ENM 531: Data-driven Modeling and Probabilistic Scientific Computing

Lecture #3: Primer on Probability and Statistics

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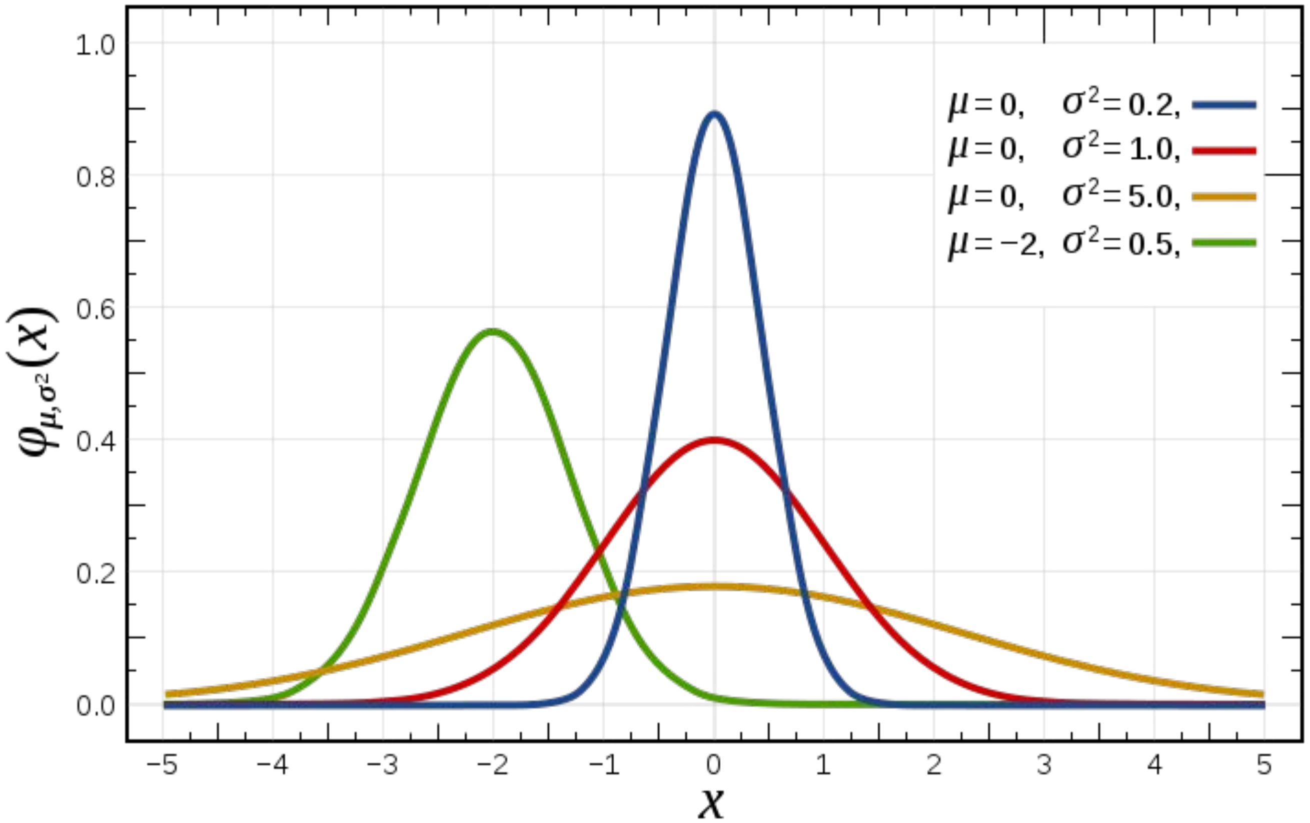
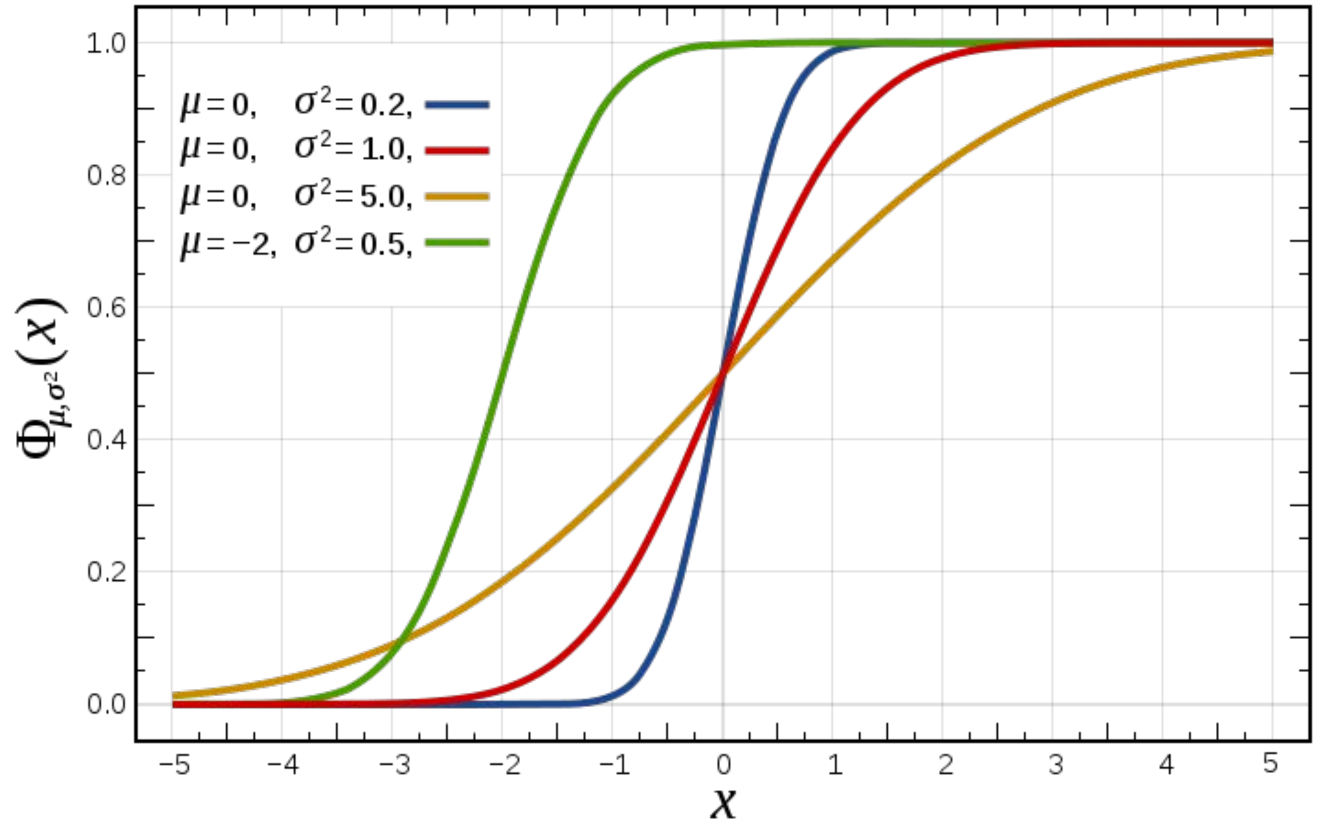
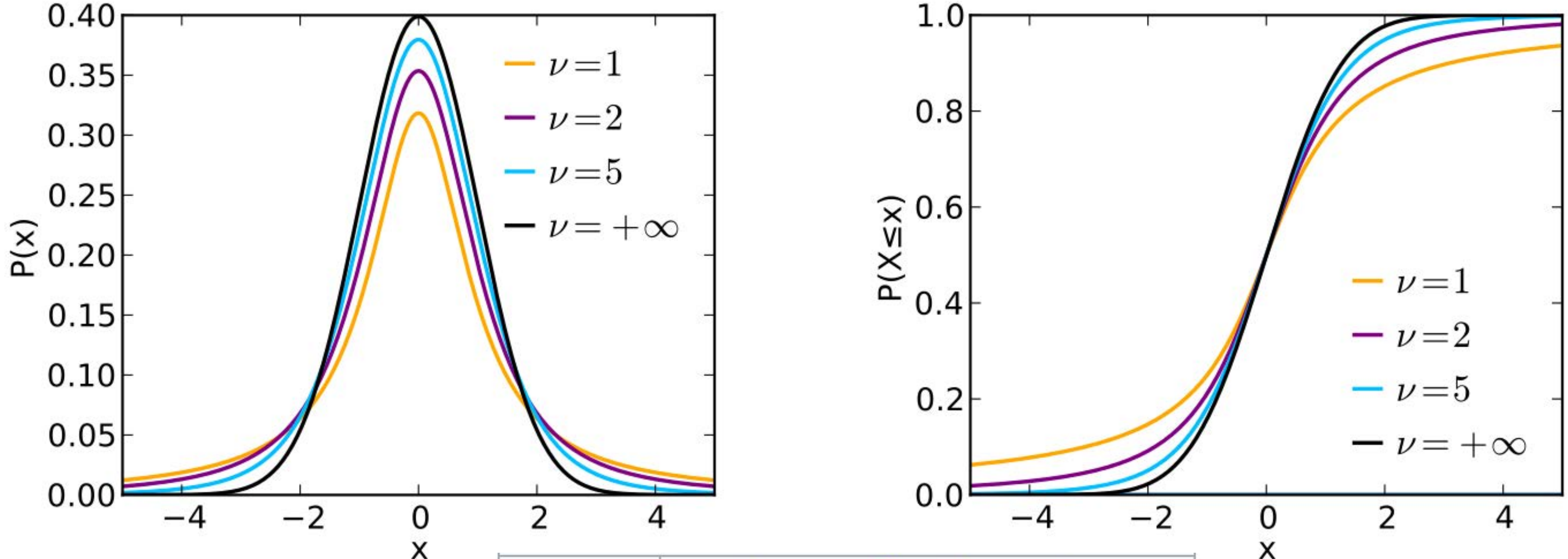
The Gaussian distribution





