

Machine Learning

# Problem motivation

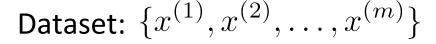
#### **Anomaly detection example**

Aircraft engine features:

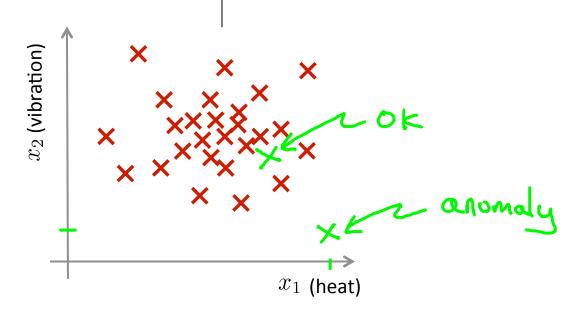
 $\rightarrow x_1$  = heat generated

 $\Rightarrow x_2$  = vibration intensity

...

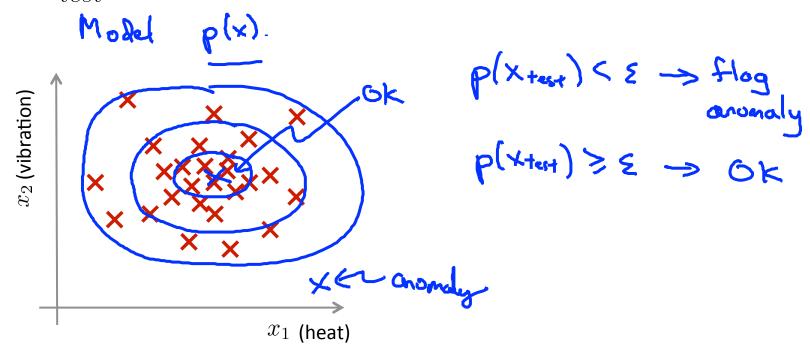


New engine:  $x_{test}$ 



#### **Density estimation**

- $\rightarrow$  Dataset:  $\{x^{(1)}, x^{(2)}, \dots, x^{(m)}\}$
- $\rightarrow$  Is  $x_{test}$  anomalous?



#### **Anomaly detection example**

- → Fraud detection:
  - $\rightarrow x^{(i)}$  = features of user *i* 's activities
  - $\rightarrow$  Model p(x) from data.
  - ightharpoonup Identify unusual users by checking which have  $p(x) < \varepsilon$

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X4

p(x)

- → Manufacturing
- Monitoring computers in a data center.
  - $\rightarrow x^{(i)}$  = features of machine i
    - $x_1$  = memory use,  $x_2$  = number of disk accesses/sec,
    - $x_3$  = CPU load,  $x_4$  = CPU load/network traffic.

