



# Administration & Operations

Architecture

# Objectives

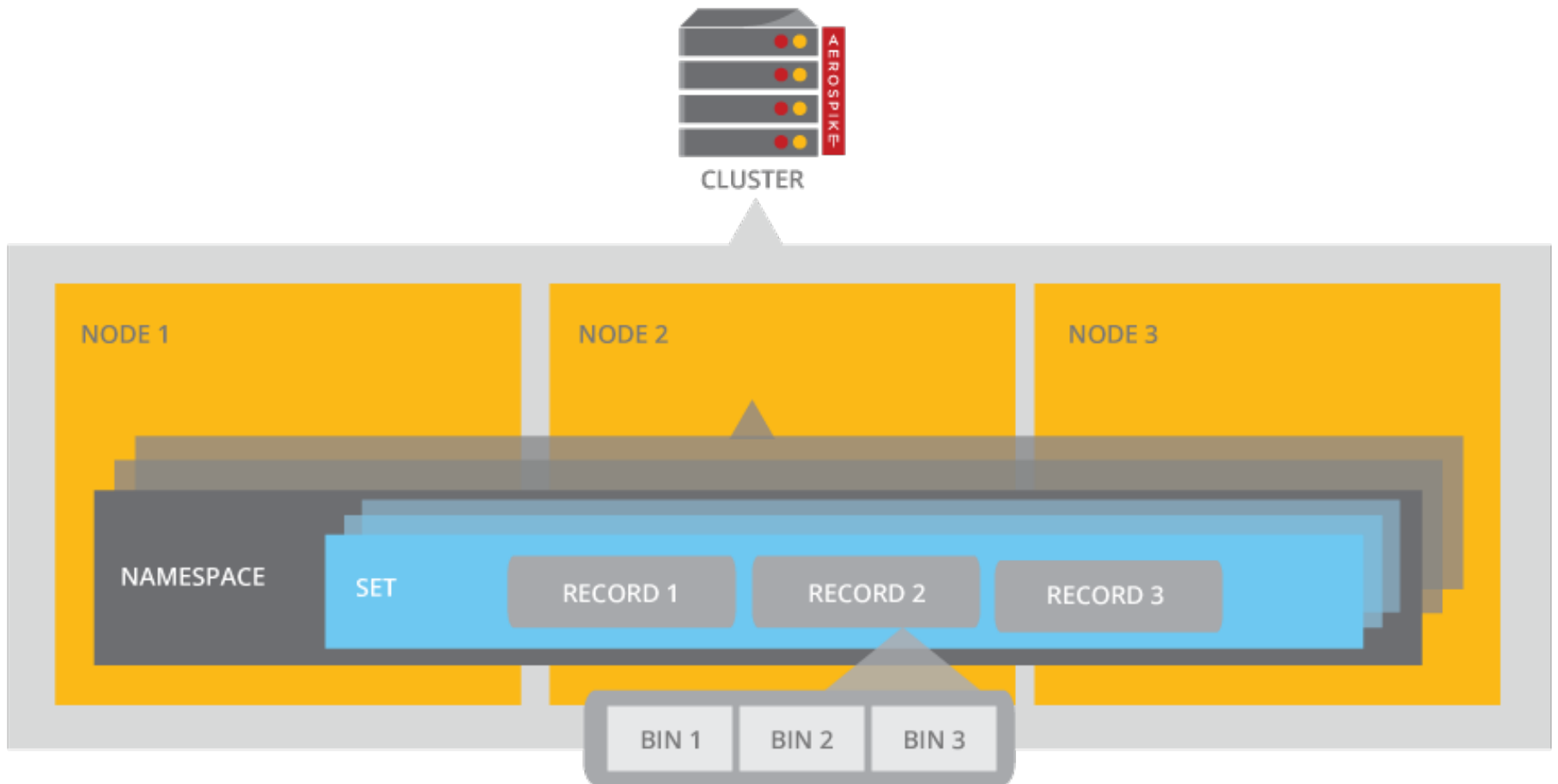
This module covers the following:

- Data hierarchy.
- High level architecture.
- Data partitioning.



# Data Hierarchy

# Data Hierarchy



# Nodes

- Each node should have **identical hardware**.
- Should have **identical configuration**.
- Data (and their associated traffic) will be **evenly balanced** across the nodes.
- Big **differences** between nodes implies a **problem**.
- Node **capacity** should take into account **node failure** patterns.

