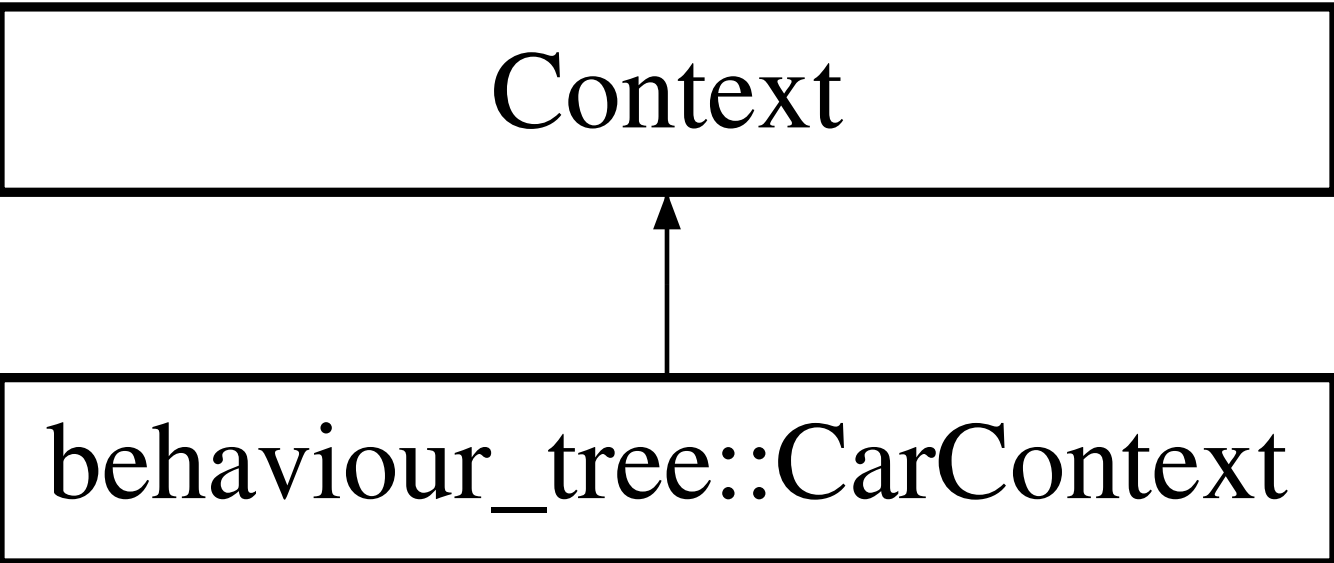
Context
behaviour_tree::CarContext