

CaliFormer: Leveraging Unlabeled Measurements for Calibration with Self-supervised Learning

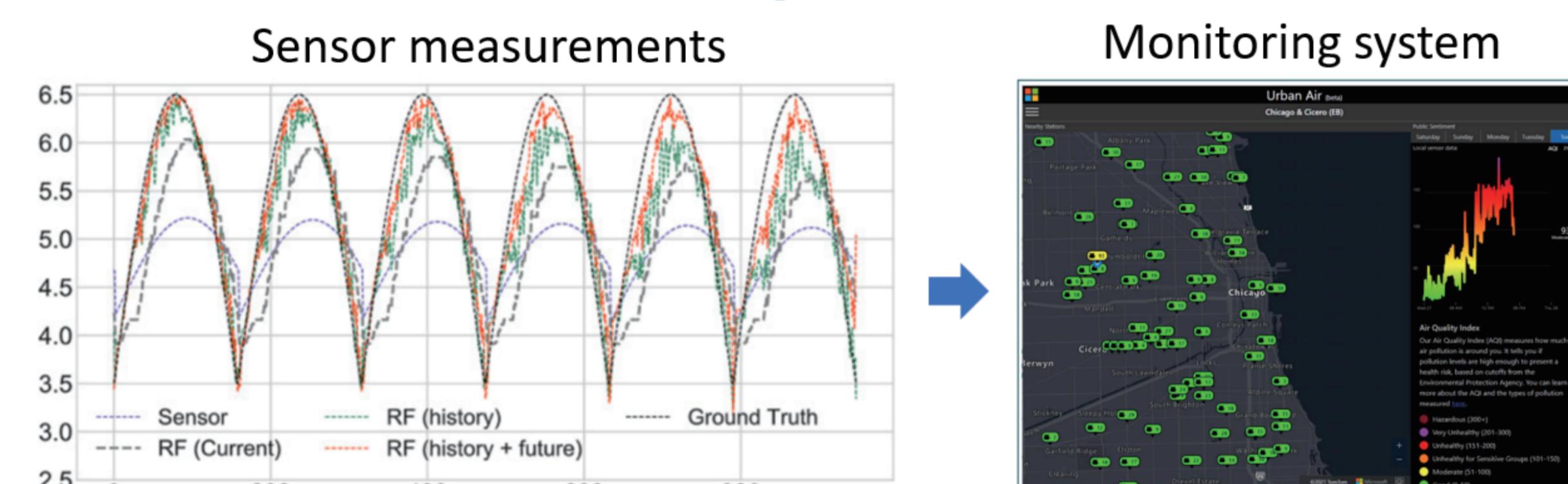
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Abstract

Accurate calibration of low-cost sensors is essential for their utilization in environmental monitoring. SOTA methods¹ take recent past and close future measurements to achieve accurate calibration. However, these methods heavily rely on labeled data, which is hard to collect in the real world. In this work, We propose CaliFormer, a representation learning model that learn the time and spatial invariant knowledge from unlabeled measurements in self-supervised learning phase. A set of enhancements in pre-train and model architecture is proposed to facilitate the training of CaliFormer. Subsequently, the calibration model built on CaliFormer is trained with limited labeled data in supervised learning phase. We extensively evaluate the calibration system with a dataset measured by low-cost sensors. Results show that our method outperforms SOTA methods.

