

Sorting and Hashing

See R&G Chapters:
9.1, 13.1-13.3, 13.4.2



Why Sort?



- Rendezvous
 - Eliminating duplicates
 - Summarizing groups of items
- Ordering
 - Sometimes, output must be ordered
 - e.g., return results in decreasing order of relevance
- Upcoming fundamentals:
 - *Sort-merge join* algorithm involves sorting (rendezvous)
 - First step in bulk loading *tree indexes* (ordering)
- Problem: sort 100GB of data with 1GB of RAM.
 - why not virtual memory?

But First...



- Important to know a little something about disks

Disks and Files



- A lot of databases still use magnetic disks.
 - Disks are a mechanical anachronism!
- Major implications!
 - No “pointer derefs”. Instead, an API:
 - READ: transfer “page” of data from disk to RAM.
 - WRITE: transfer “page” of data from RAM to disk.
 - Both API calls are expensive
 - Plan carefully!
 - An explicit API can be a good thing
 - Minimizes the kind of pointer errors you see in C

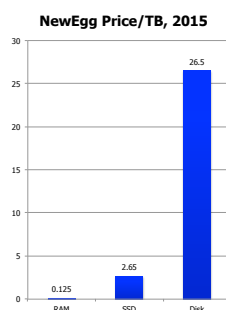
Economics



For \$1000, NewEgg offers:

- ~0.125TB of RAM
- ~2.65TB of Solid State Disk
- ~26.5TB of Magnetic Disk

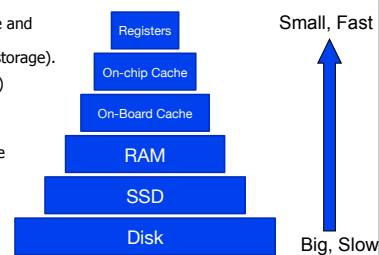
(desktop grade disks)



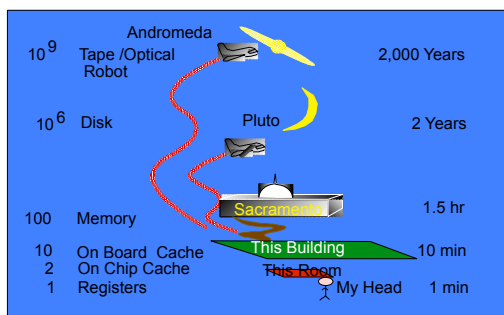
The Storage Hierarchy



- Main memory (RAM) for currently used data.
- Disk for main database and backups/logs (secondary & tertiary storage).
- The role of Flash (SSD) varies by deployment
 - Sometimes the DB
 - Sometimes a cache

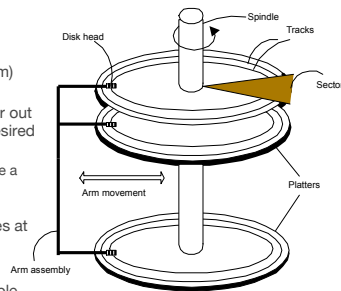


Jim Gray's Latency Analogy: How Far Away is the Data?



Components of a Disk

- Platters spin (say 7200 rpm)
- Arm assembly moved in or out to position a head on a desired track.
 - Tracks under heads make a cylinder (imaginary)
- Only one head reads/writes at any one time
- Block/page size is a multiple of (fixed) sector size



Accessing a Disk Page

- Time to access (read/write) a disk block:
 - seek time (moving arms to position disk head on track)
 - ~8-10msec on average
 - rotational delay (waiting for block to rotate under head)
 - ~2-4msec (at 7200 RPM one rotation is 4.2msec)
 - transfer time (actually moving data to/from disk surface)
 - ~0.3 msec per 64KB page
- Key to lower I/O cost: reduce seek/rotation delays!
 - Hardware vs. software solutions?

Arranging Pages on Disk

- 'Next' block concept:
 - blocks on same track, followed by
 - blocks on same cylinder, followed by
 - blocks on adjacent cylinder
- Arrange file pages sequentially on disk
 - minimize seek and rotational delay.
- For a sequential scan, pre-fetch
 - several pages at a time!

