Pair_HMM

February 22, 2021

Written report see end of the file

```
[223]: import numpy as np
       import os
       import collections
       import copy
       import pickle
       import random
       import time
       import matplotlib.pyplot as plt
  [2]: """
       Read alignment file into numpy array
       def func_file2seq(filepath):
           seq_list = []
           with open(filepath, 'r') as f1:
               for line in f1:
                   if line[0] == '>':
                       continue
                   else:
                       seq = list(line.strip().replace('\n','').upper())
                       seq_list.append(seq)
           return np.array(seq_list)
```

```
[3]: """
function to convert aligned sequence to pure sequence without '-' mark
"""

def pure_seq(seq_list):
    pure_list=[]
    for i in seq_list:
        seq_pair = []
        for j in i:
            seq_pair.append([aa for aa in j if aa != '-' ])
        pure_list.append(seq_pair)
    return pure_list
```

```
[47]: """
      The code to calculate the log(x+y+z) known log(x), log(y) and log(z)
      def logsum(num_list):
          #already logrithmic entry
          if len(num_list) == 0: return -np.inf
          anker = np.inf
          second_half = np.inf
          if type(num_list) == list:
              num_list = np.array(num_list).reshape(-1)
          else:
              num_list = num_list.reshape(-1)
          for i in range(num_list.shape[0]):
              if (not np.isinf(num_list[i])) and (not np.isnan(num_list[i])):
                  anker = num_list[i]
                  second_half = np.delete(num_list,i)
                  break
          if anker == np.inf:
              return -np.inf
          second_half = np.clip(second_half - anker, -np.inf,1233.9)
          return anker+np.log(np.exp(second_half).sum()+1)
 [6]: """
      Helper function when calculate backward matrix to determine index
      def index_determ(i,j,s2):
          if s2 == 0:
              return i+1, j+1, s2
          elif s2 == 1:
              return i+1, j, s2
          elif s2 == 2:
              return i, j+1, s2
 [7]: one2all ={'A': ('A', 'ALA', 'alanine'),
                    'R': ('R', 'ARG', 'arginine'),
                    'N': ('N', 'ASN', 'asparagine'),
                    'D': ('D', 'ASP', 'aspartic acid'),
                    'C': ('C', 'CYS', 'cysteine'),
                    'Q': ('Q', 'GLN', 'glutamine'),
                    'E': ('E', 'GLU', 'glutamic acid'),
                    'G': ('G', 'GLY', 'glycine'),
```

```
'H': ('H', 'HIS', 'histidine'),
'I': ('I', 'ILE', 'isoleucine'),
'L': ('L', 'LEU', 'leucine'),
'K': ('K', 'LYS', 'lysine'),
'M': ('M', 'MET', 'methionine'),
'F': ('F', 'PHE', 'phenylalanine'),
'P': ('P', 'PRO', 'proline'),
'S': ('S', 'SER', 'serine'),
'T': ('T', 'THR', 'threonine'),
'W': ('W', 'TRP', 'tryptophan'),
'Y': ('Y', 'TYR', 'tyrosine'),
'V': ('V', 'VAL', 'valine'),
'X': ('X', 'GLX', 'glutaminx'),
'Z': ('Z', 'GLI', 'glycine'),
'J': ('J', 'NLE', 'norleucine'),
  'U': ('U', 'CYC', 'cysteinc')}
```

```
[8]: """
    dictionary to convert aa to num
    """

aa2index={}
for i, aa in enumerate(list(one2all.keys())):
    if i == 20: break
    aa2index[aa] = i
```

```
[36]: """
    load training data
    """
    #load training data

with open("super_dataset_sampled100.txt", "rb") as fp: # Unpickling
    super_list_sampled = pickle.load(fp)

with open("twil_dataset_sampled100.txt", "rb") as fp: # Unpickling
    twil_list_sampled = pickle.load(fp)

super_list_train=super_list_sampled[:90]
super_list_val = super_list_sampled[:90]
twil_list_train = twil_list_sampled[:90]
twil_list_val = twil_list_sampled[:90]
```

```
[38]: """

calcualte blosum frequence as match state emit probability and

amino acid background frequency as insertion state emit frequency
"""
```

```
blosum_filepath = "/home/chingyuenliu/TTIC31160_bioinfo/hw2/BLOSUM62"
blosum = blosum2mat(blosum_filepath)
blosum_f = np.exp(blosum)
aa background f = np.zeros(20)
for i in super_list_train:
   values,counts = np.unique(i,return_counts=True)
   for v in range(values.shape[0]):
        if values[v] in aa2index:
            aa_background_f[aa2index[values[v]]] += counts[v]
aa_background_f=aa_background_f/aa_background_f.sum()
for i in range(blosum_f.shape[0]):
   for j in range(blosum_f.shape[1]):
       blosum_f[i,j] = blosum_f[i,j] * aa_background_f[i] * aa_background_f[j]
blosum_f = blosum_f/blosum_f.sum()
def l_para_init():
   states = ["Match", "Insert_X", "Insert_Y"]
```

```
[252]: """initiate the parameters of a local alignment HMM model"""
           1_para = {}
           emit_M = np.log(blosum_f)
           emit_X = np.tile(np.log(aa_background_f).reshape(-1,1),[1,20])
           emit_Y = np.tile(np.log(aa_background_f), [20,1])
           l_para['lgtau'] = np.log(0.1)
           tau = 0.1
           de = 0.3
           eta = 0.6
           l_para['trans_mat'] = np.
        \rightarrowarray([1-2*de,de,de,1-eta-tau,eta,0,1-eta-tau,0,eta]).reshape([3,3])
           l_para['trans_mat'] = np.log(l_para['trans_mat'])
           \#MM, MX, MY, XM, XX, XY, YM, YX, YY
           #there is no transition probability from match state to end state
           emit mat = np.zeros([20,20,3])
           emit_mat[:,:,0] = emit_M
           emit_mat[:,:,1] = emit_X
```

```
emit_mat[:,:,2] = emit_Y

l_para['emit_mat'] = emit_mat

return l_para
```

```
[253]: """initiate the parameters of a global alignment HMM model"""
       def g_para_init():
           states = ["Match", "Insert_X", "Insert_Y"]
           g_para = {}
           emit_M = np.log(blosum_f)
           emit_X = np.tile(np.log(aa_background_f).reshape(-1,1),[1,20])
           emit_Y = np.tile(np.log(aa_background_f), [20,1])
           g_para['lgtau'] = np.log(0.1)
           tau = 0.1
           de = 0.3
           eta = 0.6
           g_para['trans_mat'] = np.
        \rightarrowarray([1-2*de-tau,de,de,1-eta-tau,eta,0,1-eta-tau,0,eta]).reshape([3,3])
           g_para['trans_mat'] = np.log(g_para['trans_mat'])
           \#MM, MX, MY, XM, XX, XY, YM, YX, YY
           #here the match state has transition probability to ending state
           emit_mat = np.zeros([20,20,3])
           emit_mat[:,:,0] = emit_M
           emit_mat[:,:,1] = emit_X
           emit_mat[:,:,2] = emit_Y
           g_para['emit_mat'] = emit_mat
           return g_para
```

```
[41]: l_para = l_para_init()
```