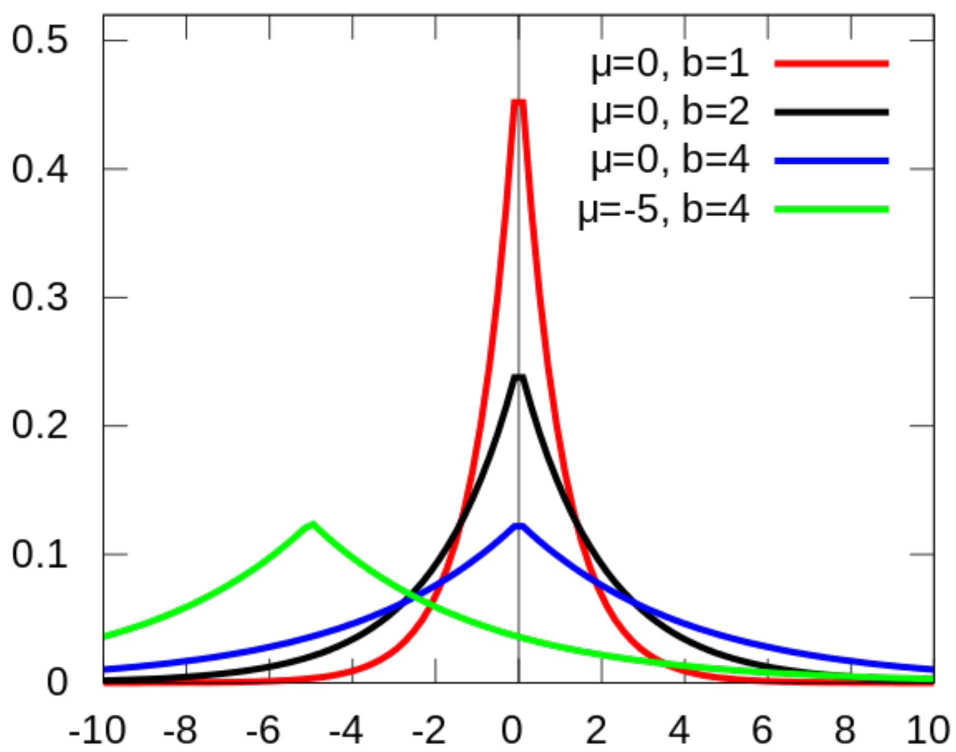
Notation	$\mathcal{N}(\mu,\, \sigma^2)$
Parameters	$\mu \in \mathbb{R}$ = mean (location) $\sigma^2 > 0$ = variance (squared scale)
Support	$x \in \mathbb{R}$
PDF	$\frac{1}{\sqrt{2\pi\sigma^2}}\, e^{-\frac{(x-\mu)^2}{2\sigma^2}}$
CDF	$\frac{1}{2}\left[1 + \operatorname{erf}\left(\frac{x-\mu}{\sigma\sqrt{2}}\right)\right]$
Quantile	$\mu + \sigma\sqrt{2}\,\operatorname{erf}^{-1}(2F-1)$
Mean	μ
Median	μ
Mode	μ
Variance	σ^2

