

$$1. (a) \langle S_y \rangle = \frac{\hbar}{2} \langle \psi | \sigma_y | \psi \rangle \quad 1 \text{ point}$$

$$= \frac{\hbar}{2} \left( \frac{1}{2} \right) (1 \ -i) \underbrace{\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$= \frac{\hbar}{4} (1 \ -i) \begin{pmatrix} 1 \\ i \end{pmatrix} = \frac{\hbar}{2}$$

You may notice that  $|\psi\rangle$  is an eigenstate of  $\hat{S}_y$  (spin-up along y-axis)

$$\therefore \Delta S_y = 0$$

(otherwise use  $\Delta A = \sqrt{\langle A^2 \rangle - \langle A \rangle^2}$ )

(b)  $\therefore |\psi\rangle$  is spin-up along +y

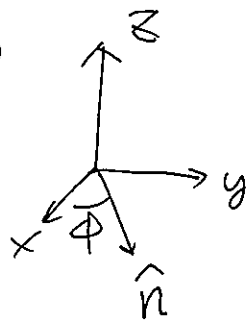
$$\langle S_x \rangle = \langle S_z \rangle = 0$$

$$\Delta S_x = \Delta S_z = \frac{\hbar}{2}$$

2. (a) Same as Prob. 3.15 in the textbook  
(In "Extra Problem Solution" on Moodle)

$$\Rightarrow |1,1\rangle_x \rightarrow \frac{1}{2} \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix}$$

2. (b)



$|1,1\rangle_n = \text{Rotate } |1,1\rangle_x \text{ about the } z\text{-axis by } \phi$  1 point

$$|1,1\rangle_n = e^{-i \frac{\hat{J}_z \phi}{\hbar}} |1,1\rangle_x$$

0.5 point

Note that  $e^{-i \frac{\hat{J}_z \phi}{\hbar}}$  is diagonal in the

$\hat{J}_z$ -basis:

$$\hat{J}_z \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \hbar \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad \hat{J}_z \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 0 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \hat{J}_z \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = -\hbar \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow \begin{pmatrix} e^{i\phi} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & e^{-i\phi} \end{pmatrix}$$

$$e^{-i \frac{\hat{J}_z \phi}{\hbar}} |1,1\rangle_x = \begin{pmatrix} e^{-i\phi} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & e^{i\phi} \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^{-i\phi} \\ \sqrt{2} \\ e^{i\phi} \end{pmatrix}$$

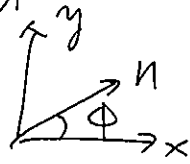
$$\begin{aligned} {}_n \langle 1,1 | 1,1 \rangle_x &= \frac{1}{4} (e^{i\phi} \cdot \sqrt{2} \cdot e^{-i\phi}) \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix} \\ &= \frac{1}{4} (e^{i\phi} + e^{-i\phi} + 2) = \frac{1}{2} (1 + \cos 2\phi) \end{aligned}$$

$$P_{nb} = |{}_n \langle 1,1 | 1,1 \rangle_x|^2 = \frac{1}{4} (1 + \cos 2\phi)^2$$

2. (c) You can use

$$\langle S_x \rangle = \hbar \langle 1, 1 | \hat{J}_x | 1, 1 \rangle$$

or by physics intuition



that  $\langle S_x \rangle = \hbar \cos \phi$

3. (a) 
$$\begin{vmatrix} -E & -A \\ -A & -E \end{vmatrix} = 0 \Rightarrow E^2 = A^2, E = \pm A$$

$E_1 = -A$

$$\begin{pmatrix} 0 & -A \\ -A & 0 \end{pmatrix} \begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix} = -A \begin{pmatrix} \chi_1 \\ \chi_2 \end{pmatrix}$$

$$\begin{pmatrix} -A\chi_2 \\ -A\chi_1 \end{pmatrix} \Rightarrow \chi_1 = \chi_2, |E_1\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$E_2 = A, \chi_1 = -\chi_2, |E_2\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