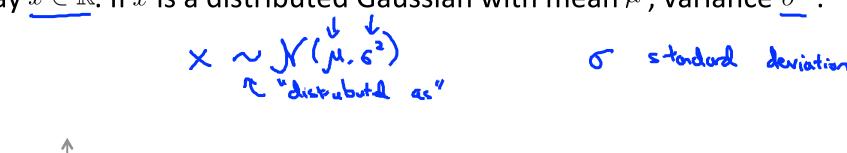


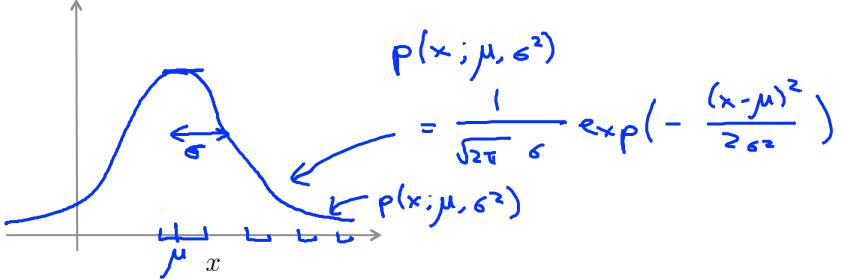
Machine Learning

# Gaussian distribution

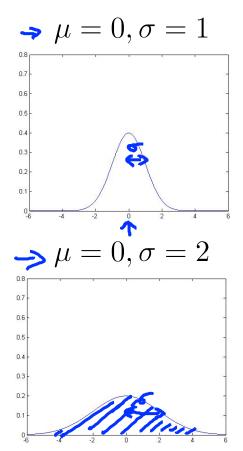
#### Gaussian (Normal) distribution

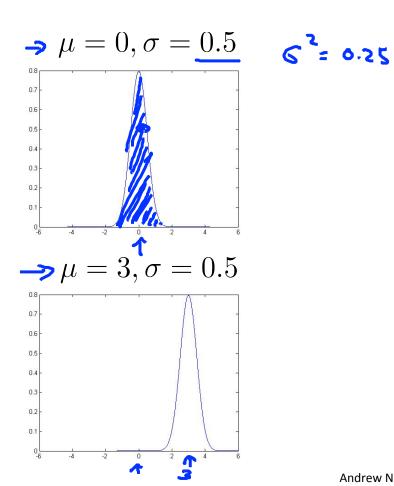
Say  $x \in \mathbb{R}$ . If x is a distributed Gaussian with mean  $\mu$ , variance  $\sigma^2$ .

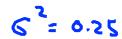




#### **Gaussian distribution example**

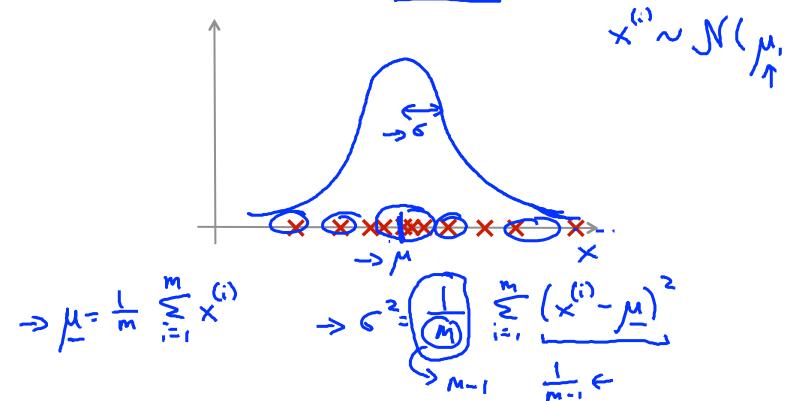






#### **Parameter estimation**

o Dataset:  $\{x^{(1)}, x^{(2)}, \dots, x^{(m)}\}$   $\underline{x^{(i)}} \in \mathbb{R}$ 





#### Machine Learning

# Anomaly detection

# Algorithm

### Density estimation

 $\rightarrow$  Training set:  $\{x^{(1)}, \dots, x^{(m)}\}$ Each example is  $x \in \mathbb{R}^n$ 

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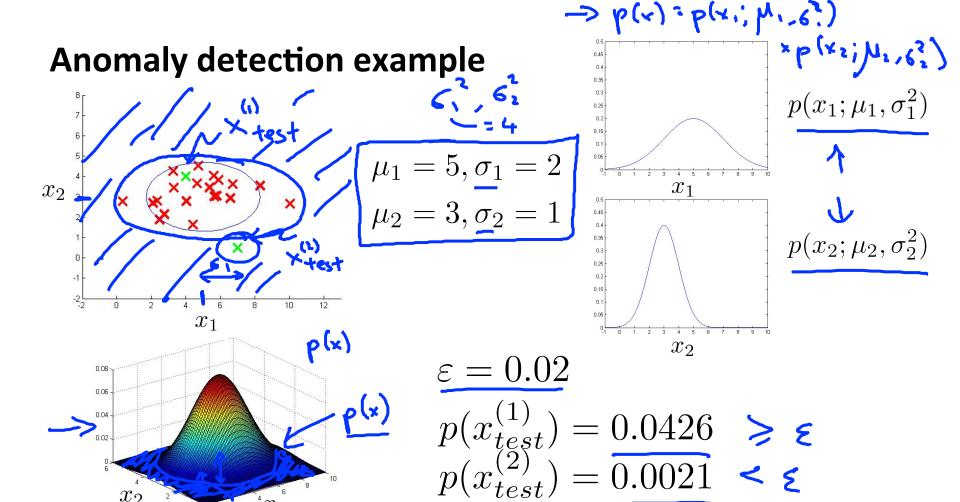
#### **Anomaly detection algorithm**