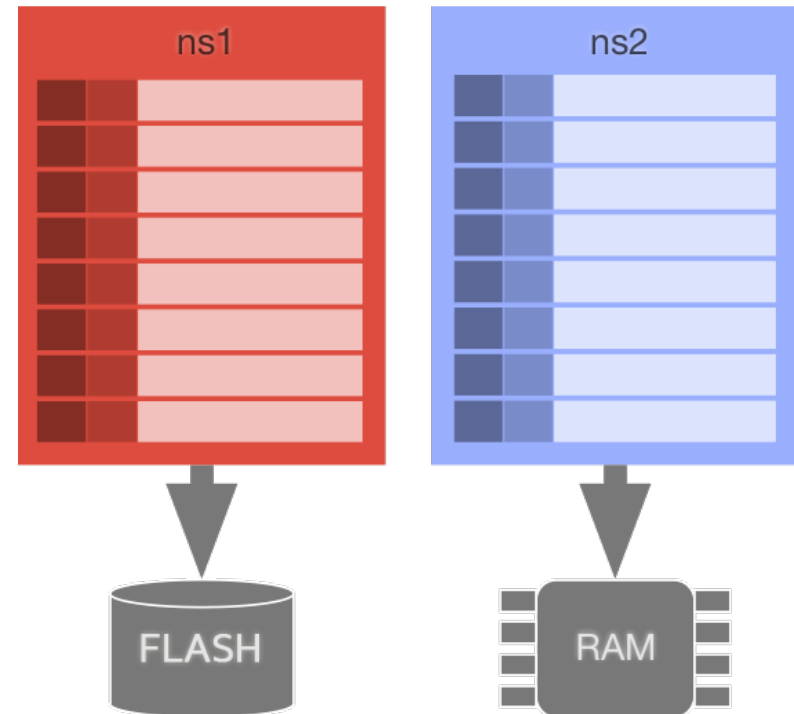
If you have an 8 node cluster distributed evenly on 4 racks, make sure that 6 nodes can handle the data and traffic volume in the event you lose a single rack.



# Namespace

Similar to a table space or database

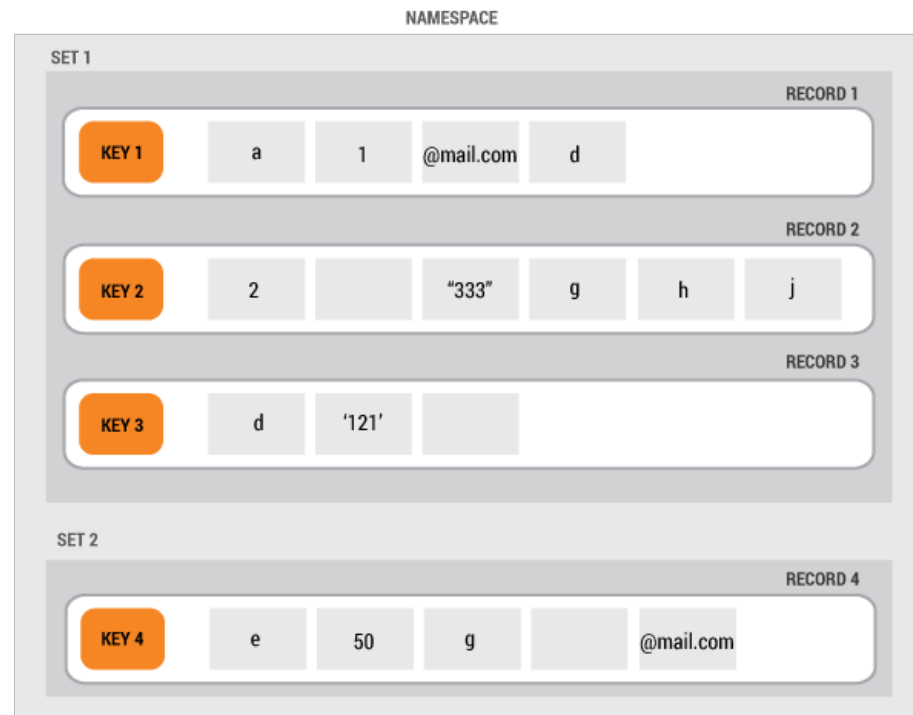
- **Storage** definition - DRAM or Flash
  - Hybrid
    - RAM for index and flash for data
  - RAM + disk for persistence only
    - RAM for index + data
  - RAM only
    - RAM for index + data
- **Policy** container
  - Replication factor
    - change requires cluster-wide restart
  - RAM and disk configuration
  - High-watermark
  - Default TTL - The client can override
    - TTL = 0 records never expire.
- **Difficult** to **add** or **remove**
  - Cluster wide restart - downtime



# Set

Sets are **similar** to tables

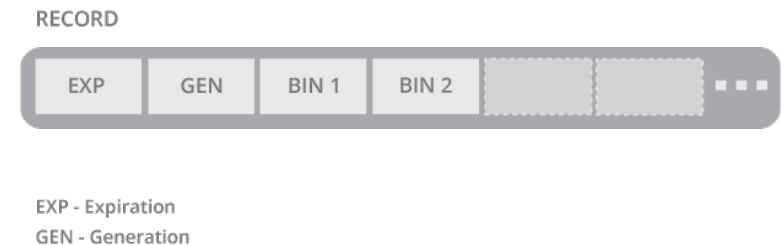
- But it has **no schema**
- Arbitrary grouping of records
- Inherits policy from namespace
- Prefix to **primary key**
- Set name  $\leq 63$  characters
- **1023** per namespace
- Cannot be deleted or renamed



# Record

A record is a “**row**” of Key-value – (Object)

- **Value**: one or more bins
- Bin has a **name and type**
  - Bin types: String, integer, double, BLOB, list, map, GeoJSON
- Bins can be added at any time
- **Generation** counter
  - Optimistic Concurrency
  - After 64K - reset to Zero
- **Time-to-live** = auto expiration
- Reads/Writes are **atomic**
- Any change = **complete rewrite**
- Data stored **contiguously** on the same node.