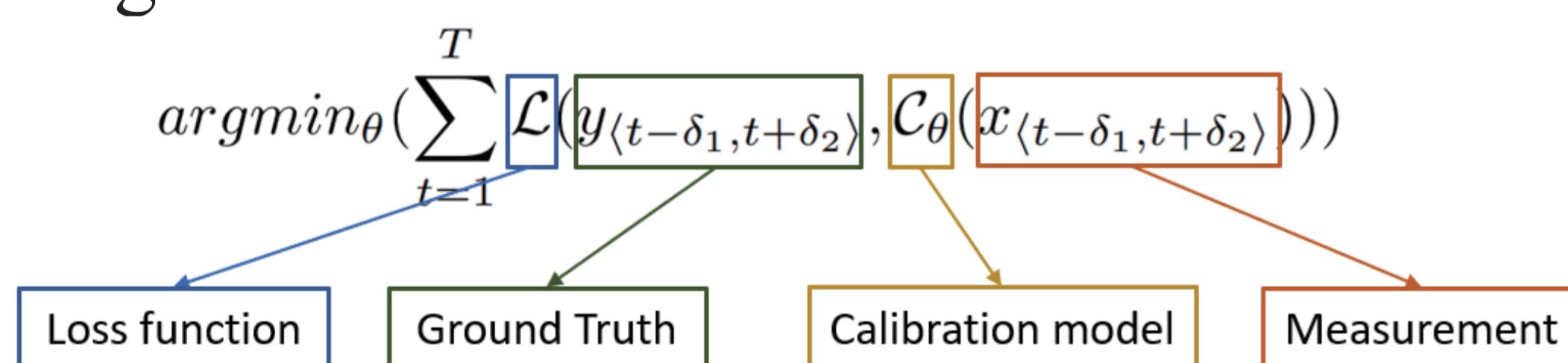
Background



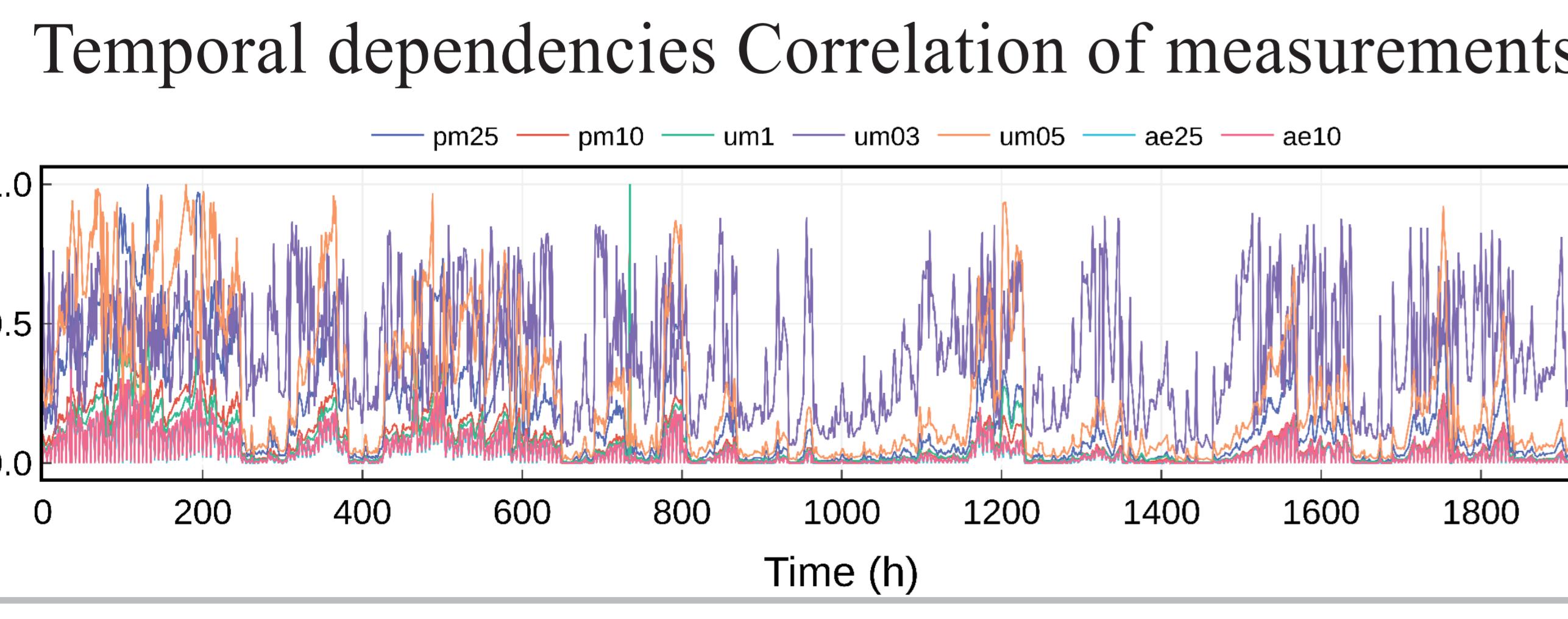
Monitoring systems heavily depends on measurements quality

Research Question

How to scale the **data-driven system** to large-scale environment sensing calibration with **limited labeled data**?

