

CS230 course note

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Contents

1	Week 1	3
1.1	Number Representation	3
2	Week 2	4
2.1	Boolean Algebra and circuits	4
2.2	Binary Arithmetic and Two's Complement	6
3	Week 3	7
3.1	Floating Point Introduction	7
3.2	Floating Point continue	8
4	week 4	9
4.1	Endianness and Characters	9
4.2	Assembly Language Intro	10
5	Week 5	11
5.1	Conditional Execution	11
5.2	Emeory and Input/Output	11
6	Machine Internals	12
6.1	Basic control	12
6.2	pipelining	14
6.3	Memory hierarchy	16
7	Build and Execute	17
8	Concurrency	19

1 Week 1

1.1 Number Representation

1. Base R number

Assume given a n-digit number of base r which

$$x = d_{n-1}d_{n-2} \dots d_1d_0$$

where $d = [0, r - 1]$

$$\text{then } x = \sum_{i=0}^{n-1} d_i r^i$$

2. Common base

Decimal = base 10, Binary = base 2, Hexadecimal = base 16 (0x..... is a way to mark base 16)

3. Decimal \rightarrow Other Base

- Devide by the target base until quocient = 0
- Get the remainder together backward

4. Base 2 \iff Base 16

group digits in group of 4

2 Week 2

2.1 Boolean Algebra and circuits

1. different operator

- or = \cup
- and = \cap
- not = \neg
- NAND = $|$
- NOR = a arrow down
- XOR = \oplus = exactly one
- XNOR = a dot in a circle = can't be exactly one

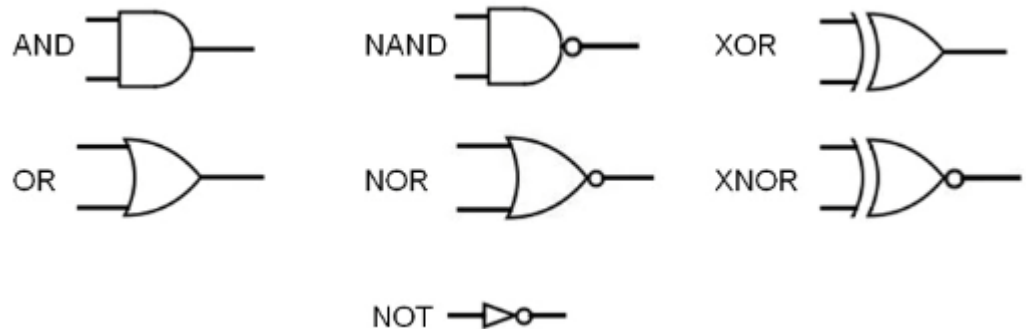
2. Precedence

Not > and = NAND > XOR = XNOR > OR = NOR

3. Algebra Rules

- Identities
 - $A \cup 0 = A$
 - $A \cap 1 = A$
 - $A \cup A = A$
 - $A \cap A = A$
- Involution
 - $\neg\neg A = A$
- Anihilators
 - $A \cup 1 = 1$
 - $A \cap 0 = 0$
- Complements
 - $A \cup \neg A = 1$
 - $A \cap \neg A = 0$
- Commutative Law
 - $A \cup B = B \cup A$
 - $A \cap B = B \cap A$
- Associative Law
 - $A \cup (B \cap C) = (A \cup B) \cap C$
 - $A \cap (B \cup C) = (A \cap B) \cup C$
- Distributive Law
 - $A \cap (B \cup C) = A \cap B \cup A \cap C$
 - $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$
- De Morgan's Law
 - $\neg(A \cup B) = \neg A \cap \neg B$
 - $\neg(A \cap B) = \neg A \cup \neg B$

4. Digital Circuits



2.2 Binary Arithmetic and Two's Complement

1. Addition and multiplication
just like normal stuff
2. Signed Magnitude
MSB is sign
3. One complement
Negative numbers are inverted positive numbers
4. Two's complement
Negative numbers are inverted (each digit)positive number and add 1

3 Week 3

3.1 Floating Point Introduction

1. Formal fraction method: multiply fraction part by 2
determin the number before the decimal place
2. From binary to decimal
just do negative exponents
3. Meaning of Point
 - Radix Point
Decimal point for base-10
Binary point for base -2
 - Floating point
explicit exponents \rightarrow radix point can move
more flexible than fixed point
wider range, variable precision
 - Fixed-point
fixed number of digits before and after radix point
less flexible, less range, but faster, more precision
Can use integer arithmetic operations
4. Floating point
 $(-1)^S * 1.F * 2^{E-B}$
 - 1 - integer
 - 2 - base
 - S - sign
 - F - fraction
 - E - exponent
 - B - bias
 - 1.F - significand or mantissa
5. Example:
bit 0..3 fraction, bit 4..6 exponent bit 7 : sign, bias is 3