# Bins

- Bins have a:
  - Name – 14 characters or less
  - Type – one of the following
- A Bin can have a different type in another record
- One or more bins updated in a **single operation**
  - Increment (add)
  - Operate

Id	lname	fname	address	favorites
1	Able	John	123 First	cats, dogs, mice
2	Baker	916570	234 Second	
3	Charlie			
4	Delta	Moe	456 Fourth	stake, ice cream, apples

## Types

- String
- Integer
- Double
- Blob
- List
- Map
- GeoJSON

There is a limit of 32K bin names in a namespace.

Bin names cannot be deleted or renamed.

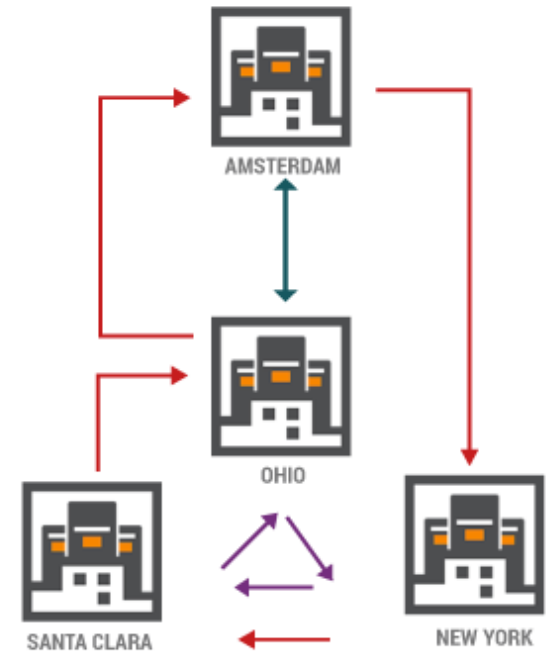
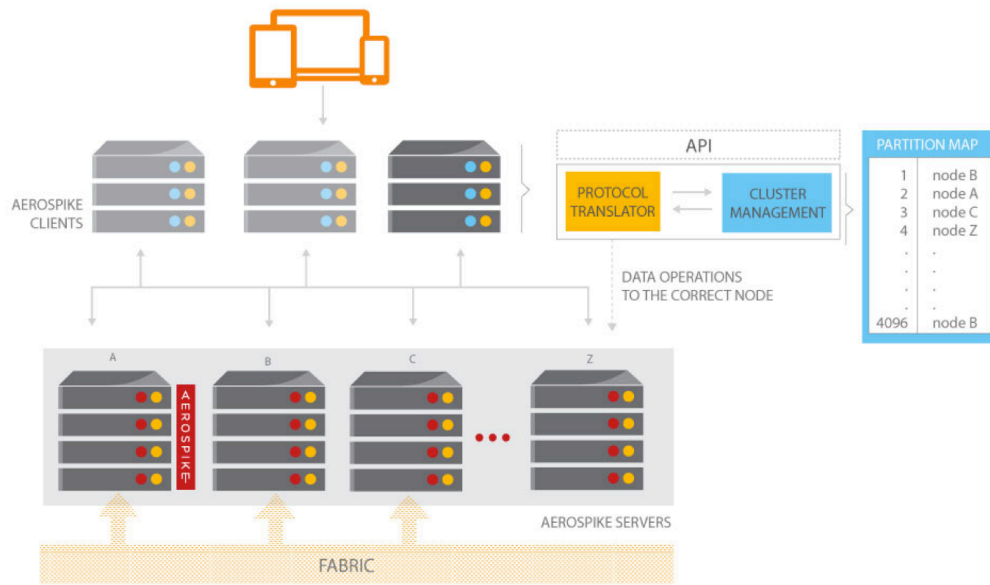
# Database Hierarchy

Term	RDBMs	Definition	Notes
Cluster	-	An Aerospike cluster services a single database service.	While a company may deploy multiple clusters, applications will only connect to a single cluster.
Node	-	A single instance of an Aerospike database. A node will act as a part of the whole cluster.	For production deployments, a host should only have a single node. For development, you may place more than one node on a host.
Namespace	Database	An area of storage related to the media. Can be either RAM or flash (SSD based). Setting up new/removing namespaces requires a cluster-wide restart.	
Set	Table	An unstructured grouping of data that has some commonality.	Similar to “tables” in a relational database, but do not require a schema.
Record	Row	A key and all data related to that key.	Aerospike always stores all data for a record on the same node.
Bin	Column	One part of data related to a key.	Bins in Aerospike are typed, but the same bin in different records can have different types. Bins are not required. Single bin optimizations are allowed.



