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Content

- 1. Matrix algebra
- 2. Projection
- 3. Mean and variance
- 4. Principal component analysis

Projection I

Let $\mathbf{x} = (x_1, \dots, x_p)^T$ and $\mathbf{v} = (v_1, \dots, v_p)^T$ are vectors in \mathbb{R}^p . The projection of \mathbf{x} on \mathbf{v} is a vector defined as

$$\begin{pmatrix} \mathbf{x}^T \mathbf{v} \\ |\mathbf{v}| \end{pmatrix} \cdot \frac{\mathbf{v}}{|\mathbf{v}|}$$
Length $\uparrow \quad \text{theorem}$

Remark

If \mathbf{v} is a unit vector, then the projection of \mathbf{x} on \mathbf{v} is $(\mathbf{x}^T \mathbf{v})\mathbf{v}$.



Orthogonality

Definition

Let $\mathbf{v} = (v_1, \dots, v_p)^T$ and $\mathbf{w} = (w_1, \dots, w_p)^T$ are vectors in \mathbb{R}^p , then

- 1. **v** and **w** are said to be orthogonal if $\mathbf{v}^T \mathbf{w} = 0$.
- 2. \mathbf{v} and \mathbf{w} are said to be orthonormal if $\mathbf{v}^T \mathbf{w} = 0$ and both \mathbf{v} and \mathbf{w} are unit vectors, i.e. $|\mathbf{v}| = |\mathbf{w}| = 1$.
- 3. A $n \times n$ matrix \mathbf{V} is said to be orthogonal if $\mathbf{V}^{\mathsf{T}}\mathbf{V} = \mathbf{I}_n$

Projection II

Remarks

Let
$$\mathbf{x} = (x_1, \dots, x_p)^T$$
 and $\mathbf{V} = \begin{pmatrix} \mathbf{v_1} & \dots & \mathbf{v_q} \end{pmatrix}$ where $\mathbf{v_i}$ are

vectors in \mathbb{R}^p and **V** is orthogonal, i.e. $\mathbf{v_i}$ are mutually orthonormal. Then, the projection of x on the hyperplane spanned by $\mathbf{v_1}, \dots, \mathbf{v_q}$ is defined as

$$\underbrace{(\mathbf{x}^{T}\mathbf{V})\mathbf{V}^{T}}_{} = \mathbf{x}^{T} \left(\mathbf{v}_{1} \dots \mathbf{v}_{q}\right) \left(\mathbf{v}_{1}^{T} \dots \mathbf{$$

Examples

1. Let
$$\mathbf{x} = (1, 2, 3)^T$$
 and $\mathbf{V} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$.

Examples

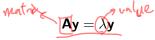
1. Let
$$\mathbf{x} = (-1,0,1,2)^T$$
 and $\mathbf{V} = \begin{pmatrix} 0 & \frac{3}{5} \\ -1 & \frac{4}{5} \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$.

$$v_i \text{ and } V_2$$

$$= (X^TV_1)V_1 + (X^TV_2)V_2 =$$

Eigenvalues and eigenvectors

Let $\mathbf{A}_{p \times p}$ be a matrix and \mathbf{y} be a non-zero $p \times 1$ vector such that



where λ is a constant (scale).

Then, ${\bf y}$ is called a eigenvector of ${\bf A}$ and λ is the corresponding eigenvalue of ${\bf A}$.

$$A = \begin{pmatrix} 12 \\ 3-4 \end{pmatrix} \text{ claim the eigenvalues are } \lambda_1 = 2 \\ y = (y_1, y_2)^T \qquad Ay = 2 \\ y = (y_1, y_2)^T \qquad Ay = 2 \\ y = (y_1, y_2)^T \qquad Ay = -5 \\ y = (y_1, y_2)^T \qquad Ay = 2 \\ y = (y_1, y_2)^T \qquad Ay = -5 \\ y = (y_1, y_2)^T$$

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Eigenvalues and eigenvectors

Property

 λ is an eigenvalue of $\mathbf{A}_{p \times p}$ if and only if $\det(\mathbf{A} - \lambda \mathbf{I}_p) = 0$

Property

If \mathbf{y} is an eigenvector of a matrix \mathbf{A} , then for any constant c, vector $c\mathbf{y}$ is also an eigenvector of a matrix \mathbf{A} with the same associated eigenvalue.