Notes on Flash (SSD)

- Various technologies, things still evolving
- Read is smallish and fast
 - Single read access time: 0.03 ms
 - 4KB random reads: ~500MB/sec
 - Sequential reads: ~525MB/sec
- Write is slower for random
 - Single write access time: 0.03ms
 - 4KB random writes: ~120MB/sec
 - Sequential writes: ~480MB/sec
- Some concern about write endurance
 - 2K-3K cycle lifetimes?
 - 6-12 months?

http://www.tonshardware.com/charts/ssd-charts-2014/benchmarks_129.html
<http://www.storagesearch.com/ssdmyths-endurance.html>

Storage Pragmatics & Trends

- Many significant DBs are not that big.
 - Daily weather, round the globe, 1929-2009: 20GB
 - 2000 US Census: 200GB
 - 2009 English Wikipedia: 14GB
- But data sizes grow faster than Moore's Law
- What is the role of disk, flash, RAM?
 - The subject of some debate!

Bottom Line (for now!)



- Very Large DBs: relatively traditional
 - Disk still the best cost/MB by orders of magnitude
 - SSDs improve performance and *performance variance*
- Smaller DB story is changing quickly
 - Entry cost for disk is not cheap, so flash wins at the low end
 - Many interesting databases fit in RAM
- Change brewing on the HW storage tech side
- Lots of uncertainty on the SW/usage side
 - It's Big: Can generate and archive data cheaply and easily
 - It's Small: Many rich data sets have (small) fixed size
- Hmmm...!
- Many people will continue to worry about magnetic disk for some time yet.

Meanwhile...

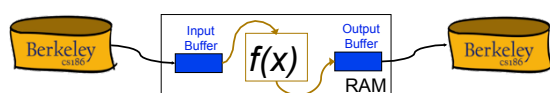


- Back in the land of out-of-core algs...

Remember this slide?



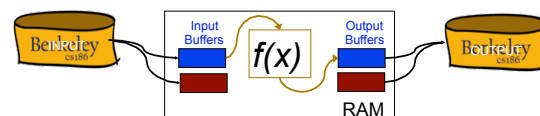
- Simple case: "Map".
 - Goal: Compute $f(x)$ for each record, write out the result
 - Challenge: minimize RAM, call read/write rarely
- Approach
 - Read a chunk from INPUT to an *Input Buffer*
 - Write $f(x)$ for each item to an *Output Buffer*
 - When Input Buffer is consumed, read another chunk
 - When Output Buffer fills, write it to OUTPUT



Better: Double Buffering



- Main thread runs $f(x)$ on one pair I/O bufs
- 2nd "I/O thread" fills/drains unused I/O bufs
- Main thread ready for a new buf? Swap!
- Usable in any of the subsequent discussion
 - Assuming you have RAM buffers to spare!
 - But for simplicity we won't bring this up again.



Sorting & Hashing: Formal

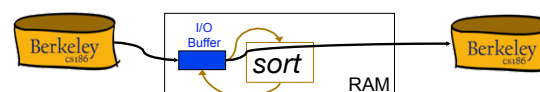


- Given:
 - A file F :
 - containing a multiset of records R
 - consuming N blocks of storage
 - Two "scratch" disks
 - each with $\gg N$ blocks of free storage
 - A fixed amount of space in RAM
 - memory capacity equivalent to B blocks of disk
- Sorting
 - Produce an output file F_S
 - with contents R **stored in order by a given sorting criterion**
- Hashing
 - Produce an output file F_H
 - with contents R , **arranged on disk so that no 2 records that are incomparable (i.e. "equal" in sort order) are separated by a greater or smaller record.**
 - I.e. matching records are always "stored consecutively" in F_H .

Sorting: 2-Way

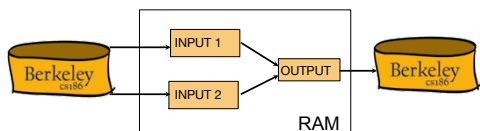


- Pass 0 (conquer):
 - read a page, sort it, write it.
 - only one buffer page is used
 - a repeated "batch job"



Sorting: 2-Way

- Pass 0 (conquer):
 - read a page, sort it, write it.
 - only one buffer page is used
 - a repeated “batch job”
- Pass 1, 2, 3, ..., etc. (merge):
 - requires 3 buffer pages
 - note: this has nothing to do with double buffering!
 - merge pairs of runs into runs twice as long
 - a streaming algorithm, as in the previous slide!