/home/chingyuenliu/miniconda3/lib/python3.7/sitepackages/ipykernel_launcher.py:17: RuntimeWarning: divide by zero encountered in log

```
function to update match states of a local alignment model when do forward \Box
       \hookrightarrow algorithm
       11 11 11
      def forward_M_compute_l(i,j):
           if i == 0 or j == 0:
               return -np.inf
           fm = f_matrix[i-1,j-1,0]
           fx = f_{matrix}[i-1,j-1,1]
           fy = f_{matrix}[i-1,j-1,2]
           inf_index = [index for index, value in enumerate([fm,fx,fy]) if value !=__
       \rightarrow-np.inf]
           if len(inf_index) == 0:
               return -np.inf
           else:
               log_list = []
               for index in inf_index:
                    log_list.
       →append(l_para['emit_mat'][aa2index[seq1[i-1]],aa2index[seq2[j-1]]][0] + \
                                    l_para['trans_mat'][index,0] +

       \hookrightarrow f_matrix[i-1,j-1,index]
               if len(log_list) == 1:
                    return log_list[0]
               else:
                    return logsum(log_list)
[19]: """
      function to update match states of a local alignment model when do backward_{\sqcup}
       \hookrightarrow algorithm
       11 11 11
      def backward_M_compute_l(i,j):
           if i \ge m and j \ge n: return -np.inf
           if i == m and j < n:
               bm = -np.inf
               bx = -np.inf
               by = b_{matrix}[i, j+1, 2]
           elif i < m \text{ and } j == n:
               bm = -np.inf
               by = -np.inf
               bx = b_matrix[i+1,j,1]
           else:
               bm = b_matrix[i+1,j+1,0]
```

[18]: """

```
bx = b_matrix[i+1,j,1]
       by = b_{matrix}[i, j+1, 2]
   inf_index = [index for index, value in enumerate([bm,bx,by]) if value !=__
\rightarrow-np.inf]
   if len(inf index) == 0:
       return -np.inf
   else:
       log_list = []
       for index in inf_index:
           if index == 0:
                log_list.
→append(l_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
                           l_para['trans_mat'][0,index] +

\rightarrowb_matrix[i+1,j+1,index]
           if index == 1:
                log_list.append(l_para['emit_mat'][aa2index[seq1[i]],0][1] + \
                           l_para['trans_mat'][0,index] + b_matrix[i+1,j,index]__
→)
           if index == 2:
                log_list.append(l_para['emit_mat'][0,aa2index[seq2[j]]][2] + \
                           l_para['trans_mat'][0,index] + b_matrix[i,j+1,index]__
→)
       if len(log_list) == 1:
           return log_list[0]
       else:
           return logsum(log_list)
```

```
[21]: """
      function to update insertion states in sequence1 of a local alignment model \sqcup
       ⇔when do backward algorithm
      def backward_X_compute_l(i,j):
          if i >= m : return -np.inf
          if j > n: return -np.inf
          by = -np.inf
          if i < m and j == n:
              bm = -np.inf
              by = -np.inf
              bx = b_matrix[i+1,j,1]
          else:
              bm = b_matrix[i+1,j+1,0]
              bx = b_{matrix}[i+1,j,1]
          inf_index = [index for index, value in enumerate([bm,bx,-np.inf]) if value !
       \rightarrow= -np.inf]
          if len(inf_index) == 0:
              return -np.inf
          else:
              log_list = []
              for index in inf_index:
                   if index == 0:
                       log_list.
       append(l_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
                                   l_para['trans_mat'][1,index] +

       \rightarrowb_matrix[i+1,j+1,index]
                                   )
                   if index == 1:
                       log_list.append(l_para['emit_mat'][aa2index[seq1[i]],0][1] + \
                                   l_para['trans_mat'][1,index] + b_matrix[i+1,j,index]__
       →)
```

```
if len(log_list) == 1:
    return log_list[0]
else:
    return logsum(log_list)
```

```
[22]: """
      function to update insertion states in sequence2 of a local alignment model \sqcup
       ⇒when do forward algorithm
      def forward_Y_compute_l(i,j):
          if j == 0:
              return -np.inf
          fm = f_matrix[i, j-1, 0]
          fy = f_matrix[i, j-1, 2]
          inf_index = [index for index, value in enumerate([fm, -np.inf, fy]) if_
       →value != -np.inf]
          if len(inf_index) == 0:
              return -np.inf
          else:
              log_list = []
              for index in inf_index:
                  log_list.append(l_para['emit_mat'][0,aa2index[seq2[j-1]]][2] + \
                                  l_para['trans_mat'][index,2] + f_matrix[i,j-1,index]
              if len(log_list) == 1:
                  return log_list[0]
              else:
                  return logsum(log_list)
```

```
bm = b_matrix[i+1,j+1,0]
               by = b_{matrix}[i, j+1, 2]
           inf_index = [index for index, value in enumerate([bm,-np.inf,by]) if value !
        \rightarrow= -np.inf]
           if len(inf index) == 0:
                return -np.inf
           else:
               log_list = []
                for index in inf_index:
                    if index == 0:
                        log_list.
        \rightarrowappend(l_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
                                    l_para['trans_mat'][2,index] +

        \rightarrowb_matrix[i+1,j+1,index]
                    if index == 2:
                        log_list.append(l_para['emit_mat'][0,aa2index[seq2[j]]][2] + \
                                    l_para['trans_mat'][2,index] + b_matrix[i,j+1,index]__
        →)
                if len(log_list) == 1:
                    return log_list[0]
                else:
                    return logsum(log_list)
  []:
  []:
       """HMM model parameter training started"""
  []:
[257]: """initialize the model parameter"""
       l_para = l_para_init()
      /home/chingyuenliu/miniconda3/lib/python3.7/site-
      packages/ipykernel_launcher.py:18: RuntimeWarning: divide by zero encountered in
      log
[258]: """
       computation of updating the model parameter
       due to limit of computational power and lack of optimization, each sample is_{\sqcup}
        \hookrightarrow only do EM once.
```

