# Topological Manifolds: A Categorical Perspective

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### October 14, 2024

In this paper, we discuss how topological manifolds play a crucial role in geometric mathematics. Recall that a topological manifold is a finite-dimensional space with additional structure of topological orders. The most obvious example of a topological manifold is the space S itself (so called the k-manifold). Given a point  $x \in S$ , its neighborhood has a total ordering. In the present paper, we show that we have two key theorems that relate these two types of topological manifolds: (1) the topology on the set of points in a topological manifold can be reduced to the set of elements that are contained in any topology order on the space; and (2) topological manifolds are defined as spaces equipped with a topology (and thus a topology-preserving inclusion functor). Topologists commonly think of manifolds as objects for their topology, whereas mathematicians, on the other hand, believe that manifolds are data for their topology.

A more concrete, more detailed perspective on topological manifolds will be presented in Section 3, where we construct an extended category of manifolds, which we call  $_{\infty}$  and show how it plays a role in geometric theory. We then make use of this construction to provide new results concerning manifolds. For instance, we introduce a class of topological manifolds, known as  $_{\infty}$ , that we characterize by a property analogous to that of equivalences in various categories; and we prove the following result:

[[?, Theorem 6.17]] If a set X is equivariant, then so are its images. More precisely, let X be a subspace of a topological manifold and suppose that the image of its base point contains every element of X. Then X is equivalent to any subset of the image.

Recall that a manifold (M, d) is equivalent to its connected product if the connected component containing each vertex in M is a finite n-manifold. Recall that n is the number of vertices in M. For each edge (u, v) in M, its connected component  $(u, v) \subseteq M$  can be regarded as being a subspace of M. Furthermore, given two topological edges (u, v) and (w, x) in M, we say that (w, x) belongs to (u, v) if there exists a common vertex (y) such that (w, x) = (y, v). This gives a notion of topological intersection:

Let (M,d) be a topological manifold. An edge in M is said to belong to M if for any  $y \in M$  and any  $x \in (u,v)$ ,  $x \leq y$ . Thus, an edge f in M intersects  $(M_f,d_f)$  if for any  $y \in M_f$  and any  $x \in (u,v)$ , there exists  $z \in M$  such that  $f = y \cup z$ , i.e.,

$$f = y \cup zandx \le y$$
.

A pair (M, d) and (M', d') are said to be topologically intersected if  $(M', d') = (M, d) \cap (M', d')$ .

Let M be a topological manifold. Given a topological edge (u,v) in M, define its intersection (u',v') as follows:

$$u' := min\{(x : (u', v)) \mid x \in (u, v)\}.$$

This edge is said to be a co-topological edge if the intersection edge is a cotopology. For example, let  $M =_{3,2}^*$  be the regular triangle manifold. There are two co-topological edges (0,1) and (1,2), which correspond to co-edge labels of the form (i+j)modn. Note that co-edges have no special meaning in this diagram. Let x=0 be the co-topology of the regular triangle M. By definition, x is a maximal co-edge of (0,1) since (0,1) lies in the co-topology of the regular triangle M. However,  $(0,1) \subseteq M$  is a co-topological edge because M is a regular triangle manifold. Moreover,  $(0,1) = (0,1) \cup (1,2)$ , so that x is a maximal coedge of  $(0,1) \cup (1,2)$ , too. Hence, we get the following definitions:

- $(M, (M')) \cong (M')$  if M and M' are topologically equivalent;
- $_{\infty}(M,_{\infty}(M',d_f)) \cong_{\infty} (M',d_f)$  if the intersection  $M \cap M'$  is topologically equivalent;
- M is a topological manifold if it has only one co-edge;
- M is complete if for all  $u, v \in M$  there exists a co-edge (u', v') between them, satisfying  $u' \le v'$  and  $(u', v') \in x$  for some co-topology x.

In order to define the topology of manifolds as a field, we recall the following lemma from [?, §5.3].

If M is a topological manifold, then the induced -linear field of the space of points of M forms a manifold over  $^{n}$ .

The map  $m:^n \to M$  is defined as follows:

$$m(x) := x$$
.

Since M is a topological manifold, every point of M is a point of M. Therefore, a point is a point of M if and only if it lies in the domain of m. Thus, if m is well-defined and sends a point x to a point of M, then x belongs to M. In particular,  $_{\infty}(M,M')\cong_{\infty}(M')$ . Hence, this map is a field homomorphism.