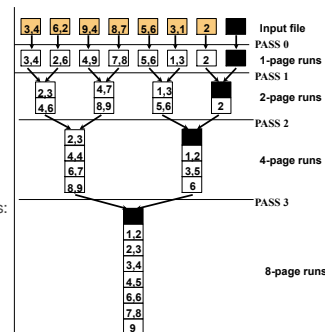


Two-Way External Merge Sort

- **Conquer and Merge:** sort subfiles and merge
- Each pass we read + write each page in file.
- N pages in the file. So, the number of passes is:

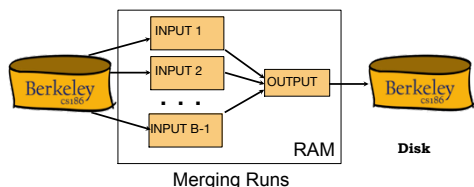
$$\lceil \log_2 N \rceil + 1$$
- So total cost is:

$$2N(\lceil \log_2 N \rceil + 1)$$



General External Merge Sort

- More than 3 buffer pages. How can we utilize them?
- To sort a file with N pages using B buffer pages:
 - Pass 0: use B buffer pages. Produce $\lceil N/B \rceil$ sorted runs of B pages each.
 - Pass 1, 2, ..., etc.: merge B-1 runs.



Cost of External Merge Sort

- Number of passes: $1 + \lceil \log_{B-1} \lceil N/B \rceil \rceil$
- Cost = $2N * (\text{\# of passes})$
- E.g., with 5 buffer pages, to sort 108 page file:
 - Pass 0: $\lceil 108 / 5 \rceil = 22$ sorted runs of 5 pages each (last run is only 3 pages)
 - Pass 1: $\lceil 22 / 4 \rceil = 6$ sorted runs of 20 pages each (last run is only 8 pages)
 - Pass 2: 2 sorted runs, 80 pages and 28 pages
 - Pass 3: 1 run => Sorted file of 108 pages

Formula check: $1 + \lceil \log_4 22 \rceil = 1 + 3 \rightarrow 4 \text{ passes} \checkmark$

of Passes of External Sort

(I/O cost is $2N$ times number of passes)

N	B=3	B=5	B=9	B=17	B=129	B=257
100	7	4	3	2	1	1
1,000	10	5	4	3	2	2
10,000	13	7	5	4	2	2
100,000	17	9	6	5	3	3
1,000,000	20	10	7	5	3	3
10,000,000	23	12	8	6	4	3
100,000,000	26	14	9	7	4	4
1,000,000,000	30	15	10	8	5	4

Memory Requirement for External Sorting

- How big of a table can we sort in two passes?
 - Each “sorted run” after Phase 0 is of size B
 - Can merge up to B-1 sorted runs in Phase 1
- Answer: $B(B-1)$.
 - Sort N pages of data in about \sqrt{N} space

Internal Sort

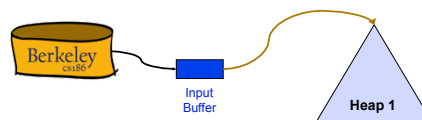


- Quicksort is a fast way to sort in memory.
- Alternative: "tournament sort"
 - a.k.a. "heapsort", "replacement selection"
- Keep two heaps in memory, **H1** and **H2**
 read $B-2$ pages of records, inserting into **H1**;
 while (records left) {
 $m = H1.removeMin()$; put m in output buffer;
 if (**H1** NOT empty)
 read in a new record r (use 1 buffer for input pages);
 if ($r < m$) **H2.insert**(r);
 else **H1.insert**(r);
 else
 H1 = H2; **H2.reset**();
 start new output run;
 }
H1.output(); start new run; **H2.output**();

Tournament Sort (Heapsort)



First, load a heap with $B-2$ pages of records



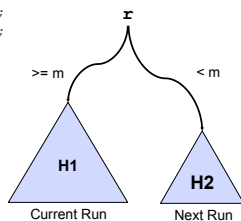
This is a priority heap, so it is in sorted order (hence called Heapsort)

Tournament Sort (2)



```
while (records left on input) {
  m = H1.removeMin(); // get smallest value
  Output(m)           // put m in output buffer;
  if (H1 NOT empty)
    r = InputRecord()
    if (r < m) H2.insert(r);
    else     H1.insert(r);

  else
    H1 = H2; H2.reset();
    start new output run;
}
```



More on Heapsort



- Fact: **average length of a run = $2(B-2)$**

- The "snowplow" analogy

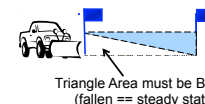
- Worst-Case:

- What is min length of a run?
- How does this arise?



- Best-Case:

- What is max length of a run?
- How does this arise?



- Quicksort is faster, but ... longer runs often means fewer passes!

Alternative: Hashing



- Idea:
 - Many times we don't require order
 - E.g.: removing duplicates
 - E.g.: forming groups
- Often just need to *rendezvous* matches
- Hashing does this
 - And may be cheaper than sorting! (Hmmm...!)
 - But how to do it out-of-core??