else:

```
Here is to training the local alignment model on superfamily dataset
for seq_pair in super_list_train:
    seq1,seq2 = pure_seq([seq_pair])[0]
    #1.0 ca.1.
    m = len(seq1)
    n = len(seq2)
    for loop in range(1):
        #order match:0,x:1,y:2
        f_matrix = np.full([m+1,n+1, len(states)], -np.inf)
        b_matrix = np.full([m+1,n+1, len(states)], -np.inf)
        #the forward matrix is initiate with only insertion states has ____
 → transition probabilit from begin state
        #match state does not have transition probability
        f_{matrix}[0,0,1] = np.log(0.5)
        f matrix[0,0,2] = np.log(0.5)
        for i in range(0,m+1):
            for j in range(0,n+1):
                if i==0 and j ==0: continue
                f_matrix[i,j,0] = forward_M_compute_l(i,j)
                f_matrix[i,j,1] = forward_X_compute_l(i,j)
                f_matrix[i,j,2] = forward_Y_compute_l(i,j)
        #the backward matrix is initiated with only tau value on two insertion_
 \rightarrowstates
        b_matrix[m,n,1] = l_para['lgtau']
        b_matrix[m,n,2] = l_para['lgtau']
        for i in range(m,-1,-1):
            for j in range(n,-1,-1):
                if i ==m and j == n: continue
                b_matrix[i,j,0] = backward_M_compute_l(i,j)
                b_matrix[i,j,1] = backward_X_compute_l(i,j)
                b_matrix[i,j,2] = backward_Y_compute_l(i,j)
        gamma_matrix=f_matrix+b_matrix
        #Update parameter value
        trans_mat_new = np.zeros(l_para['trans_mat'].shape)
```

```
for s1 in range(trans_mat_new.shape[0]):
           for s2 in range(trans_mat_new.shape[1]):
                if (s1 == 1 \text{ and } s2 == 2) or (s1 == 2 \text{ and } s2 == 1):
                    trans_mat_new[s1,s2] = -np.inf
                    continue
                mat = np.zeros([m,n])
                for i in range(m):
                    for j in range(n):
                        mat[i,j] = 
\hookrightarrow f_matrix[i,j,s1]+b_matrix[index_determ(i,j,s2)] + l_para['trans_mat'][s1,s2]_\( \text{L} \)
→+ \
→l_para['emit_mat'] [aa2index[seq1[i]],aa2index[seq2[j]]][s2]
                trans_mat_new[s1,s2] = logsum(mat) - logsum(gamma_matrix[:,:
→,s1])
       l_para['lgtau'] = np.clip(np.log((3-np.exp(trans_mat_new).sum())/
\rightarrow2),-10,-1e-5)
       emit_mat_new = np.zeros(l_para['emit_mat'].shape)
       for aa1 in aa2index:
           for aa2 in aa2index:
                aal_index = [index for index, value in enumerate(seq1) if value_
→== aa1]
                aa2_index = [index for index, value in enumerate(seq2) if value_
→== aa2]
                value list = []
                for aa1_i in aa1_index:
                    for aa2_i in aa2_index:
                        value_list.append(gamma_matrix[aa1_i,aa2_i])
                if len(value_list) == 0:
                    for k in range(gamma_matrix.shape[2]):
                        emit mat new[aa2index[aa1],aa2index[aa2],k] = -np.inf
                    continue
                value_np = np.array(value_list)
                for k in range(value_np.shape[1]):
                    emit_mat_new[aa2index[aa1],aa2index[aa2],k] =__
→logsum(value_np[:,k])
       for it in range(emit_mat_new.shape[2]):
```

```
emit_mat_new[:,:,it] -= logsum(gamma_matrix[:,:,it])
               for it in range(20):
                   emit_mat_new[it,0,1] = logsum(emit_mat_new[it,:,1])
                   emit_mat_new[0,it,2] = logsum(emit_mat_new[:,it,2])
               emit_mat_new[:,:,1] = np.tile(emit_mat_new[:,0,1].reshape(-1,1),[1,20])
               emit_mat_new[:,:,2] = np.tile(emit_mat_new[0,:,2].reshape(1,-1),[20,1])
               emit_mat_new = np.clip(emit_mat_new,-10,-1e-5)
               l_para['emit_mat'] = emit_mat_new
               l_para['trans_mat'] = trans_mat_new
[262]: """save the model parameter
       1_para_super = copy.deepcopy(1_para)
[71]: """initiate the global HMM parameter"""
       g_para = g_para_init()
      /home/chingyuenliu/miniconda3/lib/python3.7/site-
      packages/ipykernel_launcher.py:17: RuntimeWarning: divide by zero encountered in
      log
  []:
[72]: """
       function to update match states of a global alignment model when do forward \sqcup
       \hookrightarrow algorithm
       def forward_M_compute_g(i,j):
           if i == 0 or j == 0:
               return -np.inf
           fm = f_matrix[i-1,j-1,0]
```

inf_index = [index for index, value in enumerate([fm,fx,fy]) if value !=_

fx = f_matrix[i-1,j-1,1]
fy = f_matrix[i-1,j-1,2]

if len(inf_index) == 0:
 return -np.inf

 \rightarrow -np.inf]

```
[73]: """
      function to update match states of a global alignment model when do backward \Box
       \hookrightarrow algorithm
       11 11 11
      def backward_M_compute_g(i,j):
          if i \ge m and j \ge n: return -np.inf
          if i == m and j < n:
               bm = -np.inf
               bx = -np.inf
               by = b_{matrix}[i,j+1,2]
          elif i < m and j == n:</pre>
               bm = -np.inf
               by = -np.inf
               bx = b_matrix[i+1,j,1]
          else:
               bm = b_matrix[i+1,j+1,0]
               bx = b_{matrix}[i+1,j,1]
               by = b_{matrix}[i,j+1,2]
           inf_index = [index for index, value in enumerate([bm,bx,by]) if value !=_
       \rightarrow-np.inf]
          if len(inf_index) == 0:
               return -np.inf
          else:
               log_list = []
               for index in inf_index:
                   if index == 0:
                        log_list.
       →append(g_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
                                    g_para['trans_mat'][0,index] + __
       →b_matrix[i+1,j+1,index]
                                    )
```

```
[74]: """
      function to update insert states of a global alignment model when do forward \Box
       \hookrightarrow algorithm
      def forward_X_compute_g(i,j):
          if i == 0:
              return -np.inf
          fm = f_matrix[i-1,j,0]
          fx = f_{matrix}[i-1,j,1]
          inf_index = [index for index, value in enumerate([fm,fx,-np.inf]) if value !
       \rightarrow= -np.inf]
          if len(inf_index) == 0:
               return -np.inf
          else:
              log_list = []
               for index in inf_index:
                   log_list.append(g_para['emit_mat'][aa2index[seq1[i-1]],0][1] + \
                                   g_para['trans_mat'][index,1] + f_matrix[i-1,j,index]
               if len(log_list) == 1:
                   return log_list[0]
               else:
                   return logsum(log_list)
```

```
if i >= m : return -np.inf
    if j > n: return -np.inf
    by = -np.inf
    if i < m and j == n:
        bm = -np.inf
        by = -np.inf
        bx = b_{matrix}[i+1, j, 1]
    else:
        bm = b_matrix[i+1,j+1,0]
        bx = b_{matrix}[i+1,j,1]
    inf_index = [index for index, value in enumerate([bm,bx,-np.inf]) if value !
 \rightarrow= -np.inf]
    if len(inf_index) == 0:
        return -np.inf
    else:
        log_list = []
        for index in inf index:
            if index == 0:
                 log_list.
→append(g_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
                             g_para['trans_mat'][1,index] +__
\rightarrowb_matrix[i+1,j+1,index]
            if index == 1:
                 log_list.append(g_para['emit_mat'][aa2index[seq1[i]],0][1] + \
                             g_para['trans_mat'][1,index] + b_matrix[i+1,j,index]__
→)
        if len(log_list) == 1:
            return log_list[0]
        else:
            return logsum(log_list)
function to update insert states of a global alignment model when do forward \Box
\hookrightarrow algorithm
```

```
[77]: """
      function to update insert states of a global alignment model when do backward \Box
       \hookrightarrow algorithm
      def backward_Y_compute_g(i,j):
          if j >= n: return -np.inf
          if i > m : return -np.inf
          bx = -np.inf
          if i == m and j < n:
               bm = -np.inf
               by = b_{matrix}[i, j+1, 2]
          else:
               bm = b_matrix[i+1,j+1,0]
               by = b_matrix[i, j+1, 2]
          inf_index = [index for index, value in enumerate([bm,-np.inf,by]) if value !
       \rightarrow= -np.inf]
          if len(inf_index) == 0:
               return -np.inf
          else:
               log_list = []
               for index in inf_index:
                   if index == 0:
                       log_list.
       →append(g para['emit mat'][aa2index[seq1[i]],aa2index[seq2[j]]][0] + \
```

