<u>DERIVATION OF FOURTH ORDER APPROXIMATION OF THE SECOND ORDER</u> DERIVATIVE:

CENTRAL DIFFERENCE METHOD:

Numerical Stencil for Central Difference,



For the above stencil, Hypothesis equation is,

$$(\partial^2 u)/(\partial x^2) = af(i-2)+bf(i-1)+cf(i)+df(i+1)+ef(i+2)$$
.....(1)

The values of the co-efficient (a, b, c, d, & e), are found using Taylor Table Method.

Taylor Series expansion for a f(i-2) term,

$$\hat{a}(i-2) = af(i) - (af^{\prime\prime}(i)(2dx))/(1!) + (af^{\prime\prime\prime}(i)(2dx)^{\prime}2)/(2!) - (af^{\prime\prime\prime\prime}(i)(2dx)^{\prime}3)/(3!) + (af^{\prime\prime\prime\prime\prime}(i)(2dx)^{\prime}4)/(4!) - (af^{\prime\prime\prime\prime\prime\prime}(i)(2dx)^{\prime}5)/(5!) + (af^{\prime\prime\prime\prime\prime\prime\prime}(i)(2dx)^{\prime}6)/(6!) + \cdots$$

Simplifying above equation,

$$af(i-2)=af(i)-(2af^{(i)}(dx))/1+(4af^{(i)}(dx)^2)/2-(8af^{(i)}(dx)^3)/6+(16af^{(i)}(dx)^4)/24-(32af^{(i)}(dx)^5)/120+(64af^{(i)}(dx)^6)/720+\cdots$$

Similarly, Taylor Series expansion for b f(i-1) term,

$$\begin{tabular}{l} bf(i-1)=bf(i)-(bf^{\prime\prime}\ (i)(dx))/1+(bf^{\prime\prime\prime}\ (i)\ (dx)^{\prime}2)/2-(bf^{\prime\prime\prime\prime}\ (i)\ (dx)^{\prime}3)/6+(bf^{\prime\prime\prime\prime\prime\prime}\ (i)\ (dx)^{\prime}4)/24-(bf^{\prime\prime\prime\prime\prime\prime}\ (i)\ (dx)^{\prime}5)/120+(bf^{\prime\prime\prime\prime\prime\prime\prime}\ (i)\ (dx)^{\prime}6)/720+\cdots\\ \end{tabular}$$

Similarly, Taylor Series expansion for c f(i) term,

Similarly, Taylor Series expansion for d f(i+1) term,

$$\hat{d}f(i+1) = df(i) + (df^{\prime\prime}(i)(dx))/1 + (df^{\prime\prime\prime}(i)(dx)^{\prime}2)/2 + (df^{\prime\prime\prime\prime}(i)(dx)^{\prime}3)/6 + (df^{\prime\prime\prime\prime\prime}(i)(dx)^{\prime}4)/24 + (df^{\prime\prime\prime\prime\prime\prime}(i)(dx)^{\prime}5)/120 + (df^{\prime\prime\prime\prime\prime\prime\prime}(i)(dx)^{\prime}6)/720 + \cdots)$$

Similarly, Taylor Series expansion for e f(i+2) term,

$$\dot{f}(i-2) = ef(i) + (2ef^{\prime\prime}(i)(dx))/1 + (4ef^{\prime\prime\prime}(i)(dx)^{\prime}2)/2 + (8ef^{\prime\prime\prime\prime}(i)(dx)^{\prime}3)/6 + (16ef^{\prime\prime\prime\prime\prime}(i)(dx)^{\prime}4)/24 + (32ef^{\prime\prime\prime\prime\prime\prime}(i)(dx)^{\prime}5)/120 + (64ef^{\prime\prime\prime\prime\prime\prime\prime}(i)(dx)^{\prime}6)/720 + \cdots$$