Divide



- Streaming Partition (divide):
 Use a hash function h_p to stream records to disk partitions
 - All matches rendezvous in the same partition.
 - Streaming algorithm to create partitions on disk:
 - "Spill" partitions to disk via output buffers

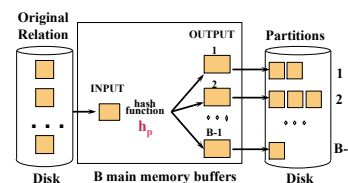
Divide & Conquer



- Streaming Partition (divide):
Use a hash function h_p to stream records to disk partitions
 - All matches rendezvous in the same partition.
 - *Streaming* algorithm to create partitions on disk:
 - “Spill” partitions to disk via output buffers
- ReHash (conquer):
Read partitions into RAM hash table one at a time, using different hash h_r
 - Then go through each bucket of this hash table to achieve rendezvous in RAM (rendezvous in the bucket)

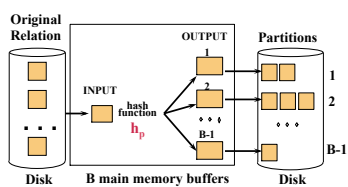
Two Phases

- Partition: (Divide)

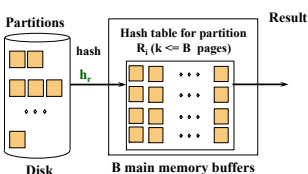


Two Phases

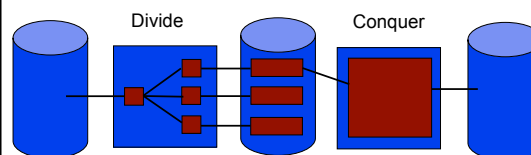
- Partition: (Divide)



- Rehash: (Conquer)



Cost of External Hashing



cost = 4*N IO's

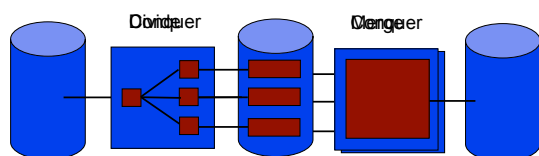
Memory Requirement



- How big of a table can we hash in two passes?
 - B-1 “partitions” result from Pass 1
 - Each should be no more than B pages in size
 - Answer: B(B-1).
 - We can hash a table of size N pages in about \sqrt{N} space
 - Note: assumes hash function distributes records evenly!
- Have a bigger table? Recursive partitioning!

How does this compare with
external sorting?

Cost of External Sorting

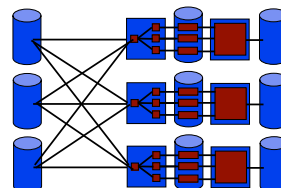


cost = $4 * N$ IO's

Parallelize me! Hashing



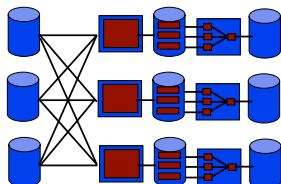
- Phase 1: partition data across machines
 - *streaming* out to network as it is scanned
 - which machine for this record?
use (yet another) independent hash function h_n
- Receivers proceed with phase 1
as data streams in
 - from local disk and network



Parallelize me! Sorting



- Pass 0: partition data across machines
 - *streaming* out to network as it is scanned
 - which machine for this record?
check value range (e.g. $[-\infty, 10]$, $[11, 100]$, $[101, \infty]$).
- Receivers proceed with pass 0
as data streams in
- **A Wrinkle: How to ensure ranges are the same size?!**
 - i.e. avoid data skew?



So which is better ??



- Simplest analysis:
 - Same memory requirement for 2 passes
 - Same I/O cost
 - But we can dig a bit deeper...
- Sorting pros:
 - Great if input already sorted (or almost sorted) w/heapsort
 - Great if need output to be sorted anyway
 - Not sensitive to “data skew” or “bad” hash functions
- Hashing pros:
 - For duplicate elimination, scales with # of values
 - Not # of items! We'll see this again.
 - Can simply conquer sometimes! (Think about that)

Summary



- Sort/Hash Duality
 - Hashing is Divide & Conquer
 - Sorting is Conquer & Merge
- Sorting is overkill for rendezvous
 - But sometimes a win anyhow
- Sorting sensitive to internal sort alg
 - Quicksort vs. HeapSort
 - In practice, QuickSort tends to win
- Don't forget double buffering