[24]:

```
[78]: """
      computation of updating the model parameter
      due to limit of computational power and lack of optimization, each sample is_{\sqcup}
       \hookrightarrow only do EM once.
      Here is to training the global alignment model on superfamily dataset
      11 11 11
      #qlobal
      for seq_pair in super_list_train:
          seq1,seq2 = pure_seq([seq_pair])[0]
          m = len(seq1)
          n = len(seq2)
          \#order\ match:0,x:1,y:2
          for loop in range(1):
               f_matrix = np.full([m+1,n+1, len(states)], -np.inf)
              b_matrix = np.full([m+1,n+1, len(states)], -np.inf)
              f_{matrix}[0,0,0] = np.log(1/3)
              f_{matrix}[0,0,1] = np.log(1/3)
              f_{matrix}[0,0,2] = np.log(1/3)
              for i in range(0,m+1):
                   for j in range(0,n+1):
                       if i==0 and j ==0: continue
                       f_matrix[i,j,0] = forward_M_compute_g(i,j)
                       f_matrix[i,j,1] = forward_X_compute_g(i,j)
                       f_matrix[i,j,2] = forward_Y_compute_g(i,j)
              b_matrix[m,n,0] = g_para['lgtau']
```

```
b_matrix[m,n,1] = g_para['lgtau']
       b_matrix[m,n,2] = g_para['lgtau']
       for i in range(m,-1,-1):
           for j in range(n,-1,-1):
               if i ==m and j == n: continue
               b_matrix[i,j,0] = backward_M_compute_g(i,j)
               b_matrix[i,j,1] = backward_X_compute_g(i,j)
               b_matrix[i,j,2] = backward_Y_compute_g(i,j)
       gamma_matrix=f_matrix+b_matrix
       trans_mat_new = np.zeros(g_para['trans_mat'].shape)
       for s1 in range(trans_mat_new.shape[0]):
           for s2 in range(trans_mat_new.shape[1]):
               if (s1 == 1 \text{ and } s2 == 2) or (s1 == 2 \text{ and } s2 == 1):
                   trans_mat_new[s1,s2] = -np.inf
                   continue
               mat = np.zeros([m,n])
               for i in range(m):
                  for j in range(n):
                      mat[i,j] = 
→f_matrix[i,j,s1]+b_matrix[index_determ(i,j,s2)] + g_para['trans_mat'][s1,s2]_
→+ \
trans_mat_new[s1,s2] = logsum(mat) - logsum(gamma_matrix[:,:
→,s1])
       g_para['lgtau'] = np.clip(np.log((3-np.exp(trans_mat_new).sum())/3),__
⊶-10,-1e-5)
       emit_mat_new = np.zeros(g_para['emit_mat'].shape)
       for aa1 in aa2index:
           for aa2 in aa2index:
               aa1_index = [index for index, value in enumerate(seq1) if value_
\rightarrow == aa1
               aa2_index = [index for index, value in enumerate(seq2) if value_
→== aa21
               value_list = []
```

```
for aa1_i in aa1_index:
                           for aa2_i in aa2_index:
                               value_list.append(gamma_matrix[aa1_i,aa2_i])
                       if len(value_list) == 0:
                           for k in range(gamma_matrix.shape[2]):
                               emit_mat_new[aa2index[aa1],aa2index[aa2],k] = -np.inf
                           continue
                       value_np = np.array(value_list)
                       for k in range(value_np.shape[1]):
                           emit_mat_new[aa2index[aa1],aa2index[aa2],k] =__
        →logsum(value_np[:,k])
               for it in range(emit_mat_new.shape[2]):
                   emit_mat_new[:,:,it] -= logsum(gamma_matrix[:,:,it])
               for it in range(20):
                   emit_mat_new[it,0,1] = logsum(emit_mat_new[it,:,1])
                   emit_mat_new[0,it,2] = logsum(emit_mat_new[:,it,2])
               emit_mat_new[:,:,1] = np.tile(emit_mat_new[:,0,1].reshape(-1,1),[1,20])
               emit_mat_new[:,:,2] = np.tile(emit_mat_new[0,:,2].reshape(1,-1),[20,1])
               emit_mat_new = np.clip(emit_mat_new,-10,-1e-5)
               g_para['emit_mat'] = emit_mat_new
               g_para['trans_mat'] = trans_mat_new
[93]: g_para_super = copy.deepcopy(g_para)
[264]: | 1_para = 1_para_init()
      /home/chingyuenliu/miniconda3/lib/python3.7/site-
      packages/ipykernel_launcher.py:18: RuntimeWarning: divide by zero encountered in
      log
[106]: """
       computation of updating the model parameter
       due to limit of computational power and lack of optimization, each sample is_{\sqcup}
```

Here is to training the local alignment model on twilight dataset

 \hookrightarrow only do EM once.

n n n

```
for seq_pair in twil_list_train:
    seq1,seq2 = pure_seq([seq_pair])[0]
    #local
    m = len(seq1)
    n = len(seq2)
    for loop in range(1):
        #order match:0,x:1,y:2
        f_matrix = np.full([m+1,n+1, len(states)], -np.inf)
        b_matrix = np.full([m+1,n+1, len(states)], -np.inf)
        f_{\text{matrix}}[0,0,1] = \text{np.log}(0.5)
        f_{matrix}[0,0,2] = np.log(0.5)
        for i in range(0,m+1):
            for j in range(0,n+1):
                if i==0 and j ==0: continue
                f_matrix[i,j,0] = forward_M_compute_l(i,j)
                f_matrix[i,j,1] = forward_X_compute_l(i,j)
                f_matrix[i,j,2] = forward_Y_compute_l(i,j)
        b_matrix[m,n,1] = l_para['lgtau']
        b_matrix[m,n,2] = l_para['lgtau']
        for i in range(m,-1,-1):
            for j in range(n,-1,-1):
                if i ==m and j == n: continue
                b_matrix[i,j,0] = backward_M_compute_l(i,j)
                b_matrix[i,j,1] = backward_X_compute_l(i,j)
                b_matrix[i,j,2] = backward_Y_compute_l(i,j)
        gamma_matrix=f_matrix+b_matrix
        trans_mat_new = np.zeros(l_para['trans_mat'].shape)
        for s1 in range(trans_mat_new.shape[0]):
            for s2 in range(trans_mat_new.shape[1]):
                if (s1 == 1 \text{ and } s2 == 2) or (s1 == 2 \text{ and } s2 == 1):
                     trans_mat_new[s1,s2] = -np.inf
                     continue
                mat = np.zeros([m,n])
                for i in range(m):
                     for j in range(n):
                         mat[i,j] = 

→f_matrix[i,j,s1]+b_matrix[index_determ(i,j,s2)] + l_para['trans_mat'][s1,s2]

□
```

```
→l_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][s2]
               trans_mat_new[s1,s2] = logsum(mat) - logsum(gamma_matrix[:,:
\rightarrow,s1])
       l_para['lgtau'] = np.clip(np.log((3-np.exp(trans_mat_new).sum())/2),__
\rightarrow-10,-1e-5)
       emit_mat_new = np.zeros(l_para['emit_mat'].shape)
       for aa1 in aa2index:
           for aa2 in aa2index:
               aal_index = [index for index, value in enumerate(seq1) if value_
→== aa1]
               aa2_index = [index for index, value in enumerate(seq2) if value_
→== aa2]
               value_list = []
               for aa1_i in aa1_index:
                   for aa2_i in aa2_index:
                       value_list.append(gamma_matrix[aa1_i,aa2_i])
               if len(value_list) == 0:
                   for k in range(gamma_matrix.shape[2]):
                       emit_mat_new[aa2index[aa1],aa2index[aa2],k] = -np.inf
                   continue
               value_np = np.array(value_list)
               for k in range(value_np.shape[1]):
                   emit_mat_new[aa2index[aa1],aa2index[aa2],k] =__
→logsum(value_np[:,k])
       for it in range(emit_mat_new.shape[2]):
           emit_mat_new[:,:,it] -= logsum(gamma_matrix[:,:,it])
       for it in range(20):
           emit_mat_new[it,0,1] = logsum(emit_mat_new[it,:,1])
           emit_mat_new[0,it,2] = logsum(emit_mat_new[:,it,2])
       emit_mat_new[:,:,1] = np.tile(emit_mat_new[:,0,1].reshape(-1,1),[1,20])
       emit_mat_new[:,:,2] = np.tile(emit_mat_new[0,:,2].reshape(1,-1),[20,1])
       emit_mat_new = np.clip(emit_mat_new,-10,-1e-5)
```

```
l_para['emit_mat'] = emit_mat_new
l_para['trans_mat'] = trans_mat_new
```