- $\rightarrow$  1. Choose features  $x_i$  that you think might be indicative of anomalous examples. {x(1) ... x(\*)]
- $\rightarrow$  2. Fit parameters  $\mu_1, \ldots, \mu_n, \sigma_1^2, \ldots, \sigma_n^2$

 $\rightarrow$  3. Given new example x, compute  $\underline{p}(x)$ :

$$p(x) = \prod_{j=1}^{n} p(x_j; \mu_j, \sigma_j^2) = \prod_{j=1}^{n} \frac{1}{\sqrt{2\pi}\sigma_j} \exp\left(-\frac{(x_j - \mu_j)^2}{2\sigma_j^2}\right)$$

Anomaly if  $p(x) < \varepsilon$ 





Machine Learning

Developing and evaluating an anomaly detection system

#### The importance of real-number evaluation

When developing a learning algorithm (choosing features, etc.), making decisions is much easier if we have a way of evaluating our learning algorithm.

- -> Assume we have some labeled data, of anomalous and nonanomalous examples. (y = 0 if normal, y = 1 if anomalous).
- $\rightarrow$  Training set:  $x^{(1)}, x^{(2)}, \dots, x^{(m)}$  (assume normal examples/not anomalous)



#### Aircraft engines motivating example

- → 10000 good (normal) engines
- flawed engines (anomalous) 2-50
- Training set: 6000 good engines (y=0)  $p(x)=p(x,\mu,\epsilon^2,\dots,\mu_n,\epsilon^2)$ CV: 2000 good engines (y=0), 10 anomalous (y=1) Test: 2000 good engines (y=0), 10 anomalous (y=1)

#### Alternative:

Training set: 6000 good engines

- ightharpoonup CV: 4000 good engines (y=0), 10 anomalous (y=1)
- $\rightarrow$  Test: 4000 good engines (y=0) 10 anomalous (y=1)

#### **Algorithm evaluation**

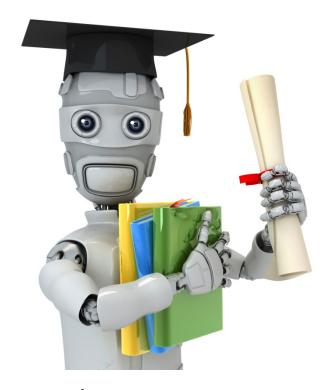
- $\rightarrow$  Fit model  $\underline{p(x)}$  on training set  $\{x^{(1)},\ldots,x^{(m)}\}$
- $\rightarrow$  On a cross validation/test example x , predict

$$y = \begin{cases} \frac{1}{0} & \text{if } p(x) < \varepsilon \text{ (anomaly)} \\ \hline 0 & \text{if } p(x) \ge \varepsilon \text{ (normal)} \end{cases} \qquad \mathbf{y} = \mathbf{0}$$

Possible evaluation metrics:

- -> True positive, false positive, false negative, true negative
- Precision/Recall
- → F<sub>1</sub>-score <</p>

Can also use cross validation set to choose parameter  $\varepsilon$ 



Machine Learning

Anomaly detection vs. supervised learning

- > Very small number of positive examples (y = 1). (0-20 is common).
- $\rightarrow$  Large number of negative (y=0) examples.
- Many different "types" of anomalies. Hard for any algorithm to learn from positive examples what the anomalies look like;
- → future anomalies may look nothing like any of the anomalous examples we've seen so far.