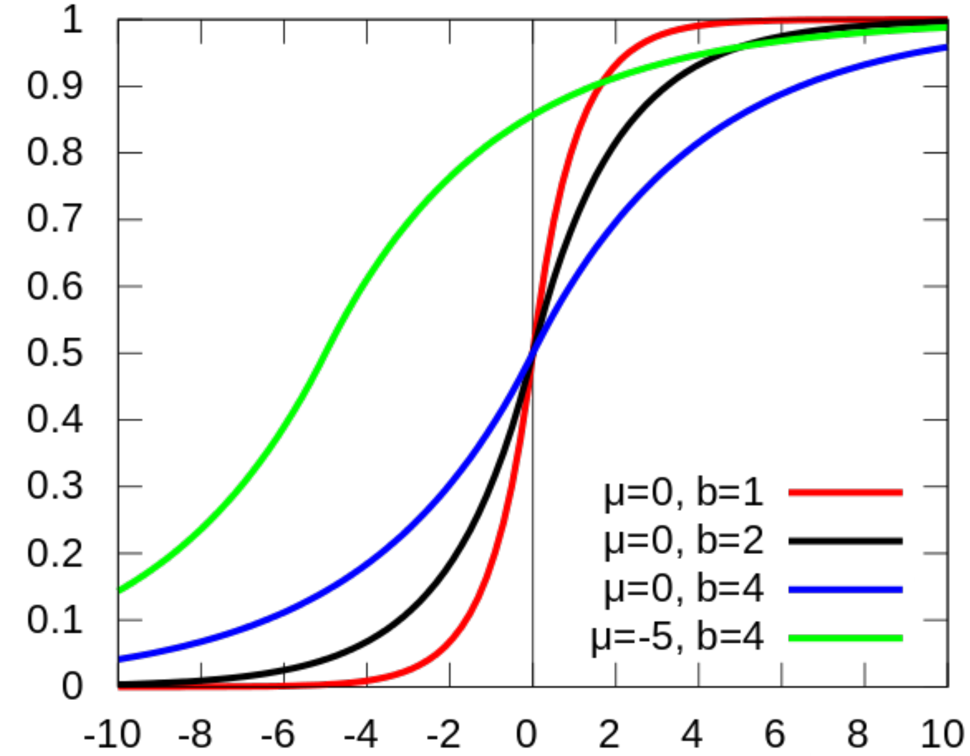
The Student-t distribution



Parameters	$\nu > 0$ degrees of freedom (real)
Support	$x \in (-\infty; +\infty)$
PDF	$\frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\,\Gamma\left(\frac{\nu}{2}\right)}\left(1+\frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}$
CDF	$\frac{1}{2} + x\Gamma\left(\frac{\nu+1}{2}\right) \times \frac{{}_2F_1\left(\frac{1}{2},\frac{\nu+1}{2};\frac{3}{2};-\frac{x^2}{\nu}\right)}{\sqrt{\pi\nu}\,\Gamma\left(\frac{\nu}{2}\right)}$ where ${}_2F_1$ is the hypergeometric function
Mean	0 for $\nu > 1$, otherwise undefined
Median	0
Mode	0
Variance	$\frac{\nu}{\nu-2}$ for $\nu > 2$, ∞ for $1 < \nu \le 2$, otherwise undefined

The Laplace distribution





Parameters	μ location (real) $b > 0$ scale (real)
Support	$x \in (-\infty; +\infty)$
PDF	$\frac{1}{2\,b} \exp\left(-\frac{\lvert x-\mu \rvert}{b}\right)$
CDF	$\begin{cases} \frac{1}{2}\exp\left(\frac{x-\mu}{b}\right) & \text{if } x < \mu \\ 1-\frac{1}{2}\exp\left(-\frac{x-\mu}{b}\right) & \text{if } x \geq \mu \end{cases}$
Mean	μ
Median	μ
Mode	μ
Variance	$2b^2$

