

1. Items done this session:

Adding a new PD control feedback system to replace the single sin-wave in the previous lab.

In this feedback system, the  $H(s)$  is a over-simplified form of the real system.

In order to find the appropriate  $K_p$  and  $K_v$ , we're going to formulate the damping ratio  $\zeta$  and natural frequency  $\omega_n$  of the second order system using equation

(1).  $\zeta = (\ln(OP)^2 / (\pi^2 + \ln(OP)^2))^{1/2}$ , where  $OP$  is overshooting percentage of 0.05 and

(2).  $\omega_n = \pi / (t_p \sqrt{1 - \zeta^2})^{1/2}$ , where  $t_p$  is peak time of 0.15

Given the Overshooting ratio 0.05 and peak time 0.15, we'll get  $\zeta = 0.69$  and  $\omega_n = 23.9398$ .

The next step is to find the relation between  $\zeta$ ,  $\omega_n$  and the  $K_p$ ,  $K_v$ .

2. Items for next session:

Find the characteristic parameters of the second order system to calculate  $K_p$  and  $K_v$ .