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#TakeHome 2

Balancing the Dataset

We have 83 AEP class vectors and 2482 non-AEP class vectors. Clearly the Dataset is imbalanced.

Final Dataset Used:

240 AEP-vectors, 240 non-AEP vectors, total **480** vectors

Methods Used to Balance the dataset (Training Dataset)

1. **SMOTE(Synthetic Minority Over-sampling Technique)**
 - a. Taking 3 more synthetic samples per original sample in minority class(3*60)
 - b. 3 Different neighbors are used to generate 3 different points
 - c. Total class of 240 is created
 - d. Taking more synthetic samples may lead to over-generalization if samples are far from original space, or overtraining if samples are close to one another.
2. **K-nearest neighbors Cluster Classification:**
 - a. Down-sampling majority class based on clustering
 - b. 20 different clusters are used and 12 vectors from each class taken
 - c. Taking less samples may lead to loss of information
3. Combined data is used for Training purpose

Test Data-Set:

1. All remaining Vectors from above process taken into Test Data-set.
2. **23 AEP-Class vectors, 2242 non-AEP Class**
3. Ignoring some vectors from available dataset can be misleading. Hence, All dataset is used either for Training or for Testing purpose.

Case #1: Base Case (Without Bias)

EPOCH Iterations = 10000

LRATE= 0.00009/SIZE_TRAIN;

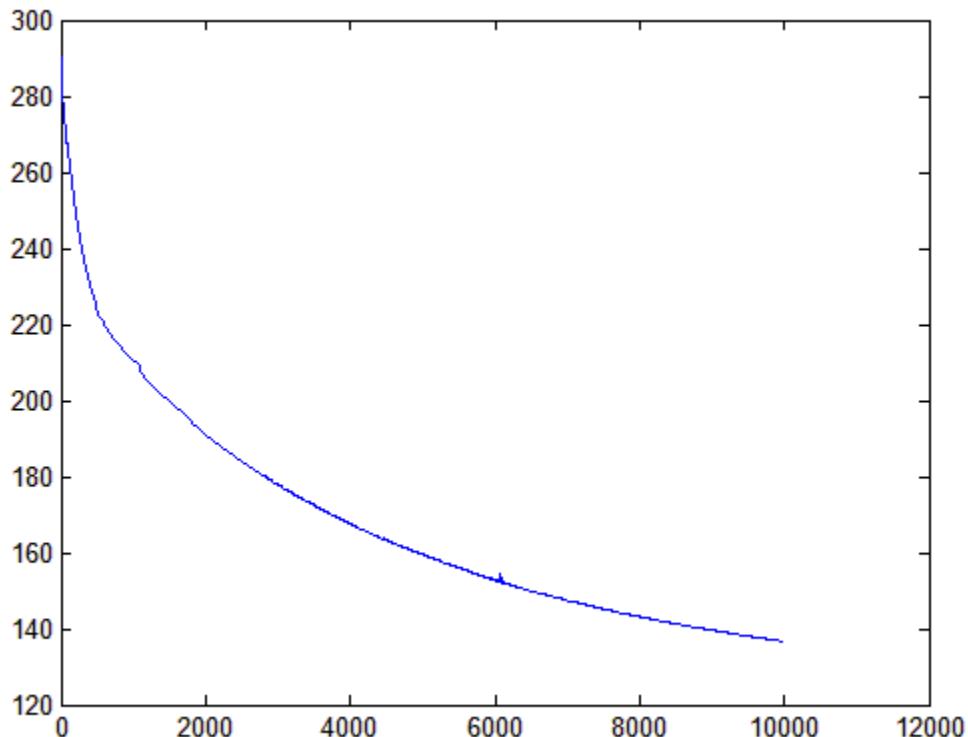
ETSS=737.0998

Specificity= TN/(TN+FP)= 0.6713

Sensitivity= TP/(TP+FN) = 0.9130

Learning Rate: Learning Rate is chosen in every case so that:

1. We will have minimal oscillations in E per Iterations graphs
2. Training converges fast enough for good Sensitivity-Specificity Values
3. Depends on Size of training dataset, as we add deltas together. Hence SIZE_TRAIN is used in LRATE equation to make algorithm dynamic for any training dataset
4. Learning Rate selected here is 0.0009/SIZE_TRAIN. This allows smooth variations in the weight space
5. Random Weight Initialization: Weights are selected such that no output should stuck at saturation, at least in initial iterations .



CASE # 2: (With Bias)

