



Single-cycle RISC-V processor for solving Linear system of equations

Group 3

| Name | Enrollment no. | Branch |
|---------------|-----------------------|---------------|
| Chinmay Patel | B23487 | VLSI |
| Garvit Garg | B23488 | VLSI |
| Rushabh Lodha | B23495 | VLSI |
| Jigeesha Sur | B22212 | Electrical |
| Vani Dhiman | B23505 | VLSI |
| Talla Bhavana | B23471 | VLSI |
| Parv A. Joshi | B23090 | VLSI |

The Problem Statement

Design your own custom single-cycle RISC-V processor using Verilog-HDL by choosing instructions based on your own consideration to achieve a **Linear system of equation solver (at-least 3 variables)**.

Overview

The implementation follows the RV32I base integer instruction set and completes all stages (fetch, decode, execute, memory, write-back) in a single clock cycle. The processor includes:

1. Program Counter (PC)
2. Instruction Memory
3. Instruction Decoder
4. 32 General-purpose registers(32×32 -bit)
5. ALU (Arithmetic Logic Unit)
6. Data Memory
7. Control Unit
8. MUXes and ALU Control

Steps to achieve the solution:

1. Begin by writing C code: To solve a system of 3 linear equations with 3 variables, represented in augmented matrix form (3×4). It uses Gaussian elimination with partial pivoting and avoids floating-point operations by:

- Multiplying via repeated addition

- Dividing via repeated subtraction

Matrix initialization as:

A = {
 {1, 2, 3, 4},
 {2, 3, 4, 5},
 {3, 4, 5, 6}
 }

Represented as:

$$1x + 2y + 3z = 4$$

$$2x + 3y + 4z = 5$$

$$3x + 4y + 5z = 6$$

Why It's Easy to run for our process

- No floats
- Fixed-size arrays
- Controlled branching

2. Cross compilation to assembly

We used the RISC-V GCC toolchain to convert the C code into assembly code which will generate the RISC-V assembly version of your C code.

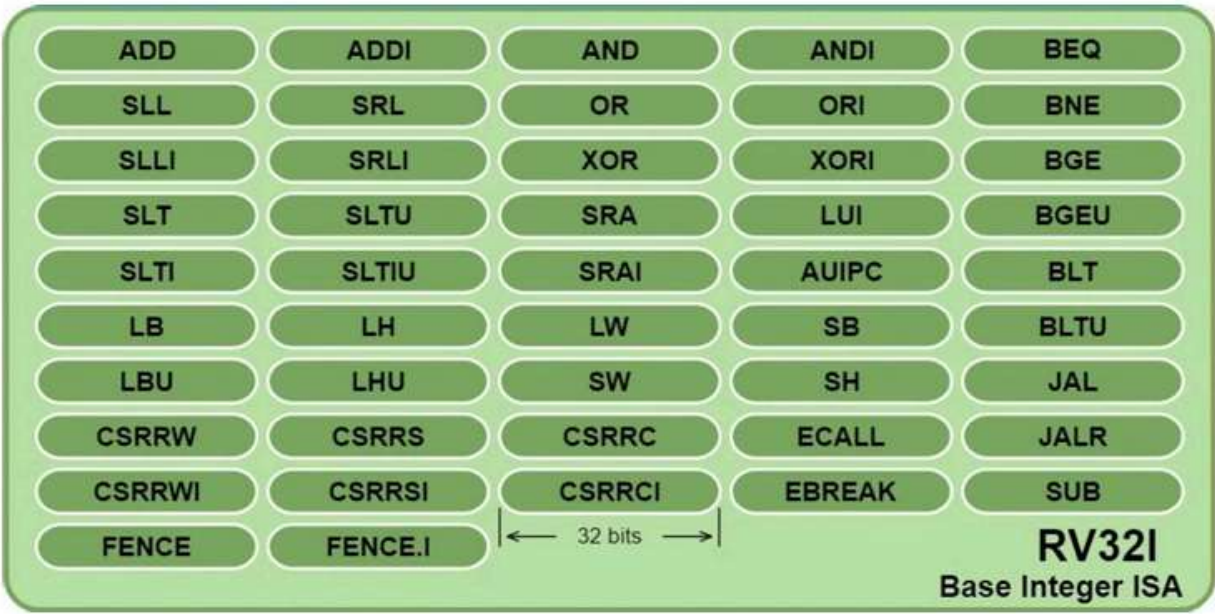
3. Replacing all pseudo instructions with their actual RISC-V instructions.

The main pseudo instructions in the code are

| Pseudo | Replaced With |
|--------|---------------|
|--------|---------------|

| | |
|---------------------|----------------|
| li (load immediate) | lui and addi |
| mv (move) | addi with zero |
| ret (return) | jalr with zero |

Required Base Instructions



Arithmetic and Logic

| Instruction | Purpose |
|-------------|--|
| add | Basic addition(used in loops and array calculations) |
| sub | Subtraction (used in division and elimination) |
| addi | Add immediate (loop counters, constants) |

| | |
|------|---|
| lui | Load upper immediate (for li replacement) |
| slli | Shift left |
| jal | Jump And Link |
| beq | Branch if equal to |

Memory Access

| Instruction | Purpose |
|-------------|---|
| lw | Load Word (read array elements like A[i][j]) |
| sw | Store word (write back updated matrix values) |

4. Testing

We tested the processor using individual instructions. The output is stored in the registers or data memory printed to the console upon simulation end. To run the simulation:

1. Load files in Vivado
2. Compile all modules
3. Run simulation and observe output

Acknowledgement and Contributions

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- Rushabh Lodha: GNU compilation, algorithm simplification
- Parv A. Joshi: Data Memory Integration, Verification, Debugging
- Chinmay Patel: Instruction memory, Control Unit design, Testing, debugging
- Garvit Garg: Data memory setup, PC and Immediate, TB development (also got TCL console running)
- Jigeesha Sur: Algorithm design, Documentation and report
- Vani Dhiman: Main and ALU decoder, Instruction verification
- Talla Bhavana: Main and ALU decoder, Instruction verification