Wenyuan Chen

Contact Department of ECE (647)877-0437Information University of Toronto chenwy.chen@mail.utoronto.ca 1101 Bay Street, #2503 Toronto, ON CANADA Computer vision, robotics, automation, image processing and deep learning, structured Research Interests **EDUCATION** Graduate, University of Toronto MASc. in Electrical & Computer Engineering (expected Sep 2020) • Dissertation Topic: Highly reflective surface metrology with single-exposure images enhanced by convolutional neural network • GPA:3.86 Undergraduate, Huazhong university of science and technology BA. in Computer Science, Sep 2018 • Dissertation Topic: Development of deep-learning based glass surface defect detection system • GPA:3.78 • TOEFL:110(1:29,s:24,w:27,:r:30) (two years ago, may need to retake the test) GRE:323(V:155,Q:168)+4 X. Liu¹, W. Chen¹, H. Madhusudanan, J. Ge, C. Ru and Y. Sun, "Optical Measure-**PUBLICATIONS** ment of Highly Reflective Surfaces from a Single Exposure," in IEEE Transactions on Industrial Informatics, doi: 10.1109/TII.2020.2991458. (co-first author and accepted) H. Madhusudanan¹, X. Liu¹, W. Chen, D. Li, L. Du, J.Li, J.Ge and Y. Sun, "Automated Eye-In-Hand Robot-3D Scanner Calibration for Low Stitching Errors" in 2020 IEEE international conference on robotics and automation(ICRA). (second author) Teaching Winter 2020 Teaching Assistant, Computer Fundamentals EXPERIENCE GRADUATE ☐ Foundations of Computer Vision ☐ Digital Image Processing and Applications Coursework ☐ Introduction to Data Science □ Statistical Learning □ Algorithms and Data Structures Scientific Research EXPERIENCE

2019— Performed research for highly reflective surface metrology with single-exposure images enhanced by convolutional neural network. In this work, a new semantic segmentation neural network is designed for enhancing single low illuminated images to achieve measurement for highly reflective surface. This research was completed and a joint paper is currently being revised for future submission

to a related journal.

2018–2019 Participated in the development of structure-light based 3D scan-

ner system, and responsible for calibration, ellipse detection, point cloud reconstruction parts. This project was collaborated with the KIRCHHOFF automotive company and the scanner will be used

in industrial plant.

2017–2018 Developing a deep-learning based glass surface defect detection sys-

tem which first use morphology processing and connected domain analysis to locate the defect, and use the lightweight CNN, Glass-

Net to classify the defects.

2017 Calibrated the two-laser system by programming to acquire data

from the laser and built a 3D display scene based on OpenGL.

Relevant Skills Programming Languages: C, C++, Python, Matlab Script

Development Tools: Matlab, Visual Studio, Jupyter Notebook

Deep-learning Tools: Tensorflow, Caffe, Pytorch