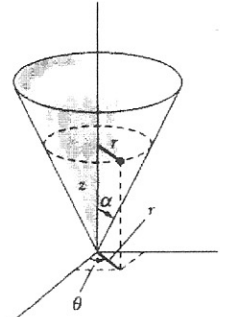


## Theoretical Mechanics II: Midterm Exam, April 20<sup>th</sup>, 2015 (10:10AM – 12:00PM)

**Useful relation:**  $U_{ij} = (1 - \cos \theta)n_i n_j + \cos \theta \delta_{ij} - \epsilon_{ijk} n_k \sin \theta$

1. A particle of mass  $m$  is confined to move on the surface of a smooth cone of half-angle  $\alpha$ , see figure. For simplicity, let's assume that there is no gravity ( $g = 0$ ).
  - a) (24 pts) Find the conjugate momenta, the Hamiltonian, and the Hamilton's equations.
  - b) (6 pts) For simplicity, let  $m = \cot \alpha = 1$  and initially  $p_\theta = 1$ . Draw the phase trajectory of the particle of  $H = 1$  in the  $r$ - $p_r$  phase plane (projection of the trajectory on  $r$ - $p_r$  phase plane).



2. (a) (8 pts) Prove the following properties of the rotation matrix  $U$ :  $U^T(\hat{n}, \theta) = U^{-1}(\hat{n}, \theta) = U(-\hat{n}, \theta)$ .  
 (b) (12 pts) The intermediate coordinate system  $S'$  is obtained by rotating the original coordinate system  $S$  around its  $z$ -axis by 45 degrees. Then the new coordinate system  $S''$  is obtained by rotating the intermediate coordinate system  $S'$  around its  $x$ -axis by 90 degrees. Find the rotation matrix  $U$  that relates the components of a vector in the original coordinate system and that in the new coordinate system,  $\mathbf{r}_{original} = U \mathbf{r}_{new}$ .  
 (c) (10 pts) Previous two-step operation can be achieved through one simple rotation around a certain axis. Please find the rotational angle  $\theta$  and the direction of the rotation axis ( $n_x : n_y : n_z = ? : ? : ?$ ).

3. (a) (12 pts) Given the relation of the rate of the vector change in the space and the body frames,

$$\left. \frac{d\vec{r}}{dt} \right|_{space} = \left. \frac{d\vec{r}}{dt} \right|_{body} + \vec{\omega} \times \vec{r},$$

Show that Newton's law observed in a body frame is  $m\vec{a}_b = \vec{F} - 2m\vec{\omega} \times \vec{v}_b - m\dot{\vec{\omega}} \times \vec{r} - m\vec{\omega} \times (\vec{\omega} \times \vec{r})$ .

- (b) (6 pts) For simplicity, let's ignore the effects due to the Euler force and the centrifugal force. Please determine the direction of deflection of a free falling object in the south hemisphere, and why?
4. (a) (10 pts) Consider a pure rotation case (the origin of the inertial frame is chosen to be a stationary point in a rigid body of  $N$  mass points), the angular momentum is

$$\vec{L} = \sum_{i=1}^N \vec{r}_i \times m_i (\vec{\omega} \times \vec{r}_i) = \vec{I} \cdot \vec{\omega}$$

Start from this relation to show that the moment of inertia has the form of

$$I_{\alpha\beta} = \sum_{i=1}^N m_i (\vec{r}_i \cdot \vec{r}_i \delta_{\alpha\beta} - r_{i\alpha} r_{i\beta})$$

- (b) (12 pts) Three particles with identical mass  $m$  are located at  $(a, 0, 0)$ ,  $(0, a, 2a)$ , and  $(0, 2a, a)$ . Calculate the moment of inertia tensor with respect to the origin. And find the principal moments and corresponding principal axes.
5. (Extra 15 pts) Make graphs and derive a general expression of the rotation matrix for a rotation of angle  $\theta$  about the direction  $\hat{n}$ .

$$U_{ij} = (1 - \cos \theta)n_i n_j + \cos \theta \delta_{ij} - \epsilon_{ijk} n_k \sin \theta.$$