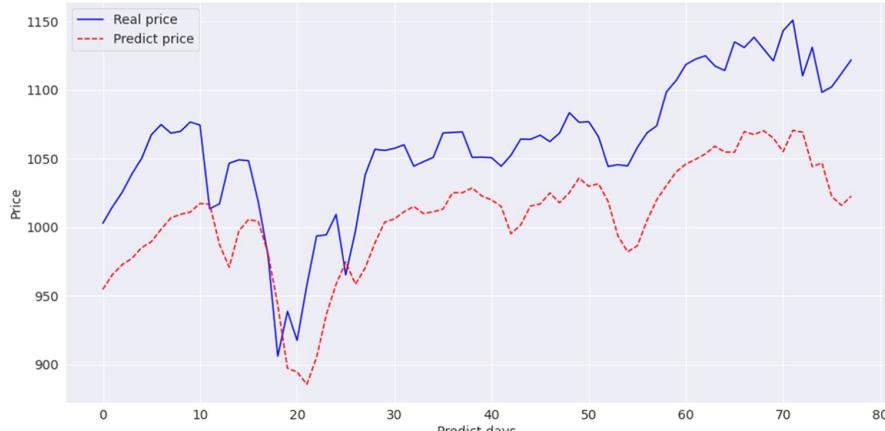
Sihong Xie, AI Thrust, Information  
Hub

*Lecture 8*  
W2 201, 9-11:50 AM F

# Uncertainty in Machine Learning

## Example: Fintech

For stock market forecasting, **regression** models analyze **numerical variables** to assist traders in predicting whether stock prices will rise or fall. However, traders prioritize sound investments over high-risk profit-seeking strategies, underscoring prediction uncertainty information.



Fintech: Stock Market Forecasting



Despite the model predicting a rise in stock prices tomorrow, I still want to sell the stocks that have already gone up today.

Beyond model predictions, uncertainty influences decision making.

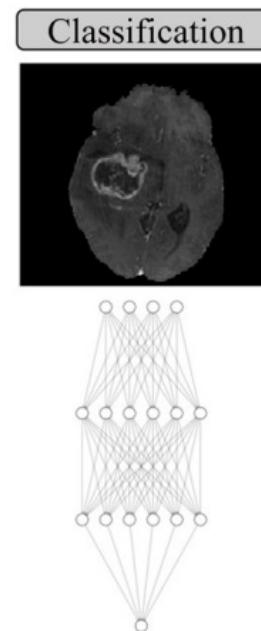
# Uncertainty in Machine Learning

## Example: Healthcare

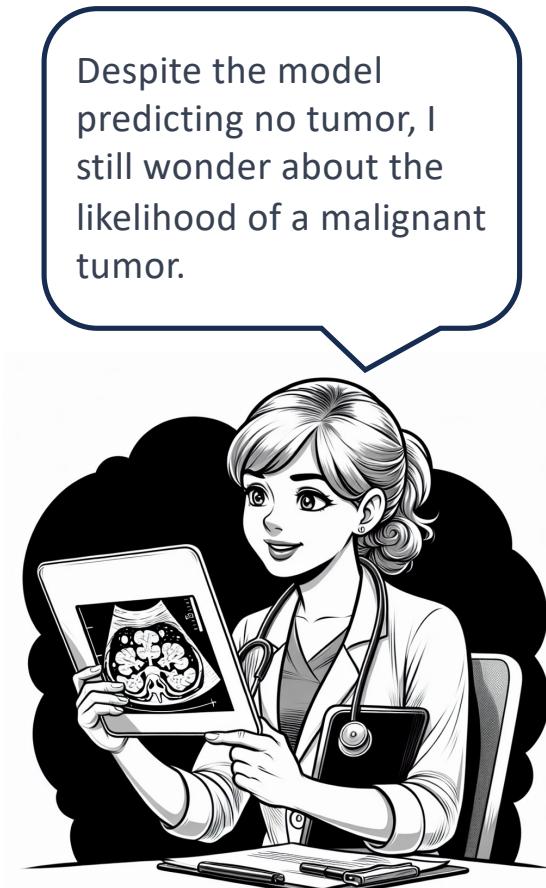
Doctors utilize **classification** models in healthcare to classify medical **images** and assist in diagnosing illnesses.

A binary prediction is insufficient and can mislead the decision making. Uncertainty has complementary information.

Doctors should consider the uncertainty of these predictions when deciding on treatment options for their patients.



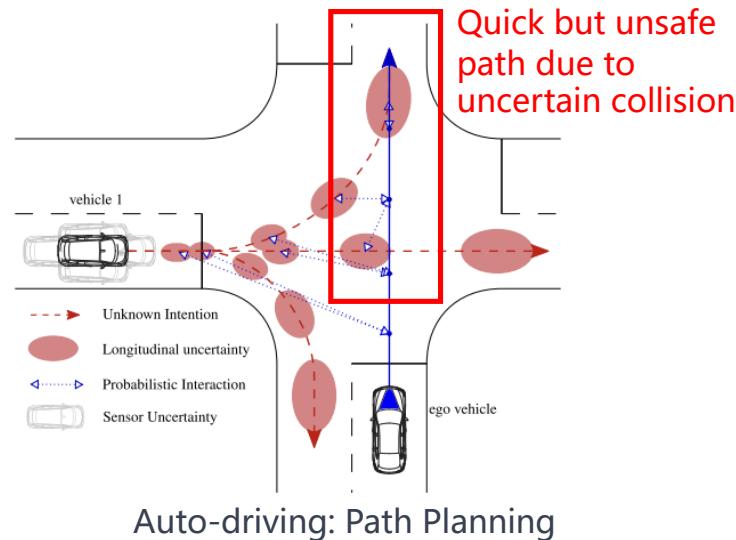
Medicine Imagining



# Uncertainty in Machine Learning

## Example: Auto-driving

Autonomous driving necessitates models to handle **multimodal inputs**, such as video and vehicle state data, to make driving decisions. The decisions should prioritize risk avoidance and rely on more certain predictions.



I'd rather arrive home safe than arrive home quickly.

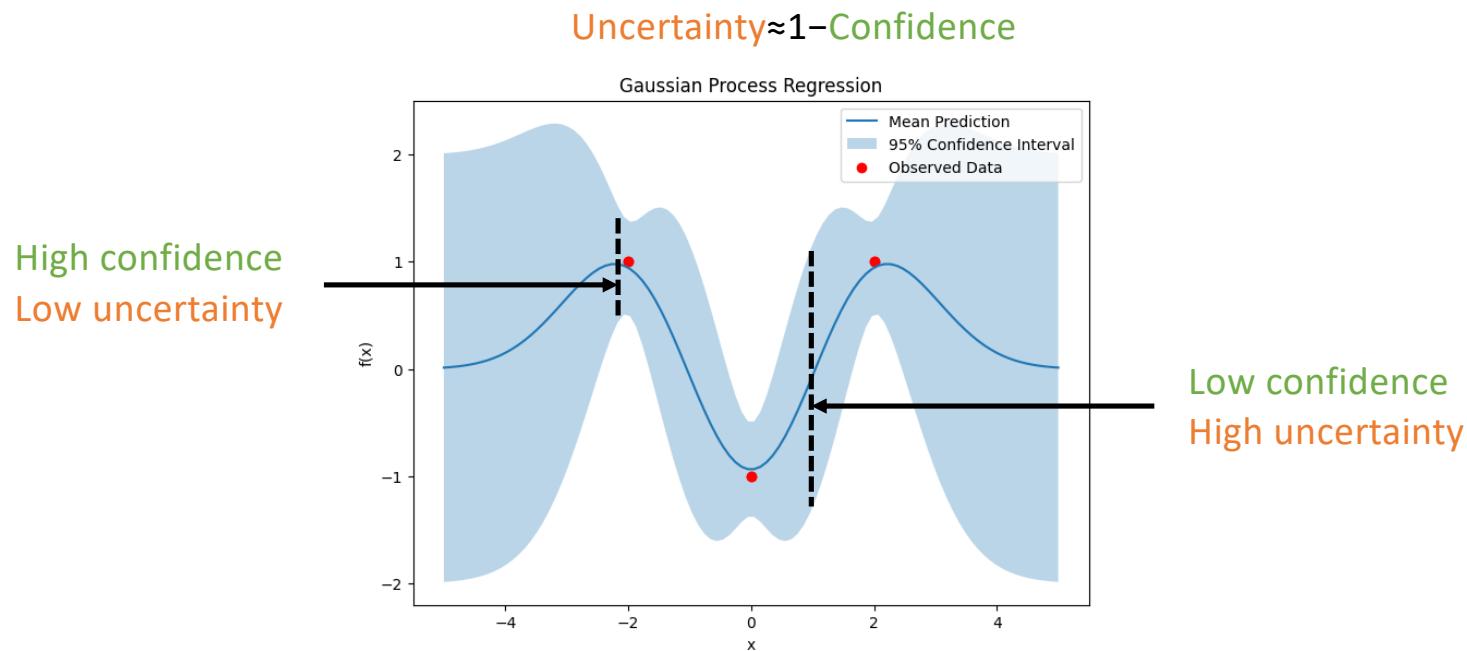
# Uncertainty in Machine Learning

## Motivation

In high-stakes fields like fintech, healthcare, and auto-driving, stakeholders should consider prediction **confidence** and **uncertainty** to make more informed decisions and mitigate potential risks.

**Uncertainty** is the general concept of how unsure a model is about its prediction. It quantifies the “lack of certainty.”

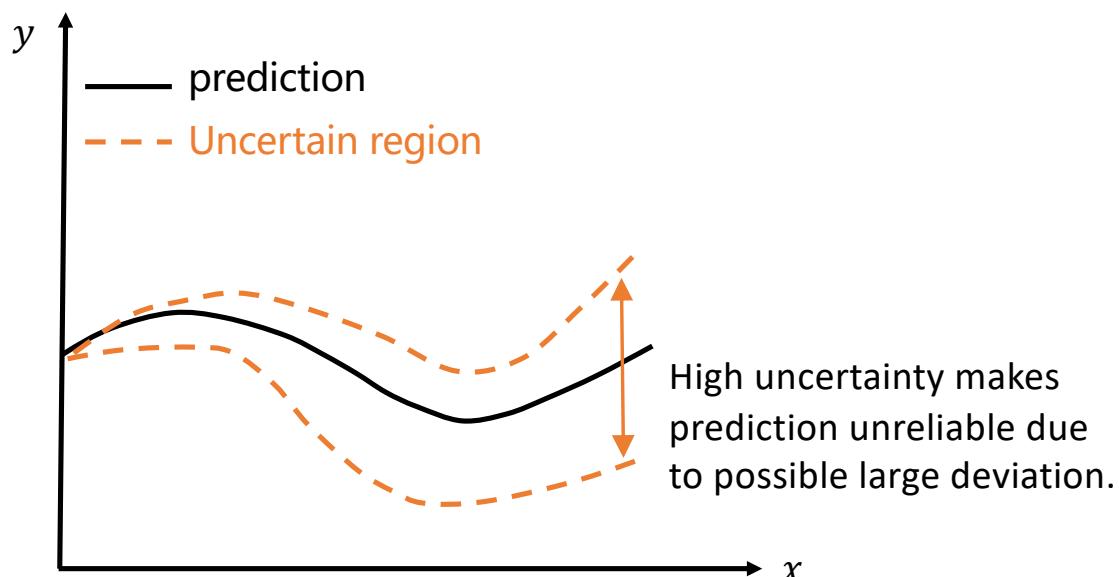
**Confidence** is a specific measure of certainty (or the complement of uncertainty) for a particular prediction.



# Uncertainty in Machine Learning

Moreover, when uncertainty is too high, the prediction should be abstained in safety-critical applications.

For example, due to poor visibility in adverse weather conditions, it may be unsafe for the autonomous vehicle to make a decision with high uncertainty. In such cases, the system could be programmed to abstain from taking action. It should pull over to the side of the road until the uncertainty decreases to an acceptable level.