The above Taylor Series expansion is in represented in Taylor's Table,

		f(i)	$\Delta x f'(i)$	$\Delta x^2 f''(i)$	$\Delta x^3 f^{\prime\prime\prime}(i)$	$\Delta x^4 f^{\prime\prime\prime\prime}(i)$	$\Delta x^5 f^{\prime\prime\prime\prime\prime}(i)$
Numerical Stencil	af(i)	а	0	0	0	0	0
	<i>bf</i> (<i>i</i> + 1)	b	b	$\frac{b}{2}$	$\frac{b}{6}$	$\frac{b}{24}$	$\frac{b}{120}$
	cf(i+2)	С	2c	$\frac{4c}{2}$	$\frac{8c}{6}$	$\frac{16c}{24}$	$\frac{32c}{120}$
	df(i+3)	d	3d	$\frac{9d}{2}$	$\frac{27d}{6}$	$\frac{81d}{24}$	$\frac{243d}{120}$
	ef(i-4)	e	4e	$\frac{16e}{2}$	64e 6	$\frac{256e}{24}$	$\frac{1024e}{120}$
	gf(i-4)	g	5g	$\frac{25g}{2}$	$\frac{125g}{6}$	$\frac{625g}{24}$	$\frac{3125g}{120}$
	Sum of co- efficient	0	0	1	0	0	0

Linear equations obtained from the above table is solved using a matrix for a, b, c, d, & e.

$$A*B = X$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 2 & 1/2 & 0 & 1/2 & 2 \\ -8/6 & -1/6 & 0 & 1/6 & 8/6 \\ 16/24 & 1/24 & 0 & 1/24 & 16/24 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$X = inv(A)*B$$

After solving the above matrix, we get the values of all the coefficients as:

Substituting the above values in equation 1 and dividing by $(\Delta x)^2$.

$$(\partial^2 u)/(\partial x^2) = ((-0.0833)f(i-2) + (1.3333)f(i-1) + (-2.5000)f(i) + (1.3333)f(i+1) + (-0.0833)f(i+2))/(\Delta x)^2$$

SKEWED RIGHT-SIDED DIFFERENCE:

The order of accuracy $\mathbf{P} = Number$ of nodes in the stencil \mathbf{N} - order of derivative \mathbf{Q}

Number of nodes in the stencil N = 4 + 2 = 6

Numerical Stencil for Skewed Right-Sided Difference,



For the above stencil, Hypothesis equation is,

$$(\partial^2 u)/(\partial x^2) = af(i) + bf(i+1) + cf(i+2) + df(i+3) + ef(i+4) + gf(i+5)$$
(2)

Expanding all the terms in the above equation (2) using Taylor series expansion and are represented in a tabular form using Taylor's Table Method.

		f(i)	$\Delta x f'(i)$	$\Delta x^2 f''(i)$	$\Delta x^3 f^{\prime\prime\prime}(i)$	$\Delta x^4 f^{\prime\prime\prime\prime}(i)$	$\Delta x^5 f^{\prime\prime\prime\prime\prime}(i)$
Numerical Stencil	af(i)	а	0	0	0	0	0
	<i>bf</i> (<i>i</i> + 1)	b	b	$\frac{b}{2}$	$\frac{b}{6}$	$\frac{b}{24}$	$\frac{b}{120}$
	cf(i+2)	с	2c	$\frac{4c}{2}$	$\frac{8c}{6}$	$\frac{16c}{24}$	$\frac{32c}{120}$
	df(i+3)	d	3d	$\frac{9d}{2}$	$\frac{27d}{6}$	$\frac{81d}{24}$	$\frac{243d}{120}$
	ef(i - 4)	e	4e	$\frac{16e}{2}$	$\frac{64e}{6}$	$\frac{256e}{24}$	$\frac{1024e}{120}$
	gf(i-4)	g	5g	$\frac{25g}{2}$	$\frac{125g}{6}$	$\frac{625g}{24}$	$\frac{3125g}{120}$
	Sum of co- efficient	0	0	1	0	0	0

Linear equations obtained from the above table is solved using a matrix for a, b, c, d, e, & g.

