



# 影像特徵的研究

#### 目標任務

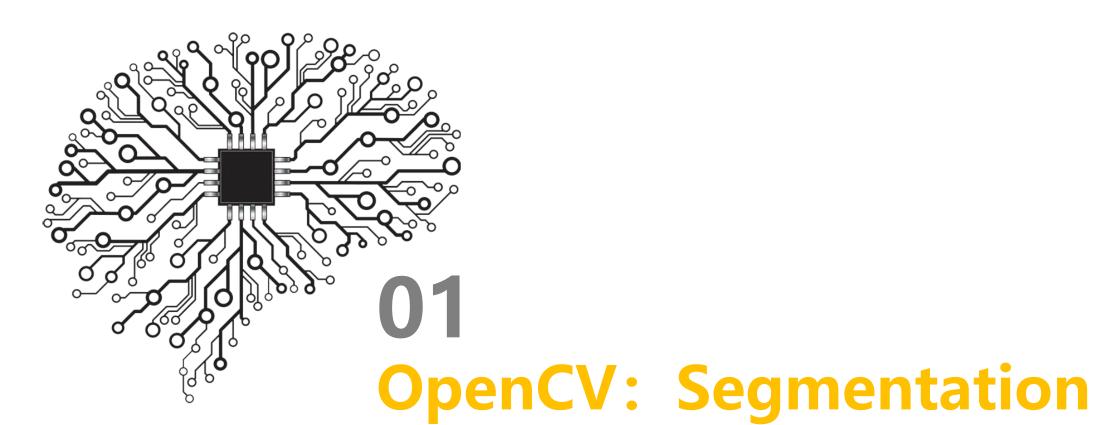


利用影像特徵進行影像處理操作。先對影像做(1)二值化(Image Binarization), (2)標籤化 (Labeling)並計算特徵參數, 再由特徵參數分割影像

- 1. 先對目標影像進行二值化,門檻值設為55
- 2. 影像標籤化並計算特徵參數
- 3. 將面積小於100的標籤連通元件去除
- 4. 將剩餘的標籤連通元件透過輪廓偵測計算周長和真圓度
- 5. 將真圓度小於0.5的標籤連通元件去除, 為了留下圓形的物體







### 影像二值化





```
def Binarization(image, threshold=55):
    grayImage = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
    ret, binaryImage = cv2.threshold(
    return grayImage, binaryImage
```

✓ 門檻值: 55

✓ Threshold Type: cv2.THRESH\_BINARY





- 將影像進行標籤化,並且取得連通元件
- 影像標籤化
  - □ cv2.connectedComponentsWithStats(image[, labels[, stats[, centroids[, connectivity[, ltype]]]])

```
def ImageLabeling(image, grayImage, binaryImage):
    kernel = cv2.getStructuringElement(cv2.MORPH_RECT, (3, 3))
    binaryClose = cv2.dilate(binaryImage, kernel, iterations=2)
    numLabels, labels, stats, centers = cv2.connectedComponentsWithStats(
```

✓ Connectivity: 8

 $\checkmark$  ltype: cv2.CV\_32S





■ 計算特徵參數,並且去除面積小於100的連通元件

```
labelingImage = np.copy(image)
segmentationImage = np.zeros(binaryImage.shape, dtype=np.uint8)
contourImage = np.zeros(binaryImage.shape, dtype=np.uint8)
for i in range(1, numLabels):
    x, y, w, h, area = stats[i]
    cx, cy = centers[i]
    if area <= ____:
        continue
    for row in range(image.shape[0]):
        if labels[row, col] != i:
            continue
        contourImage[row, col] = 255</pre>
```





✓ image : contourImage ✓ mode : cv2.RETR\_EXTERNAL 計算剩餘標籤連通元件的周長和真圓度 ✓ method : cv2.CHAIN\_APPROX\_SIMPLE □ 取得輪廓資訊用: ✓ cv2.findContours(image, mode, method[, contours[, hierarchy[, offset]]]) □ 取得物體輪廓資訊用(預設物體為白色): ✓ cv2.drawContours(image, contours, contourldx, color[, thickness[, lineType[, hierarchy[, maxLevel[, offset]]]]]) □ 計算周長: ✓ image : labelingImage ✓ Curve: cnt ✓ cv2.arclength(curve, closed) ✓ contours : contours ✓ Closed: True ✓ contourIdx : -1 □ 計算直圓度用:  $\checkmark$  color : (255, 0, 0) ✓ 4 \* numpy.pi \* 面積 / (周長)^2 ✓ thickness: 1

```
contours, hierarchy = cv2.findContours(
labelingImage = cv2.drawContours(
cnt = contours[0]
perimeter = cv2.arcLength(
cv2.circle(labelingImage, (int(cx), int(cy)), 2, (0, 255, 0), 2, 8, 0)
cv2.rectangle(labelingImage, (x, y), (x+w, y+h), (0, 0, 255), 1, 8, 0)
cv2.putText(labelingImage, f'No. {i}', (x, y-10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 255), 1)
print(f'No. {i} 周長: {perimeter:.2f}, 面積: {area:.2f},真圆度: {e:.2f}')
```