Autonomous driving under different condition

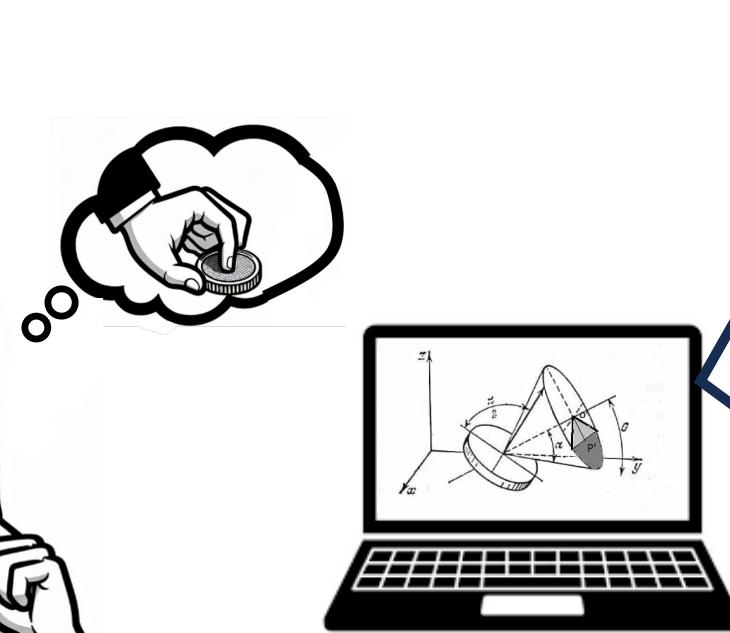
# Uncertainty in Machine Learning

## Two Sources of Uncertainty: Aleatoric and Epistemic

Aleatoric uncertainty arises from inherent data noise, whereas epistemic uncertainty stems from limited knowledge and is reducible with more data. However, **the two kinds can switch under different contexts.**



Aleatoric Uncertainty

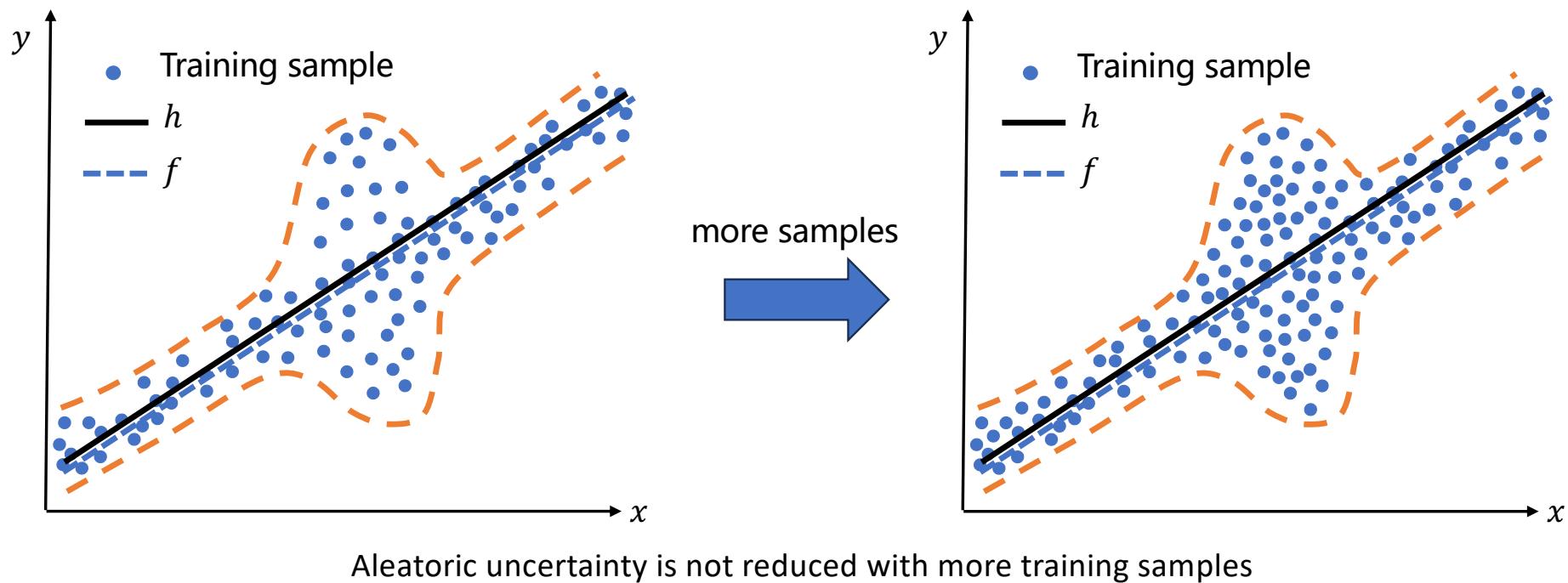


Epistemic Uncertainty

# Uncertainty in Machine Learning

## Aleatoric uncertainty

Aleatoric uncertainty is the randomness inherent to the data generation process and is irreducible with increasing amount of data (i.e. more samples).



# Uncertainty in Machine Learning

Four sources of aleatoric uncertainty:

$$\begin{bmatrix} X_1^{(1)} & X_1^{(2)} \\ X_2^{(1)} & X_2^{(2)} \\ X_3^{(1)} & X_3^{(2)} \\ X_4^{(1)} & X_4^{(2)} \\ X_5^{(1)} & X_5^{(2)} \\ X_6^{(1)} & X_6^{(2)} \\ X_7^{(1)} & X_7^{(2)} \end{bmatrix} \quad \begin{bmatrix} X_1^{(1)} & X_1^{(2)} \\ X_2^{(1)} & X_2^{(2)} \\ X_3^{(1)} & X_3^{(2)} \\ X_4^{(1)} & X_4^{(2)} \\ X_5^{(1)} & X_5^{(2)} \\ X_6^{(1)} & X_6^{(2)} \\ X_7^{(1)} & X_7^{(2)} \end{bmatrix} \quad \begin{bmatrix} Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \\ Y_7 \end{bmatrix}$$

Correct data



Omitted Features  
(unobservable data)

$$\begin{bmatrix} X_1^{(1)} & X_1^{(2)} \\ X_2^{(1)} & X_2^{(2)} \\ X_3^{(1)} & X_3^{(2)} \\ X_4^{(1)} & X_4^{(2)} \\ X_5^{(1)} & X_5^{(2)} \\ X_6^{(1)} & X_6^{(2)} \\ X_7^{(1)} & X_7^{(2)} \end{bmatrix} \quad \begin{bmatrix} Y_1 \\ Y_2 \\ Y_3 \\ Y_4 \\ Y_5 \\ Y_6 \\ Y_7 \end{bmatrix}$$

Missing Data  
(incomplete datasets)



$$\begin{bmatrix} X_1^{(1)} + \delta_X & X_1^{(2)} + \delta_X \\ X_2^{(1)} + \delta_X & X_2^{(2)} + \delta_X \\ X_3^{(1)} + \delta_X & X_3^{(2)} + \delta_X \\ X_4^{(1)} + \delta_X & X_4^{(2)} + \delta_X \\ X_5^{(1)} + \delta_X & X_5^{(2)} + \delta_X \\ X_6^{(1)} + \delta_X & X_6^{(2)} + \delta_X \\ X_7^{(1)} + \delta_X & X_7^{(2)} + \delta_X \end{bmatrix}$$

Feature with random error  $\delta_X$   
(low-resolution images)

$$\begin{bmatrix} Y_1 + \delta_Y \\ Y_2 + \delta_Y \\ Y_3 + \delta_Y \\ Y_4 + \delta_Y \\ Y_5 + \delta_Y \\ Y_6 + \delta_Y \\ Y_7 + \delta_Y \end{bmatrix}$$

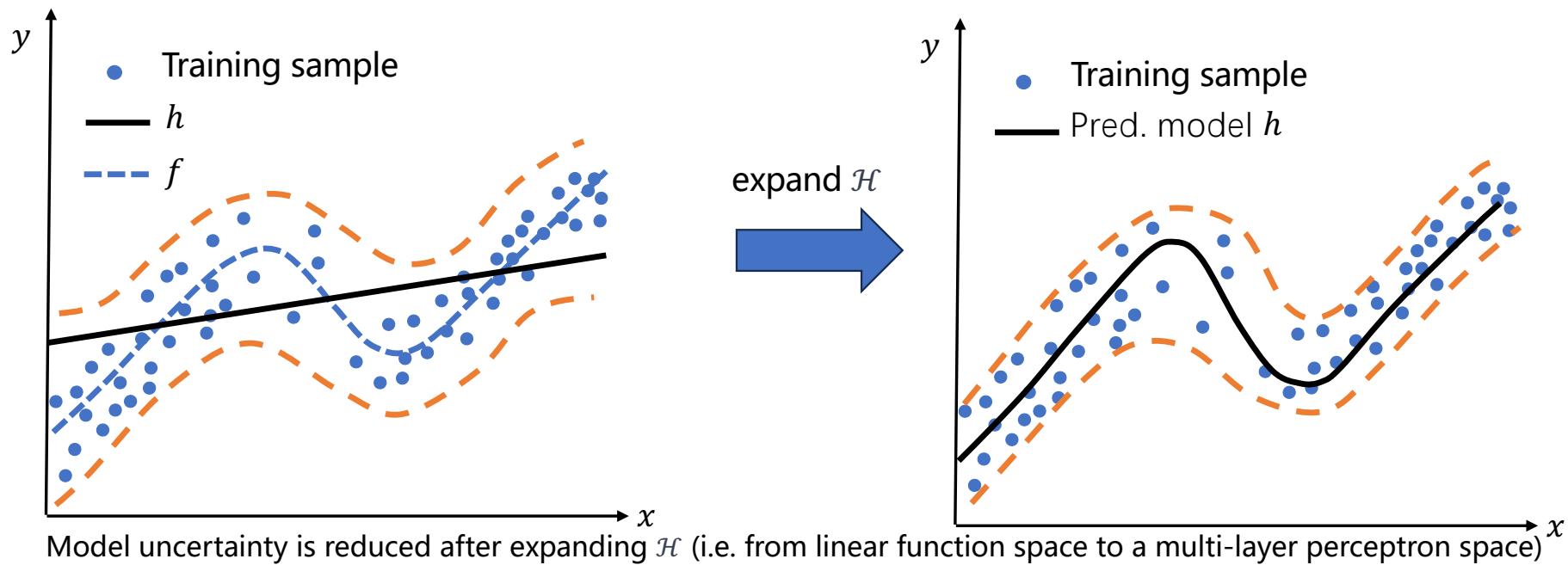
Label with random error  $\delta_Y$   
(biased labeling)

# Uncertainty in Machine Learning

## Epistemic uncertainty

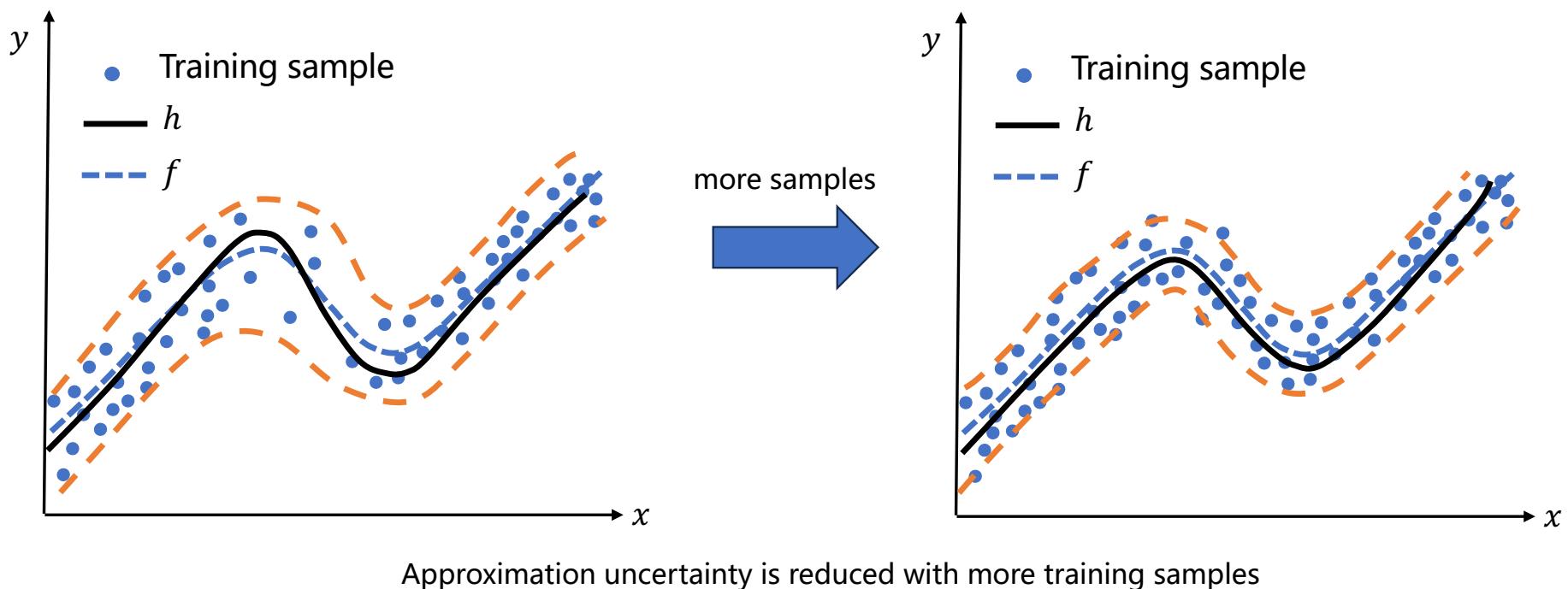
Epistemic uncertainty is reducible uncertainty, rooted in the lack knowledge. It can be further decomposed into **model uncertainty** and **approximation uncertainty**.

**Model uncertainty** measures the difference between the ground truth function  $f$  and hypothesis  $h \in \mathcal{H}$ . It can be reduced by expanding function space  $\mathcal{H}$ . This is the “underfitting” problem in machine learning.



# Uncertainty in Machine Learning

**Approximation uncertainty** is due to the limited number of training samples. It can be reduced with access to more training data.



# Uncertainty Quantification Methods

## Bayesian Approach

Bayesian methods is a pivotal approach of representing uncertainty based on Bayes' Theorem, which updates the probability of Hypothesis with Evidence.

Example: Steve is a shy American. How likely is he to be a librarian?

