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## I. Theory:

## **Hypothesis:**

## **Cost function:**

$$h_{\theta}(x) = \theta^{T} x = \theta_{0} x_{0} + \theta_{1} x_{1} + \dots + \theta_{n} x_{n}$$

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 with  $x_{0} = 1$   $J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)} - y^{(i)})^{2})^{2}$ 

### **Gradient descent algorithm:**

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)} - y^{(i)}) x_j^{(i)}$$
 Update theta

with m= number of samples 
$$\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)} - y^{(i)}) x_j^{(i)}$$

j=1....n: number of feartures

# II. Implement part supports multiple variables in vectorized version

Calculate hypothesis: with m samples x (each sample is multiple variables – n features).

Input:

$$X = \bigvee_{i=1}^{m} x^{(i)^{T}} = \begin{bmatrix} -x^{(i)^{T}} - \\ -x^{(i)^{T}} - \\ \vdots \\ \vdots \\ -x^{(i)^{T}} - \end{bmatrix} \text{ voi } x^{(i)^{T}} = \begin{bmatrix} x_{0}, x_{1}, \dots, x_{n} \end{bmatrix} \text{ n feartures} \qquad \theta = \begin{bmatrix} \theta_{0} \\ \theta_{0} \\ \vdots \\ \theta_{n} \end{bmatrix}$$

X(vectormcolumn) store m samples x

$$\mathsf{Hypothesis:} H = \sum h^{(i)} = \bigvee_{i=1}^m x^{(i)^T} \theta = \begin{bmatrix} -x^{(1)^T} \theta - \\ -x^{(2)^T} \theta - \\ \vdots \\ -x^{(m)^T} \theta - \end{bmatrix} = \begin{bmatrix} -\theta^T x^{(1)} - \\ -\theta^T x^{(2)} - \\ \vdots \\ -\theta^T x^{(m)} - \end{bmatrix} \qquad \begin{aligned} h_{\theta}(x^i) &= \theta^T x = x^T \theta \\ Note: & \theta^T x = x^T \theta \\ or & \theta^T x^{(i)} = x^{(i)^T} \theta \\ \vdots \\ -\theta^T x^{(m)} - \end{bmatrix} \end{aligned}$$
 when  $\mathbf{x}^{(i)}$  and  $\theta$  are vectors

Cost function: 
$$J(\theta) = \frac{1}{2m} (X\theta - \vec{y})^T (X\theta - \vec{y})$$

### **Gradient descent:**

$$\begin{bmatrix} \frac{\partial J}{\partial \theta_0} \\ \frac{\partial J}{\partial \theta_1} \\ \frac{\partial J}{\partial \theta_2} \\ \vdots \\ \frac{\partial J}{\partial \theta_n} \end{bmatrix} = \frac{1}{m} \begin{bmatrix} \sum_{i=1}^m \left( (h_{\theta}(x^{(i)}) - y^{(i)}) x_1^{(i)} \right) & \text{where} \\ \sum_{i=1}^m \left( (h_{\theta}(x^{(i)}) - y^{(i)}) x_1^{(i)} \right) & h_{\theta}(x) - y = \begin{bmatrix} h_{\theta}(x^{(1)}) - y^{(1)} \\ h_{\theta}(x^{(2)}) - y^{(2)} \\ \vdots \\ h_{\theta}(x^{(1)}) - y^{(m)} \end{bmatrix} \\ \vdots \\ \sum_{i=1}^m \left( (h_{\theta}(x^{(i)}) - y^{(i)}) x_n^{(i)} \right) & \sum_i \beta_i x^{(i)} = \begin{bmatrix} | & | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | & | \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_m \end{bmatrix} = X^T \beta, \\ = \frac{1}{m} X^T (h_{\theta}(x) - y). & \text{where the values } \beta_i = (h_{\theta}(x^{(i)}) - y^{(i)}). \end{bmatrix}$$

Gradient descent =  $X^T \beta$ 

## III. Results:

### Part 1: One variable

 When Gradient descent is working correctly, cost function should be decrease with each step.

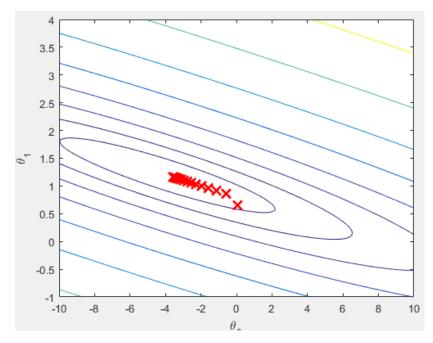


Figure 1-Gradient descent work correctly so the cost function reduce and converge at the global minimum.

When we find the good parameter theta. The linear regression fit with our data

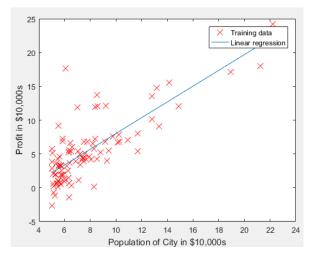
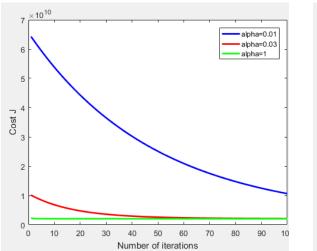


Figure 2- Training data with linear regression fit

### Part2:

Learning rate are very important in training. If we choose small learning rate, gradient descent takes a very long time to converge to the optimal value. In the other hand, with a large learning rate, gradient descent might not converge or might even diverge (as shown in Figure.3 and Figure 4)



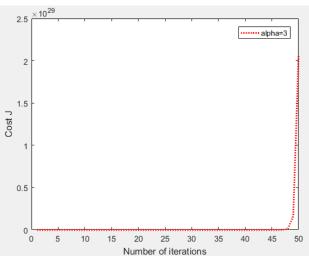


Figure 3 Cost function with different leaning rate alpha

Figure 4 Gradient descent diverge when leaning rate is too large.

Testing: Predicted price of a 1650 sq-ft, 3 bedroom house (using gradient descent):

\$293081.464335