Gaussian vs Student-t vs Laplace

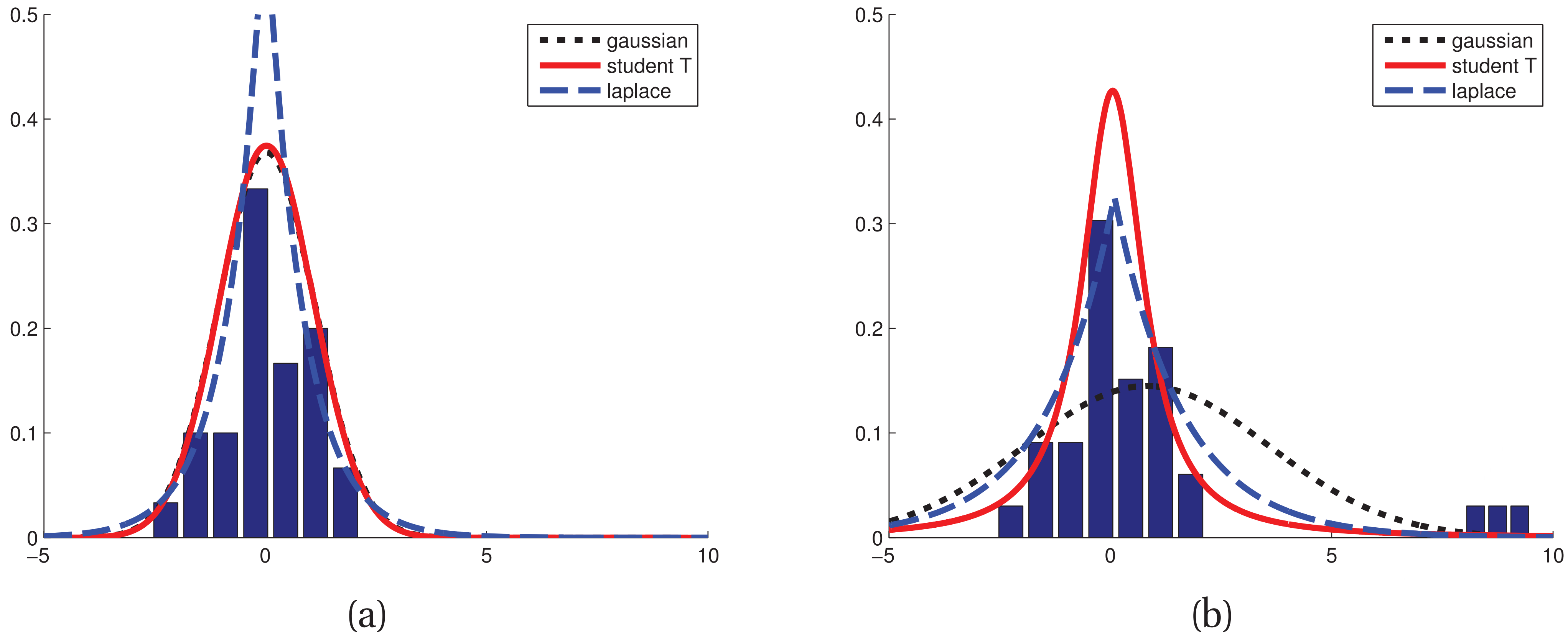
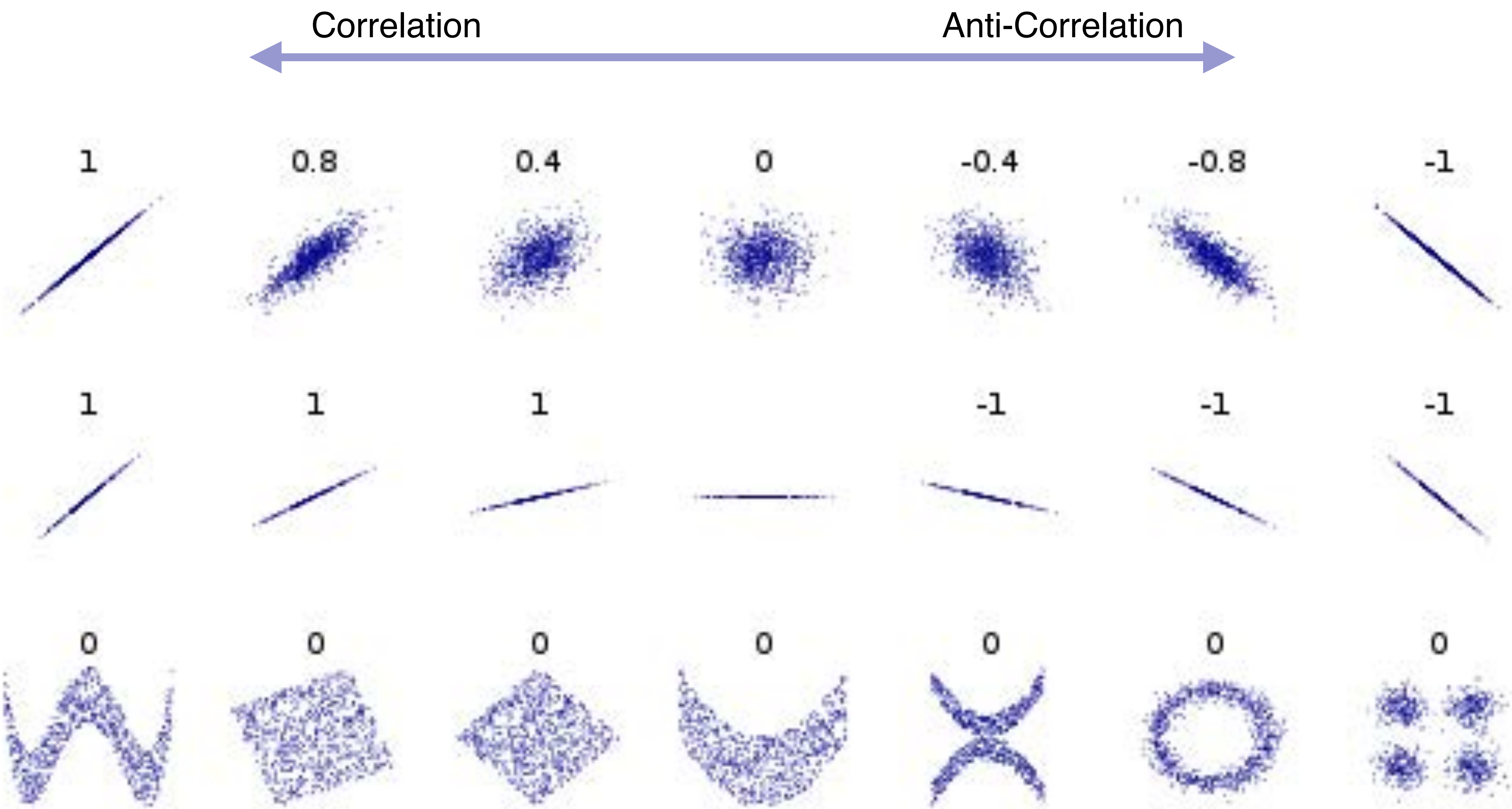
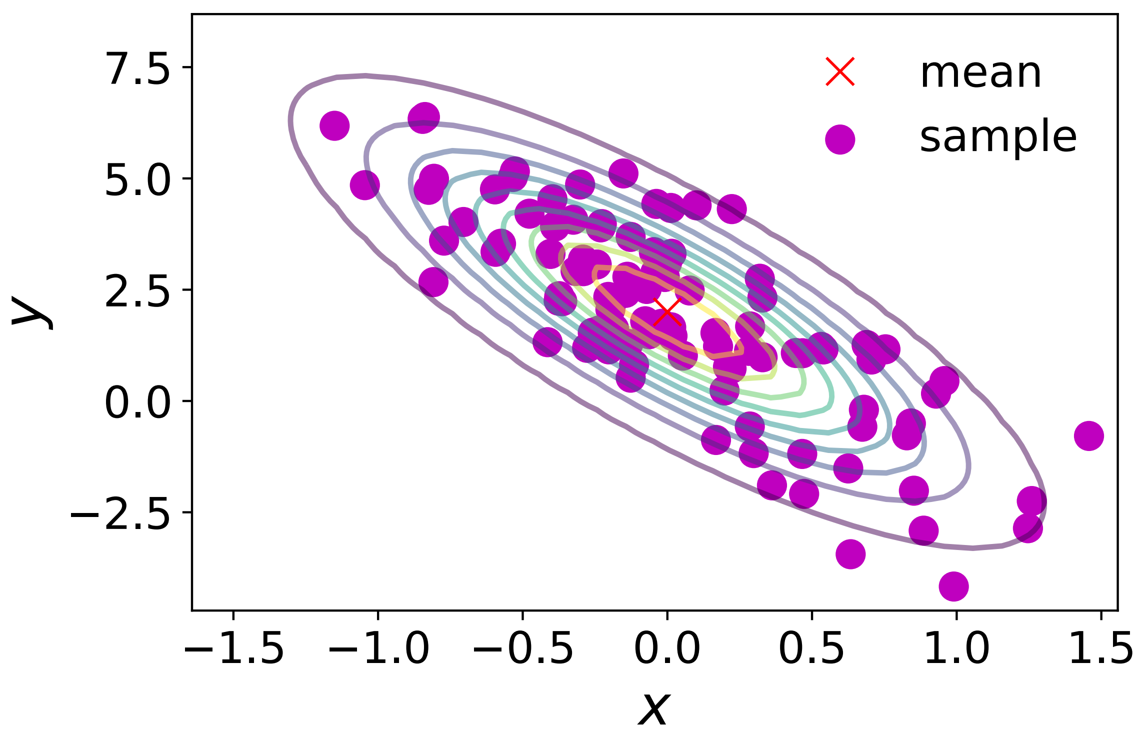


