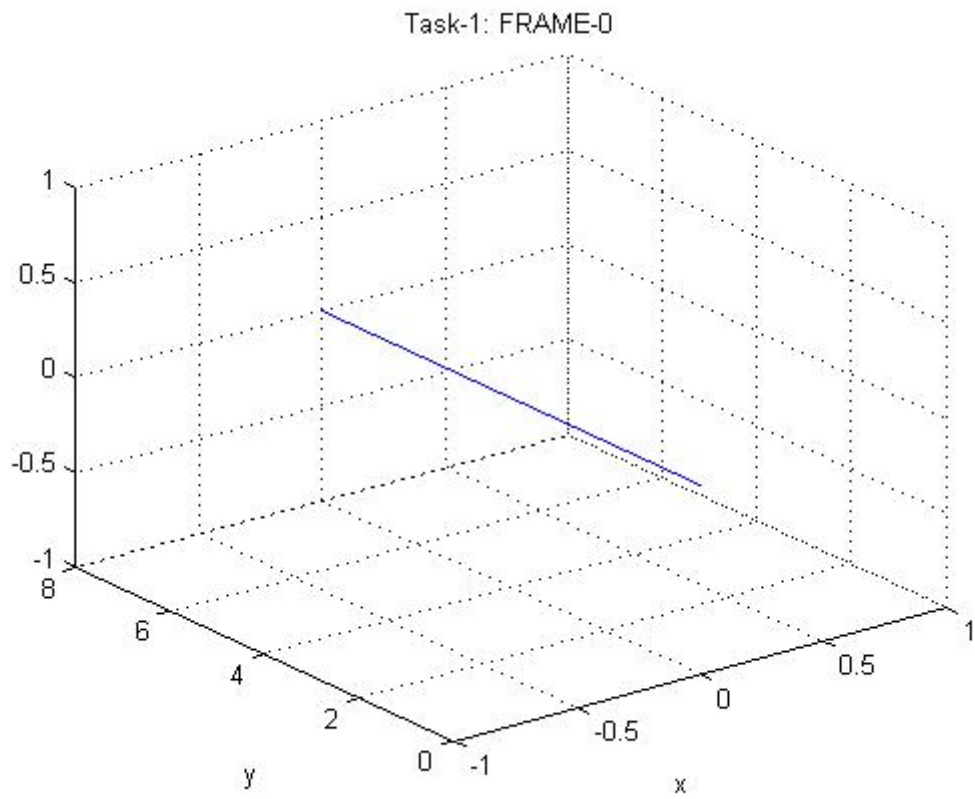
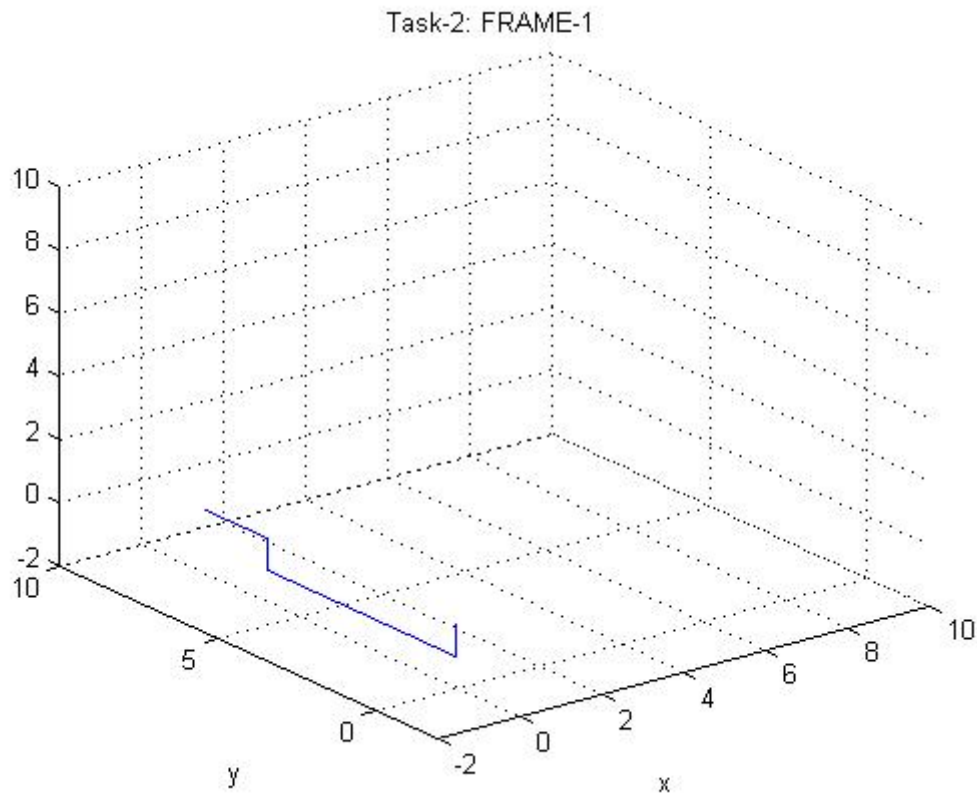