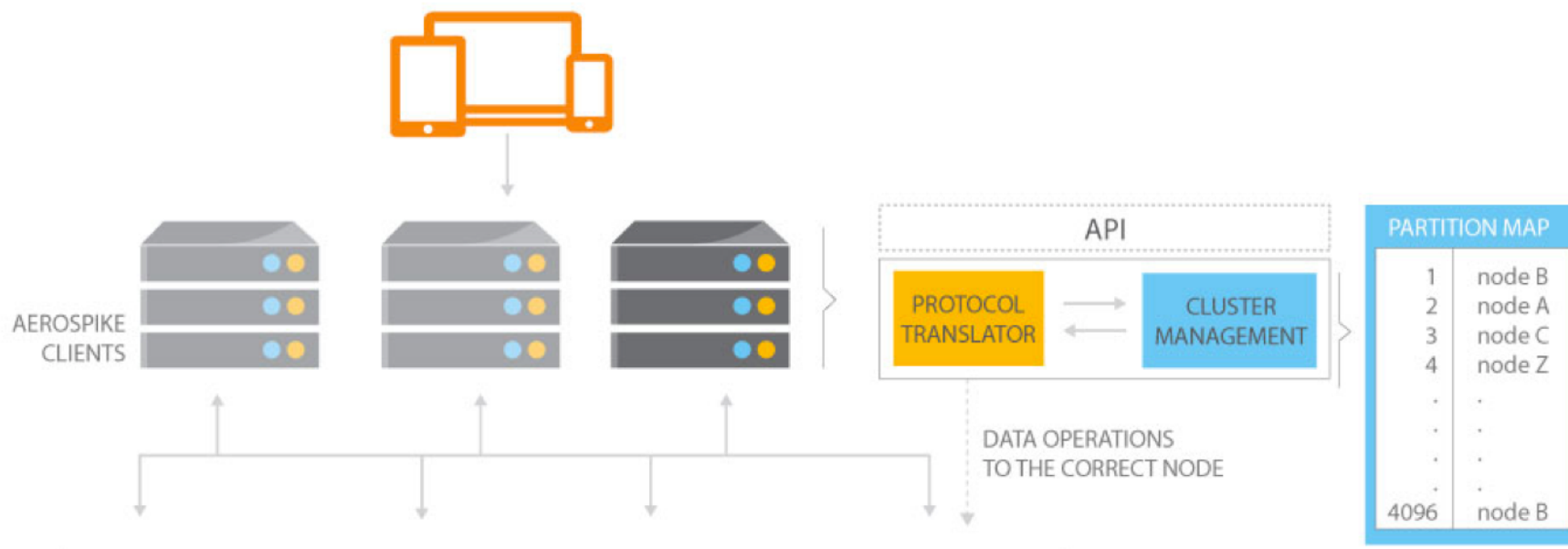
**Architecture**

# Architecture – The Big Picture



- 1) **No Hotspots**  
– Distributed Hash Table simplifies data partitioning
- 2) Smart Client – **1 hop** to data, no load balancers
- 3) **Shared Nothing Architecture**, every node is identical
- 4) Smart Cluster, **Zero Touch**  
– auto-failover, rebalancing, rolling upgrades
- 5) Operations and long-running tasks prioritized in real-time
- 6) **XDR** – sync replication across data centers ensures **Zero Downtime**

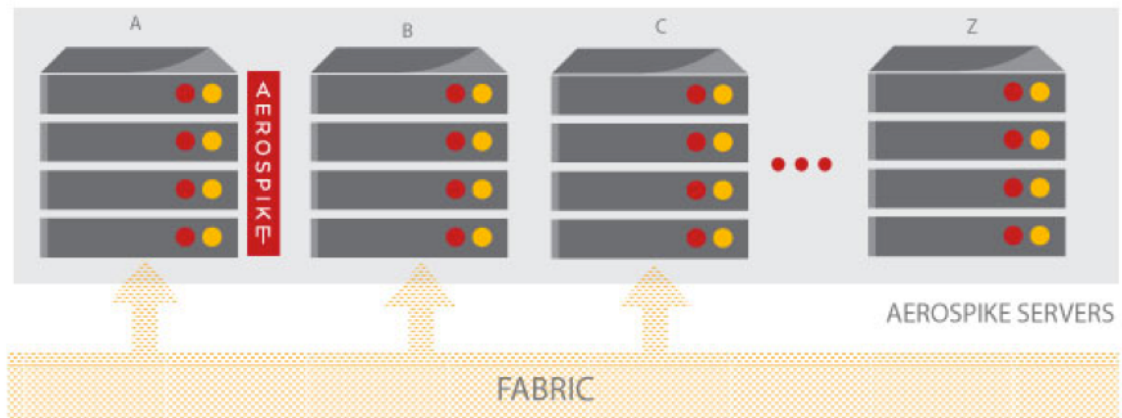
# Smart Client™



- The Aerospike Client is implemented as a **library**, JAR or DLL, and consists of 2 parts:
  - Operation APIs – These are the operations that you can execute on the cluster – **CRUD+** etc.
  - First class **observer** of the Cluster – Monitoring the state of each node and aware on new nodes or node failures.