Remark

Any eigenvector can be scaled to be a unit vector.

$$\Delta = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \quad A - \lambda I = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} - \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 1 - \lambda & 2 \\ 3 & 4 - \lambda \end{pmatrix}$$

$$\det \begin{pmatrix} 1 - \lambda & 2 \\ 3 - 4 - \lambda \end{pmatrix} = (1 - \lambda)(-4 - \lambda) - 6 = \lambda^2 + 4\lambda - \lambda - 4 - 6$$

$$= \lambda^2 + 3\lambda - 10 = (\lambda + 5)(\lambda - 2) = 0$$

$$\Rightarrow \lambda = -5 \text{ or } 2$$

Eigendecomposition $A = A^T$ $\begin{pmatrix} 3 \\ 3 \end{pmatrix}$

Spectral decomposition theorem

Any symmetric matrix $\mathbf{A}_{p \times p}$ can be expressed as

$$\mathbf{A} = \mathbf{\Gamma} \mathbf{\Lambda} \mathbf{\Gamma}^T = \begin{pmatrix} \mathbf{v}_1 & \cdots & \mathbf{v}_p \end{pmatrix} \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_p \end{pmatrix} \begin{pmatrix} \mathbf{v}_1^T \\ \vdots \\ \mathbf{v}_p^T \\ \end{pmatrix}$$

$$= \sum_{i=1}^p \lambda_i \mathbf{v}_i \mathbf{v}_i^T \qquad \mathbf{v} \mathbf{v}_i^T$$

$$\text{where}$$

$$\mathbf{\Lambda} \text{ is a diagonal matrix of eigenvalues } \lambda_i \text{ of } \mathbf{A} \text{ and}$$

 Γ is a matrix whose column vectors \mathbf{v}_i are corresponding eigenvectors. orthogonal

Mean and variance

Let
$$\mathbf{x} = (x_1, \dots, x_n)^T$$
 and $\mathbf{1}_n = (1, \dots, 1)^T$.

The mean of vector \mathbf{x} is defined as

$$E(\mathbf{x}) = \frac{1}{n} (\underline{x_1 + \dots + x_n}) = \frac{1}{n} \sum_{i=1}^{n} x_i = \frac{1}{n} \mathbf{1}_n^T \mathbf{x}$$

The variance of vector \mathbf{x} is defined as

$$Var(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^{n} (x_i - \mathbf{E}(\mathbf{x}))^2$$

$$= \frac{1}{n} \sum_{i=1}^{n} (x_i - \frac{1}{n} \mathbf{1}_n^T \mathbf{x})^2 = \sqrt{(x_i - \frac{1}{n} \mathbf{1}_n^T \mathbf{x})^2}$$

$$= \frac{1}{n} \sum_{i=1}^{n} (x_i - \frac{1}{n} \mathbf{1}_n^T \mathbf{x})^2 = \sqrt{(x_i - \frac{1}{n} \mathbf{1}_n^T \mathbf{x})^2}$$

$$= \frac{1}{n} (\mathbf{x} - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T \mathbf{x})^T (\mathbf{x} - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T \mathbf{x})$$

$$= \frac{1}{n} \mathbf{x}^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T)^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T) \mathbf{x}$$

$$= \frac{1}{n} \mathbf{x}^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T) \mathbf{x}$$

$$= \frac{1}{n} \mathbf{x}^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T) \mathbf{x}$$

$$= \frac{1}{n} \mathbf{x}^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T) \mathbf{x}$$

Mean and variance



Let
$$\mathbf{X} = \begin{pmatrix} \mathbf{x_1} & \dots & \mathbf{x_p} \end{pmatrix}_{n \times p}$$
 be a matrix (data).