3.2 Floating Point continue

1. Normalized Representation Problem
 - 1.F with a leading one before decimal
 - $(-1)^S * (1 + F) * 2^{E-B}$
2. Subnormal Representation
 - $(-1)^S * (0 + F) * 2^{1-B}$
 - If E is all zero, use subnormal
 - if 2^e have $e < 1 - B$ must be subnormal
3. Special Cases
 - Overflow:
 - E too large \rightarrow represent as $+/- \infty$
 - also for division by zero
 - Invalid result: NAN:
 - $0/0$ or $\sqrt{-1}$
 - Both can be proagate
4. Special case formula

Exponent	Fraction	Case
00000	0000	0
00000	non-zero	subnormal
11111	00000	infinity
11111	non-zero	Nan
anything	anything	normal

5. Arithmetic
 - Addition
 - align radix points
 - use normal addition
 - Multiplication
 - add exponents
 - mutiply siginificnads

4 week 4

4.1 Endianness and Characters

1. Byte = 8 bits
two's complement range $[-128, 127]$
unsigned $[0, 255]$
two hex digits
2. word = 32 or 64 bits
Individual bytes still accessible
the order are in
 - Little-endian: least-significant first
same number in memory regardless of length
can start math right away
 - Big-endian: most-significant first (in cs230)
natural way of writing

Converge it

- converge to bit first
 - revert the bytes order
3. Characters
ASCII characters - American Standard Code from hex to char
Unicode - over 100000 code points
 - U+0000 - for unicode charactering mapping
 - UTF-8 - unicode transformation format
1-4 bytes
1 byte for ASCII
 4. Bits have no inherent meaning
must state the meaning at the beginning
 5. UTF-8 converging
Check the leading of a byte
 - start with 0 → single byte character, ASCII character
 - start with 10 → continue byte
 - start with 110 → leading byte, show number of continue byte

4.2 Assembly Language Intro

1. Machine Code
Binary - 0s and 1 s
Direction execution by processor
2. Assembly Language
Human-readable "programing language"
Almost direct mapping to machine code
3. MIPS architecutre
Microprocessor without Interlocked Pipeline Stages
simplified version in CS230
4. Assembly
takes 32 bits = 4 bytes = 1 word
32 registers available
\$0 = 0
up to 3 register can be used
1st destination, 2nd, 3rd are sources
5. Immediate Addition
addi\$t, \$s, i
is just $\$t = \$s + i$
often use to initialize *addi\$t, \$0, i*
6. + and -
add\$d, \$s, \$t
is $\$d = \$s + \$t$
sub\$d, \$s, \$t
is $\$d = \$s - \$t$
7. * and /
mult\$s, \$t
lo = s*t
div\$s, \$t
lo is quotient, remainder in hi
mghi\$d get stuff from hi
mflo\$d get stuff from lo

5 Week 5

5.1 Conditional Execution

1. *beq \$s, \$t, i*
compare s and t, if equal, skip i instructions
2. *bne \$s, \$t, i*
compare s and t, if not equal, skip i instructions

5.2 Memory and Input/Output

1. *lw \$t, i(\$s)*
let t = content in address in s+i
2. *sw \$t, i(\$s)*
put content in t into s+i address
3. input/output
0xFFFF0004 = input, 0xFFFF000C = output