Hypothesis: Evidence You want: How likely is Steve to be a librarian?

Steve is a librarian. Steve is a shy.  $P(\text{Hypothesis} \text{ given Evidence}) = P(H|E)$

Given: (a) the population ratio of librarian and non-librarian is 1:20. (b) 40% of librarians meet the description and only 10% of non-librarians would.



Is Steve a librarian?

$$\text{Posterior } P(H|E) = \frac{P(H)P(E|H)}{P(E)} \quad \text{Bayes' Theorem}$$

$$\begin{aligned} & \text{Prior } P(H) \\ & \uparrow \\ & \frac{1}{20+1} \times 0.4 \\ & \downarrow \\ & P(H) \end{aligned} \quad \begin{aligned} & \text{Likelihood } P(E|H) \\ & \nearrow \\ & \frac{1}{20+1} \times 0.4 + \frac{20}{20+1} \times 0.1 \\ & \downarrow \\ & P(E|H) \end{aligned} \quad \begin{aligned} & \downarrow \\ & P(\neg H) \end{aligned} \quad \begin{aligned} & \downarrow \\ & P(E|\neg H) \end{aligned}$$

# Uncertainty Quantification Methods

## Bayesian neural networks (BNNs)

BNNs include stochastic parameters  $\theta$  with distribution  $P(\theta)$ .

In BNNs, the **Hypothesis** is  $\theta$  and the **Evidence** is training data  $D$ , with inputs  $D_X$  and labels  $D_Y$ .

With Bayes' Theorem, we have  $P(\theta|D) = \frac{P(\theta)P(D_Y|D_X, \theta)}{P(D_Y|D_X)}$ .

**Training:** To maximize the posterior  $P(\theta|D)$ , BNNs learn to maximize  $P(\theta)P(D_Y|D_X, \theta)$ .

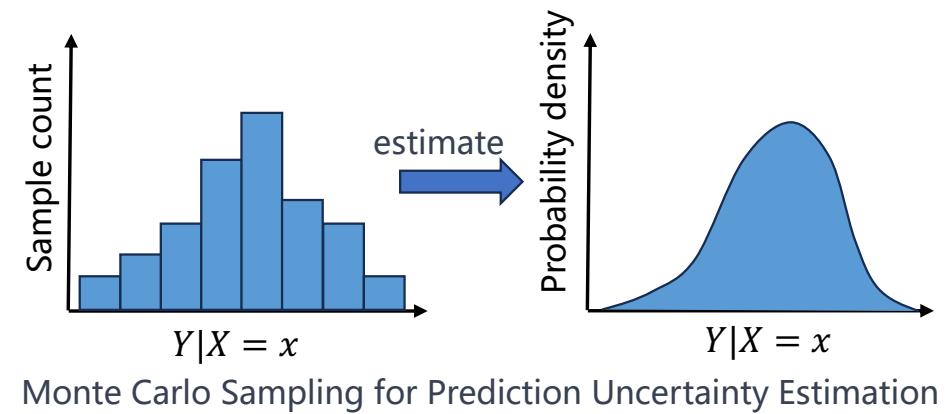
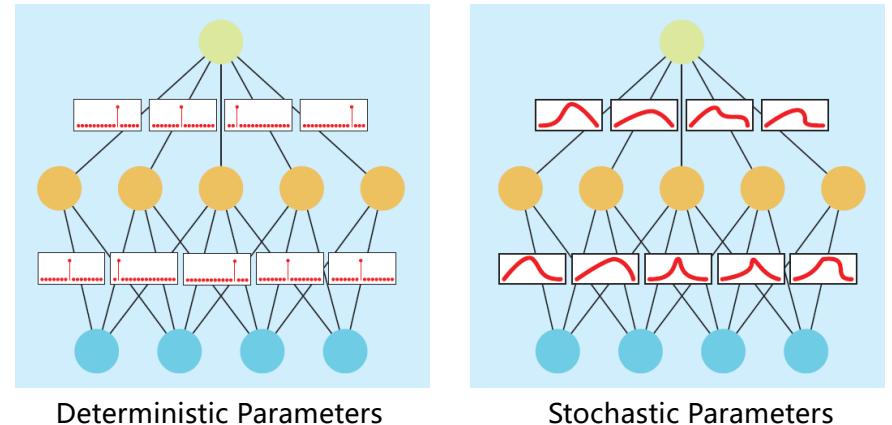
**Prediction:** with input  $x$ , BNNs output

$$\hat{P}(Y|X = x) = \int_{\theta} \hat{P}(Y|X = x, \theta) P(\theta') d\theta'$$

to quantify prediction uncertainty, which is estimated by Monte Carlo sampling in practice.

**Advantage:** Flexibility with different choices of priors; Approximation of complex posteriors with simpler, tractable distributions.

**Disadvantage:** Computational complexity in posterior optimization.



# Uncertainty Quantification Methods

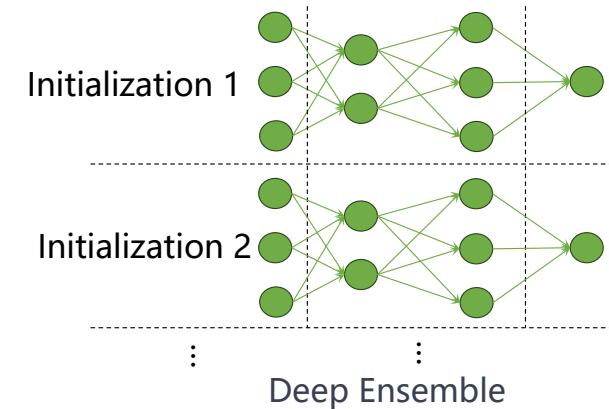
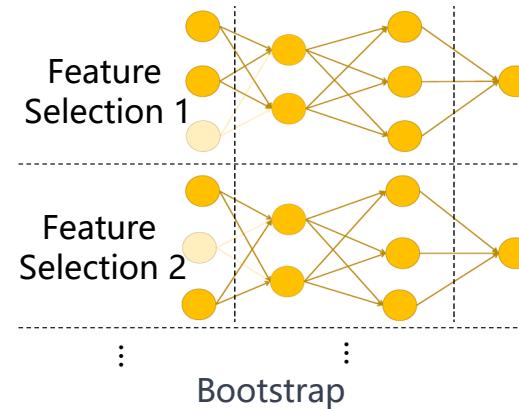
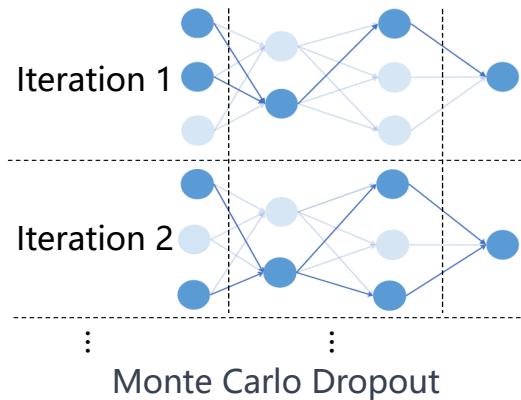
## Monte Carlo Dropout

MC dropout is a convenient surrogate of Bayesian deep learning. It uses dropout layers to create variation in outputs.

Some other ensemble methods:

**Bootstrap** trains multiple models on different parts of the training data (i.e. feature selection) and then analyzes the variance in predictions across these models.

**Deep ensemble** trains multiple models with different random initializations independently on the same data and then aggregates their predictions.



**Advantage:** Simple implementation.

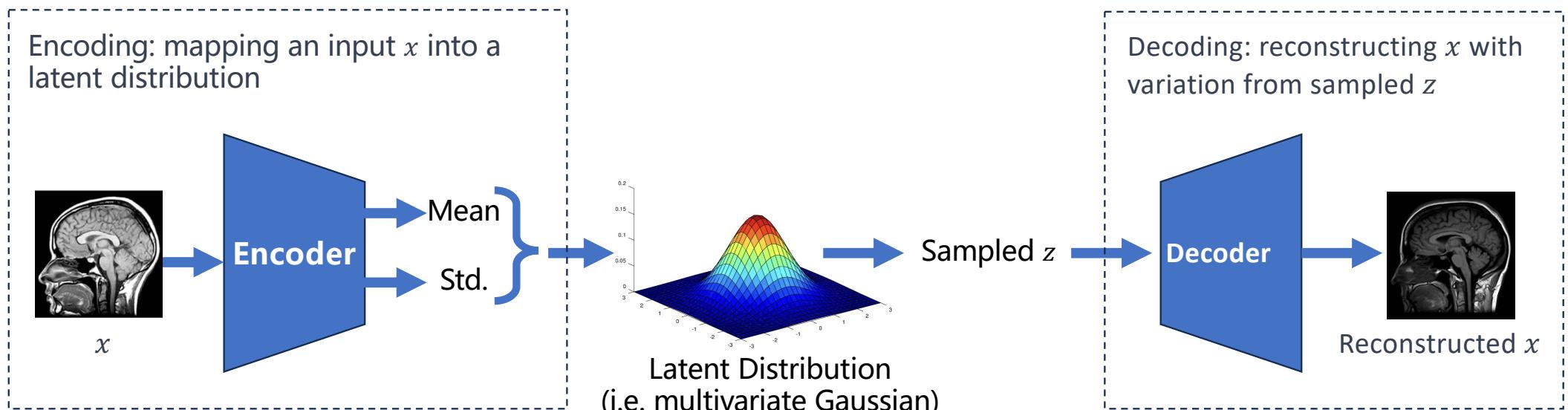
**Disadvantage:** Limited flexibility with single source of stochasticity. Lack of theoretical guarantees.

# Uncertainty Quantification Methods

## Variational Autoencoders (VAEs)

VAEs are generative models to learn the probability distribution of a given dataset.

A VAE model consists of an encoder and a decoder.



**Advantage:** Generative modeling for new samples.

**Disadvantage:** Lack of uncertainty estimation: VAEs do not provide a direct measure of uncertainty in predictions.

# Uncertainty Quantification Methods

## Closed-form UQ for Bayesian Regression Model

A scoring rule is an extended real-valued function  $S$ .

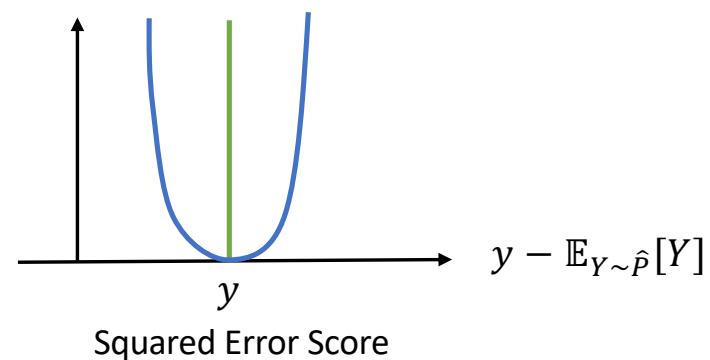
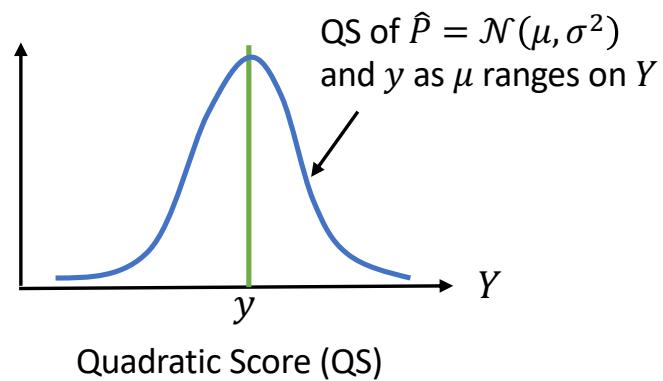
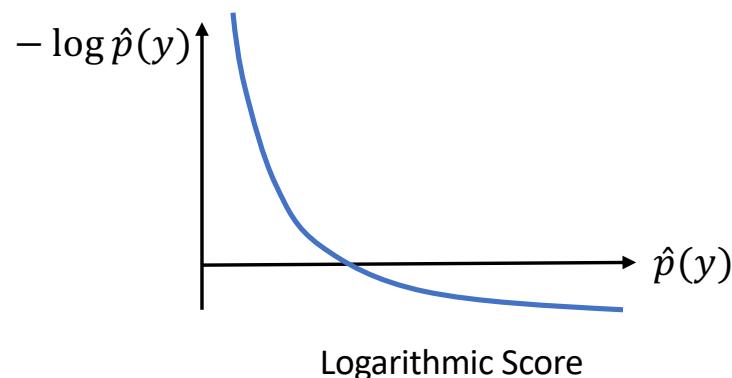
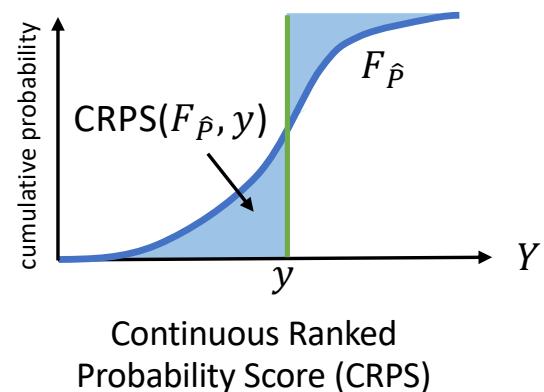
Denote the forecast  $\hat{P}(Y|X = x)$  by  $\hat{P}$  for simplicity with density  $\hat{p}$  and CDF  $F_{\hat{P}}$ .

