

Computational Physics HW9

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(a) When doing $v = B\phi$ calculation, notice that we have v as a complex vector, so when assigning v as zeros, remember to set dtype as `csingle`.

I tried solving $Av = x$ using `given_banded.py`; however, it warns that there are invalid divisions which I guess have to do with the complex values. I decided to use built-in function `np.linalg.solve` instead.

Follow the steps to get the wavefunction of the next moment. Now, define the function with this whole process but replace ϕ_0 with any previous step wavefunction, we get the general function to generate wavefunction of the next step, naming it `next_phi`. We can run this function repeatedly to generate $\phi(t)$. We define a function to calculate $\phi(t)$ with t as number of steps, so real time as $t * h$.

(b) I first made a matrix to record the wavefunction at each time step. Notice that when setting `np.zeros` of 1D and multi0dimentions, we need to give different dtype to have each elements to be of the same type. I don't really know why it is, but I get this conclusion after experimenting and checking the type of elements of the matrix.

(c) Make the animation of the wavefunction for 3000 time steps, I find that the wave is bouncing between the walls while the waveform becomes flatter and flatter.