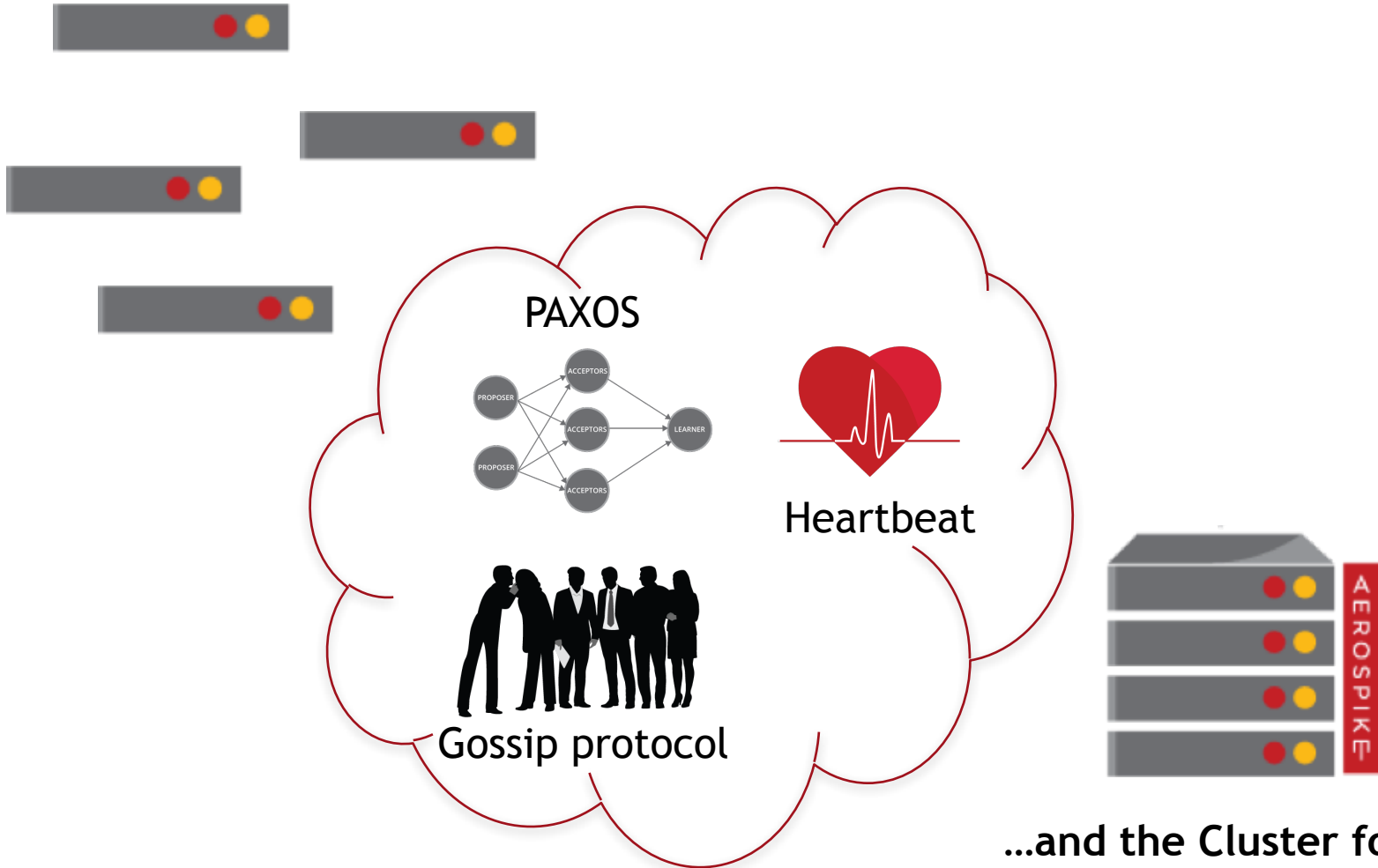
# The Cluster (servers)

- Federation of **local servers**
  - XDR to remote cluster
- Automatic **load balancing**
- Automatic **fail over**
- Detects **new nodes** (multicast or mesh)
- **Rebalances** data (measured rate)
- Adds nodes **under load**
- **Locally attached** storage



# Cluster formation

Individual nodes go in...