If true value is  $y$ , the forecaster's penalty is  $S(\hat{P}, y)$ . Different scoring rules  $S(\hat{P}, y)$  are listed below.

| Name                                | Definition   |
|-------------------------------------|--|
| Continuous ranked probability score | $\text{CRPS}(\hat{P}, y) = \int_{\mathbb{R}} (F_{\hat{P}}(t) - \mathbb{I}\{y \leq t\})^2 dt$ |
| Logarithmic score                   | $\text{LS}(\hat{P}, y) = -\log \hat{p}(y)$   |
| Quadratic score                     | $\text{QS}(\hat{P}, y) = -2\hat{p}(y) + \int_{\mathbb{R}} \hat{p}(t)^2 dt$                   |
| Squared error score                 | $\text{SE}(\hat{P}, y) = (y - \mathbb{E}_{Y \sim \hat{P}}[Y])^2$                             |

# Uncertainty Quantification Methods

Closed-form UQ for Bayesian Regression Model



# Uncertainty Quantification Methods

## Closed-form UQ for Bayesian Regression Model

We assess the predictive quality (**total uncertainty**) of the forecast  $\hat{P}$  on average over possible values of  $y$ .

$$S(\hat{P}, P) = \int S(\hat{P}, y) dP(y)$$

where  $P$  is the true distribution of  $P(Y|X = x)$ .

**Aleatoric uncertainty** is the smallest possible error that one can achieve as

$$H(P) = S(P, P) = \int S(P, y) dP(y).$$

which is **entropy** if we define  $S$  as logarithmic scoring rule.

**Epistemic uncertainty** is due to the lack of knowledge about  $\hat{P}$

$$d(\hat{P}, P) = S(\hat{P}, P) - S(P, P) = S(\hat{P}, P) - H(P),$$

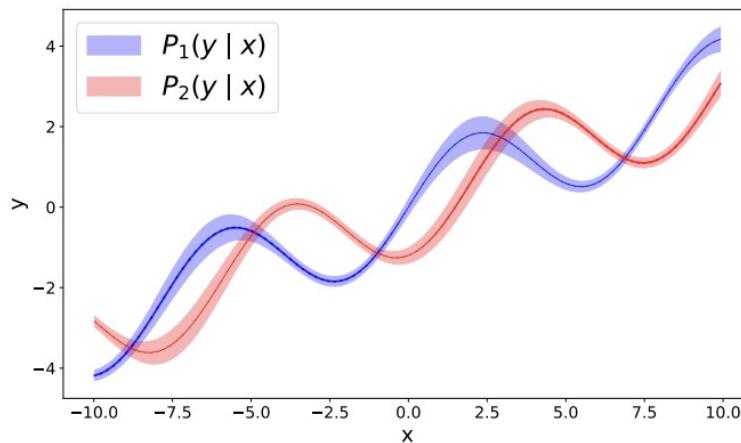
quantifying how much worse it is to predict with distribution  $\hat{P}$  than with the true data distribution  $P$ .

# Uncertainty Quantification Methods

## Closed-form UQ for Bayesian Regression Model

We show an example here. The ground-truth conditional is a heteroscedastic two-component mixture,

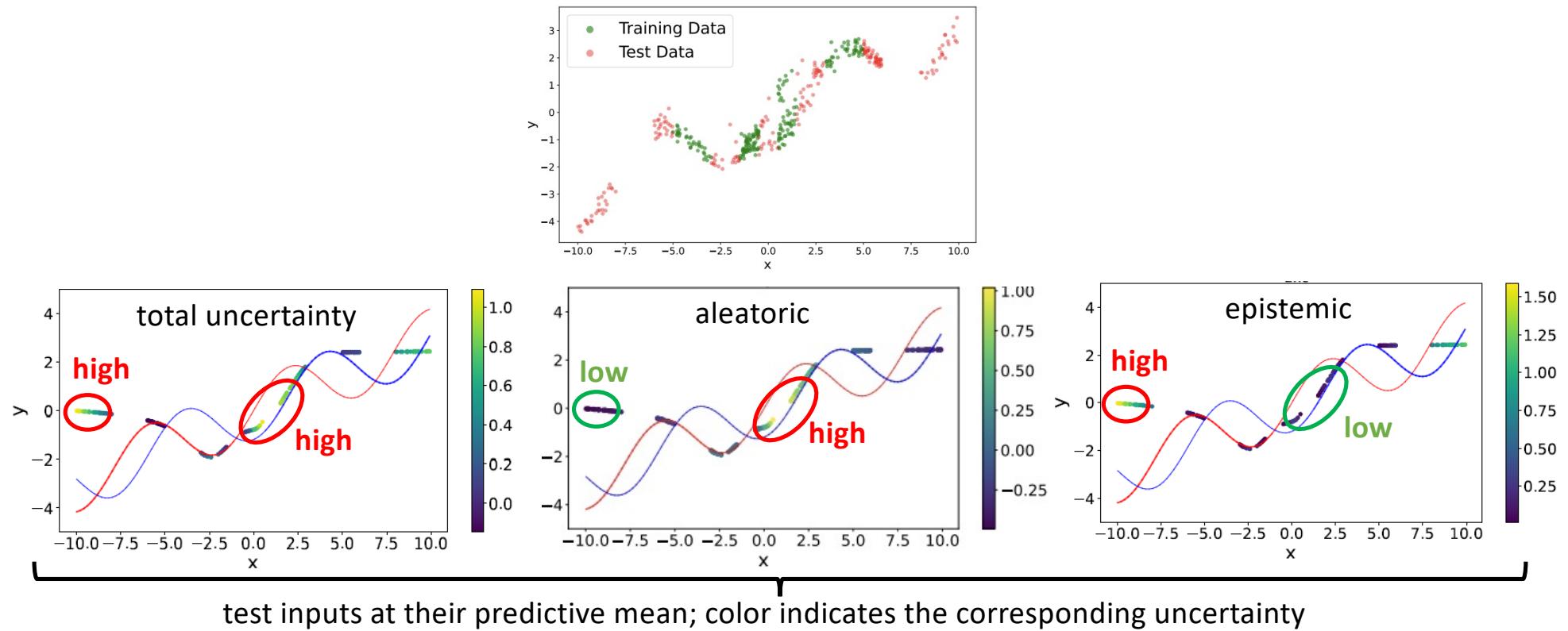
$$p^*(y | x) = \pi(x)P_1(y | x) + (1 - \pi(x))P_2(y | x)$$



# Uncertainty Quantification Methods

## Closed-form UQ for Bayesian Regression Model

We draw training pairs from  $p^*(y | x)$  and fit a regression network, and use test data to run inference.



Fishkov, Alexander, et al. "Uncertainty Quantification for Regression using Proper Scoring Rules." arXiv preprint arXiv:2509.26610 (2025).

# Uncertainty Quantification Methods

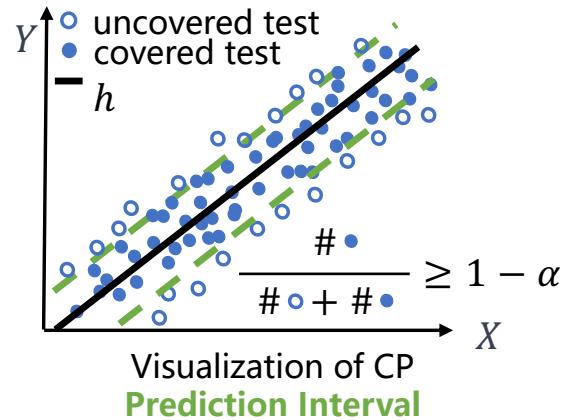
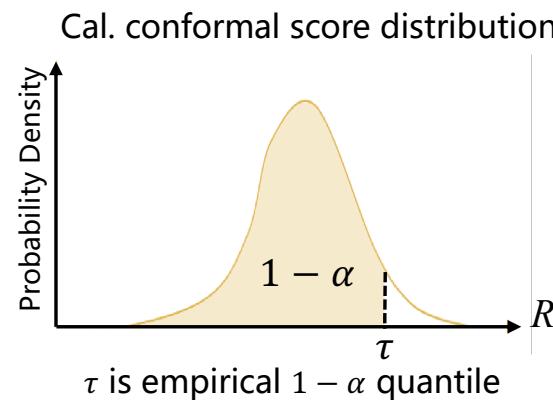
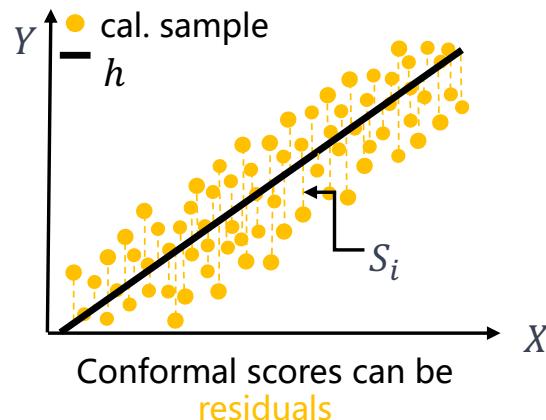
## Conformal Prediction (CP)

CP uses calibration data to output  $1 - \alpha$  confidence set of the prediction of a test input.

In regression tasks, with calibration samples  $\{(X_i, Y_i)\}_{i=1}^n$  and a trained model  $h$ , we have the **residuals**  $S_i = |h(X_i) - Y_i|$ , namely **conformal scores**. More formally, we represent  $S_i = s(X_i, Y_i)$ , where  $s(\cdot, \cdot)$  is score function.

$\tau$  is the empirical  $1 - \alpha$  quantile, which is the  $[(1 - \alpha)n]$ -th largest element of  $\{S_i\}_{i=1}^n$ .

With an exchangeable (share the same distribution of calibration data) test sample  $(X_{n+1}, Y_{n+1})$ , prediction set is  $C(X_{n+1}) = \{y: |h(X_{n+1}) - y| \leq \tau\}$ , and the **coverage guarantee** is  $\Pr(Y_{n+1} \in C(X_{n+1})) \geq 1 - \alpha$ .



**Advantage:** CP is Post-hoc method with simple implementation; CP does not rely on specific assumptions about data distribution.

**Disadvantage:** Relying on exchangeable calibration and test samples; Lack of adaptiveness to different input values.

# Uncertainty Quantification Methods

## Proof of coverage guarantee

Conformal scores  $S_1, \dots, S_n, S_{n+1}$  are exchangeable random variables.

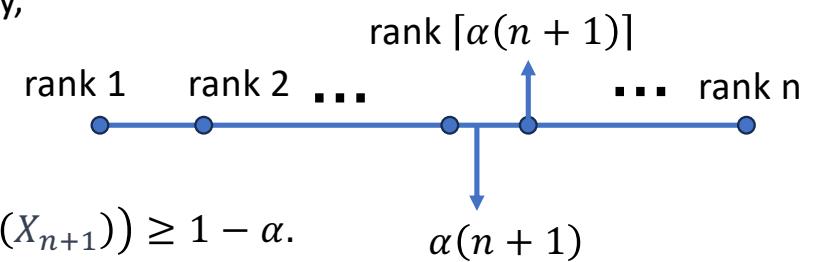
Because of exchangeability, the rank of  $S_{n+1}$  among the  $n + 1$  values is uniformly distributed over  $\{1, 2, \dots, n + 1\}$ .

$$\Pr(\text{rank}(S_{n+1}) = k) = \frac{1}{n+1}, \quad \forall k \in \{1, \dots, n+1\}.$$

Now,  $S_{n+1} \leq \tau$  iff  $S_{n+1}$  is not among the largest  $\lceil \alpha(n+1) \rceil$  scores. Equivalently,

$$\Pr(S_{n+1} \leq \tau) = \frac{\lceil (1 - \alpha)(n+1) \rceil}{n+1}$$

Since  $\frac{\lceil (1 - \alpha)(n+1) \rceil}{n+1} \geq 1 - \alpha$ , we have the guaranteed coverage  $\Pr(Y_{n+1} \in C(X_{n+1})) \geq 1 - \alpha$ .



## Intuition

Because the test score  $S_{n+1}$  is exchangeable with calibration scores, its rank is uniformly random. By taking the  $(1 - \alpha)$ -quantile threshold  $\tau$ , we ensure that at most an  $\alpha$ -fraction of scores fall above it. Thus, the probability the new test score exceeds it is at most  $\alpha$ .

# Uncertainty Quantification Methods

## Calibration

With label space  $\mathcal{Y} = \{1, \dots, K\}$ , a classification model outputs a prediction as a probability vector  $(v^1, \dots, v^K)$ .

The predicted label is  $\hat{y} = \arg \max_{k \in \mathcal{Y}} v^k$ .

The confidence of the prediction is  $c = \max_{k \in \mathcal{Y}} v^k$ .