■ 將真圓度小於0.5的標籤連通元件去除,以留下圓形的物體

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```
def ImageLabeling(image, grayImage, binaryImage):
    kernel = cv2.getStructuringElement(cv2.MORPH RECT, (3, 3))
    binaryClose = cv2.dilate(binaryImage, kernel, iterations=2)
    numLabels, labels, stats, centers = cv2.connectedComponentsWithStats(binaryClose, connectivity=8, ltype=cv2.CV_32S)
    labelingImage = np.copy(image)
    segmentationImage = np.zeros(binaryImage.shape, dtype=np.uint8)
    contourImage = np.zeros(binaryImage.shape, dtype=np.uint8)
    for i in range(1, numLabels):
        x, y, w, h, area = stats[i]
        cx, cy = centers[i]
        if area <=
           continue
        for row in range(image.shape[0]):
           for col in range(image.shape[1]):
               if labels[row, col] != i:
                    continue
               contourImage[row, col] = 255
       contours, hierarchy = cv2.findContours(
        labelingImage = cv2.drawContours()
        cnt = contours[0]
        perimeter = cv2.arcLength(
        e =
        cv2.circle(labelingImage, (int(cx), int(cy)), 2, (0, 255, 0), 2, 8, 0)
       cv2.rectangle(labelingImage, (x, y), (x+w, y+h), (0, 0, 255), 1, 8, 0)
        cv2.putText(labelingImage, f'No. {i}', (x, y-10), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 255), 1)
        print(f'No. {i} 周長: {perimeter:.2f}, 面積: {area:.2f},真圓度: {e:.2f}')
        if e <
            continue
        for row in range(image.shape[0]):
           for col in range(image.shape[1]):
               if labels[row, col] != i:
                   continue
               segmentationImage[row, col] = 255
    return contourImage, segmentationImage, labelingImage
```

#### 主程式





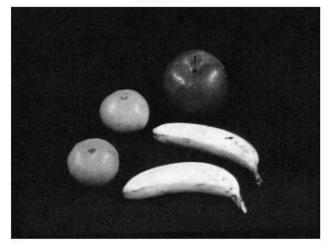
```
import cv2
import numpy as np
from matplotlib import pyplot as plt
image = cv2.imread('./fruit.bmp')
grayImage, binaryImage = Binarization(image)
contourImage, segmentationImage, labelingImage = ImageLabeling(image, grayImage, binaryImage)
images = [image, binaryImage, contourImage, segmentationImage, labelingImage]
titles = ['ORIGINAL', 'BINARY', 'CONTOUR', 'SEGMENTATION', 'LABELING']
plt.figure()
for i in range(len(images)):
   plt.subplot(2, 3, i+1), plt.imshow(images[i], 'gray')
   plt.title(titles[i])
   plt.xticks([]), plt.yticks([])
plt.show()
```

### 需呈現之結果

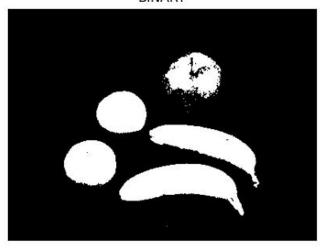


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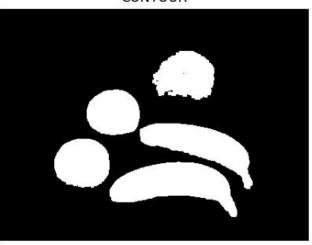
ORIGINAL

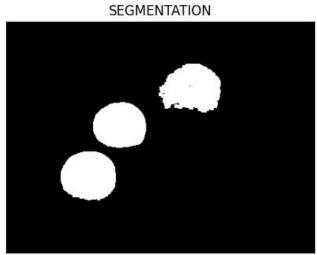


**BINARY** 

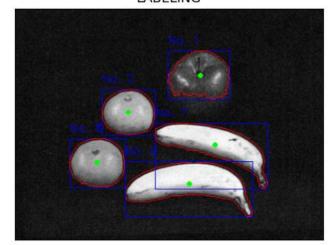


CONTOUR





**LABELING** 







# Thanks for listening