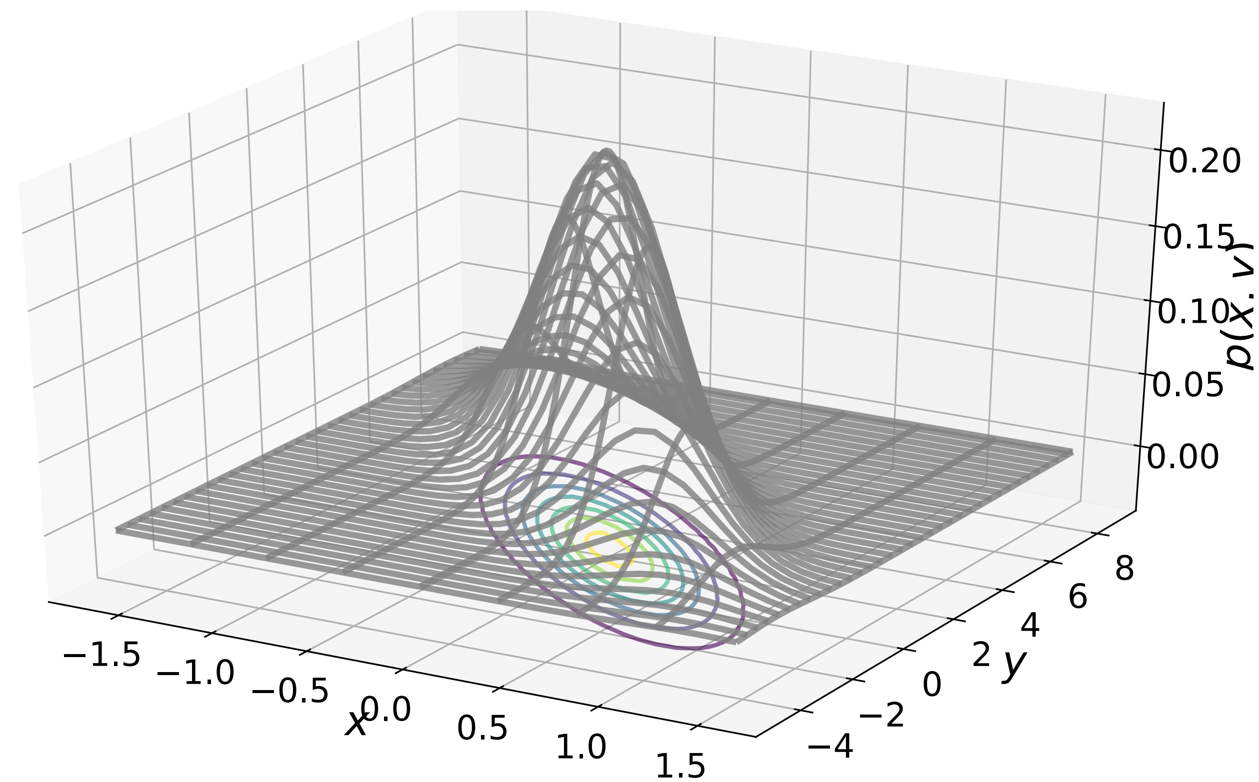
Figure 2.8 Illustration of the effect of outliers on fitting Gaussian, Student and Laplace distributions. (a) No outliers (the Gaussian and Student curves are on top of each other). (b) With outliers. We see that the Gaussian is more affected by outliers than the Student and Laplace distributions. Based on Figure 2.16 of (Bishop 2006a). Figure generated by `robustDemo`.