#### vs. Supervised learning

Large number of positive and negative examples.

Enough positive examples for algorithm to get a sense of what positive examples are like, future positive examples likely to be similar to ones in training set.

VS.

#### **Supervised learning**

Fraud detection

Email spam classification

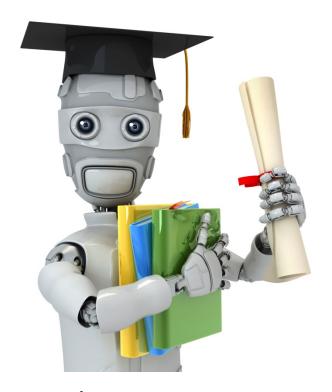
Manufacturing (e.g. aircraft engines)

Weather prediction (su<del>≤n</del>y/ rainy/etc).

Monitoring machines in a data center

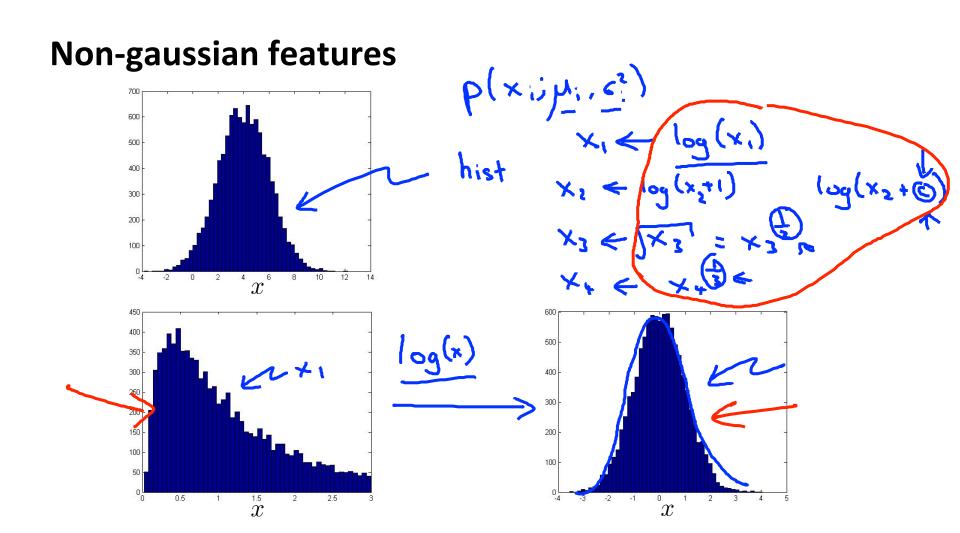
Cancer classification





Machine Learning

Choosing what features to use

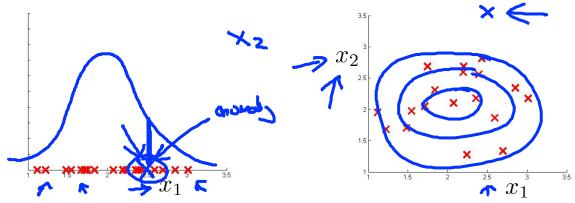


### Error analysis for anomaly detection

Want p(x) large for normal examples x. p(x) small for anomalous examples x.