We define the set  $E_{\infty}(M,)$  as the set of cohomology groups over obtained by projecting onto M induced by the equivalence classes  $(u,v)\subseteq M$  of cotopological edges. The cohomology group  $E_{\infty}(M,)$  is a localizing cohomology group, a generalization of the Laplacian cohomology group. It is always a compact object in the category  $\infty$ .

Let M be a topological manifold. The map  $_{E_{\infty}}^{\infty}(M,) \to \text{is an isometry, i.e.,}$  the following condition holds: for any  $x \in M$ , if  $x \in_{E_{\infty}}^{\infty}(M,)$ , then  $x \in M$ .

Given M and  $x \in M$ , define

$$\alpha_x := \lim_{y \in \sum_{\infty}^{\infty} (M,)} (-1)^r \int_{\sum_{x \in \Sigma} (y,)} d^n x,$$

where r is the integer root of the number of points in M satisfying  $x \in_{E_{\infty}}^{\infty} (M,)$  and  $\alpha_x = \frac{1}{N}$ . Denote by  $z \geq 0$  the largest element such that  $\alpha_z > 0$ . As x belongs to the set of points of M, it suffices to prove that  $\alpha_z < 0$ .

For this, note that  $^n \subseteq M$  consists of N points, and so, by construction,  $\alpha_z = -1$ . This proves the claim.

Note that a globalizing cohomology group is in fact a locally localizing cohomology group. Indeed, if M and N are both localizing cohomology groups and there exists an inverse mapping  $m:N\to M$  such that  $M=^\infty_{E_\infty}(N,)=^\infty_{E_\infty}(M,)$ , then the inverse mapping m defines a unique mapping  $m':M\to N$  as follows:

$$m'(x) = \{ 0 \ x \notin_{E_{\infty}}^{\infty} (M,) xx \in_{E_{\infty}}^{\infty} (M,).$$

In particular, we obtain the following result:

Let M be a topological manifold. The -linear map

$$_{E_{\infty}}^{\infty}(M,) \to$$

is an inverse isometry of the space  $\sum_{E_{\infty}}^{\infty}(M,)$ , i.e., the following conditions hold: for any  $x \in M$ , if  $x \in \sum_{E_{\infty}}^{\infty}(M,)$ , then  $x \in M$ .

In order to show the result above, it is necessary to define the maps  $\alpha_x$  for all  $x \in M$  below.

Let M be a topological manifold. Consider the map  $\delta_{\infty}(M): M \to M$  as defined above, taking limits along all cohomology groups in  $E_{\infty}^{\infty}(M, M)$ .

Suppose M is a topological manifold and  $x \in M$ . Then, for any  $n \geq 0$ , the map  $\delta_{\infty}(M)$  is a continuous monotone function, that is,

$$\delta_{\infty}(M)(n) \le \frac{1}{\sqrt{n!}} \sum_{i=1}^{n} \delta_{\infty}((i,j))(x).$$

This is simply a summation using Lemma??.

Since  $\delta_{\infty}(M)$  is a monotone function, we define the following map  $\alpha_x$  to be the limit:

$$\alpha_x := \lim_{y \in \sum_{\infty}^{\infty} (M,)} (-1)^r \int_{\frac{\infty}{E}} \int_{(y,)} d^x n \, d^$$

This is just the limit for the standard limit:

$$\lim_{y \in \frac{\infty}{E_{\infty}}(M,)} (-1)^r \int_{\frac{\infty}{E_{\infty}}(y,)} d^x n \leq \lim_{y \in \frac{\infty}{E_{\infty}}(M,)} \left( \frac{1}{\sqrt{n!}} \sum_{i=1}^n \delta_{\infty}((i,j))(x) \right) \leq \frac{1}{\sqrt{n!}} \sum_{i=1}^n \delta_{\infty}((i,j))(x) \leq \frac{1}{\sqrt{n!}} \delta_{\infty}(M)(n) \leq \frac{1}{\sqrt{n!}} \sum_{i=1}^n \delta_{\infty}((i,j))(x) \leq \frac{1}{\sqrt{n!$$

since  $\delta_{\infty}(M)(n) \leq \frac{1}{\sqrt{n!}} \delta_{\infty}((n,n)) = 1$  for all  $n \geq 1$ .

Finally, we establish the following result:

Let M be a topological manifold. The map  $\alpha_x$  is a continuous monotone function, that is,

$$\alpha_x(n) \le \frac{1}{\sqrt{n!}} \sum_{i=1}^n \delta_{\infty}((i,j))(x).$$

The argument above applies directly to the set of all points in M.

The following observation shows us that a topological manifold is a complete manifold if and only if it contains no co-edges.

It is clear that  ${\infty}_{E_{\infty}}(M,)$  is a compact object in the category  ${\infty}$ .