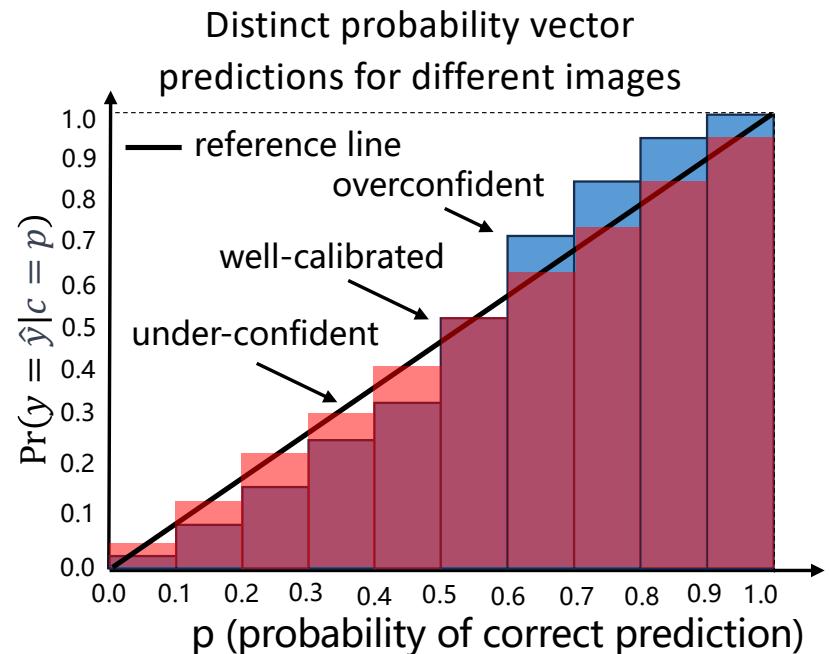
A model is well-calibrated if the probability of correct prediction (i.e. reliability) equals the prediction confidence:

$$\Pr(y = \hat{y} | c = p) = p, \forall p \in [0,1].$$

**Histogram binning:** Grouping  $n$  calibration samples into different bins according to their confidences in predicted labels and plotting the bins. The plot informs if the model is well-calibrated.

**Advantage:** High Interpretability; Compatibility with various models.

**Disadvantage:** typically not applicable to regression tasks.



# Use of Uncertainty

## Adaptive Uncertainty Quantification

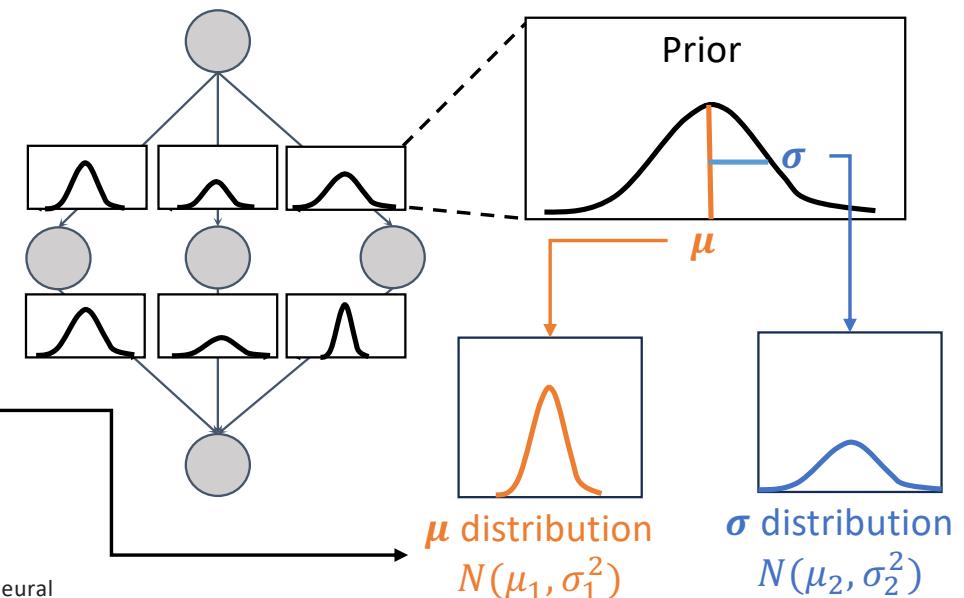
Adaptive Uncertainty Quantification aims to heteroscedasticity, which requires that prediction uncertainty is adaptive to different inputs.

**Bayesian approaches' predictions** can be more adaptive to inputs via the methods of increasing learning flexibility, such as architecture search and data augmentation.

### More tailored strategies:

BNNs with hierarchical priors take the means and variances of priors are also random variables with their own distributions.

Hierarchical priors offer BNNs greater flexibility in fitting the training data with **more trainable parameters**, thereby improving their adaptability to various patterns within the dataset.



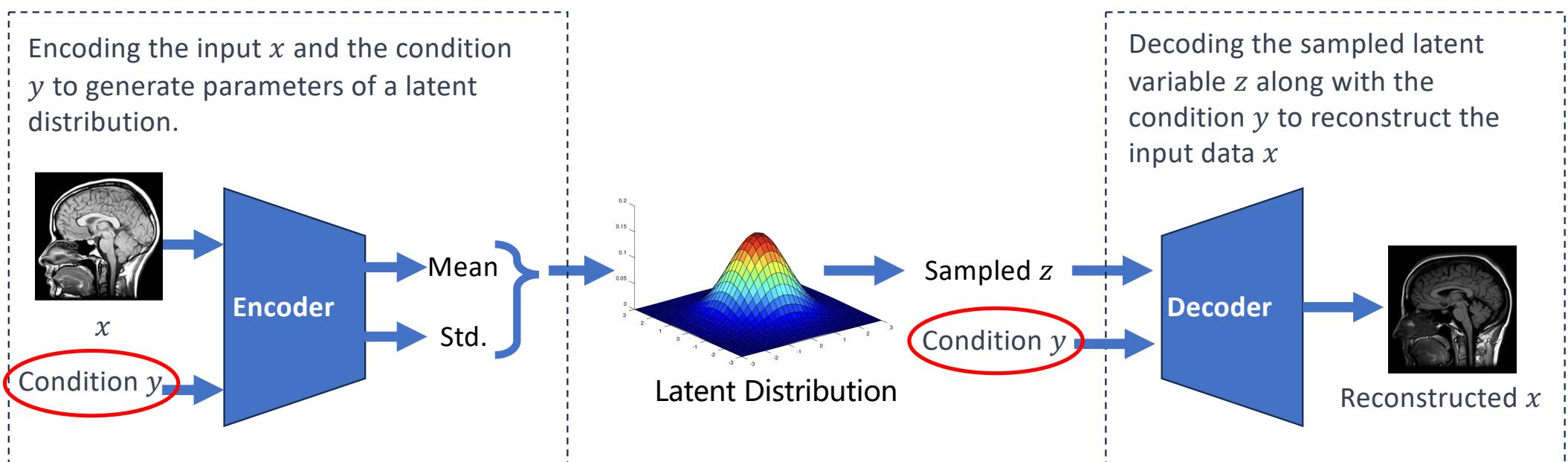
# Use of Uncertainty

## Adaptive Uncertainty Quantification

### Conditional Variational Autoencoder (CVAE)

VAE can generate outputs by sampling from the encoder-estimated latent distribution.

The generation can be more context-aware by capturing the relationship between input  $x$  and condition  $y$  (i.e. label).



# Use of Uncertainty

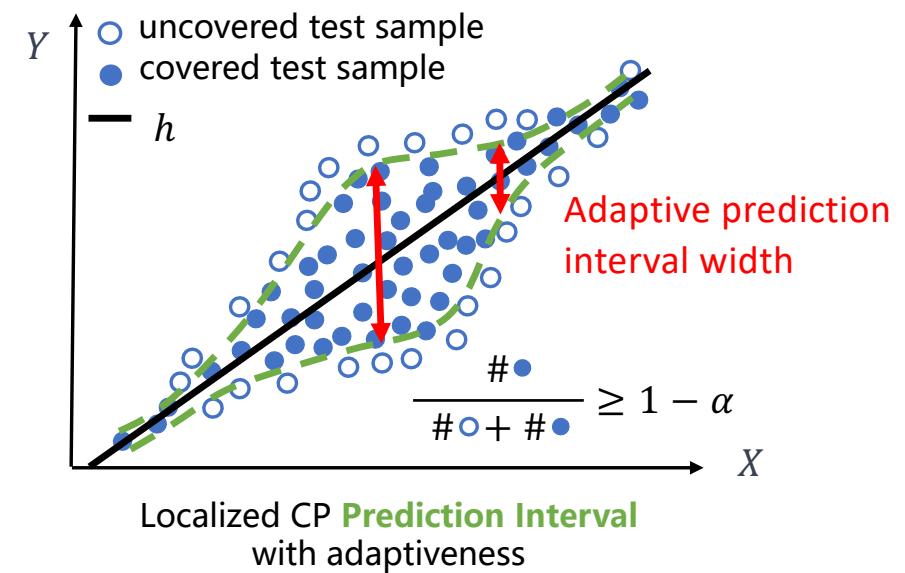
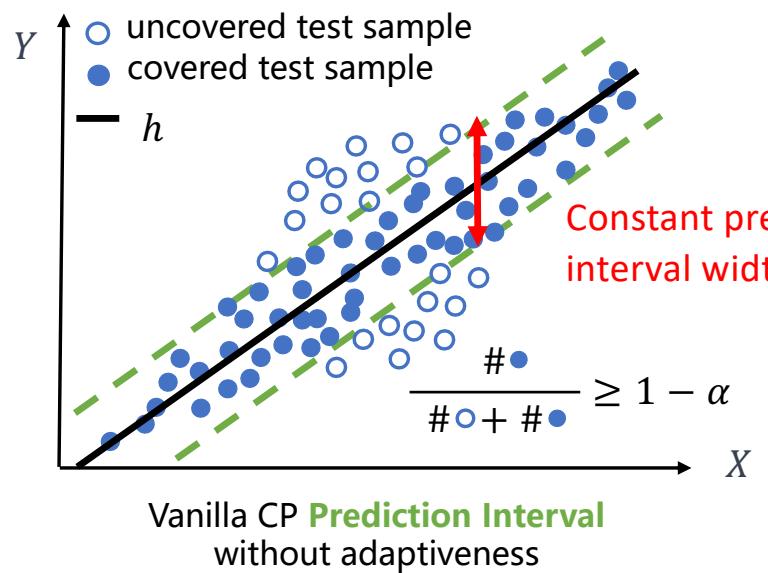
## Adaptive Uncertainty Quantification

**Localized Conformal Prediction** weights calibration conformal scores,  $S_i$ , with distance-informed weights, such as

$$S_i(X_{n+1}) = e^{-5|X_{n+1}-X_i|} \times |h(X_i) - Y_i|$$

then the  $1 - \alpha$  quantile of the weighted conformal scores  $\{S_i(X_{n+1})\}_{i=1}^n$  is a function of  $X_{n+1}$ , denoted by  $\tau(X_{n+1})$ .

As a result, the size of prediction set  $C(X_{n+1}) = \{y: |h(X_{n+1}) - y| \leq \tau(X_{n+1})\}$  is **adaptive to  $X_{n+1}$** .