### Most common problem:

p(x) is comparable (say, both large) for normal and anomalous examples



### Monitoring computers in a data center

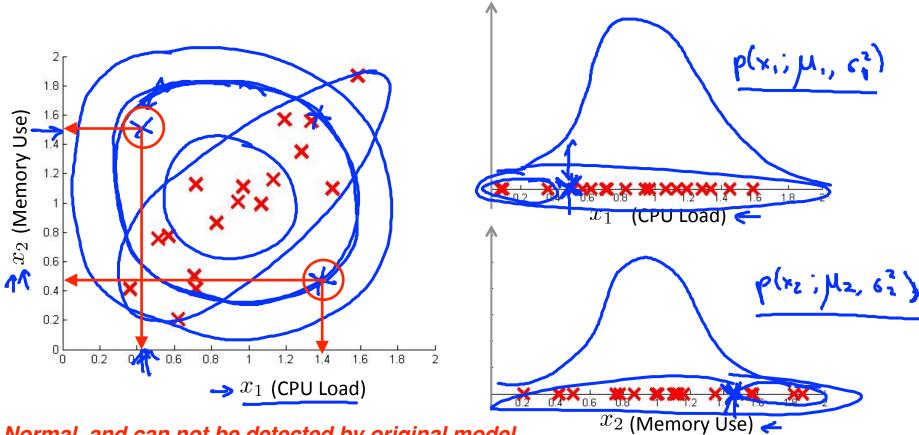
- Choose features that might take on unusually large or small values in the event of an anomaly.
  - $\rightarrow$   $x_1$  = memory use of computer
    - $\rightarrow x_2$  = number of disk accesses/sec
  - $\rightarrow x_3 = CPU load <$
  - $\rightarrow x_4$  = network traffic  $\leftarrow$



Machine Learning

Multivariate
Gaussian distribution

#### Motivating example: Monitoring machines in a data center



Normal, and can not be detected by original model

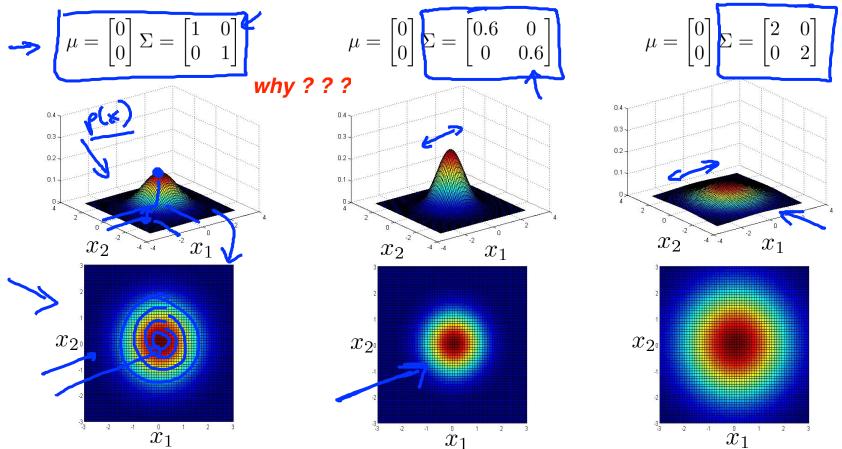
### **Multivariate Gaussian (Normal) distribution**

 $x \in \mathbb{R}^n$ . Don't model  $p(x_1), p(x_2), \ldots$ , etc. separately. Model p(x) all in one go.

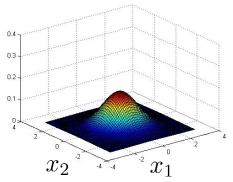
Parameters: $\mu \in \mathbb{R}^n, \Sigma \in \mathbb{R}^{n \times n}$  (covariance matrix)

$$P(x;\mu,\Xi) = \frac{1}{(2\pi)^{n/2}(15)^{3}} \exp(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu))$$

$$|\Sigma| = \det(Signa)$$

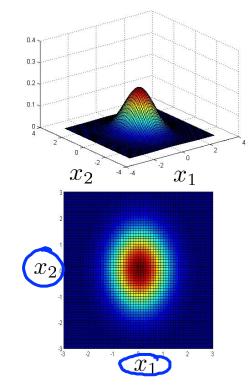


$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

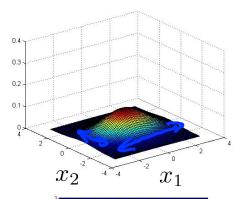


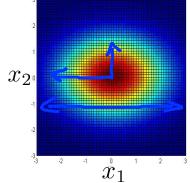
$$x_2$$

$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 0.6 & 0 \\ 0 & 1 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

