



# About the Beamer class in presentation making

## A short story

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### **Definition 1 (Plant)**

*A plant automaton is a tuple  $\mathcal{P} = (Q, \Sigma_c, \delta, q)$  where  $Q$  is a finite set of states,  $\Sigma_c$  is a set of controller commands,  $\delta : Q \times \Sigma_c \mapsto 2^Q$  is the transition function and  $q_o \in Q$  is an initial state.*

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