If M is a topological manifold and  $\sum_{E_{\infty}}^{\infty}(M,)$  is a compact object in  $\infty$ , then  $\sum_{E_{\infty}}^{\infty}(M,)$  is an exact manifold, a topological manifold is an exact manifold, and the map  $\alpha_x$  is a continuous function.

Let M be a topological manifold.  $\sum_{E_{\infty}}^{\infty}(M, 1)$  is an exact manifold. Moreover, the map  $\alpha_x$  is a continuous function.

### 0.1 Definitions, Notations and Conventions

We fix an initial base point a of M. The set (a) is denoted by  $\mathcal{P}_M = \{p \in M | (p, a) = 0\}$ . Note that there is exactly one base point for each M.

Given an edge e in M, the set (e) is denoted by  $\mathcal{E}_M(e)$ . Note that, for each vertex  $v \in M$ , there exist only one nonzero edge connecting v with any other vertex. That is, (v, w) = 0 for all  $v, w \neq v$ . Similarly, the set (e) is also denoted by  $\mathcal{E}_M(e)$ .

To denote the topological space  $_{E_{\infty}}^{\infty}(M,)$ , we employ the symbol  $\Omega$  to indicate that the set of objects does not include the identity element; and we adopt the notation  $\Omega^*$  to indicate that the set includes the identity element.

In the case where M is a topology of S and S is a subspace of M, we shall write  $S \subseteq_{E_{\infty}}^{\infty} (M,)$ . In this way, we refer to the subspace  $_{E_{\infty}}^{\infty}(M,)$  as the *canonical subspace* of M. Indeed, the set  $_{E_{\infty}}^{\infty}(M,)$  is equivalent to the full subcategory consisting of the objects of the form (M,).

To emphasise the difference between  $\sum_{E_{\infty}}^{\infty}(M,)$  and  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}$  in terms of the definition of the full subcategory  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}$ , which we abbreviate as  $C_{E_{\infty}}^{\infty}(M,)^{\Omega}$ . For each point a of M,  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}(a)$  is the set of closed curves containing a. Using these definitions, we may write the equivalence relation as follows:

If  $(M,) \subseteq C_{E_{\infty}}^{\infty}(M,)^{\Omega}$ , then the relations  $>\sim$  and  $<\sim$  between  $p\sim q$  means

[thick](0, -.65)circle(.05); [-stealth, fill=](-.65, 0) - -(.65, 0); [thick, fill=](.35, -.65)circle(.05); [-stealth, fill=](-.65, 0) - -(.65, 0); [thick, fill=](-.65, 0); [thick, fill=](-.65, 0); [thick, fill=](-.65, 0) - -(.65, 0); [thick, fill=](-.65, 0

at (.4,-.3)  $(p \sim q)$ ; at (-.4,-.3) <; = {  $forp > qandpisaclosed curve containing a}; for qisaclosed curve containing a}; 0 otherwise. (1)$ 

Thus, the space of open curves containing a is denoted by  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}(a)$ . Note that  $\mathcal{E}_{M}(e) = \mathcal{E}_{M}(e \cup e^{-1})$ .

Recall that the space of morphisms in  $\sum_{E_{\infty}}^{\infty}(M,)$  is denoted by  $\Delta_{\infty}(M)$  or simply  $\Delta(M)$ . This space is a family of functions  $\omega:_{E_{\infty}}^{\infty}(M,) \to$ , such that  $\omega(p) \leq \omega(q)$  if p < q. The morphisms are denoted by  $\omega^{(0)}$  and  $\omega^{(1)}$ . Recall that, for each  $n \geq 0$ ,  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}$  is a space of compact objects, hence the set of morphisms in  $\Delta_{\infty}(M)$  is the same as the set of morphisms in  $\sum_{E_{\infty}}^{\infty}(M,)$  since, for any  $n \geq 0$ ,  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}$  is a compact object. Moreover, the canonical inclusion functor is an inclusion of spaces.