The mean of matrix X is defined as

$$E(\mathbf{X}) = (\underline{E}(\mathbf{x}_1), \dots, \underline{E}(\mathbf{x}_p))$$

$$= (\frac{1}{n} \mathbf{1}_n^T \mathbf{x}_1, \dots, \frac{1}{n} \mathbf{1}_n^T \mathbf{x}_p)$$

$$= \frac{1}{n} \mathbf{1}_n^T \mathbf{X}$$

Mean and variance

ean and variance

Let
$$\mathbf{X} = \begin{pmatrix} \mathbf{x_1} & \dots & \mathbf{x_p} \end{pmatrix}$$
 be a matrix (data).

The covariance matrix of matrix \mathbf{X} is defined as

The covariance matrix of matrix **X** is defined as

$$var(\mathbf{X}) = \mathbf{S}_{n}^{2} = \frac{1}{n} \mathbf{X}^{T} (\mathbf{I}_{n} - \frac{1}{n} \mathbf{1}_{n}^{T}) \mathbf{X}$$

$$= \begin{pmatrix} var(\mathbf{x}_{1}) & cov(\mathbf{x}_{1}, \mathbf{x}_{2}) & \dots & cov(\mathbf{x}_{1}, \mathbf{x}_{p}) \\ cov(\mathbf{x}_{2}, \mathbf{x}_{1}) & var(\mathbf{x}_{2}) & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ cov(\mathbf{x}_{p}, \mathbf{x}_{1}) & \dots & var(\mathbf{x}_{p}) \end{pmatrix}$$

where

$$cov(\mathbf{x_i}, \mathbf{x_j}) = \frac{1}{n} (\mathbf{x_i} - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T \mathbf{x_i})^T (\mathbf{x_j} - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T \mathbf{x_j})$$
$$= \frac{1}{n} \mathbf{x_i}^T (\mathbf{I}_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T) \mathbf{x_j}$$

Properties of covariance matrix

Properties

- for any vector y y Sny = 0 = Sn p.s.d.
- 1. \mathbf{S}_n^2 is a positive semidefinite matrix, i.e. the eigenvalues of \mathbf{S}_n^2 are all non-negative.
- 2. \mathbf{S}_n^2 can apply spectual decomposition theorem

$$\mathbf{S}_{n}^{2} = \underline{\mathbf{\Gamma} \mathbf{\Lambda} \mathbf{\Gamma}^{T}}$$

Moreover, $\lambda_1, \ldots, \lambda_p$ are non-negative and $\mathbf{v}_1, \ldots, \mathbf{v}_p$ are orthonormal pairwisely.

3. The **total variance** is the sum of the diagonal elements of the covaiance matrix, i.e. $tr(\mathbf{S}_n^2)$. By the property of trace,

trace
$$tr(S_n^2) = \lambda_1 + \dots + \lambda_p$$
 $tr(AB) = tr(BA)$
 $tr(T \wedge T^{-1}) = tr(T^{-1} \wedge T^{-1}) = tr(A)$

Remark

Any $\mathbf{v} \in \mathbb{R}^p$ is a linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_p$, i.e.

$$\mathbf{v} = a_1 \mathbf{v}_1 + \dots + a_p \mathbf{v}_p$$

for some a_1, \ldots, a_p are constants.



Property

Let
$$\mathbf{X}=\begin{pmatrix}\mathbf{x_1}&\dots&\mathbf{x_p}\end{pmatrix}_{n\times p}$$
 be data, then for any $\mathbf{v}\in\mathbb{R}^p$ is a unit vector,

$$var(\mathbf{X}\mathbf{v}_1) \geq var(\mathbf{X}\mathbf{v})$$

where \mathbf{v}_1 is the eigenvector of \mathbf{S}_n^2 associated with the largest eigenvalue λ_1 .