(-1 if doesn't get normalized)

$$3. (b) \quad |E_1\rangle = \frac{1}{\sqrt{2}} (|a\rangle + |-a\rangle) \Rightarrow |-a\rangle = \frac{1}{\sqrt{2}} (|E_1\rangle - |E_2\rangle)$$

$$|E_2\rangle = \frac{1}{\sqrt{2}} (|a\rangle - |-a\rangle)$$

$$|\psi(t)\rangle = e^{-i\frac{\hat{H}_t}{\hbar}} \frac{1}{\sqrt{2}} (|E_1\rangle - |E_2\rangle)$$

$$= \frac{1}{\sqrt{2}} e^{i\frac{A^t}{\hbar}} |E_1\rangle - \frac{1}{\sqrt{2}} e^{-i\frac{A^t}{\hbar}} |E_2\rangle$$

$$\langle a | \psi(t) \rangle = \left(\frac{1}{\sqrt{2}}\right)^2 e^{+i\frac{A^t}{\hbar}} + \left(\frac{1}{\sqrt{2}}\right)^2 e^{-i\frac{A^t}{\hbar}} = \cos\left(\frac{A^t}{\hbar}\right)$$

$$\text{Prob} = |\langle -a | \psi(t) \rangle|^2 = \cos^2\left(\frac{A^t}{\hbar}\right)$$

$$(c) \quad \text{Prob. at } -a = \cos^2\left(\frac{A^t}{\hbar}\right)$$

$$\therefore \text{Prob. at } a = 1 - \cos^2\left(\frac{A^t}{\hbar}\right) = \sin^2\left(\frac{A^t}{\hbar}\right)$$

$$\langle \hat{X} \rangle = a \sin^2\left(\frac{A^t}{\hbar}\right) + (-a) \cos^2\left(\frac{A^t}{\hbar}\right)$$

$$= a \left( \sin^2\left(\frac{A^t}{\hbar}\right) - \cos^2\left(\frac{A^t}{\hbar}\right) \right) \quad (= -a \cos\left(\frac{2A^t}{\hbar}\right))$$

4. (a)  $\hat{H} = \omega_0 \hat{S}_x \Rightarrow$  eigenvalues  $= \pm \frac{\hbar}{2} \omega_0$

eigenstates = same as  $\hat{S}_x = |\pm X\rangle$

(b)  $\because [\hat{H}, \hat{S}_x] = 0$  ✓ and  $(\frac{\partial \hat{H}}{\partial t}) = 0$

at  $t=0$  the  $e^-$  is in  $|+\mathcal{Z}\rangle \Rightarrow \langle S_x \rangle = 0$  always

(c)  $|+\mathcal{Z}\rangle = \frac{1}{\sqrt{2}} (|+X\rangle + |-X\rangle), \quad \sigma t = \frac{t}{N}$

$$e^{-\frac{i\hat{H}\sigma t}{\hbar}} |+\mathcal{Z}\rangle = \frac{1}{\sqrt{2}} \left( e^{-\frac{i\omega_0(\sigma t)}{2}} |+X\rangle + e^{\frac{i\omega_0(\sigma t)}{2}} |-X\rangle \right) = |\psi(t)\rangle$$

$$\langle +\mathcal{Z} | \psi(t) \rangle = \frac{1}{2} \left( e^{-\frac{i\omega_0(\sigma t)}{2}} + e^{\frac{i\omega_0(\sigma t)}{2}} \right)$$

$$= \cos\left(\frac{\omega_0}{2} \left(\frac{t}{N}\right)\right)$$

$$\text{Prob.} = \left( |\langle +\mathcal{Z} | \psi(t) \rangle|^2 \right)^N = \cos^{2N} \left( \frac{\omega_0 t}{2N} \right)$$

$$4. (d) \quad \lim_{N \rightarrow \infty} \cos^{2N} \left( \frac{\omega t}{2N} \right) = e^{\lim_{N \rightarrow \infty} \left( \ln \left( \cos^{2N} \left( \frac{\omega t}{2N} \right) \right) \right)}$$

$$\lim_{N \rightarrow \infty} 2N \ln \cos \left( \frac{\omega t}{2N} \right) = 2 \lim_{x \rightarrow 0} \frac{\ln \left( \cos \frac{\omega t}{2} x \right)}{x}$$

$$x=0, \cos \left( \frac{\omega t}{2} x \right) = 1, \ln(1) = 0$$

$$\rightarrow \frac{d}{dx} \left( \ln \cos \left( \frac{\omega t}{2} x \right) \right) \Big|_{x=0}$$

$$= \frac{\sin \left( \frac{\omega t}{2} x \right)}{\cos \left( \frac{\omega t}{2} x \right)} \frac{\omega t}{2} \Big|_{x=0} = \frac{\omega t}{2} \tan \left( \frac{\omega t}{2} x \right) \Big|_{x=0} = 0$$

$$\therefore e^{(\rightarrow 0)} \rightarrow 1 = \text{"Quantum Zeno Effect"}$$

( half-credit if you argue that when  $\Delta t \rightarrow 0$ ,  
Prob. of observing  $|+\rangle$  each time  $\rightarrow 1$  )

A particle which is continuously measured  
will not change state, even if its not  
a stationary state.