It is natural to ask whether the class  $\Omega \times M$  of functions  $\omega^{(i)}$  is the class of functions in  $\Omega$  (respectively  $\Omega$ ). To do so, let M be a topology of S and S is a subspace of M. Assume that there is an inverse map  $m: \Omega \times M \to \Omega$  such that  $\Omega =_{E_{\infty}}^{\infty} (M,)^{\Omega}$ . We then define the class of functions  $\omega^{(0)}: \Omega \to \text{such that } m^{-1}(x) \leq x$  for all  $x \in M$ . Define  $\omega^{(1)}: \Omega \times M \to \text{by } \omega^{(1)}(y) := \omega^{(0)}(m^{-1}(y))$ . Clearly,  $\omega^{(1)}(x) \leq \omega^{(0)}(x)$  for all  $x \in M$ , and clearly  $\omega^{(1)}(y) \leq m(x)$  for all  $y \in \Omega$ . Using the definitions, we obtain a family of functions  $\omega:_{E_{\infty}}^{\infty} (M,)^{\Omega} \to \text{such that}$ 

$$\omega^{(0)} = \omega^{(0)\prime} + \epsilon,$$

where  $\omega^{(0)}{}'$  is the restriction to  $\Omega$  of the *i*-th projection to  $\Omega$ ,  $\epsilon = (\omega^{(1)} - \omega^{(0)})^{-1}$ . The restriction of a 2-morphism  $\phi: y \to x$  to  $\Omega$  corresponds to choosing the 2-morphism  $\phi' = \phi^{-1}: \Omega^2 \to M$  such that  $\phi' \circ_M = m$ . From here on, we shall say

that  $\omega^{(i)}$  is a morphism. By convention, we use  $\omega^{(0)}$  to denote the projection map  $\omega^{(0)\prime}: \Omega \times M \to \Omega$ , and  $\omega^{(1)\prime}$  for the inclusion map  $m^{-1}$ .

The class of functions  $\omega^{(0)}$  and  $\omega^{(1)}$  defined above are defined by defining the morphisms  $\omega^{(i)}$  in  $\Delta_{\infty}(M)$ :

$$\omega^{(i)} = \{ \omega^{(i)}' ifi < 1, \omega^{(i-1)'} \circ \phi + \epsilon otherwise. \}$$

We shall often consider the set of functions  $\omega^{(0)}$  and  $\omega^{(1)}$  in  $\Delta_{\infty}(M)$  together with the following relation:

For any  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ , the function  $\omega :_{E_{\infty}}^{\infty} (M,)^{\Omega} \to \text{is an isometry, i.e., for}$ all  $n \ge 0$ ,  $\omega(n) = \omega(n)'$ .

The argument is similar to Proposition.

Similar to  $\Omega$ , we often use the symbol  $\Omega^*$  to indicate that the set of objects does not include the identity element; and we adopt the notation  $\Omega^*$  to indicate that the set includes the identity element. In particular, we must define  $\Delta_{\infty}(M)$ as the intersection of  $\frac{\infty}{E_{\infty}}(M,)^{\Omega}$  with the set of points of M. Recall that the set of points of M is the closure under the inclusion functor  $\sum_{R_{\infty}}^{\infty} (M,)^{\Omega} \to M$  of every  $\mathcal{P}_M \in_{E_{\infty}}^{\infty} (M,)$  into M. Note that, for each  $n \geq 0$ ,  $\sum_{E_{\infty}}^{\infty} (M,)^{\Omega}(n) \subseteq M$ . This set is also denoted by  $\mathcal{P}_M$ .

Recall that a topological manifold is a (unique) topology of its base point a in the sense of [?, Definition 1.4].

In this section, we will define  $_{E_{\infty}}^{\infty}(M,)$  as an exact category, which consists of the set of functions  $\omega^{(0)}$  and  $\widetilde{\omega^{(1)}}$  that are compatible with the following assumptions:

- 1.  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$  is a compact object in  $_{\infty}.$  In particular, every base point of M has a fixed topology.
- 2. The map  $\alpha_x :_{E_{\infty}}^{\infty} (M,)^{\Omega} \to \text{is a continuous function for all } x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ .

As before, let us define the function  $\omega :_{E_{\infty}}^{\infty} (M,)^{\Omega} \to \text{by choosing the map}$  $\omega^{(0)}$  to be the restriction of M to  $E_{\infty}^{\infty}(M,)^{\Omega}$ , and  $\omega^{(1)}$  to be the restriction of Mto  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$ .

Let  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$  be a compact object in  $_{\infty}$ . Its objects are pairs (M,d) of a topological manifold M and a topology  $d: M \times M \to \mathbb{N}$  We call  $\sum_{E_{\infty}}^{\infty} (M, )^{\Omega}$  an  $E_{\infty}$ -

ring. We call a map of  $E_{\infty}$ -rings  $(f,g):(M,d)\to (N,d')$  an  $E_{\infty}$ -morphism. For  $x\in_{E_{\infty}}^{\infty}(M,)^{\Omega}$ , we let  $E_{\infty}^{\infty}(M,)^{\Omega}(x)$  be the set of functions  $\omega^{(0)}$  and  $\omega^{(1)}$ 

corresponding to the topology of  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}(x)$ . It is clear that the class  $\sum_{E_{\infty}}^{\infty}(M,)^{\Omega}$  of functions in  $\sum_{E_{\infty}}^{\infty}(M,)$  is again an exact category. But note that, when  $E_{\infty}^{\infty}(M,)^{\Omega}$  is a compact object in  $E_{\infty}$ , the objects are called topological manifolds instead of  $E_{\infty}$ -rings, while the morphisms are called  $E_{\infty}$ -morphisms.