/home/chingyuenliu/miniconda3/lib/python3.7/sitepackages/ipykernel_launcher.py:22: RuntimeWarning: overflow encountered in exp

```
[108]: l_para_twil = copy.deepcopy(l_para)
[194]: g_para = g_para_init()
```

/home/chingyuenliu/miniconda3/lib/python3.7/sitepackages/ipykernel_launcher.py:17: RuntimeWarning: divide by zero encountered in log

```
[195]: """
       computation of updating the model parameter
       due to limit of computational power and lack of optimization, each sample is_{\sqcup}
        \hookrightarrow only do EM once.
       Here is to training the global alignment model on twilight dataset
       11 11 11
       #qlobal
       for seq_pair in twil_list_train:
           seq1,seq2 = pure_seq([seq_pair])[0]
           m = len(seq1)
           n = len(seq2)
           \#order\ match:0,x:1,y:2
           for loop in range(1):
                f_matrix = np.full([m+1,n+1, len(states)], -np.inf)
                b_matrix = np.full([m+1,n+1, len(states)], -np.inf)
                f_{matrix}[0,0,0] = np.log(1/3)
                f_{matrix}[0,0,1] = np.log(1/3)
                f_{\text{matrix}}[0,0,2] = \text{np.log}(1/3)
                for i in range(0,m+1):
                    for j in range(0,n+1):
                        if i==0 and j ==0: continue
                        f_matrix[i,j,0] = forward_M_compute_g(i,j)
                         f_matrix[i,j,1] = forward_X_compute_g(i,j)
                         f_matrix[i,j,2] = forward_Y_compute_g(i,j)
```

```
b_matrix[m,n,0] = g_para['lgtau']
       b_matrix[m,n,1] = g_para['lgtau']
       b_matrix[m,n,2] = g_para['lgtau']
       for i in range(m,-1,-1):
           for j in range(n,-1,-1):
               if i == m and j == n: continue
                b_matrix[i,j,0] = backward_M_compute_g(i,j)
                b_matrix[i,j,1] = backward_X_compute_g(i,j)
                b_matrix[i,j,2] = backward_Y_compute_g(i,j)
       gamma_matrix=f_matrix+b_matrix
       trans_mat_new = np.zeros(g_para['trans_mat'].shape)
       for s1 in range(trans_mat_new.shape[0]):
           for s2 in range(trans_mat_new.shape[1]):
                if (s1 == 1 \text{ and } s2 == 2) or (s1 == 2 \text{ and } s2 == 1):
                    trans_mat_new[s1,s2] = -np.inf
                    continue
               mat = np.zeros([m,n])
                for i in range(m):
                    for j in range(n):
                        mat[i,j] =
→f_matrix[i,j,s1]+b_matrix[index_determ(i,j,s2)] + g_para['trans_mat'][s1,s2]_⊔
→+ \

→g_para['emit_mat'][aa2index[seq1[i]],aa2index[seq2[j]]][s2]

                trans_mat_new[s1,s2] = logsum(mat) - logsum(gamma_matrix[:,:
→,s1])
       g_para['lgtau'] = np.clip(np.log((3-np.exp(trans_mat_new).sum())/3),__
\rightarrow-10,-1e-5)
       emit_mat_new = np.zeros(g_para['emit_mat'].shape)
       for aa1 in aa2index:
           for aa2 in aa2index:
                aal_index = [index for index, value in enumerate(seq1) if value_
→== aa1]
                aa2_index = [index for index, value in enumerate(seq2) if value_
\rightarrow == aa2
```

```
value_list = []
                       for aa1_i in aa1_index:
                           for aa2_i in aa2_index:
                               value_list.append(gamma_matrix[aa1_i,aa2_i])
                       if len(value_list) == 0:
                           for k in range(gamma_matrix.shape[2]):
                               emit_mat_new[aa2index[aa1],aa2index[aa2],k] = -np.inf
                           continue
                       value_np = np.array(value_list)
                       for k in range(value_np.shape[1]):
                           emit_mat_new[aa2index[aa1],aa2index[aa2],k] =__
        →logsum(value_np[:,k])
               for it in range(emit_mat_new.shape[2]):
                   emit_mat_new[:,:,it] -= logsum(gamma_matrix[:,:,it])
               for it in range(20):
                   emit_mat_new[it,0,1] = logsum(emit_mat_new[it,:,1])
                   emit_mat_new[0,it,2] = logsum(emit_mat_new[:,it,2])
               emit_mat_new[:,:,1] = np.tile(emit_mat_new[:,0,1].reshape(-1,1),[1,20])
               emit_mat_new[:,:,2] = np.tile(emit_mat_new[0,:,2].reshape(1,-1),[20,1])
               emit_mat_new = np.clip(emit_mat_new,-10,-1e-5)
               g_para['emit_mat'] = emit_mat_new
               g_para['trans_mat'] = trans_mat_new
[197]: g_para_twil = copy.deepcopy(g_para)
 []: """testing/accuracy"""
[198]: """Loading 100 test datapoints"""
       with open("super_dataset_sampled1000.txt", "rb") as fp: # Unpickling
           super_list_test = pickle.load(fp)[100:200]
       with open("twil_dataset_sampled1000.txt", "rb") as fp: # Unpickling
           twil_list_test = pickle.load(fp)[100:200]
[150]: """viterbi algorithm for match state"""
       def forward_M_compute_v(i,j):
           if i == 0 or j == 0:
              return -np.inf, -np.inf
```

```
log_np = np.zeros(3)
           for index in range(log_np.shape[0]):
               log_np[index] =
        \hookrightarrow (l_para_vit['emit_mat'][aa2index[seq1[i-1]],aa2index[seq2[j-1]]][0] + \
                                    l_para_vit['trans_mat'][index,0] +__
        \rightarrowv matrix[i-1,j-1,index,0]
           return log_np.max(),log_np.argmax()
[128]: """viterbi algorithm for seg1 insertion state"""
       def forward_X_compute_v(i,j):
           if i == 0:
               return -np.inf, -np.inf
           log_np = np.zeros(2)
           for index in range(log_np.shape[0]):
               log_np[index] = (l_para_vit['emit_mat'][aa2index[seq1[i-1]],0][1] + \
                                   l_para_vit['trans_mat'][index,1] +

        \rightarrowv_matrix[i-1,j,index,0]
                             )
           return log_np.max(),log_np.argmax()
[151]: """viterbi algorithm for seg2 insertion state"""
       def forward_Y_compute_v(i,j):
           if j == 0:
               return -np.inf, -np.inf
           log_np = np.zeros(3)
           log_np[1] = -np.inf
           for index in [0,2]:
               log np[index] = (1_para_vit['emit_mat'][0,aa2index[seq2[j-1]]][2] + \
                                    l_para_vit['trans_mat'][index,2] +
__
        \rightarrowv_matrix[i,j-1,index,0]
           return log_np.max(),log_np.argmax()
[205]: """index the sequence for calculating accuracy"""
       def seq_idx(seq):
           #change the letter sequence to index sequence
           seq_lst = []
           counter = 0
           for i in seq:
               if i.isalpha():
```