$$A*B = X$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 1/2 & 4/2 & 9/2 & 16/2 & 25/2 \\ 0 & 1/6 & 8/6 & 27/6 & 64/6 & 125/6 \\ 0 & 1/24 & 16/24 & 81/24 & 256/24 & 625/24 \\ 0 & 1/120 & 32/120 & 243/120 & 1024/120 & 3125/120 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ g \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$X = inv(A)*B$$

After solving the above matrix using Matlab, we get the values of all the coefficients as:

3.7500

-12.8333

17.8333

-13.0000

5.0833

-0.8333

a = 3.7500

b = -12.8333

c = 17.8333

d = -13.0000

$$e = 5.0833$$

 $g = -0.8333$

Substituting the above values in equation 2 and dividing by $(\Delta x)^2$.

$$(\partial^2 u)/(\partial x^2) = ((3.75)f(i) + (-12.8333)f(i+1) + (17.8333)f(i+2) + (-13)f(i+3) + (5.0833)f(i+4) + (-0.8333)f(i+5))/(\Delta x)^2$$

SKEWED LEFT-SIDED DIFFERENCE:

The order of accuracy P = Number of nodes in the stencil N - order of derivative Q

Number of nodes in the stencil N = 4 + 2 = 6

Numerical Stencil for Skewed Left-Sided Difference,



For the above stencil, Hypothesis equation is,

$$(\partial^2 u)/(\partial x^2) = af(i-5) + bf(i-4) + cf(i-3) + df(i-2) + ef(i-1) + gf(i)$$
.....(3)

Expanding all the terms in the above equation (3) using Taylor series expansion and are represented in a tabular form using Taylor's Table Method.

		f(i)	$\Delta x f'(i)$	$\Delta x^2 f''(i)$	$\Delta x^3 f^{\prime\prime\prime}(i)$	$\Delta x^4 f^{\prime\prime\prime\prime}(i)$	$\Delta x^5 f^{\prime\prime\prime\prime\prime}(i)$
	0.6: =X		_	0.5	105	605	2125
Numerical	af(i-5)	а	-5a	$\frac{25a}{2}$	$\frac{-125a}{6}$	$\frac{625a}{24}$	$\frac{-3125a}{122}$
Stencil					6	24	120
	bf(i-4)	b	-4b	$\frac{16b}{2}$	$\frac{-64b}{6}$	256b	-1024b
				2		24	120
	cf(i - 3)	С	-3c	9 <i>c</i>	-27 <i>c</i>	81 <i>c</i>	-243 <i>c</i>
				2	6	24	120
	df(i-2)	d	-2d	$\frac{4d}{2}$	$\frac{-8d}{6}$	16d	-32d
				2	6	24	120
	<i>ef</i> (<i>i</i> – 1)	е	-е	$\frac{e}{2}$	$\frac{-e}{6}$	<u>e</u>	<u>-e</u>
				2	6	24	120
	gf(i)	g	0	0	0	0	0
	Sum of	0	0	1	0	0	0
	co-						
	efficient						

Linear equations obtained from the above table is solved using a matrix for a, b, c, d, e, & g.

$$A*B = X$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ -5 & -4 & -3 & -2 & -1 & 0 \\ 25/2 & 16/2 & 9/2 & 4/2 & 1/2 & 0 \\ -125/6 & -64/6 & -27/6 & -8/6 & -1/6 & 0 \\ 625/24 & 253/24 & 81/24 & 16/24 & 1/24 & 0 \\ -3125/120 & -1024/120 & -243/120 & -32/120 & -1/120 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ g \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$X = inv(A)*B$$

After solving the above matrix using Matlab, we get the values of all the coefficients as:

- -0.8333
- 5.0833
- -13.0000
- 17.8333
- -12.8333
 - 3.7500
- a = -0.8333
- b = 5.0833
- c = -13.0000
- d = 17.8333
- e = -12.8333
- g = 3.7500

Substituting the above values in equation 3 and dividing by $(\Delta x)^2$.