Correlation and linear dependence



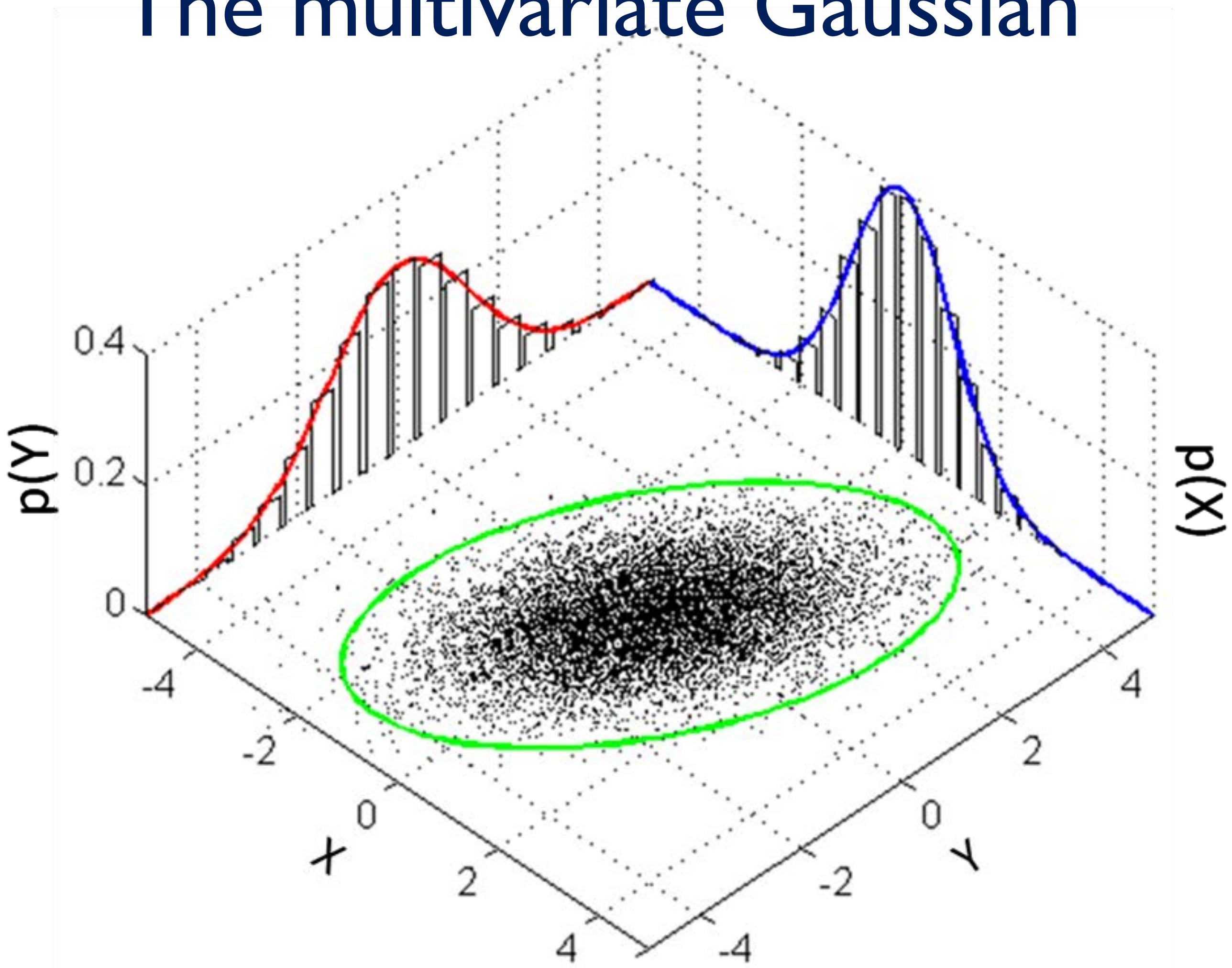
The multivariate Gaussian





$$p(\boldsymbol{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = (2\pi)^{-\frac{D}{2}} |\boldsymbol{\Sigma}|^{-\frac{1}{2}} \exp\big(-\tfrac{1}{2}(\boldsymbol{x}-\boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1}(\boldsymbol{x}-\boldsymbol{\mu})\big)$$