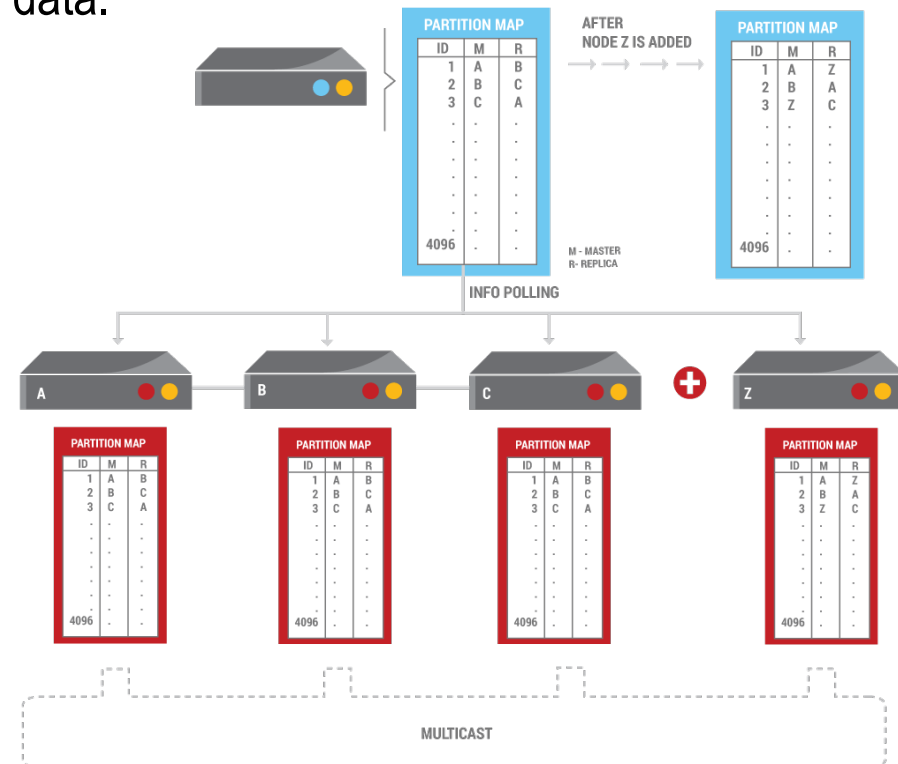
# Distributing Data: The Partition Map

Distributing data can be done in many ways. Aerospike has chosen a method that:

1. Automatically **balances** data across **nodes**.
2. Makes it easy to **migrate (rebalance)** should a node crash or be added.
3. Does not require the developer to understand how the data is **distributed**.
4. Takes into account **replica** copies of the data.

## 1 Hop to data

- Smart Client simply calculates Partition ID to determine Node ID
- No Load Balancers required





# Even record distribution

Application

AerospikeClient

Node A

Z'

Node B

Y'

Node C

X'

# Data is Distributed Randomly

cookie-abcdefg-12345678



182023kh15hh3kahdjsh



Partition ID	Master node	Replica node
...	1	4
1820	2	3
1821	3	2
4096	4	1

- Every key is hashed into a 20 byte (fixed length) string using the **RIPEMD160** hash function
- This hash + additional data (fixed 64 bytes) are stored in RAM in the index
- 12 bits of this hash are used to compute the partition id
- There are 4096 partitions
- Partition id maps to node id based on cluster membership

# Losing a Node

Let's take a 3 node cluster with 12 partitions and a replication factor of 2. When everything is stable, every thing will be evenly distributed.

Partition Map

Partition	Master	Replica
1	A	B
2	B	C
3	C	A
4	A	C
5	B	A
6	C	B
7	A	B
8	B	C
9	C	A
10	A	C
11	B	A
12	C	B

A

Mas	Rep
1	3
4	5
7	9
10	11

B

Mas	Rep
2	1
5	6
8	7
11	12

C

Mas	Rep
3	2
6	4
9	8
12	10

# Losing a Node

So what happens if a **node** dies?

Partition Map

Partition	Master	Replica
1	A	B
2	B	C
3	C	A
4	A	C
5	B	A
6	C	B
7	A	B
8	B	C
9	C	A
10	A	C
11	B	A
12	C	B

A

Mas	Rep
1	3
4	5
7	9
10	11

B

Mas	Rep
2	1
5	6
8	7
11	12

C

Mas	Rep
3	2
6	4
9	8
12	10

# Losing a Node

Some of the **partitions** will only have a single copy.

Partition Map

Partition	Master	Replica
1	A	B
2	B	C
3	C	A
4	A	C
5	B	A
6	C	B
7	A	B
8	B	C
9	C	A
10	A	C
11	B	A
12	C	B

A

Mas	Rep
1	3
4	5
7	9
10	11

B

Mas	Rep
2	1
5	6
8	7
11	12

C

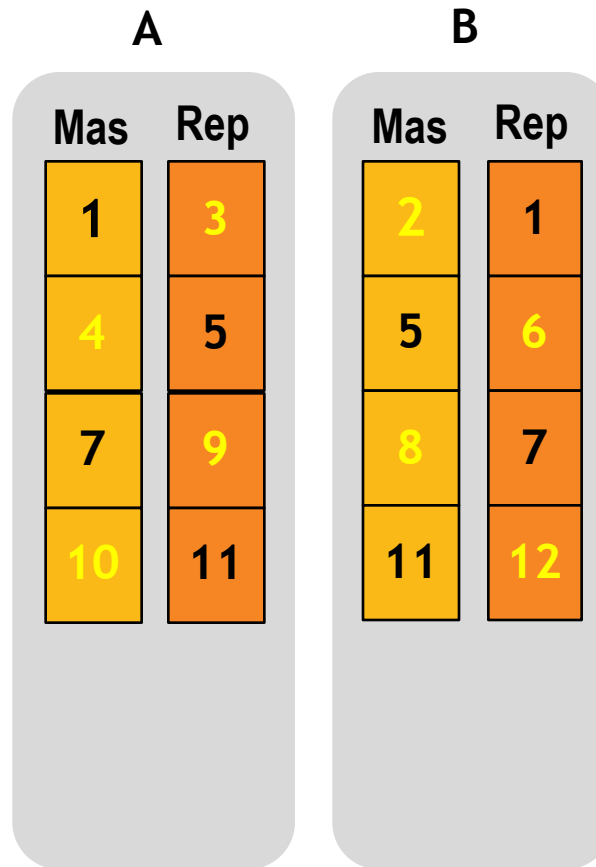
Mas	Rep
3	2
6	4
9	8
12	10

# Losing a Node

So the **cluster** will exclude the missing **node** and create a new **partition map**.