seq_lst.append(counter)

```
counter +=1
        else:
            seq_lst.append(-1)
    return seq_lst
"""accuracy calculating"""
def accuracy(seq0_gt,seq1_gt,seq0_al,seq1_al):
    seq1_gt_lst = seq_idx(seq1_gt)
    seq0_gt_lst = seq_idx(seq0_gt)
    seq0_al_lst = seq_idx(seq0_al)
    seq1_al_lst = seq_idx(seq1_al)
    gt_aln_idx = list(zip(seq0_gt_lst,seq1_gt_lst))
    al_aln_idx = list(zip(seq0_al_lst,seq1_al_lst))
    #count how many alignment in both cases
    true_pos=[]
    for i in al_aln_idx:
        if i in gt_aln_idx:
            true_pos.append(i)
    precision = len(true_pos)/len(gt_aln_idx)
    recall = len(true_pos)/len(al_aln_idx)
    f1 = 2/(precision**-1+recall**-1)
    return precision, recall, f1
```

```
[202]: """tracing function for local alignment
       when initate, only two insertion state are considered
       11 11 11
       def local_backtracing(seq1,seq2,mtx):
           seq1 list=[]
           seq2_list=[]
           m=len(seq1)
           n=len(seq2)
           index = int(mtx[m,n,1:,0].argmax()+1)
           m1 = m
           n1 = n
           while (True):
               new_index = mtx[m1,n1,index,1]
               if index == 0:
                   seq1_list.append(seq1[m1-1])
                   seq2_list.append(seq2[n1-1])
                   m1 -= 1
                   n1 -= 1
```

```
elif index == 1:
    seq1_list.append(seq1[m1-1])
    seq2_list.append('-')
    m1 -= 1
elif index == 2:
    seq2_list.append(seq2[n1-1])
    seq1_list.append('-')
    n1 -= 1

else:
    break
if new_index == -np.inf:
    break
else:
    index = int(new_index)
return seq1_list[::-1], seq2_list[::-1]
```

```
[203]: """tracing function for global alignment
       def global_backtracing(seq1,seq2,mtx):
           seq1_list=[]
           seq2_list=[]
           m=len(seq1)
           n=len(seq2)
           index = int(mtx[m,n,:,0].argmax())
           m1 = m
           n1 = n
           while (True):
               new_index = mtx[m1,n1,index,1]
               if index == 0:
                   seq1_list.append(seq1[m1-1])
                   seq2_list.append(seq2[n1-1])
                   m1 -= 1
                   n1 -= 1
               elif index == 1:
                   seq1_list.append(seq1[m1-1])
                   seq2_list.append('-')
                   m1 -= 1
               elif index == 2:
                   seq2_list.append(seq2[n1-1])
                   seq1_list.append('-')
                   n1 -= 1
               else:
```

```
break
if new_index == -np.inf:
    break
else:
    index = int(new_index)

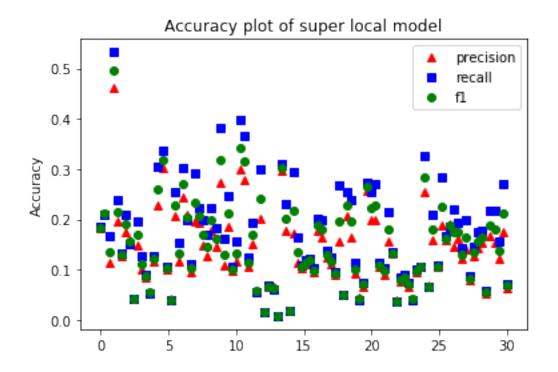
return seq1_list[::-1], seq2_list[::-1]
```

```
[267]: """accuracy calculating for local HMM model trained of superfamily ontou
        \hookrightarrow superfamily dataset"""
       #local viterbi
       precision_local_ss=[]
       recall_local_ss =[]
       f1_local_ss = []
       l_para_vit = copy.deepcopy(l_para_super)
       for seq_pair in super_list_test:
           seq1,seq2 = pure_seq([seq_pair])[0]
           m = len(seq1)
           n = len(seq2)
           #M, X, Y plus a dimension to store the index
           v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)
           v_{matrix}[0,0,1,0] = np.log(0.5)
           v_{matrix}[0,0,2,0] = np.log(0.5)
           for i in range(0,m+1):
               for j in range(0,n+1):
                   if i==0 and j ==0: continue
                   v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
                   v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
                   v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)
           seq1_aln, seq2_aln = local_backtracing(seq1,seq2,v_matrix)
           precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)
           precision_local_ss.append(precision)
           recall_local_ss.append(recall)
           f1_local_ss.append(f1)
```

```
[268]: t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_local_ss, 'r^',label='precision')
plt.plot(t, recall_local_ss, 'bs',label='recall')
plt.plot(t, f1_local_ss, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of super local model')
plt.legend()
```