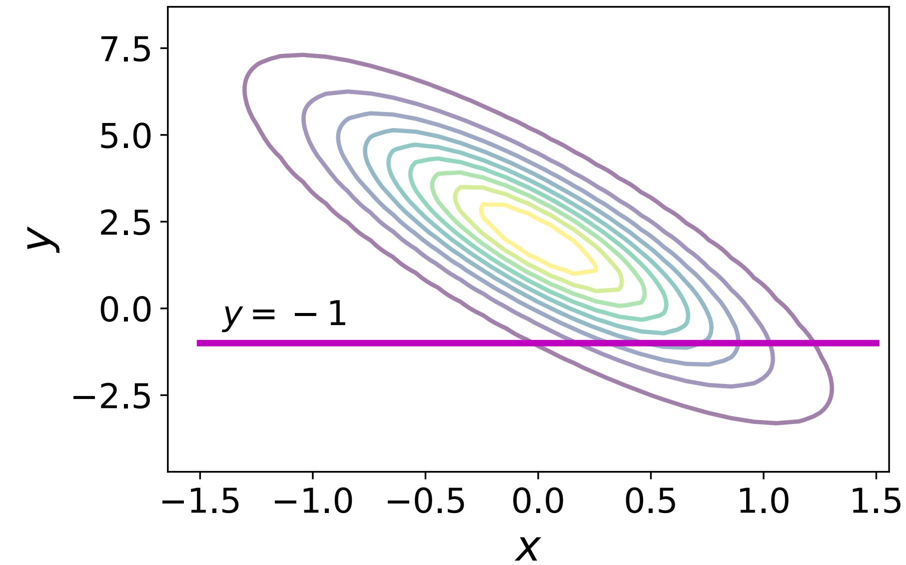
The multivariate Gaussian



Notation	$\mathcal{N}(\boldsymbol{\mu},\, \boldsymbol{\Sigma})$
Parameters	$\boldsymbol{\mu} \in \mathbf{R}^k$ — location $\boldsymbol{\Sigma} \in \mathbf{R}^{k \times k}$ — covariance (positive semi-definite matrix)
Support	$\boldsymbol{x} \in \boldsymbol{\mu} + \mathrm{span}(\boldsymbol{\Sigma}) \subseteq \mathbf{R}^k$
PDF	$\det(2\pi\boldsymbol{\Sigma})^{-\frac{1}{2}}\, e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})'\boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})}$, exists only when $\boldsymbol{\Sigma}$ is positive-definite
Mean	$\boldsymbol{\mu}$
Mode	$\boldsymbol{\mu}$
Variance	$\boldsymbol{\Sigma}$

Marginals and conditionals of a Gaussian

$$p(\boldsymbol{x}, \boldsymbol{y}) = \mathcal{N}\left(\begin{bmatrix}\boldsymbol{\mu}_x \\ \boldsymbol{\mu}_y\end{bmatrix}, \begin{bmatrix}\boldsymbol{\Sigma}_{xx} & \boldsymbol{\Sigma}_{xy} \\ \boldsymbol{\Sigma}_{yx} & \boldsymbol{\Sigma}_{yy}\end{bmatrix}\right)$$



Conditional distribution

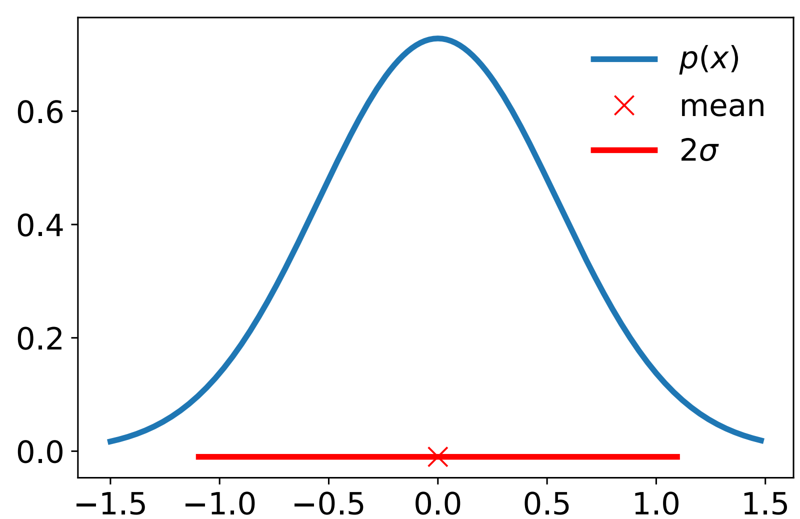
$$p(\boldsymbol{x} \,|\, \boldsymbol{y}) = \mathcal{N}\left(\boldsymbol{\mu}_{x\,|\,y}, \, \boldsymbol{\Sigma}_{x\,|\,y}\right)$$

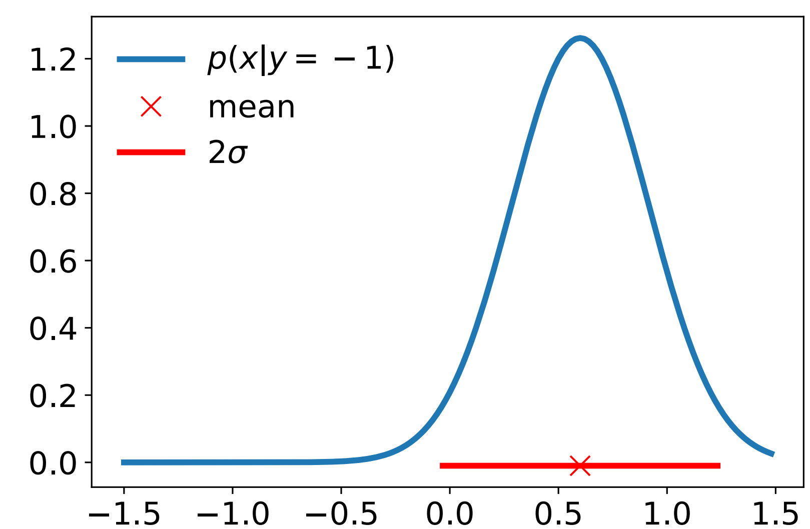
$$\boldsymbol{\mu}_{x\,|\,y} = \boldsymbol{\mu}_x + \boldsymbol{\Sigma}_{xy}\boldsymbol{\Sigma}_{yy}^{-1}(\boldsymbol{y} - \boldsymbol{\mu}_y)$$

$$\boldsymbol{\Sigma}_{x\,|\,y} = \boldsymbol{\Sigma}_{xx} - \boldsymbol{\Sigma}_{xy}\boldsymbol{\Sigma}_{yy}^{-1}\boldsymbol{\Sigma}_{yx} \,.$$

