H B CHETAN

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Components

- Icoboard
- LED
- Bread board
- Jumper wires

Method

- PWM was implemented using LED. Four bit inputs were taken. We can display 16 levels of intensity.
- These were passed on to icoboard using GPIO pins of the pi.
- Output was checked using the change in the brightness of LED.

Github link: code

Verilog code

```
module LEDPWM(input wire clk, input wire[3:0] PWMinput,output reg LED); reg [4:0] PWM; always @(posedge clk) PWM \leq PWM[3:0]+PWMinput; assign LED = PWM[4]; endmodule
```

Python code

```
import RPi.GPIO as GPIO
```

GPIO.setmode(GPIO.BOARD)

GPIO.setup(12, GPIO.OUT)

GPIO.setup(16, GPIO.OUT)

GPIO.setup(26, GPIO.OUT)

GPIO.setup(36, GPIO.OUT)

GPIO.output(12, 1)

GPIO.output(16, 1)

GPIO.output(26, 1)

GPIO.output(36, 0)

THANK YOU