



## Class List

IR I/P                      Error  
 Motor                      (x2)  
 LED  
 Buzzer  
 LCD  
 USB Debug  
 Bluetooth I/P  
 Sonar I/P  
 System State.

## Dev Sequence

- ① Led Lcd - Blink ✓
- ② State M/c follow call → Func → Return status  
status Report
- ③ Motor test α
- ④ Buzzer / IR I/P → LCD
- ⑤ Bluetooth I/P → LCD
- ⑥ Motor control by IR / Bluetooth
- ⑦ Ultra sonics stay Xcm from wall.