Marginal distribution

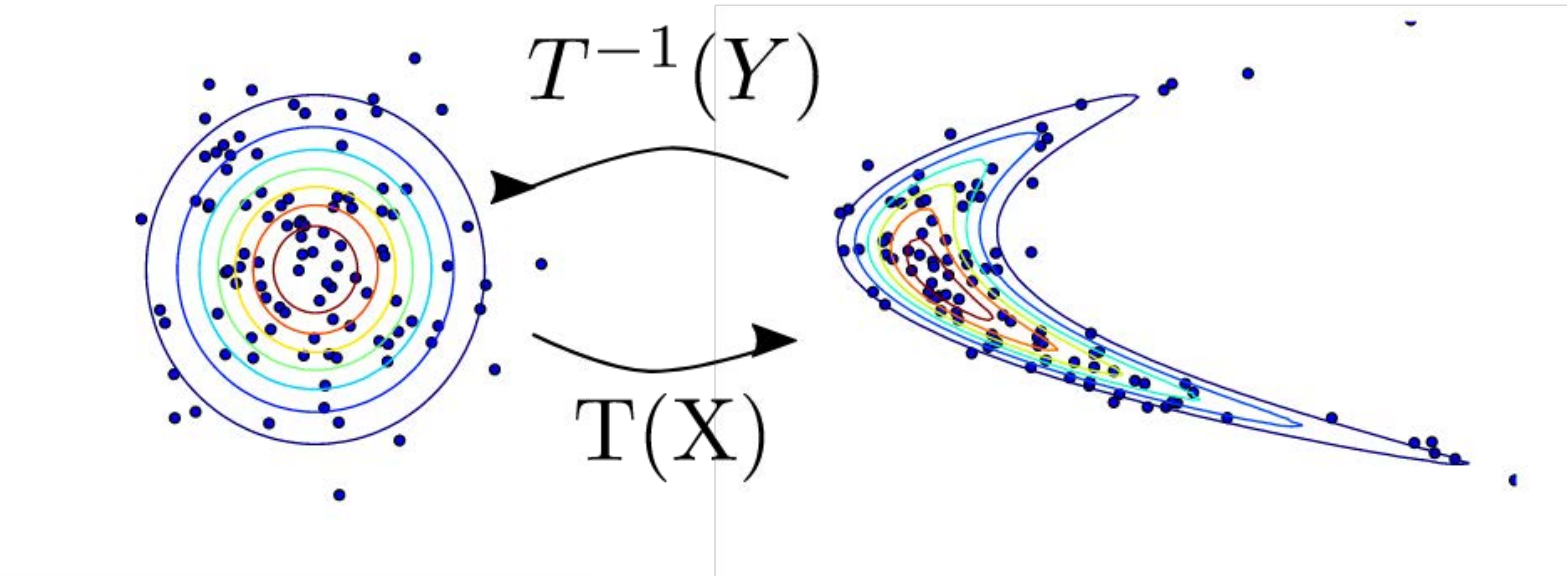
$$p(\boldsymbol{x}) = \int p(\boldsymbol{x}, \boldsymbol{y}) d\boldsymbol{y} = \mathcal{N}\left(\boldsymbol{x} \,|\, \boldsymbol{\mu}_x, \, \boldsymbol{\Sigma}_{xx}\right)$$



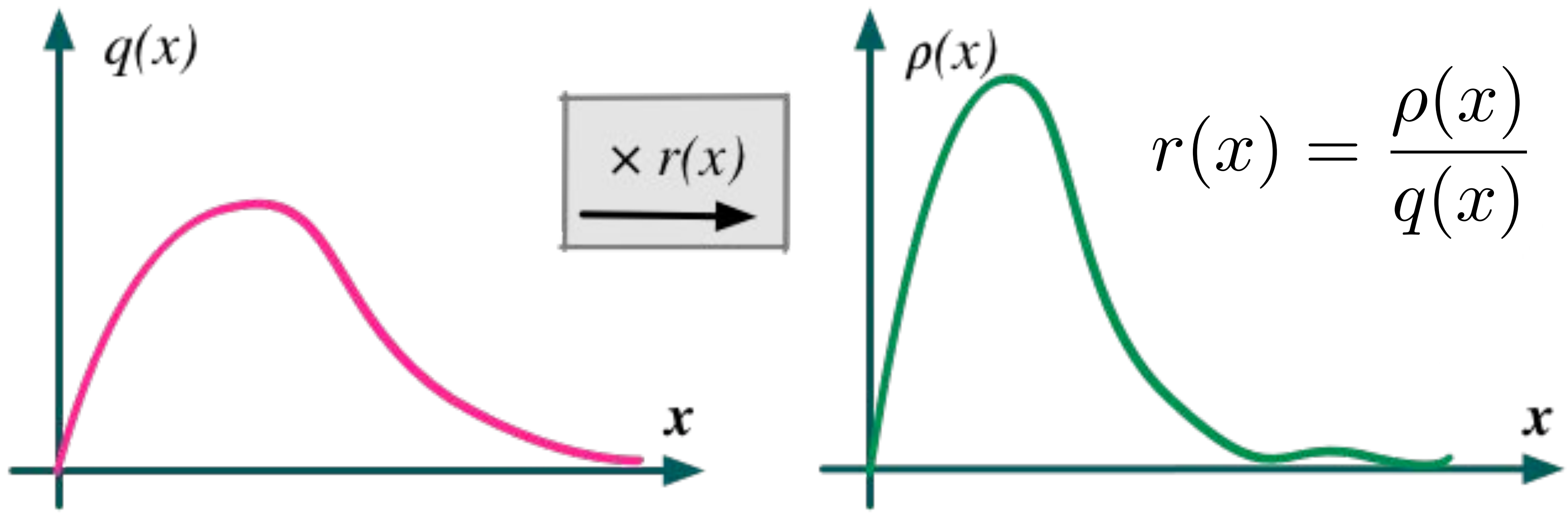


These are unique properties that make the Gaussian distribution very simple and attractive to compute with! It is essentially our main building block for computing under uncertainty.

Transformations



Statistical comparisons



$$r(x) = \frac{\rho(x)}{q(x)}$$

Maximum likelihood estimation

$$\theta_{\mathrm{MLE}} = \arg\max_{\theta \in \Theta} p(\mathcal{D}|\theta)$$