Moreover, $var(\mathbf{X}\mathbf{v}_1) = \lambda_1$.

 $\frac{\mathsf{Proof}}{\mathsf{Claim}: \ \mathit{var}(\mathbf{X}\mathbf{v_1}) \geq \mathit{var}(\mathbf{X}\mathbf{v})}$

First,

$$var(\mathbf{X}\mathbf{v}) = \frac{1}{n} (\mathbf{X}\mathbf{v})^{T} (\mathbf{I}_{n} - \frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}) \mathbf{X}\mathbf{v}$$

$$= \frac{1}{n} \mathbf{v}^{T} \mathbf{X}^{T} (\mathbf{I}_{n} - \frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}) \mathbf{X}\mathbf{v}$$

$$= \frac{1}{n} \mathbf{v}^{T} \mathbf{S}_{n}^{2} \mathbf{v}$$

$$\leq \frac{1}{n} \mathbf{v}^{T} \mathbf{S}_{n}^{2} \mathbf{v}$$

Second, by eigendecomposition,

cion,
$$\boldsymbol{\Lambda}\boldsymbol{\Gamma}^T = \sum_{i=1}^p \lambda_i \mathbf{v}_i \mathbf{v}_i^T$$

say that $\lambda_1 \geq \lambda_2 \geq \dots \lambda_p \geq 0$.

say that
$$\lambda_1 \ge \lambda_2 \ge \dots \lambda_p \ge 0$$
.
Let $\mathbf{v} = a_1 \mathbf{v}_1 + \dots + a_p \mathbf{v}_p$ (since \mathbf{v} must be the linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_p$)
$$var(\mathbf{X}\mathbf{v}) = \frac{1}{n} \mathbf{v}^T \left(\sum_{i=1}^{p} \lambda_i \mathbf{v}_i \mathbf{v}_i^T \right) \mathbf{v} = \frac{1}{N} \sum_{i=1}^{p} \lambda_i \mathbf{v}_i \mathbf{v}_i^T \right) \mathbf{v}$$

 $var(\mathbf{X}\mathbf{v}) = \frac{1}{n}\mathbf{v}^{T} \left(\sum_{i=1}^{p} \lambda_{i}\mathbf{v}_{i}\mathbf{v}_{i}^{T} \right)\mathbf{v} = \frac{1}{n} \sum_{i=1}^{p} \lambda_{i}\mathbf{v}_{i}^{T} \left(\sqrt{V_{i}} \sqrt{V_{i}} \sqrt{V_{i}} \right) \sqrt{V_{i}} \right)$

$$(\mathbf{v}_i, \mathbf{v}_i^T) \mathbf{v} = \frac{1}{n} \sum_{i=1}^{n} \lambda_i$$

$$(\mathbf{v}_i)^2 = \frac{1}{n} \sum_{i=1}^{n} \lambda_i$$

 $=\frac{1}{n}\sum_{i=1}^{p}\lambda_{i}(a_{i})^{2}\leq\lambda_{1} \text{ since } a_{1}^{2}+\cdots+a_{p}^{2}=1$

 $=\frac{1}{n}\sum_{i=1}^{p}\lambda_{i}(\mathbf{v}^{T}\mathbf{v}_{i})^{2}=\frac{1}{n}\sum_{i=1}^{p}\lambda_{i}(a_{i}V_{i}+\cdots+a_{p}V_{p})^{T}V_{i}$

$$= \frac{1}{n} \mathbf{v}^{T} \left(\sum_{i=1}^{p} \lambda_{i} \mathbf{v}_{i} \mathbf{v}_{i}^{T} \right) \mathbf{v} = \frac{1}{N} \sum_{i=1}^{p} \lambda_{i} \left(\mathbf{v}^{T} \mathbf{v}_{i} \right)^{2} = \frac{1}{N} \sum_{i=1}^{p} \lambda_{i} \left(a_{i} \mathbf{v}_{i}^{T} \mathbf{v}_{i} \right)^{2} = \frac{1}{n} \sum_{i=1}^{p} \lambda_{i} \left(a_{i} \mathbf{v}_{i}^{T} \mathbf{v}_{i} \right)^{2} = \left[a_{i} \mathbf{v}_{i}^{T} \mathbf{v}_{i} + \cdots + a_{p} \mathbf{v}_{p}^{T} \mathbf{v}_{i} \right]$$