[268]: <matplotlib.legend.Legend at 0x7fc16c40a790>



Local HMM trained from superfamily dataset has precision: 0.13959962573732296, recall: 0.17025187203562056, f1: 0.15265297783442647

```
[230]: """accuracy calculating for global HMM model trained of superfamily onto□

⇒superfamily dataset"""

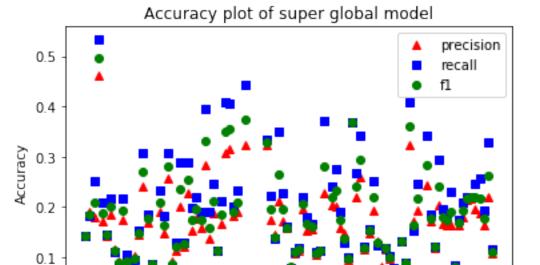
#global viterbi

precision_global_ss=[]
```

```
f1_global_ss = []
       l_para_vit = copy.deepcopy(g_para_super)
       for seq_pair in super_list_test:
           seq1,seq2 = pure_seq([seq_pair])[0]
           m = len(seq1)
           n = len(seq2)
           #M, X, Y plus a dimension to store the index
           v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)
           v_{matrix}[0,0,0,0] = np.log(1/3)
           v_{matrix}[0,0,1,0] = np.log(1/3)
           v_{matrix}[0,0,2,0] = np.log(1/3)
           for i in range(0,m+1):
               for j in range(0,n+1):
                   if i==0 and j==0: continue
                   v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
                   v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
                   v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)
           seq1 aln, seq2 aln = global backtracing(seq1,seq2,v matrix)
           precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)
           precision_global_ss.append(precision)
           recall_global_ss.append(recall)
           f1_global_ss.append(f1)
[231]: t = np.linspace(0., 30, 100)
       # red dashes, blue squares and green triangles
       plt.plot(t, precision_global_ss, 'r^',label='precision')
       plt.plot(t, recall_global_ss, 'bs',label='recall')
       plt.plot(t, f1_global_ss, 'go',label='f1')
       plt.ylabel('Accuracy')
       plt.title(f'Accuracy plot of super global model')
      plt.legend()
```

[231]: <matplotlib.legend.Legend at 0x7fc16ec27350>

recall_global_ss =[]



```
[232]: print(f"global HMM trained from superfamily dataset has precision: {np. 

→mean(precision_global_ss)},\

recall: {np.mean(recall_global_ss)}, f1: {np.mean(f1_global_ss)} ")
```

0.0

global HMM trained from superfamily dataset has precision: 0.16195043878690535, recall: 0.19083277704049906, f1: 0.1742728308620195

```
v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)

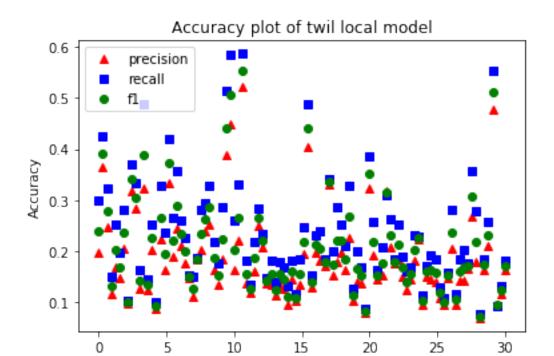
v_matrix[0,0,1,0] = np.log(0.5)
v_matrix[0,0,2,0] = np.log(0.5)
for i in range(0,m+1):
    for j in range(0,n+1):
        if i==0 and j ==0: continue
            v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
            v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
            v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)

seq1_aln, seq2_aln = local_backtracing(seq1,seq2,v_matrix)
precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)
precision_local_tt.append(precision)
recall_local_tt.append(recall)
f1_local_tt.append(f1)
```

```
[234]: t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_local_tt, 'r^',label='precision')
plt.plot(t, recall_local_tt, 'bs',label='recall')
plt.plot(t, f1_local_tt, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of twil local model')
plt.legend()
```

[234]: <matplotlib.legend.Legend at 0x7fc16c90ae50>



```
[235]: print(f"Local HMM trained from twilfamily dataset has precision: {np.

-mean(precision_local_tt)},\

recall: {np.mean(recall_local_tt)}, f1: {np.mean(f1_local_tt)} ")
```

Local HMM trained from twilfamily dataset has precision: 0.18807076966315286, recall: 0.2369704209344629, f1: 0.2090630998850981

```
v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)

v_matrix[0,0,0,0] = np.log(1/3)
v_matrix[0,0,1,0] = np.log(1/3)
v_matrix[0,0,2,0] = np.log(1/3)

for i in range(0,m+1):
    for j in range(0,n+1):
        if i==0 and j ==0: continue
            v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
            v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
            v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)

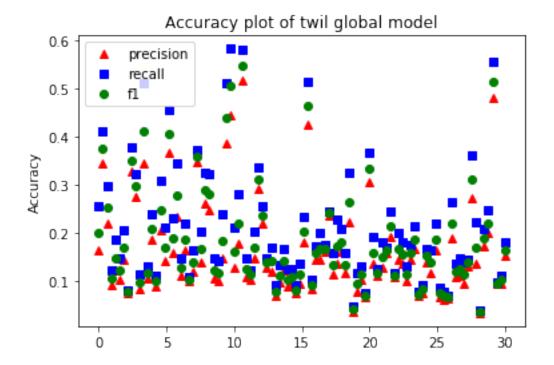
seq1_aln, seq2_aln = global_backtracing(seq1,seq2,v_matrix)
precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)

precision_global_tt.append(precision)
recall_global_tt.append(recall)
f1_global_tt.append(f1)
```

```
[238]: t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_global_tt, 'r^',label='precision')
plt.plot(t, recall_global_tt, 'bs',label='recall')
plt.plot(t, f1_global_tt, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of twil global model')
plt.legend()
```

[238]: <matplotlib.legend.Legend at 0x7fc16c76bad0>



```
[239]: print(f"global HMM trained from twilfamily dataset has precision: {np. 

→mean(precision_global_tt)},\

recall: {np.mean(recall_global_tt)}, f1: {np.mean(f1_global_tt)} ")
```

global HMM trained from twilfamily dataset has precision: 0.16361888785939016, recall: 0.21133571282306718, f1: 0.18390099334040383

```
#M,X,Y plus a dimension to store the index
v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)

v_matrix[0,0,1,0] = np.log(0.5)
v_matrix[0,0,2,0] = np.log(0.5)
for i in range(0,m+1):
    for j in range(0,n+1):
        if i==0 and j ==0: continue
            v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
            v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
            v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)

seq1_aln, seq2_aln = local_backtracing(seq1,seq2,v_matrix)
precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)

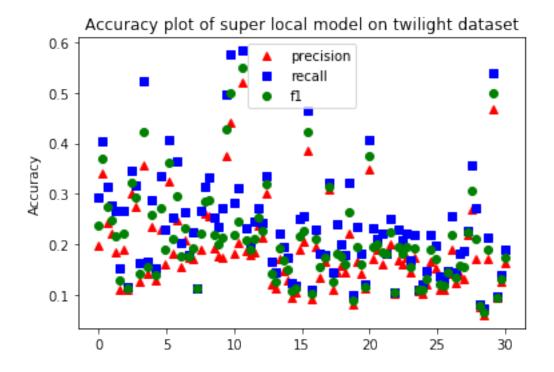
precision_local_st.append(precision)
    recall_local_st.append(recall)
    f1_local_st.append(f1)

# evenly sampled time at 200ms intervals
t = np.linspace(0, 30, 100)
```

```
[241]: # evenly sampled time at 200ms intervals
t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_local_st, 'r^',label='precision')
plt.plot(t, recall_local_st, 'bs',label='recall')
plt.plot(t, f1_local_st, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of super local model on twilight dataset')
plt.legend()
```