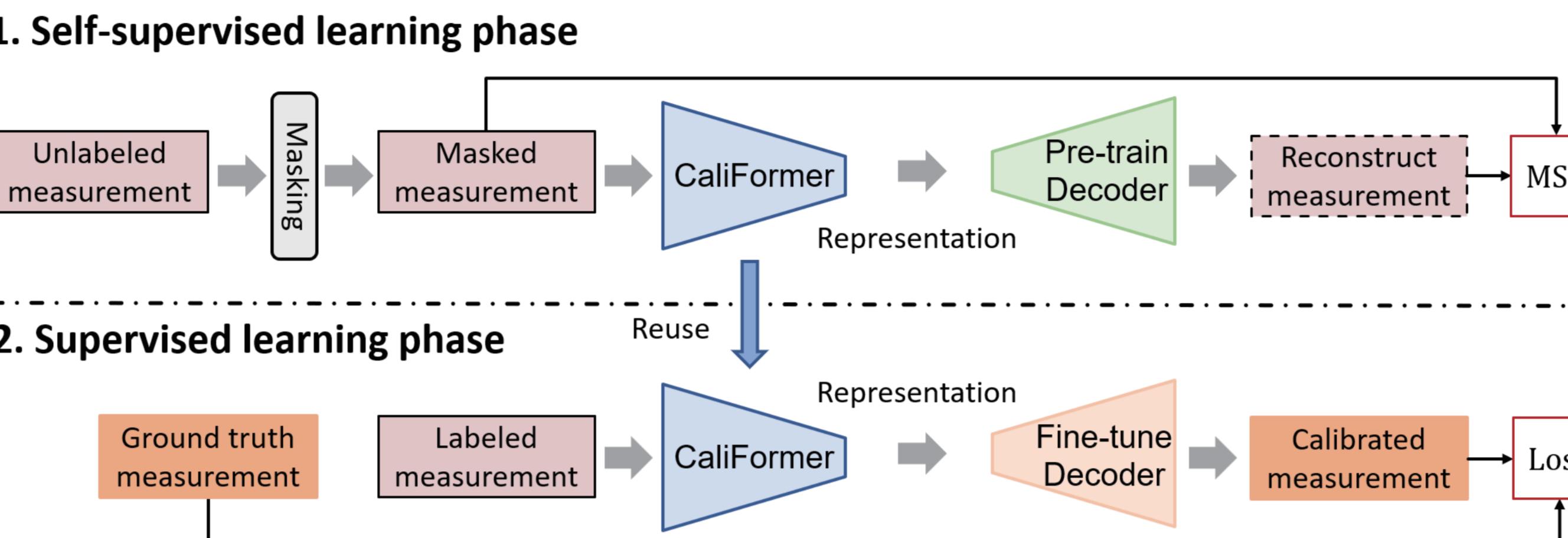


Observation

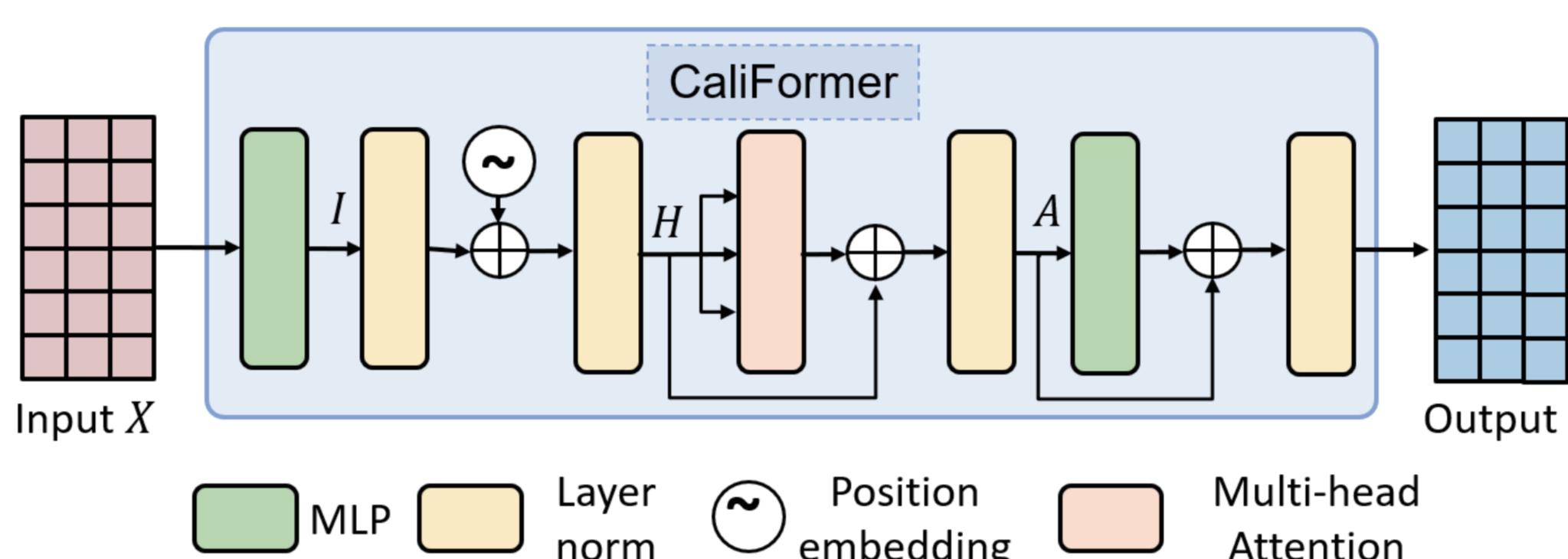