Note that

$$var(\mathbf{X}\mathbf{v}) \leq \lambda_1$$

So the $var(\mathbf{X}\mathbf{v})$ has the maximum, i.e. $var(\mathbf{X}\mathbf{v}) = \lambda_1$, if the equality holds. The equality holds as $\mathbf{v} = \mathbf{v}_1$.

Thus, data projected on the eigenvector corresponding to the largest eigenvalue has the maximal variance, and the variance is the eigenvalue.



Remarks

- 1. The data projected on the eigenvector associated with the largest eigenvalue has the largest variance than the data projected on other direction.
- 2. Note that if the data has been centralized, i.e. $\mathbf{1}_n^T \mathbf{x}_i = \text{sum of}$ the values in the *i*-th colum vector = 0, the covariance matrix $\mathbf{S}_n^2 = \frac{1}{n} \mathbf{X}^T \mathbf{X}$.
- 3. The first principal component (site score) of j-th data \mathbf{x}_j^T is defined as the projection value of the j-th data on the first eigenvector of the covariance matrix, i.e. $\mathbf{x}_i^T \mathbf{v}_1$.
- 4. The first species score of *i*-th species is defined as the projection of *i*-th axis on the first eigenvector of the covariance matrix, i.e. $\mathbf{e}_{i}^{T}\mathbf{v}_{1}=v_{1i}$.



Property

Let $X_{n \times p}$ be data after centralized and $Y_{n \times p}$ is a orthogonal projection of **X** on hyperplane of dimension q in \mathbb{R}^p , i.e.

$$Y = XBB^T$$

for some
$$\mathbf{B} = \begin{pmatrix} \mathbf{b}_1 & \dots & \mathbf{b}_q \end{pmatrix}_{p \times q}$$
 with $\mathbf{B}^T \mathbf{B} = \mathbf{I}_q$. Then, the mean squared error which is defined as

$$MSE(\mathbf{X}, \mathbf{Y}) = \frac{1}{n} \sum_{i=1}^{n} |\mathbf{x}_{i}^{T} - \mathbf{y}_{i}^{T}|^{2}$$

is minimized for
$$\mathbf{Y} = \mathbf{\Gamma} \mathbf{\Gamma}^T$$
 where $\mathbf{\Gamma} = \begin{pmatrix} \mathbf{v}_1 & \dots & \mathbf{v}_q \end{pmatrix}$ and \mathbf{v}_i is the eigenvector of \mathbf{S}_n^2 associated with the *i*-th largest eigenvalues.

Moreover,

$$MSE(\mathbf{Y}, \mathbf{X}) = (\sum_{i=1}^{n} \lambda_i - \sum_{i=1}^{q} \lambda_i)/n$$

where λ_i is the *i*-th largest eigenvalues.

Conclusions

Consider a species composition matrix (site \times species) $\mathbf{X}_{n \times p}$. The plots are in the *p*-dimensional species space. If we want to project the plots on a **lower two dimensional plane**,

- The projection on the plane that spanned by the eigenvectors corresponding to the two largest eigenvalues of the covariance matrix of species composition matrix preserve the most variation.
- The explained variation of the two PCA axes are the sum of the two largest eigenvalues of the covariance matrix. The total variance is the sum of all the eigenvalues of the covariance matrix.
- 3. The **site score** of *j*-th data is the projection value of the *j*-th data on the PCA axes, i.e. the eigenvectors of the covariance matrix.
- 4. The **species score** of the *i*-th species is the projection value of the original *i*-th axis on the PCA axes, i.e. the eigenvectors of the covariance matrix.