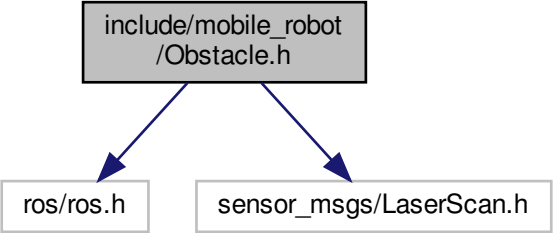


include/mobile\_robot  
/Obstacle.h



```
graph TD; A["include/mobile_robot/Obstacle.h"] --> B["ros/ros.h"]; A --> C["sensor_msgs/LaserScan.h"]
```

The diagram illustrates a C++ header file's dependencies. At the top, a grey box contains the text 'include/mobile\_robot/Obstacle.h'. Two blue arrows originate from the bottom of this box. The left arrow points to a white box containing 'ros/ros.h'. The right arrow points to a white box containing 'sensor\_msgs/LaserScan.h'.

ros/ros.h

sensor\_msgs/LaserScan.h