Model Design

1. Overview

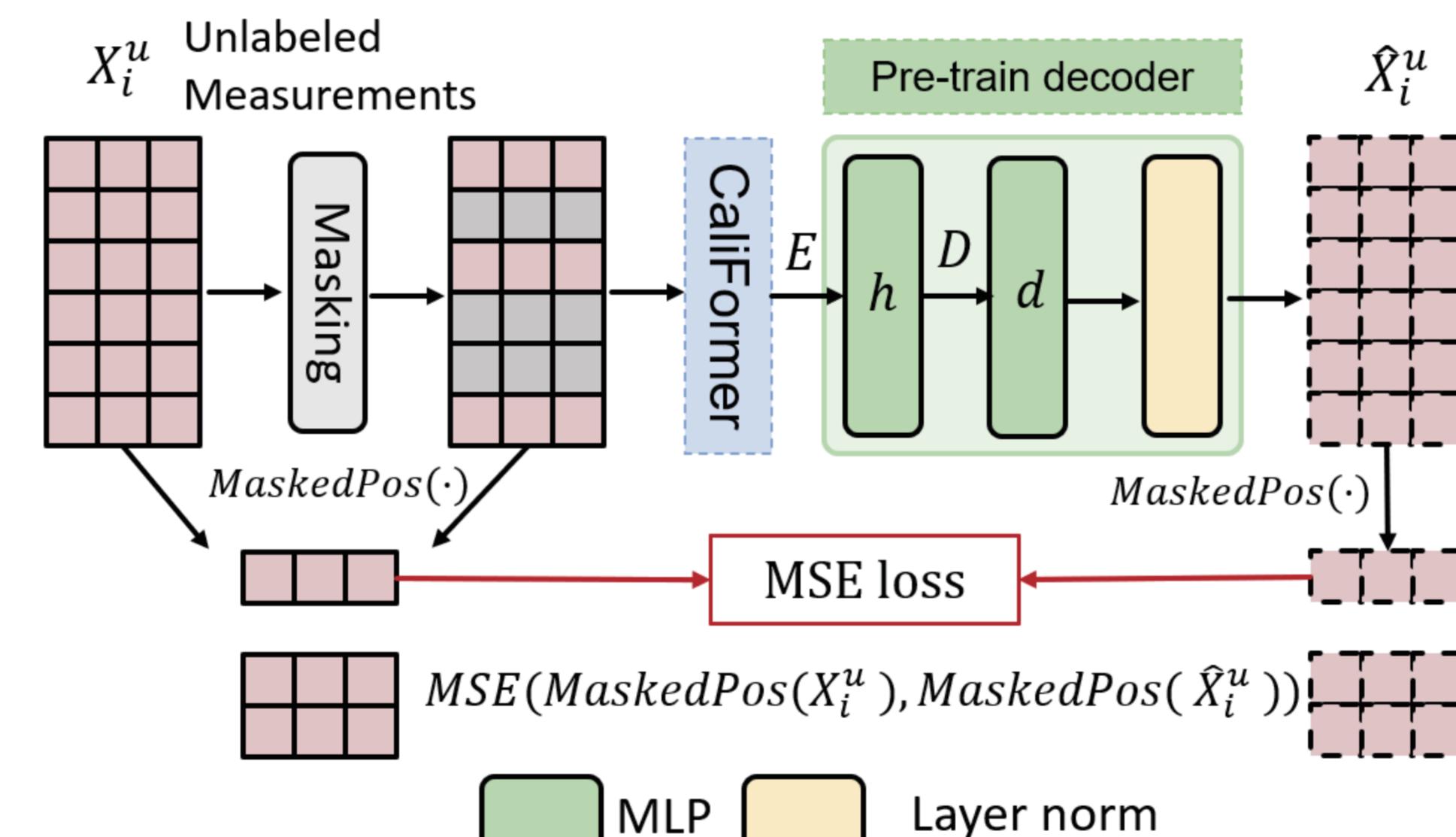


2. CaliFormer Design