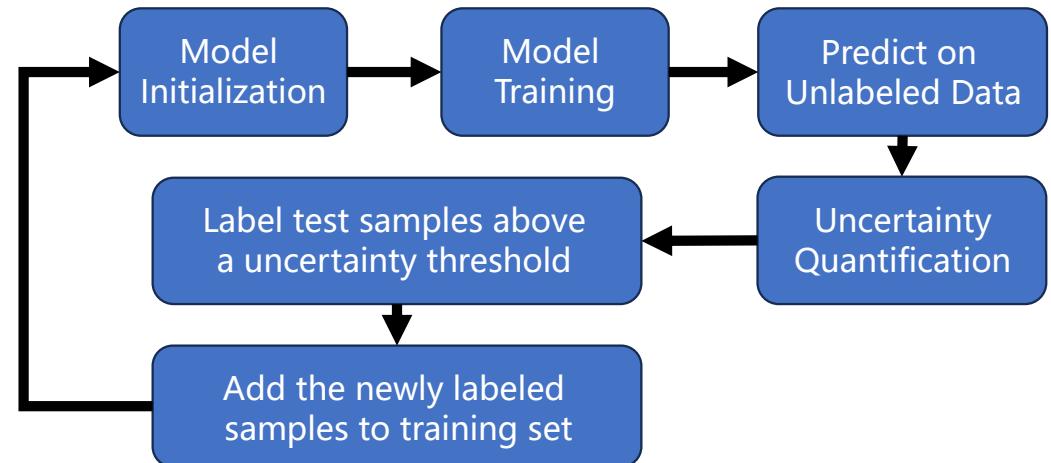


# Use of Uncertainty

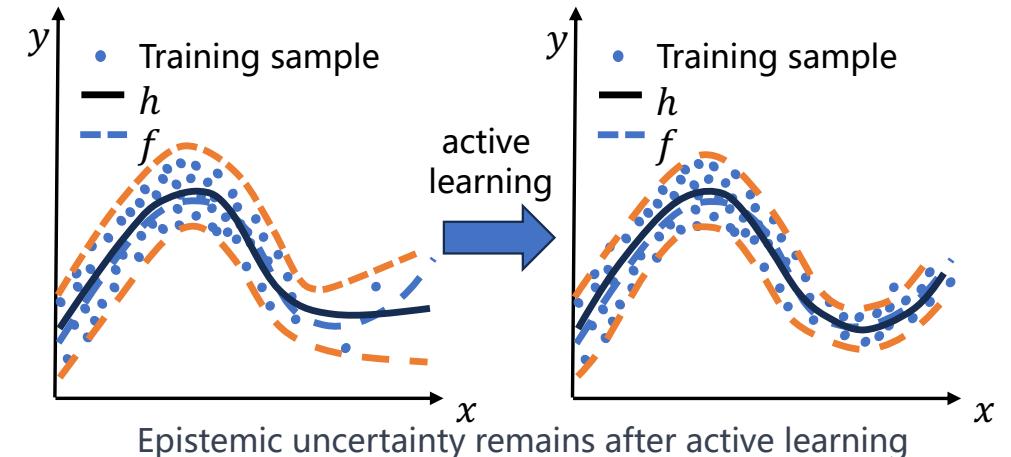
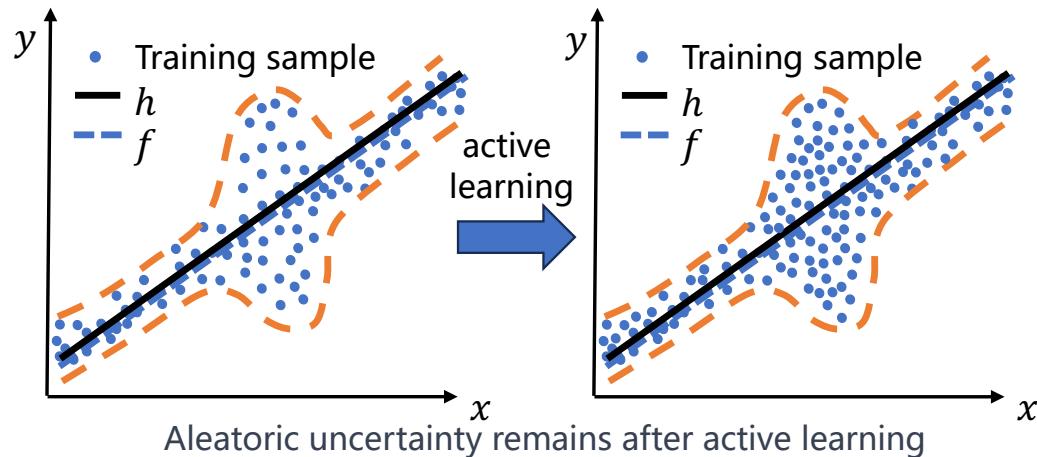
## Active Learning in Uncertainty Quantification

Active Learning in Uncertainty Quantification is an essential approach for uncertainty reduction.

However, active learning can reduce epistemic uncertainty, while can not reduce aleatoric uncertainty.



Workflow of Active Learning in Uncertainty Quantification

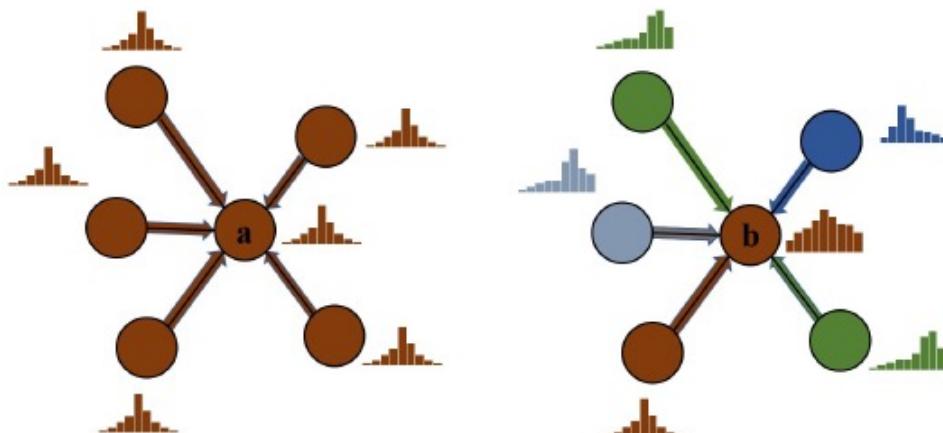


# Uncertainty Quantification for Structural Data

## Uncertainty Quantification for Graph Data

**Challenges:** Most traditional uncertainty quantification methods assume that samples are independent, allowing them to statistically estimate uncertainty in predictions, such as coverage guarantees in CP.

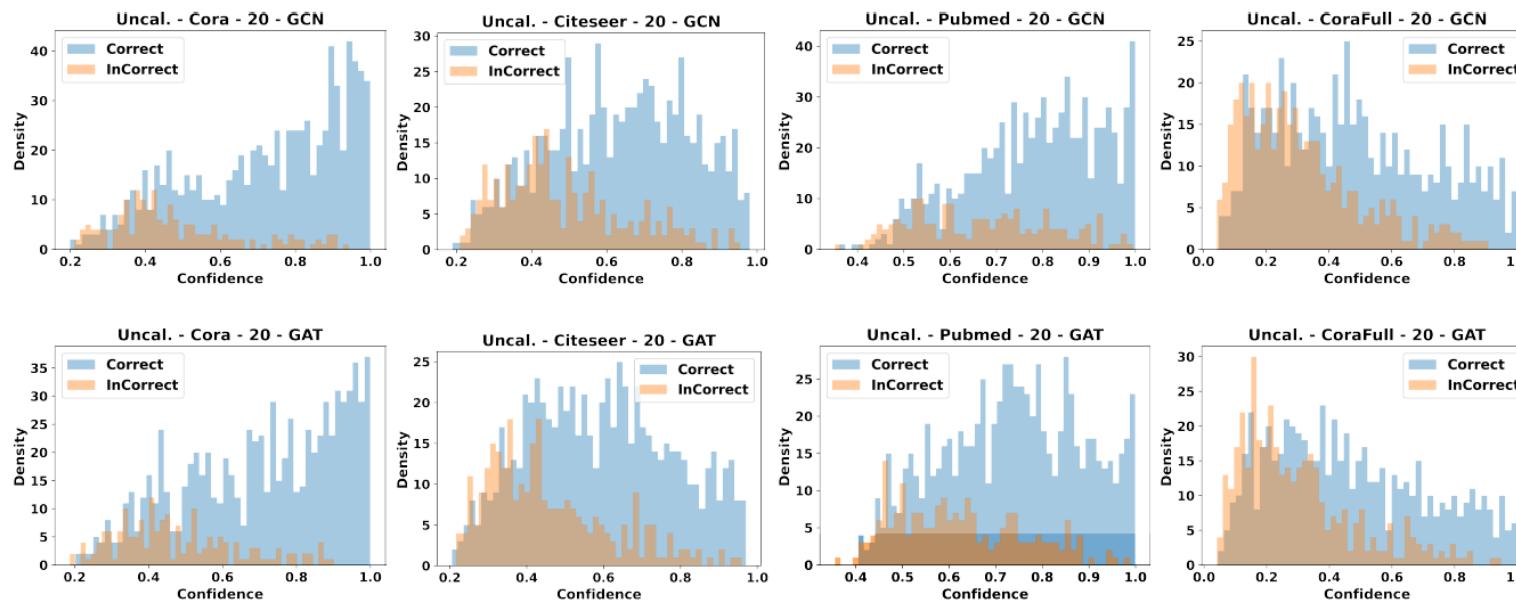
However, in graph data, when a node is **homophilic with its neighbors**, neighbors provide **sufficient information for the prediction of the center node**, leading to a higher confidence. On the other hand, if a node is surrounded by **neighbors with different labels**, we are not sure which community it belongs to, so the confidence of the center node prediction should be lowered. This dependence make conventional methods ineffective.



The ground-truth confidence distribution in a graph is interdependent

# Uncertainty Quantification for Structural Data

Based on confidence distributions of correct and incorrect prediction, we can see GCN tends to be under-confident in correct prediction.



**Phenomenon:** under-confident in correct predictions.

# Uncertainty Quantification for Structural Data

**Work 1:** CaGCN is a post-processed graph convolutional network (GCN) calibration method.

CaGCN is a model trained on a validation set  $D_{val}$  on top of a classification model. Denote the K-class one-hot label for node  $i$  as  $(y_{i,1}, \dots, y_{i,K})$  and prediction probability vector as  $(z_{i,1}, \dots, z_{i,K})$ . CaGCN is trained with two purposes.

- Preserve the prediction accuracy of the classification model by NLL loss.

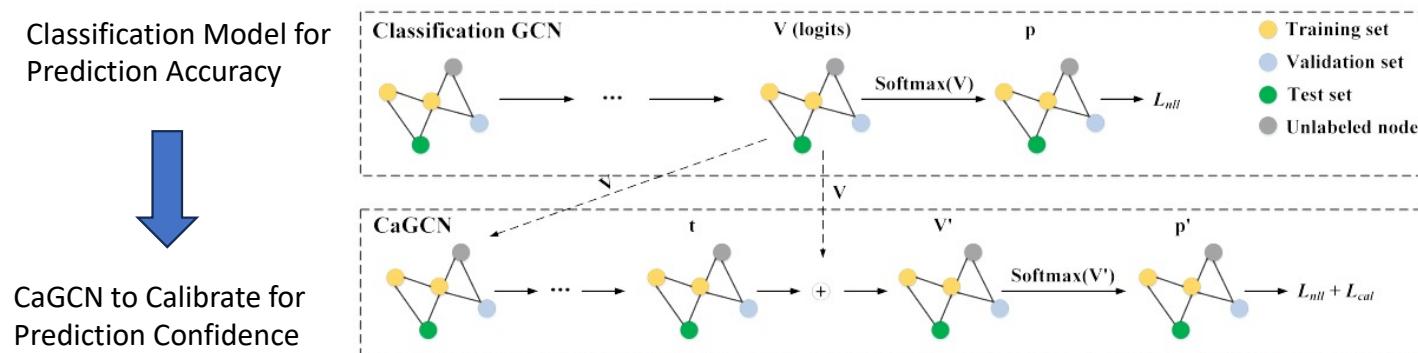
$$\mathcal{L}_{nll} = - \sum_{i=1}^{|D_{val}|} \sum_{k=1}^K y_{i,k} \log(z_{i,k}).$$

- Increase the confidence of correct prediction and lower the confidence of incorrect prediction.

$$\mathcal{L}_{cal} = \frac{1}{n} \left( \sum_{i=1}^{|cor|} 1 - z_{i,m}^{(cor)} + z_{i,s}^{(cor)} + \sum_{i=1}^{|inc|} z_{i,m}^{(inc)} - z_{i,s}^{(inc)} \right)$$

where  $|cor|$  and  $|inc|$  are the number of nodes correctly and incorrectly predicted, and  $z_{i,m}$  and  $z_{i,s}$  are the max and submax prediction probability. Intuitively, the confidence of incorrect predictions is decreased by reducing the gap between the max and the submax value of prediction probability and vice versa.

# Uncertainty Quantification for Structural Data



To implement CaGCN, given output  $\mathbf{V}$  of a classification GCN, CaGCN learns a temperature  $t_i$  for each node  $i$ .

$$\mathbf{t} = \sigma^+(\mathbf{A}\sigma(\cdots\mathbf{A}\sigma(\mathbf{A}\mathbf{V}\mathbf{W}^{(1)})\mathbf{W}^{(2)}\cdots)\mathbf{W}^{(l)}) = [t_1, \dots, t_N]^T (t_i > 0, \forall i \in \{1, \dots, N\}),$$

Then, CaGCN get a calibrated logit  $\mathbf{v}'_i$  by transforming its original logit  $\mathbf{v}_i$  using  $t_i$ , and finally obtain calibrated confidence  $\hat{p}_i$ .

$$\mathbf{v}'_i = h(\mathbf{v}_i, t_i) = [v_{i,1}/t_i, \dots, v_{i,K}/t_i]^T, \mathbf{z}_i = [\sigma_{SM}(v'_{i,1}), \dots, \sigma_{SM}(v'_{i,K})]^T, \hat{p}_i = \max_k z_{i,k},$$