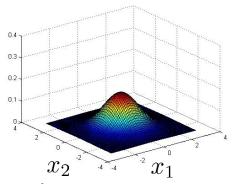


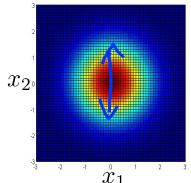
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$



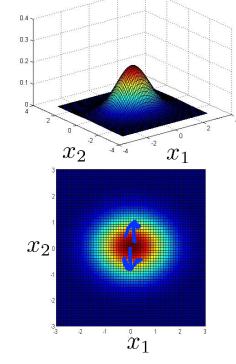


$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

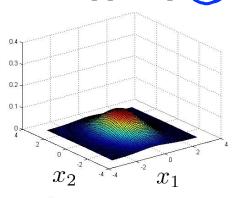


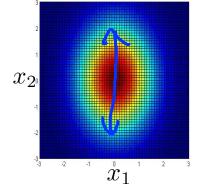


$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 0.6 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

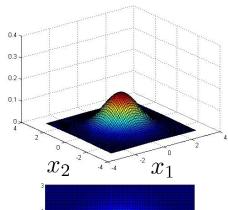


$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$



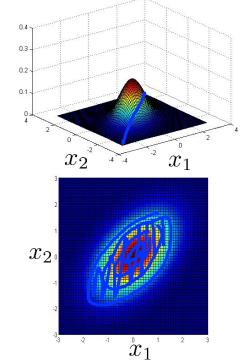


$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

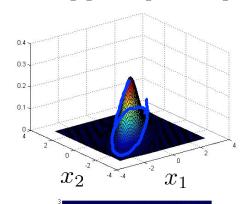


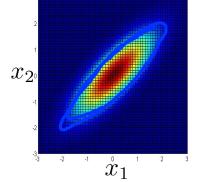
$$x_2$$

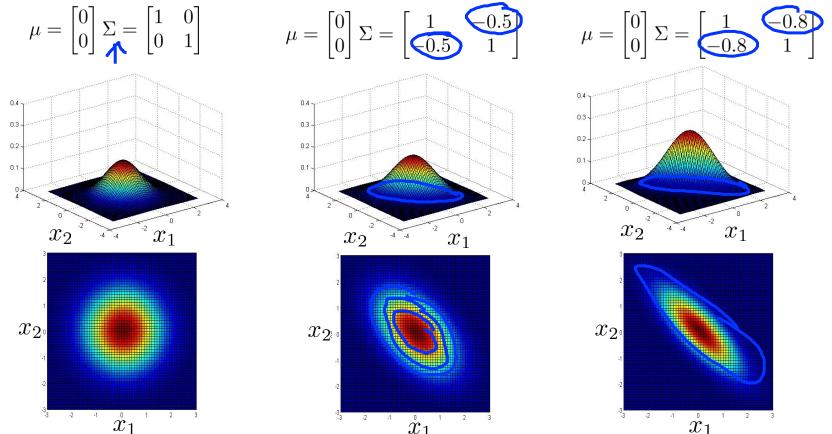
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix} \qquad \qquad \mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$