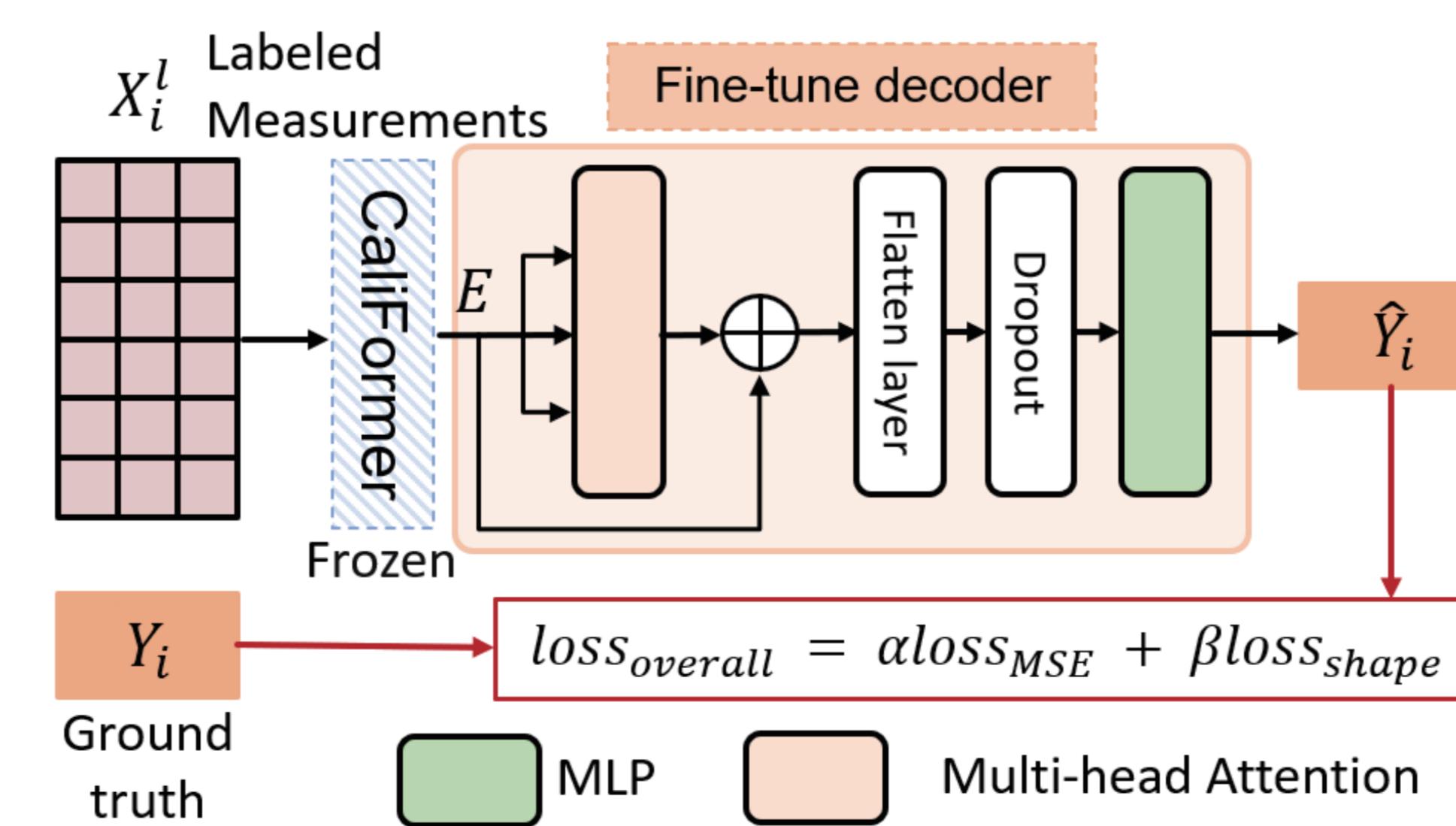
- Inspired by TransFormer² encoder architecture