**Pros:** Topology-aware, Accuracy-preserving.

**Cons:** Requiring sufficient data to train the post-processed GCN model.

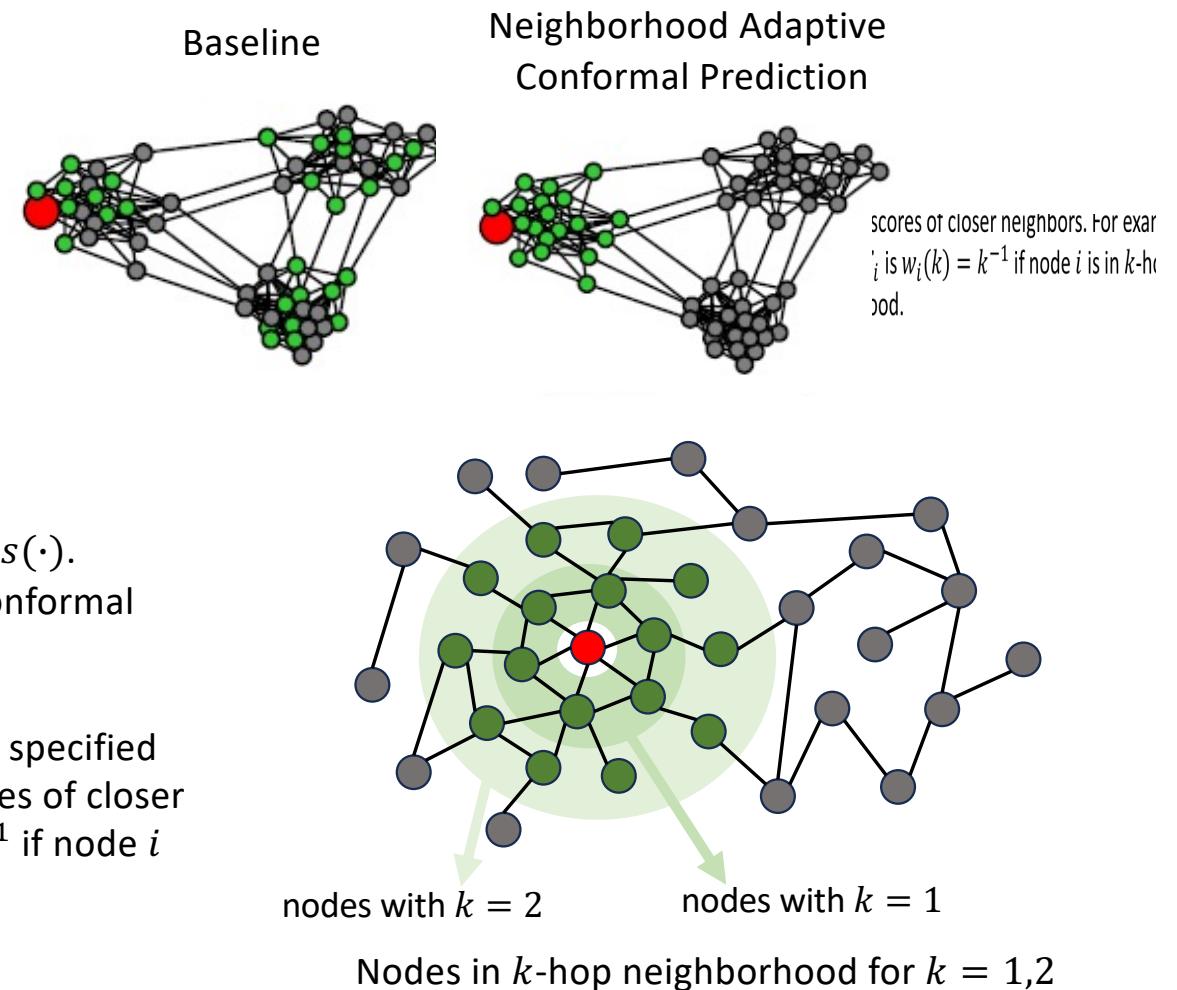
# Uncertainty Quantification for Structural Data

**Work 2:** Homophily: nodes in a neighborhood usually play similar roles in the network and are considered interchangeable on average. Therefore, nodes in a neighborhood better satisfying the exchangeability assumption.

Neighborhood Adaptive Conformal Prediction uses this insight by **taking the nodes surrounding the test node as calibration samples**.

To do so, consider we have a predefined score function  $s(\cdot)$ . Let  $(X_i, Y_i)$  be the feature and label of node  $i$ , whose conformal score is  $S_i = s(X_i, Y_i)$ .

Given a test node with feature  $X_{test}$ , a scheme includes specified neighbors and assigns higher weights to conformal scores of closer neighbors. For example, the weight of  $S_i$  is  $w_i(k) = k^{-1}$  if node  $i$  is in  $k$ -hop neighborhood.



# Uncertainty Quantification for Structural Data

We may consider including  $n$  nodes within 1-hop and 2-hop neighborhoods as calibration samples.

Assume  $\{S_i\}_{i=1}^n$  is in increasing order and denote  $\bar{w}_i$  is normalized weights of  $w_i$ .

We compute the quantile  $\tau$  by

$$\tau = \inf\{S_q : \sum_{i=1}^q \bar{w}_i \geq 1 - \alpha\}.$$

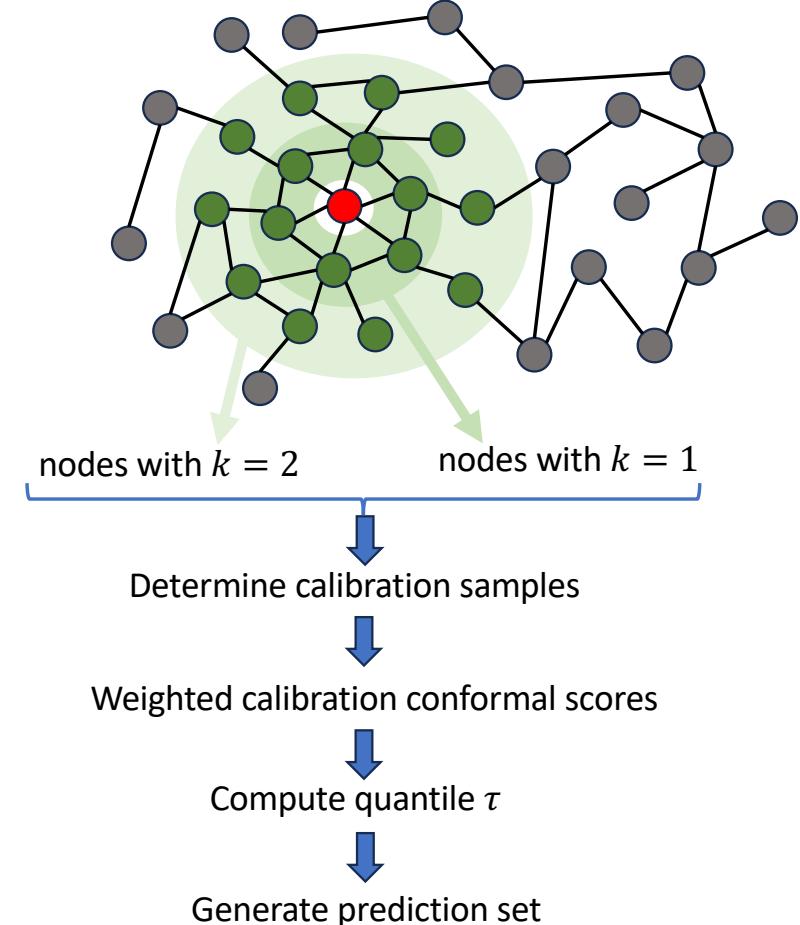
Finally, the prediction set is

$$C(X_{test}) = \{y : s(X_{test}, y) \leq \tau\}.$$

In summary this work takes advantage of homophily to better satisfy the exchangeability assumption and thus make prediction set coverage closer to desired  $1 - \alpha$ .

**Pros:** Topology-aware; Adaptive to different test nodes.

**Cons:** Not directly applicable to both weighted and directed networks;  
Neighborhood size should be well-tuned; Rely on Homophily.

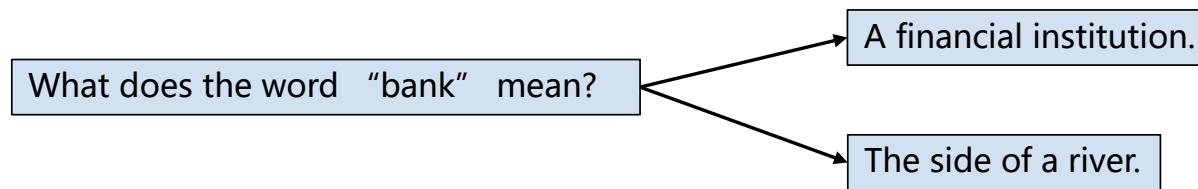


# Uncertainty Quantification for Structural Data

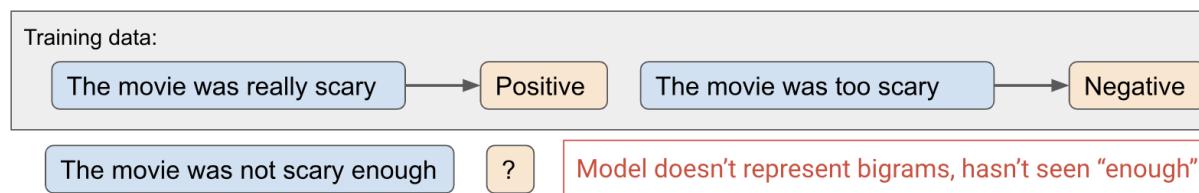
## Uncertainty Quantification for Textual Data

**Challenge:** Aleatoric and epistemic uncertainties are prevalent in textual data.

Aleatoric uncertainty is inherent in the input task data.



Epistemic uncertainty exists due to lack of knowledge.



# Uncertainty Quantification for Structural Data

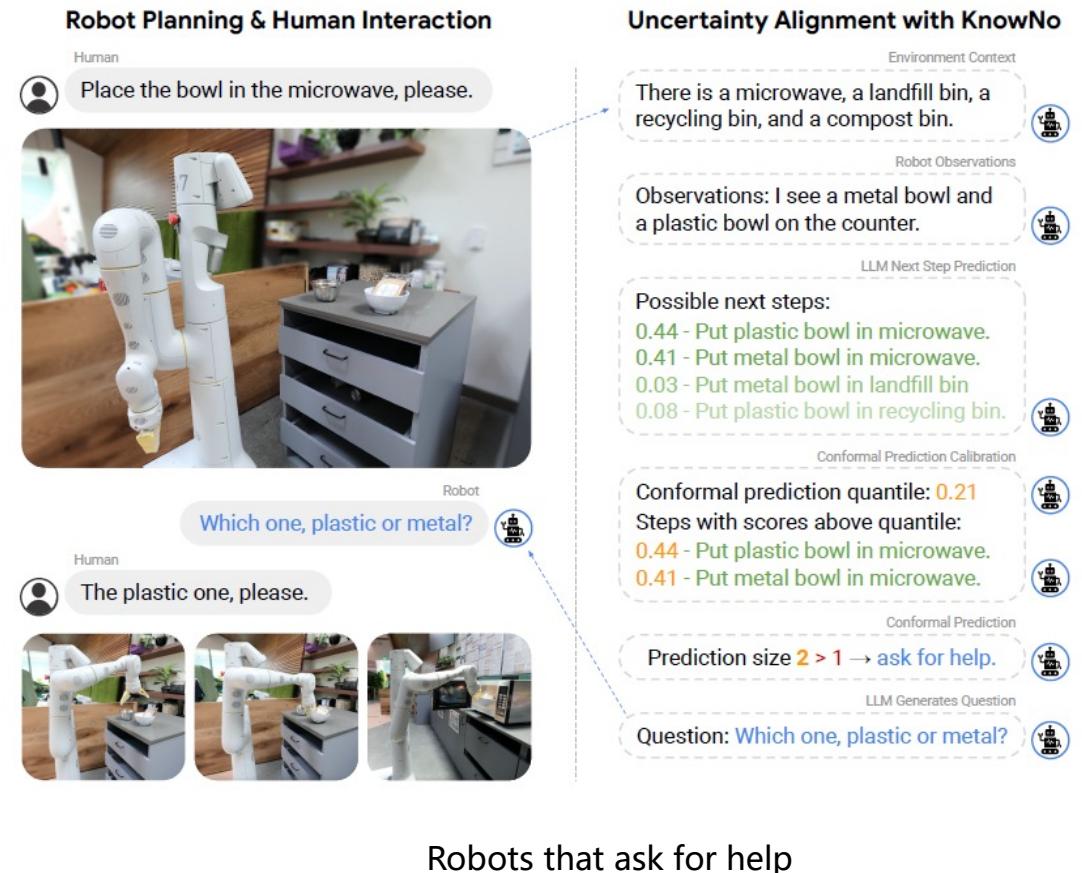
## Uncertainty Quantification for Textual data

**Work:** Large language models (LLM) can generate probabilistic outputs by autoregressive samplings where the model predicts the next word in a sequence based on the probabilities assigned to each word in its vocabulary.

Robots that ask for help is based on conformal prediction. It empowers LLM with visual context information to discern between high confidence in their knowledge and low confidence in what they don't know, enabling them to ask further questions for confirmation.