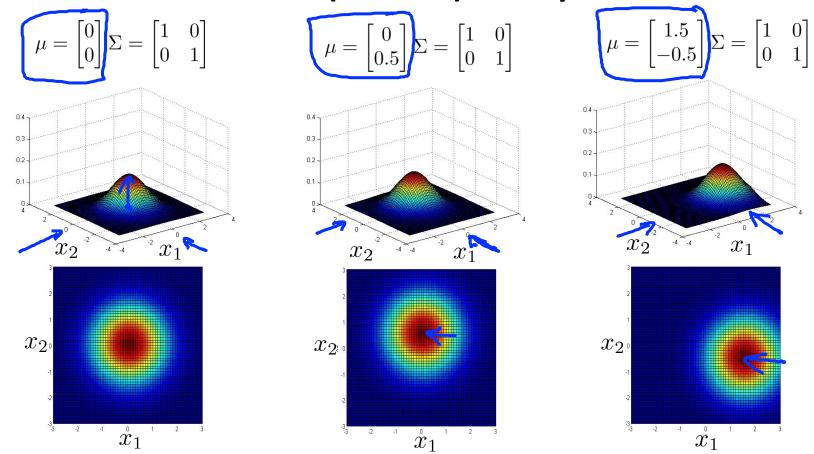
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Sigma = \begin{bmatrix} 1 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$







Andrew Ng





Machine Learning

Anomaly detection using the multivariate
Gaussian distribution

#### **Multivariate Gaussian (Normal) distribution**

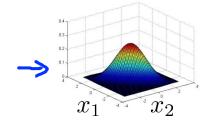
Parameters  $\mu, \Sigma$ 

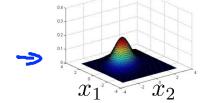


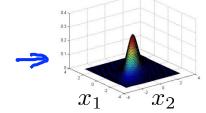


co-variance matrix

$$p(x;\mu,\Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)\right)$$







Parameter fitting:

Given training set 
$$\{x^{(1)}, x^{(2)}, \dots, x^{(m)}\}$$
  $\leftarrow$ 

$$= \frac{1}{m} \sum_{i=1}^{m} x^{(i)} = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu)(x^{(i)} - \mu)^{T}$$

#### Anomaly detection with the multivariate Gaussian

1. Fit model 
$$p(x)$$
 by setting 
$$\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)}$$
 
$$\Sigma = \frac{1}{m} \sum_{i=1}^{m} (x^{(i)} - \mu)(x^{(i)} - \mu)^T$$

X1 (CPU Load)

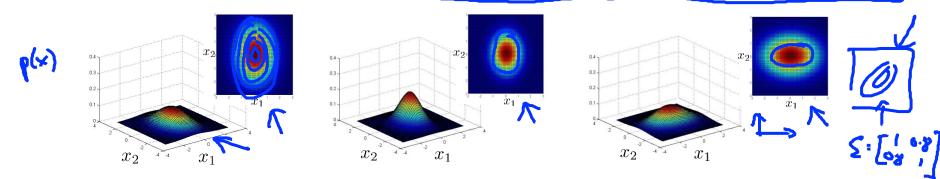
2. Given a new example x, compute

$$p(x) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$

Flag an anomaly if  $p(x) < \varepsilon$ 

#### Relationship to original model

Original model: 
$$p(x) = p(x_1; \mu_1(\sigma_1^2) \times p(x_2; \mu_2, \sigma_2^2) \times \cdots \times p(x_n; \mu_n, \sigma_n^2)$$



Corresponds to multivariate Gaussian

$$\Rightarrow p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)\right)$$

where



#### Original model

$$p(x_1; \mu_1, \sigma_1^2) \times \cdots \times p(x_n; \mu_n, \sigma_n^2)$$

Manually create features to capture anomalies where  $x_1, x_2$  take unusual combinations of values.

Computationally cheaper (alternatively, scales better to lærge n=10,000, n=100,000)
OK even if m (training set size) is

small

#### vs. Multivariate Gaussian

$$p(x; \mu, \Sigma) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x-\mu)^{T} \Sigma^{-1}(x-\mu)\right)$$

Automatically captures
 correlations between features

Computationally more expensive



Must have m > n or else  $\Sigma$  is non-invertible.

Andrew Ng