6 Machine Internals

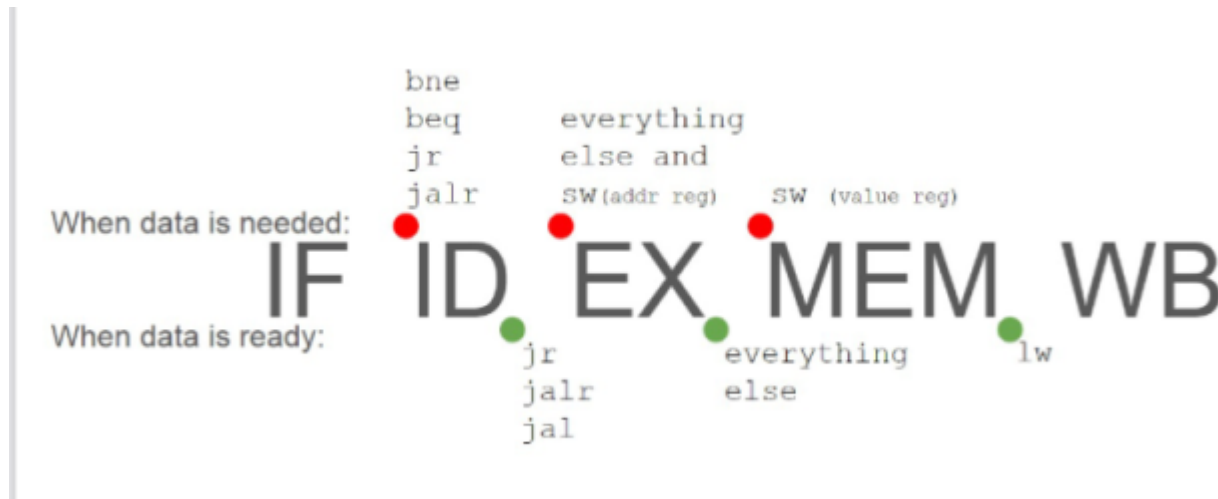
6.1 Basic control

1. Clock cycle
beat of computer
2. Cycle Execution
 - One Instruction per clock cycle
fixed cycle length must cover slowest instruction
which will slow down the speed
 - One instruction - multiple clock cycles
each instruction is divided into subtasks
some instructions take fewer cycles than others
ex. lw take 5, add takes 4
3. Typical Instruction cycle
 - IF: instruction fetch
load 32-bit instruction from address in PC, pass it to ID
Increment PC by 4
 - ID: instruction decode
decode instruction
 - EX: execute
run the instruction
 - MEM: memory access
access memory
 - WB: write back
write results back to registers
4. Performance
 - elapsed time
total response time
 - CPU time
time spent processing instruction
5. Clock period
SI units of time in seconds per clock cycle
 $10^9 * 10^{-12}s = 10^9ps = 10^6ns = 10^3\mu s = ms = 10^{-3}$
6. Clock frequency
cycle per second: Hertz(Hz)
 $10^{12} = THz = 10^3Ghz = 10^6MHz = 10^9Khz = 10^9 * 10^3$
250ps = 4GHz

7. CPI
= clock cycles / instruction
8. CPU time
- Instruction count \times CPI \times Cycle time

6.2 pipelining

1. Speed up
 - if all stages are balanced
 - time between instruction(pipelined) = time between instructions (no pipelined) / number of stages
 - if not balanced, speed up less
2. Pipeline diagram
 - show what MIPS is doing for each clock cycles
3. Hazards
 - Structural: Combination of instruction types
Resource is busy
 - Data: dependency between instruction
need to wait for data read/write
always 2 bubble
 - Control: dependency between instruction
control depends on previous instruction
always 1 bubble
4. Forwarding
 - allowed to use resource most efficiently



Branch will be ready after ID

5. Branch prediction
 - Static branch prediction
forward not taken, backward taken

- Dynamic branch prediction
Depends on the result of last same branch (first one like static branch prediction)

6.3 Memory hierarchy

1. Terms
 - hit: data found in cache
 - miss: data not found, get it in main memory
 - hit time: cost of direct fetch
 - miss penalty: cost of get from main
 - byte-addressable: each byte have it's own address
 - evict: the content in cache got kicked
2. Direct-mapped cache
Assume M block of cache with size B
request address p
map to cache $c = (p/B) \bmod M$
3. Fully associative caches
4. 2-way associative
Combine 2 cache, allowed more space in each
i.e. have 00, 01, 10, 11 for direct, but 2 wayassociiative will combine by 2,
remain 0 (contain 00, 10), 1(contain 01, 11)
5. full associative
combine all together, size = B
6. CPI calculation
- Instruction cache miss rate * miss penalty + Base CPI + % of memory
access of instruction * data cache miss eate * miss penalty
7. Average memoty access time
= hit time + miss rate * miss penalty

7 Build and Execute

1. Deterministic Finite Automata(DFA)
 - Have exactly one start state
 - Have at least one final state
 - Finite set of input alphabet
 - One transition per alphabet per state
2. Non-deterministic finite automata (NFA)
 - Can have many transition per alphabet per state
 - can have ϵ symbol, go to new state without consuming input
 - all DFA is NFA
 - can always get DFA from NFA
3. Regular expression
 - $R|S$ means one of it
 - RS means S after R
 - R^* means $0 - \infty$ number of R
 - a^+ means $1 - \infty$ number of a
 - $a^?$ means $0 - 1$ number of a
 - $.$ represent anything
 - $[a - z]$ means anything between them
4. UNIX tools
 - egrep: search regular expression in text files
 - sed: stream editor for transforming text files
 - awk: pattern scanning and processing language
 - make: software building utility
5. Scanner
convert input string to tokens, use regular languages
6. Specification Components
Terminal/token: atomic symbol
no-terminal/variable: abstract component
 - does not literally appear in input
 - designated start symbol
 - notation: angle brackets

Rules: go from one variable to another

ϵ : empty, can be a terminal

7. Derivation

application of rules to generate valid input string

replace one variable by one rule

continue until everything is token

8. Context-free grammar

- formalism to specify languages
- context-free: no overlap between blocks

9. Leftmost Derivation

always start from the leftmost non-terminal

10. Parse trees (derivation trees)

non-terminal are internal nodes

terminals are leaf nodes

11. Associativity and precedence

order of evaluating expression:

associativity: grouping equivalent operations

precedence: grouping non-equivalent symbols

12. Tools

- lex: scanner generator
define regular expression rules
generates scanner
- yaccL parser generator
define context-free grammar
generates parser

13. Assembler

convert one line instruction to one line machine code

14. Linking

- Goal: combine multiple object files
avoid compiling whole program each time
- resolve external symbols
- produce executable file

8 Concurrency

1. Deadlocks
if 2 threads contain a lock that each other wants, and they are waiting
each other, they will wait forever
which is deadlock