#### An Exact Category of Topological Manifolds 0.2

Given a topological manifold M, we would like to obtain its exact topology. The set of functions  $\omega^{(0)}$  and  $\omega^{(1)}$  is exactly what is required for this goal, and the only thing that needs to be determined is the topology.

First, we define the topology of  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$ . Let  $\varphi$  be a morphism of  $E_{\infty}$ -rings. Then, we have the following:

Let  $\varphi$  be a  $E_{\infty}$ -morphism between  $E_{\infty}$ -rings. Let  $\omega :_{E_{\infty}}^{\infty} (M,)^{\Omega} \to$  be a continuous function. Then,  $\varphi \mapsto \omega(n)$ ,  $n \in$ , is a continuous monotone function in  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$ .

Since, for any  $n \geq 0$ , the function  $\omega(n)$  is a continuous monotone function,  $\varphi \mapsto \omega(n)$  is a continuous monotone function. However, if  $n \leq 0$ , then  $\omega(n)$  is never a continuous monotone function. On the contrary,  $\varphi \mapsto \omega(n)$  is always a continuous monotone function. This implies that for all  $n \leq 0$ ,  $\omega(n) = 0$ . Hence,  $\omega^{(0)}$  is either zero, or it is continuous, and hence a continuous monotone function.

Recall that, by definition, the function  $\omega^{(0)}: \Omega \times M \to \text{is a localizing cohomology map, that is,}$ 

$$\omega^{(0)}((i,j)) = \omega(i)\omega(j).$$

However, we could be more specific about the function  $\omega^{(0)}: \Omega \times M \to \text{since}$ , for each  $i, j \in M$ ,  $\omega(i)\omega(j) = 0$  if and only if i < j. For the moment, we shall just write  $\omega^{(0)}$  for convenience. Hence, the function  $\omega^{(0)}$  is the usual map  $\omega^{(0)}: \Omega \to$ , but we will omit the notation for clarity.

Let M be a topological manifold. For each point  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ , the function  $\omega^{(0)}(x)$  is a continuous function. Furthermore, for each  $n \geq 0$ , the function  $\omega^{(0)}(n)$  is continuous.

If  $n \leq 0$ , then  $\omega^{(0)}(n) = 0$ . So, by the previous result,  $\omega^{(0)}(x) = 0$  for all  $x \in M$ . Further, since  $\omega^{(0)}$  is a continuous monotone function, for all  $n \leq 0$ , the function  $\omega^{(0)}(n)$  is also continuous, which is shown by Proposition 0.2. For the contrary, if n0, then  $n \in \Omega$ , and therefore  $\omega^{(0)}(n) = 0$ , which is shown by the previous result.

Next, we proceed to define the topology of  $_{E_{\infty}}^{\infty}(M,)^{\Omega}$ . Recall that a function  $\omega:_{E_{\infty}}^{\infty}(M,)^{\Omega} \to \text{is a continuous monotone map if its value on } x \in_{E_{\infty}}^{\infty}(M,)^{\Omega}$  satisfies the following equations:

1. 
$$\omega(n) \leq \frac{1}{n!} \sum_{i=0}^{n} (-1)^{i+1} \delta_{\infty}(M)(x)$$
 for all  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ ;

2. 
$$\omega(n) \leq \frac{1}{\sqrt{n!}} \sum_{i=0}^{n-1} \delta_{\infty}(M)(x)$$
 for all  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ ;

3. 
$$\omega(n) \leq \frac{1}{\sqrt{n!}} \sum_{i=1}^{n-1} \delta_{\infty}((i,j))(x)$$
 for all  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ .

Now we shall see that the function  $\omega$  is continuous monotone, and we should therefore have the following two properties:

Let  $\omega :_{E_{\infty}}^{\infty} (M,)^{\Omega} \to \text{be a continuous monotone function.}$  Then, the function  $\omega$  is continuous monotone.

Let  $x \in_{E_{\infty}}^{\infty} (M,)^{\Omega}$ . First, by the previous result, there is only one base point