 $\hat{(} \partial^2 u)/(\partial x^2) = ((-0.8333)f(i-5) + (5.0833)f(i-4) + (-13)f(i-3) + (17.8333)f(i-2) + (-12.8333)f(i-1) + (3.75)f(i))/(\Delta x)^2)$

MATLAB PROGRAM:

MAIN CODE:

 $\mbox{\$ A program to calculate the second-order derivative of the analytical function <math display="inline">\exp{(x)} \, {}^*\!\cos{(x)} \, .$

```
clear all
close all
clc
```

- % value of x
- x = pi/3;

```
% range of dx
dx = linspace(pi/4, pi/4000, 20);
% Loop for solving a particular approximation for all values of dx
for i=1:length(dx)
central difference error(i) = central differencing approximation(x, dx(i));
right sided skewed error(i) = right skewed approximation(x, dx(i));
left sided skewed error(i) = left skewed approximation(x,dx(i));
end
% Plotting
figure(1)
loglog(dx,central_difference_error,'b')
hold on
loglog(dx,right sided skewed error,'r')
hold on
loglog(dx,left sided skewed error,'g')
xlabel('dx')
ylabel('Error')
legend ('Central Difference Error', 'Skewed Right-Sided Error', 'Skewed Left-Sided
Error','Location','northwest')
figure (2)
plot(dx,central difference error,'b')
hold on
plot(dx,right sided skewed error,'r')
hold on
plot(dx,left sided skewed_error,'g')
xlabel('dx')
ylabel('Absolute Error')
legend ('Central Difference Error', 'Skewed Right-Sided Error', 'Skewed Left-Sided
Error', 'Location', 'northwest')
```

FUNCTION CODE FOR CENTRAL DIFFERENCE:

```
function Error central differencing = central differencing approximation (x, dx)
% analytic function exp(x) *cos(x)
% analytic derivative
% f'(x) = -2*exp(x)*sin(x)
analytical_derivative = -2*exp(x)*sin(x);
% Values of all the coefficients
a = -0.0833;
b = 1.3333;
c = -2.5000;
d = 1.3333;
e = -0.0833;
% Central differencing
central difference = ((a*exp(x-2*dx)*cos(x-2*dx))...
    + (b*exp(x-dx)*cos(x-dx))...
    +(c*exp(x)*cos(x))...
    +(d*exp(x+dx)*cos(x+dx))...
    +(e^*exp(x+2*dx)*cos(x+2*dx)))/(dx^2);
Error central differencing= abs(central difference- analytical derivative);
```

FUNCTION CODE FOR SKEWED RIGHT-SIDED DIFFERENCE:

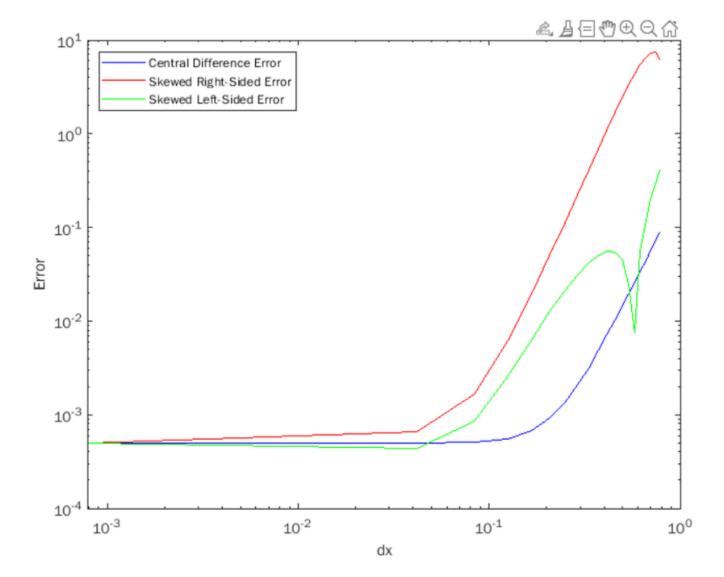
```
function Error right skewed = right skewed approximation (x, dx)
```