[241]: <matplotlib.legend.Legend at 0x7fc16f8dc990>

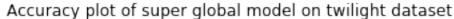


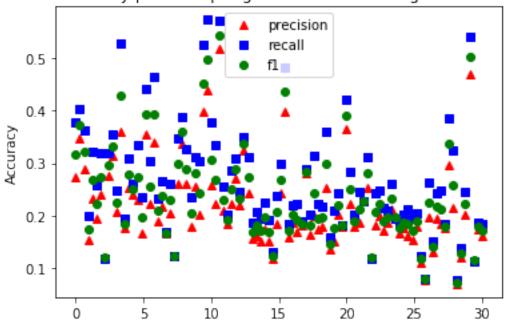
Local HMM trained from superfamily dataset has precision: 0.18812863939816027, recall: 0.23739871062451848, f1: 0.2093055739634981

```
[244]: t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_global_st, 'r^',label='precision')
plt.plot(t, recall_global_st, 'bs',label='recall')
plt.plot(t, f1_global_st, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of super global model on twilight dataset')
plt.legend()
```

[244]: <matplotlib.legend.Legend at 0x7fc16c78a490>





global HMM trained from superfamily dataset has precision: 0.21655679776450623, recall: 0.2667934896898755, f1: 0.23843377958409648

```
v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)

v_matrix[0,0,1,0] = np.log(0.5)
v_matrix[0,0,2,0] = np.log(0.5)
for i in range(0,m+1):
    for j in range(0,n+1):
        if i==0 and j ==0: continue
        v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
        v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
        v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)

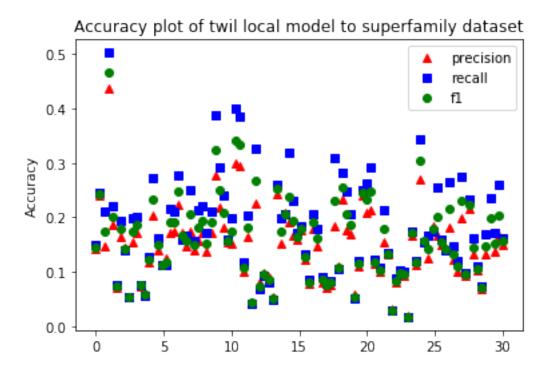
seq1_aln, seq2_aln = local_backtracing(seq1,seq2,v_matrix)
precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)

precision_local_ts.append(precision)
recall_local_ts.append(recall)
f1_local_ts.append(f1)
```

```
[247]: t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_local_ts, 'r^',label='precision')
plt.plot(t, recall_local_ts, 'bs',label='recall')
plt.plot(t, f1_local_ts, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of twil local model to superfamily dataset')
plt.legend()
```

[247]: <matplotlib.legend.Legend at 0x7fc16c55c690>



```
[248]: print(f"Local HMM trained from twilfamily dataset has precision: {np. 

→mean(precision_local_ts)},\

recall: {np.mean(recall_local_ts)}, f1: {np.mean(f1_local_ts)} ")
```

Local HMM trained from twilfamily dataset has precision: 0.15039429309041574, recall: 0.18047789672790196, f1: 0.16322383768011245

```
[249]:
    """accuracy calculating for global HMM model trained of twilight onto
    superfamily dataset"""
    #global viterbi
    #twil to super
    precision_global_ts=[]
    recall_global_ts =[]
    f1_global_ts = []

    l_para_vit = copy.deepcopy(g_para_twil)

    for seq_pair in super_list_test:
        seq1,seq2 = pure_seq([seq_pair])[0]
        m = len(seq1)
        n = len(seq2)

    #M,X,Y plus a dimension to store the index
```

```
v_matrix = np.full([m+1,n+1, len(states),2], -np.inf)

v_matrix[0,0,0,0] = np.log(1/3)
v_matrix[0,0,1,0] = np.log(1/3)
v_matrix[0,0,2,0] = np.log(1/3)
for i in range(0,m+1):
    if i==0 and j ==0: continue
        v_matrix[i,j,0,:] = forward_M_compute_v(i,j)
        v_matrix[i,j,1,:] = forward_X_compute_v(i,j)
        v_matrix[i,j,2,:] = forward_Y_compute_v(i,j)

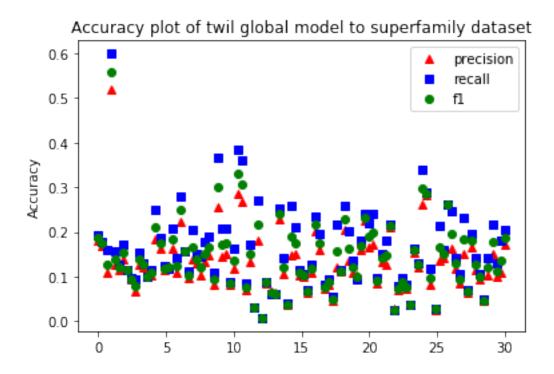
seq1_aln, seq2_aln = global_backtracing(seq1,seq2,v_matrix)
precision, recall, f1 = accuracy(seq_pair[0],seq_pair[1],seq1_aln,seq2_aln)

precision_global_ts.append(precision)
recall_global_ts.append(f1)
```

```
[250]: # evenly sampled time at 200ms intervals
t = np.linspace(0., 30, 100)

# red dashes, blue squares and green triangles
plt.plot(t, precision_global_ts, 'r^',label='precision')
plt.plot(t, recall_global_ts, 'bs',label='recall')
plt.plot(t, f1_global_ts, 'go',label='f1')
plt.ylabel('Accuracy')
plt.title(f'Accuracy plot of twil global model to superfamily dataset')
plt.legend()
```

[250]: <matplotlib.legend.Legend at 0x7fc16c53e090>



```
[251]: print(f"global HMM trained from twilfamily dataset has precision: {np. 

→mean(precision_global_ts)},\

recall: {np.mean(recall_global_ts)}, f1: {np.mean(f1_global_ts)} ")
```

global HMM trained from twilfamily dataset has precision: 0.13176823179562913, recall: 0.16205758288738245, f1: 0.1446183693787298

Due to the limit of computational power and optimization, only 100 datapoints is used for training and 100 datapoints for testing, so all the accuracy value do not have any significance.

The model implemented are two of the most simple pair HMM. One begin state, one end state, one insertion state for seq1, one insertion state for seq2 and a match state. Two insertion state do not have transition probability and local alignment model, match state do not transit from begin state or to end state. The begin state transition probability and end state transition probability are spread equally.

For superfamily local model, it has precision: 0.14, recall: 0.17, f1: 0.15. However, this model performed better onto the twilight dataset, with precision: 0.18, recall:0.24, f1: 0.20. This happened same for superfamily global alignment model as well. It performed better on twilight dataset than on superfamily dataset. The general trend is that all the model performed better on twilight dataset than on superfamily dataset. Even it is counter intuitive that a model is performed better on a unseen dataset, but given the information that twilight dataset is less similar than superfamily, suggesting pairHMM is doing better with weak connections

For the model trained from same dataset, there is no general trend. For superfamily dataset, global alignment model performed better(f1 score:0.17 vs. 0.15). For twilight dataset, local alignment model performed better.(f1 score:0.21 vs. 0.18). I was expecting local alignment model would

perform better on precision while global alignment model would perform better on recall. However, none of this happened. But this observation can be explained. Since accuracy for all the models are quite low, as superfamily dataset is more similar, global alignment with more converage would cover more hits, thus better precision as well. And since twilight dataset is less similar, local alignment model would better find those alignments.

The details of all the accuracy of different scenario can be seen from all the plots prior generated.