

view_frames Result

Recorded at time: 115.862

odom

Broadcaster: /gazebo
Average rate: 20.202 Hz
Most recent transform: 115.824 (0.038 sec old)
Buffer length: 4.950 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 115.836 (0.026 sec old)
Buffer length: 4.900 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 115.836 (0.026 sec old)
Buffer length: 4.900 sec

right_wheel