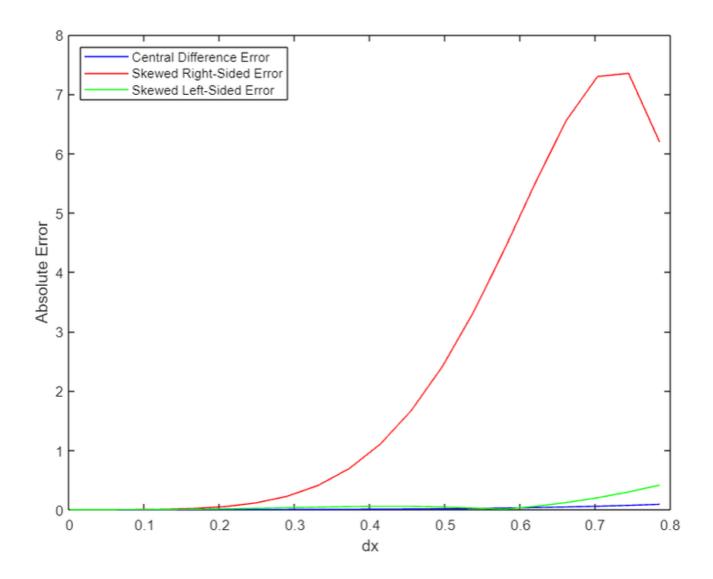
```
% analytic function exp(x) *cos(x)
% analytic derivative
% f'(x) = -2*exp(x)*sin(x)
analytical derivative = -2 \times \exp(x) \times \sin(x);
% Values of all the coefficients
a = 3.7500;
b = -12.8333;
c = 17.8333;
d = -13.0000;
 e = 5.0833;
 g = -0.8333;
% Right Side Skewed
right skewed = ((a*exp(x)*cos(x))...
    + (b*exp(x+dx)*cos(x+dx))...
    +(c*exp(x+2*dx)*cos(x+2*dx))...
    +(d*exp(x+3*dx)*cos(x+3*dx))...
    +(e^*exp(x+4*dx)*cos(x+4*dx))...
    +(g*exp(x+5*dx)*cos(x+5*dx)))/(dx^2);
Error right skewed = abs(right skewed - analytical derivative);
end
```

FUNCTION CODE FOR SKEWED LEFT-SIDED DIFFERENCE:

```
function Error left skewed = left skewed approximation (x, dx)
% analytic function exp(x) *cos(x)
% analytic derivative
% f'(x) = -2*exp(x)*sin(x)
analytical derivative = -2*exp(x)*sin(x);
% Values of all the coefficients
 a = -0.8333; b = 5.0833; c = -13.0000;
  d = 17.8333; e = -12.8333; g = 3.7500;
% Left Side Skewed
left skewed = ((a*exp(x-5*dx)*cos(x-5*dx))...
    + (b*exp(x-4*dx)*cos(x-4*dx))...
    +(c*exp(x-3*dx)*cos(x-3*dx))...
    +(d*exp(x-2*dx)*cos(x-2*dx))...
    +(e*exp(x-dx)*cos(x-dx))...
    +(g*exp(x)*cos(x)))/(dx^2);
% Error
Error left skewed= abs(left skewed- analytical derivative);
end
```

OUTPUT:





CONCLUSION:

From the above plot we can conclude that the error from the Central Difference scheme is less as compared to Skewed scheme.

Why a skewed scheme is useful? What can a skewed scheme do that a CD scheme cannot?

The system which doesn't contain sufficient information on both side of the considered point of interest. In such cases we cannot use central differencing scheme so skewed scheme is useful in such cases. Central differencing scheme cannot not be employed at the boundary nodes due to unavailability of right and left nodes at the same time. In this situation skewed difference method can be used, as in the skewed scheme data from one side can be used to compute numerical approximation at a point.