New Partition Map

Partition	Master	Replica
1	A	B
2	B	A
3	B	A
4	A	B
5	B	A
6	A	B
7	A	B
8	B	A
9	B	A
10	A	B
11	B	A
12	A	B

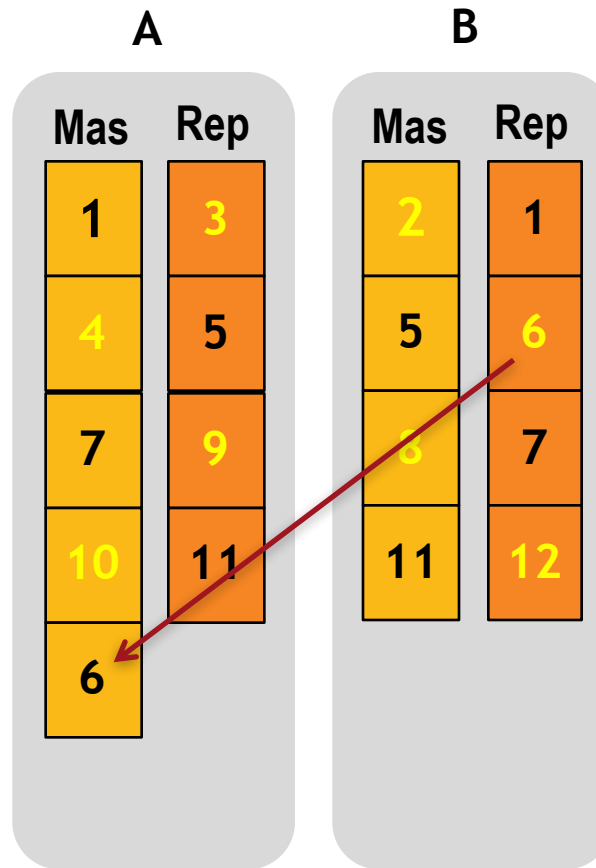


# Losing a Node

It will then begin to make copies of all the data

New Partition Map

Partition	Master	Replica
1	A	B
2	B	A
3	B	A
4	A	B
5	B	A
6	A	B
7	A	B
8	B	A
9	B	A
10	A	B
11	B	A
12	A	B



# Losing a Node

Once it has completed all the **partitions**, the **cluster** will be in a stable state again. With 2 full copies of all data.

New Partition Map

Partition	Master	Replica
1	A	B
2	B	A
3	B	A
4	A	B
5	B	A
6	A	B
7	A	B
8	B	A
9	B	A
10	A	B
11	B	A
12	A	B

A		B	
Mas	Rep	Mas	Rep
1	3	2	1
4	5	5	6
7	9	8	7
10	11	11	12
6	2	3	4
12	8	9	10

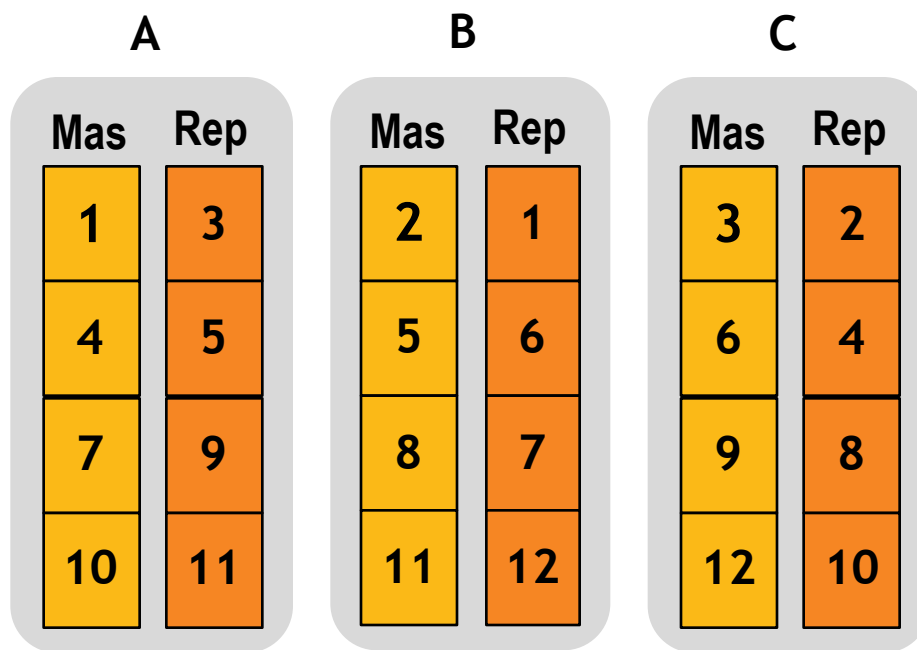


# Adding a Node

Now let's start with the same situation, but add a **node** this time. The same starting state: 12 **partitions**, 3 **nodes**, **replication factor** of 2.