**Pros:** Addressing uncertainty alignment for language-instructed robots.

**Cons:** Environments must be fully grounded in the text input to the LLM.

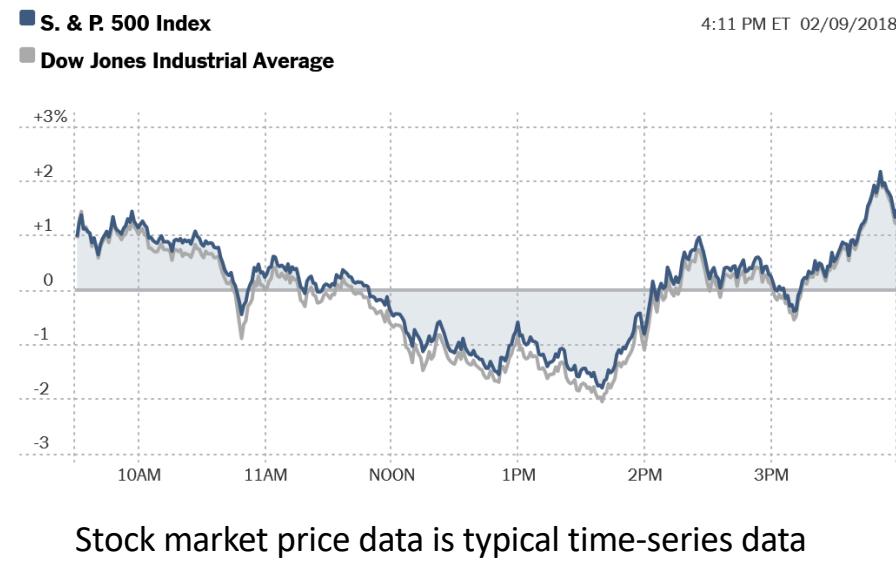


# Uncertainty Quantification for Structural Data

## Uncertainty Quantification for Time-series Data

**Challenge:** Time-series data poses unique challenges in uncertainty quantification due to the **sequential nature**.

For example, **temporal relationships and patterns** in the stock market data can lead to complex dependencies that need to be considered when forecasting prices and estimating uncertainties.



# Uncertainty Quantification for Structural Data

## Uncertainty Quantification for Time-series Data

**Work 1:** The Bayesian Structural Time-series (BSTS) model contains stochastic parameters, introducing uncertainty into its predictions. It decomposes the prediction of  $y_{n+1}$  of  $x_{n+1}, t_{n+1}$  with given training data  $\{(x_i, t_i, y_i)\}_{i=1}^n$  into multiple components.

Trend and seasonal components model the temporal dependencies and capture the sequential structure inherent in time series data.

- Trend component captures the movement in the  $y$  over  $t$ .
- Seasonal component models the repeating patterns by studying  $y$  over  $t'$ , where  $t'$  is the remainder of  $t/7$  for weekly pattern.

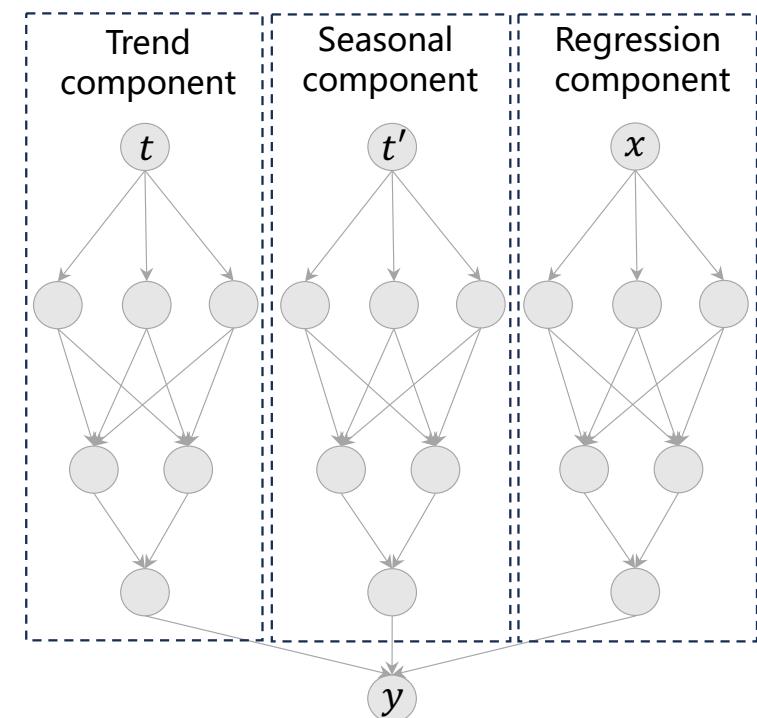
Regression component includes the impact of external variables.

- Regression component relates the feature  $x$  with target  $y$ .

**Pros:** Interpretable results; Disentangling the relation between external variables and time dependency

**Cons:** Require a sufficient amount of data; Choosing appropriate components and priors can be challenging

Bayesian Structural Time-series Model

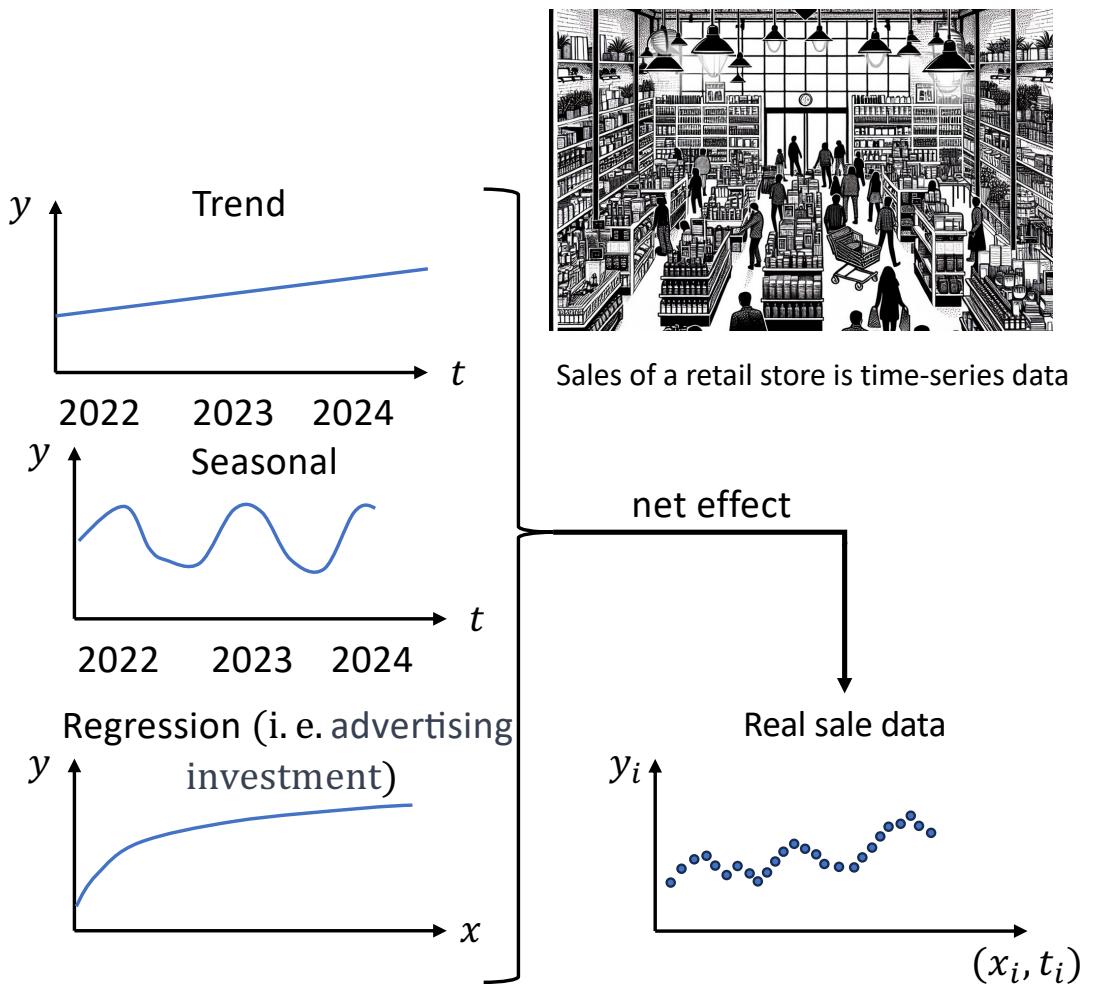


# Uncertainty Quantification for Structural Data

## Uncertainty Quantification for Time-series Data

### Example: Sales of a Retail Store

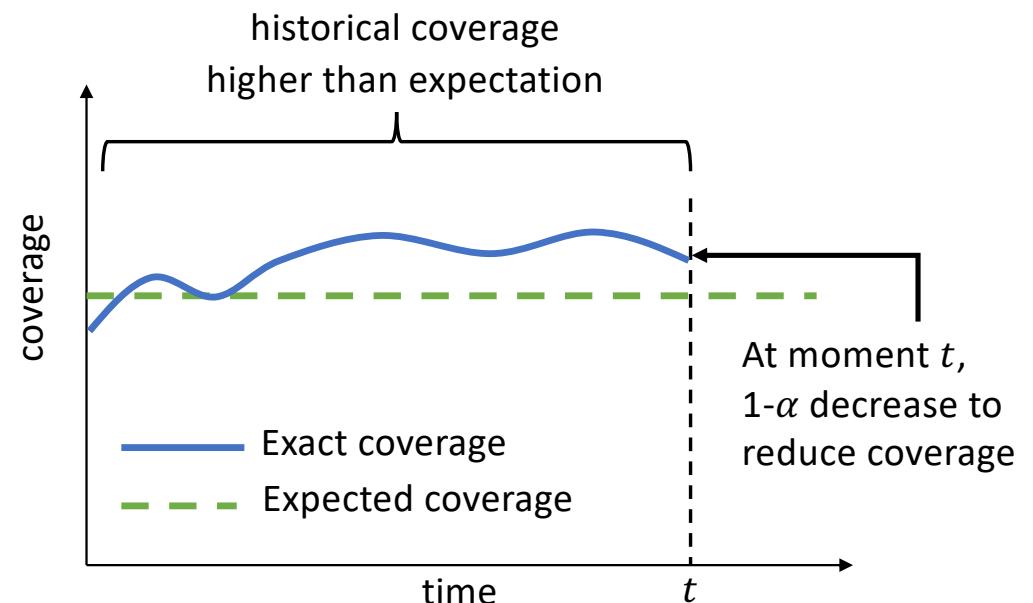
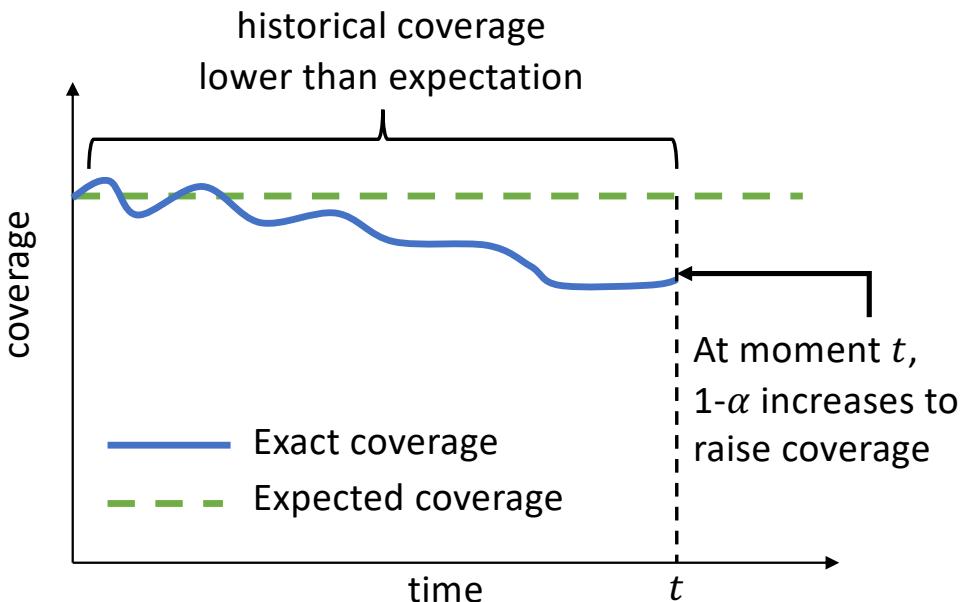
- Trend component: Suppose the store's sales have been steadily increasing by about 5% each year due to factors like improved marketing and increased customer base.
- Seasonal component: Sales might peak during the holiday season (November and December). This seasonal pattern could be modeled to account for these predictable variations in sales.
- Regression component: If an advertising campaign is launched in March, the model can assess its impact on sales during that month.



# Uncertainty Quantification for Structural Data

## Uncertainty Quantification for Time-series Data

**Work 2:** Time-series data breaks the exchangeability assumption of conformal prediction. We can dynamically adjust the parameter  $\alpha$  based on the historical coverage of prediction sets. This approach ensures that prediction sets remain robust to distribution shifts over time.



**Pros:** adaptive to dynamic distribution shift.

**Cons:** Lack of theoretical coverage guarantee.

# Conclusion

In conclusion, uncertainty in machine learning can be quantified by various methods, particularly in structural data. It is crucial for making informed decisions and understanding the reliability of predictions. By incorporating uncertainty quantification techniques, practitioners can gain valuable insights into the robustness of their models, identify potential risks, and make more confident and reliable predictions.

```
graph LR; A[In conclusion, uncertainty in machine learning can be quantified by various methods, particularly in structural data. It is crucial for making informed decisions and understanding the reliability of predictions. By incorporating uncertainty quantification techniques, practitioners can gain valuable insights into the robustness of their models, identify potential risks, and make more confident and reliable predictions.] --> B[Aleatoric uncertainty]; A --> C[Epistemic uncertainty]
```

Aleatoric uncertainty

Epistemic uncertainty

```
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```

Bayesian Approaches

Conformal Prediction

Calibration

```
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```

Graph Data

Textual Data

Time-series Data

**Thank you**



**HKUST (GZ)**