3. Self-supervised learning phase



- Utilize unlabeled measurements to train the model

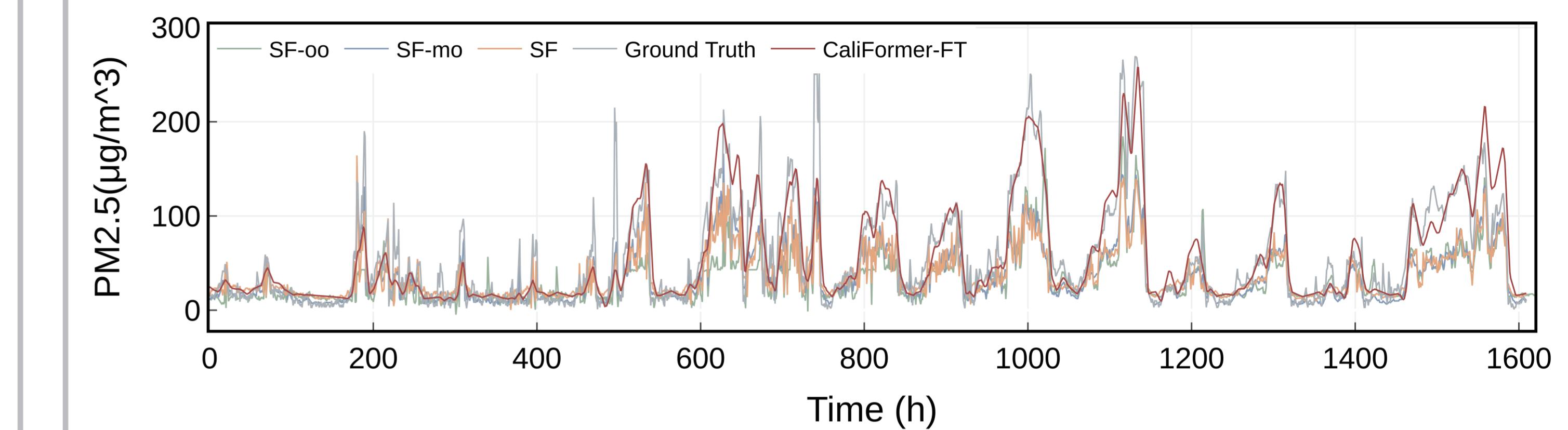
4. Supervised learning phase



- Utilize a small number of labeled measurements to train the calibration network

Experimental Results

1. Calibration result



Our method outperform the SOTA methods with 1% labeled data

2. Quantitative analysis

TABLE I
OVERALL PERFORMANCE WITH 1% LABELED DATA, WHICH IS SHOWN IN MAE($\mu\text{G}/\text{m}^3$).

Methods	Naive	SF-oo	SF-mo	SF	CaliFormer-FT
MAE	31.25	25.20	24.91	24.08	18.20

- Our method outperforms the SOTA method SF by 25%.

TABLE II
PERFORMANCE WITH DIFFERENT LABELING RATES, WHICH IS SHOWN IN MAE($\mu\text{G}/\text{m}^3$).

Labeling rate	0.5%	1%	2%	5%	10%	Average
Naive	31.25	31.25	31.25	31.25	31.25	31.25
SF-oo	29.89	25.20	24.68	21.93	21.78	24.70
SF-mo	29.72	24.91	22.33	21.77	20.86	23.92
SF	29.74	24.08	22.11	21.70	20.37	23.60
CaliFormer-FT	19.91	18.20	15.20	14.84	14.57	16.54

- The gain is significant with low labeling rate.

Conclusions

- To the best of our knowledge, CaliFormer is the first attempt to incorporate SSL into sensor calibration, which **necessitates significantly less labeled data**. This constitutes a advancement toward practical in-field sensor calibration.
- We develop the CaliFormer to process multi-modal sensor data. A set of enhancements in pre-training methodology and model architecture is proposed to facilitate the training of the calibration model.
- A prototype system is developed and compared with SOTA methods. Results demonstrate the effectiveness of the CaliFormer based calibration system.

1. Cheng Y, Saukh O, Thiele L. SensorFormer: Efficient Many-to-Many Sensor Calibration With Learnable Input Subsampling[J]. IEEE Internet of Things Journal, 2022, 9(20): 20577-20589.

2. Vaswani A, Shazeer N, Parmar N, et al. Attention is all you need[J]. Advances in neural information processing systems, 2017, 30.