1. Items done this session:

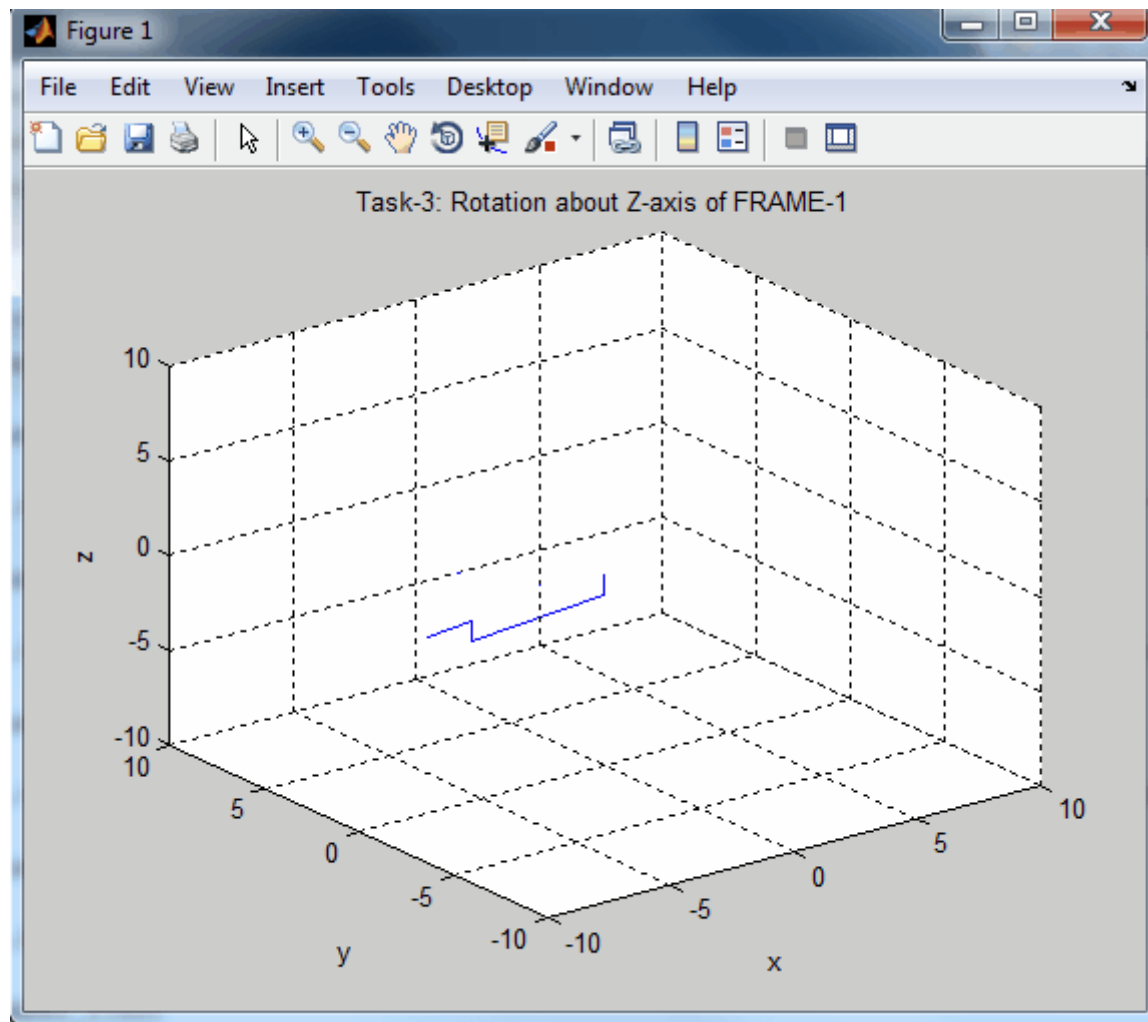
Task-1: Plot base of robot on frame-0



Task-2: Draw base of robot in Frame-1 with following points: (0,0,0), (0,0,-1), (0,6,-1), (0,6,0) and (0,8,0).



Task-3: To convert points, write a function TRANS0_1 which takes theta1 as input argument and plot animation of the rotation about Z-axis.



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2. Items for next session:

Task-4 to 5