Partition Map

Partition	Master	Replica
1	A	B
2	B	C
3	C	A
4	A	C
5	B	A
6	C	B
7	A	B
8	B	C
9	C	A
10	A	C
11	B	A
12	C	B



# Adding a Node

When the new **node** is added, it starts empty.

Partition Map

Partition	Master	Replica
1	A	B
2	B	C
3	C	A
4	A	C
5	B	A
6	C	B
7	A	B
8	B	C
9	C	A
10	A	C
11	B	A
12	C	B

A

Mas	Rep
1	3
4	5
7	9
10	11

B

Mas	Rep
2	1
5	6
8	7
11	12

C

Mas	Rep
3	2
6	4
9	8
12	10

D

Mas	Rep
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# Adding a Node

The cluster creates a new **partition map**, with the new **node** included.

Partition Map

Partition	Master	Replica
1	A	B
2	B	D
3	C	A
4	D	C
5	B	A
6	C	B
7	A	D
8	D	C
9	C	A
10	A	C
11	B	D
12	D	B

A

Mas	Rep
1	3
4	5
7	9
10	11

B

Mas	Rep
2	1
5	6
8	7
11	12

C

Mas	Rep
3	2
6	4
9	8
12	10

D

Mas	Rep
-----	-----

# Adding a Node

The cluster will then **migrate (rebalance)** the **partitions**, one at a time to the new **node**. During this time it is possible for the **partition map** to be out of sync with the actual data distribution. Aerospike **nodes** will **proxy** the request.

Partition Map

Partition	Master	Replica
1	A	B
2	B	D
3	C	A
4	D	C
5	B	A
6	C	B
7	A	D
8	D	C
9	C	A
10	A	C
11	B	D
12	D	B

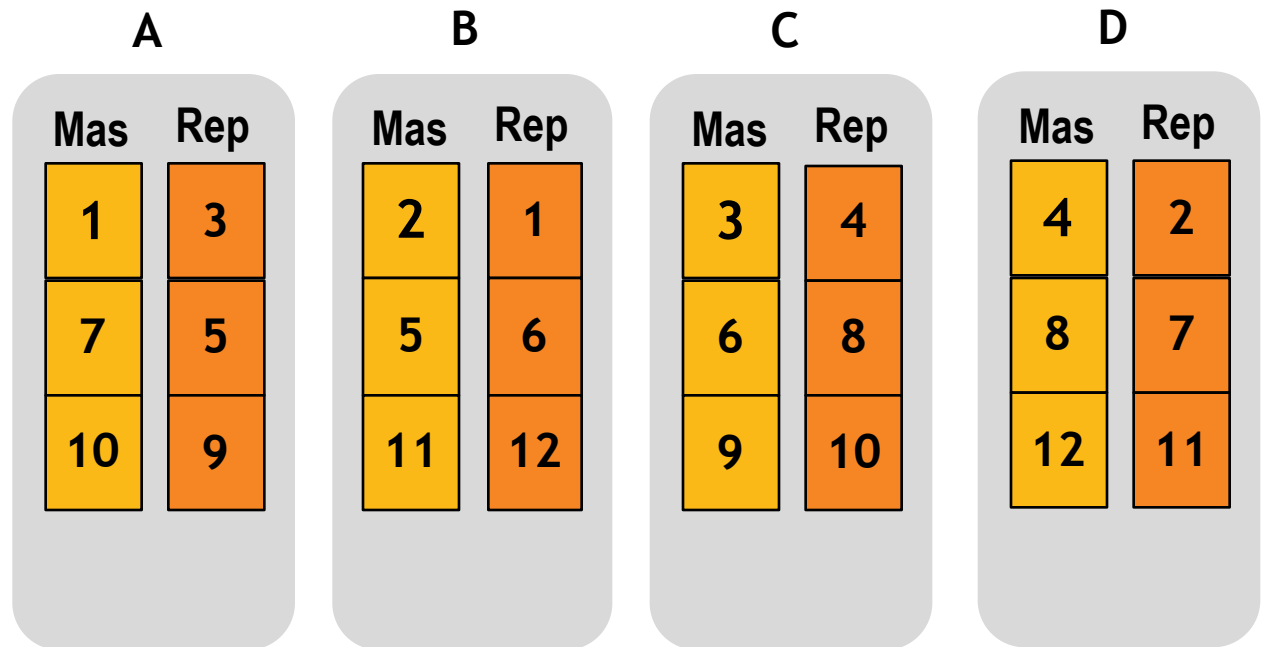


# Adding a Node

Once all the **partitions** have **migrated**, the database will be in a new stable state, with **replicated** copies of all data again.

Partition Map

Partition	Master	Replica
1	A	B
2	B	D
3	C	A
4	D	C
5	B	A
6	C	B
7	A	D
8	D	C
9	C	A
10	A	C
11	B	D
12	D	B



# Summary

In this module, we covered:

- Data hierarchy.
- High level architecture.
- Data partitioning.