ETSS= 836.9497

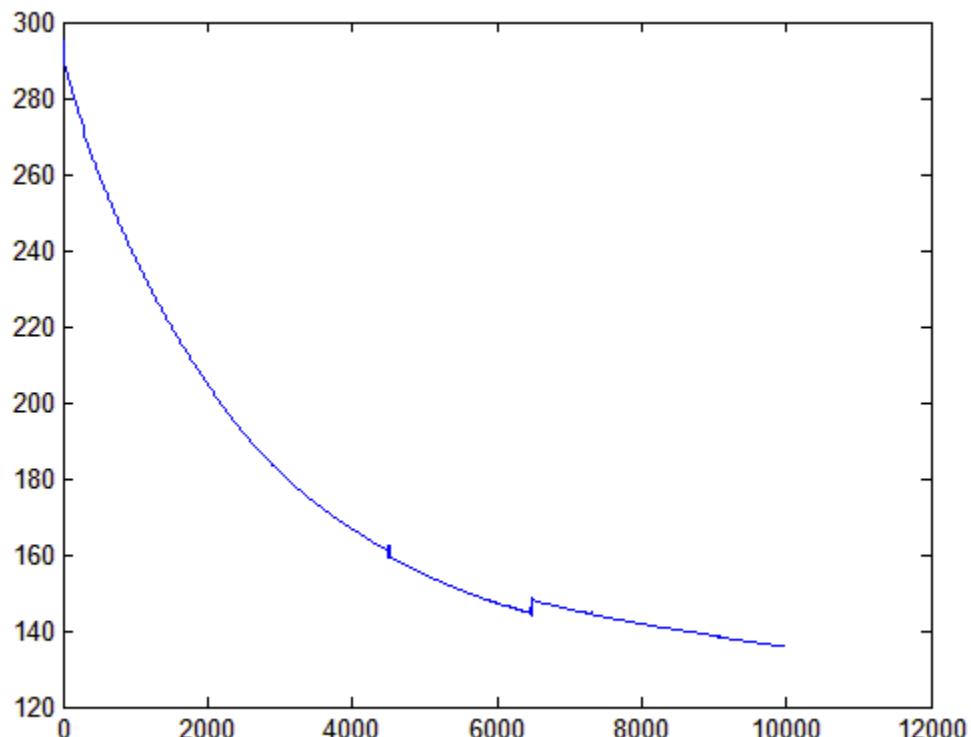
Sensitivity=0.9130

Specificity=0.6713

Iterations= 10000

Learning Rate= 0.00009/SIZE_TRAIN

Using Bias allows quicker convergence for good results.



CASE # 3: ROM Weight Initialization

ETSS= 1051.8

Sensitivity= 0.9130

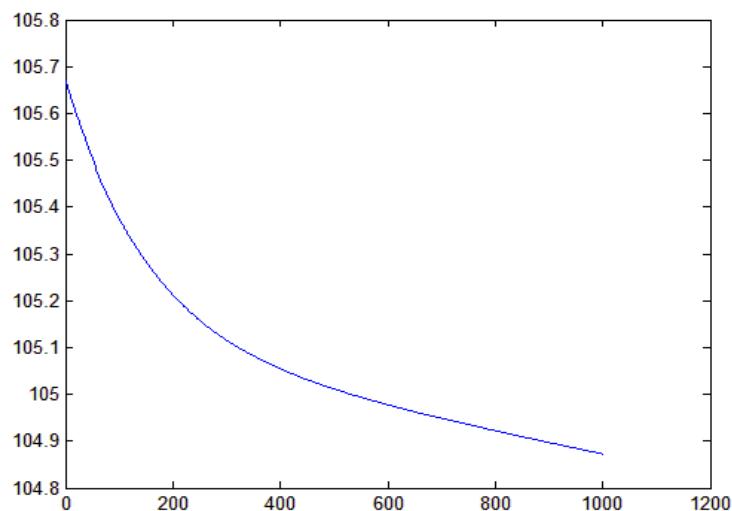
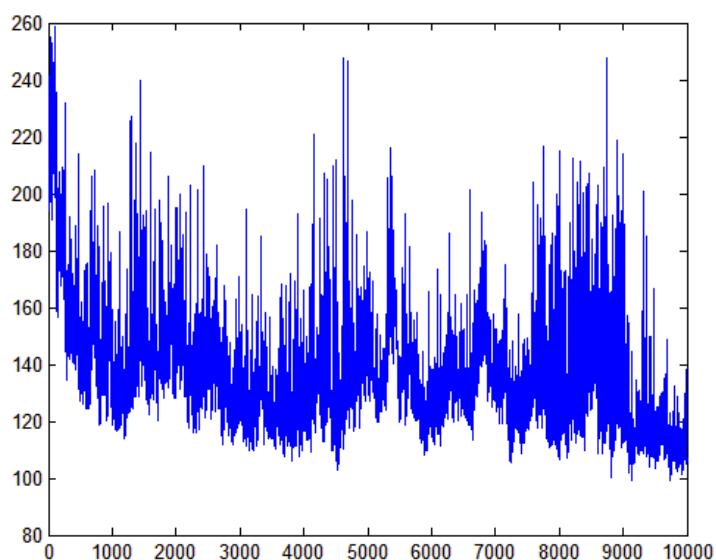
Specificity= 0.6481

ROM Iterations = 10000

Gradient Descent iterations = 1000;

LRATE= 0.0002/SIZE_TRAIN

Figures: 1. ETSS vs ROM Iterations 2. ETSS vs GDR



Case#4: Momentum

Common Parameters:

Weights_initial: from ROM

Iterations=15000

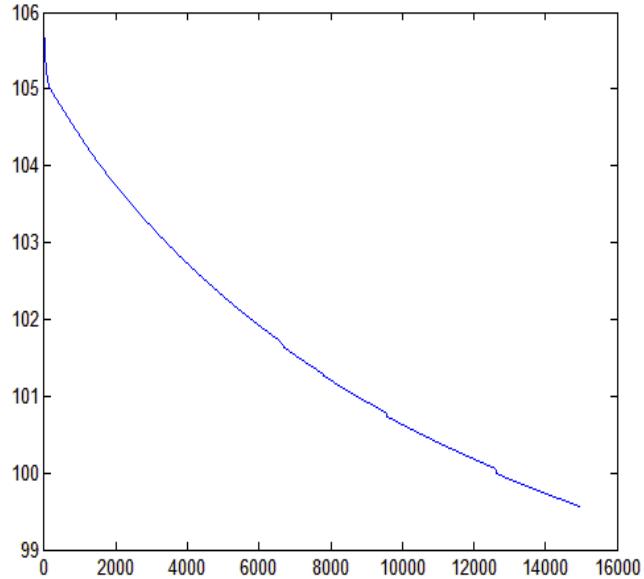
LRATE=0.0006/SIZE_TRAIN

Without momentum:

Sensitivity= 0.9130

Specificity= 0.5607

ETSS = 1240;



With momentum

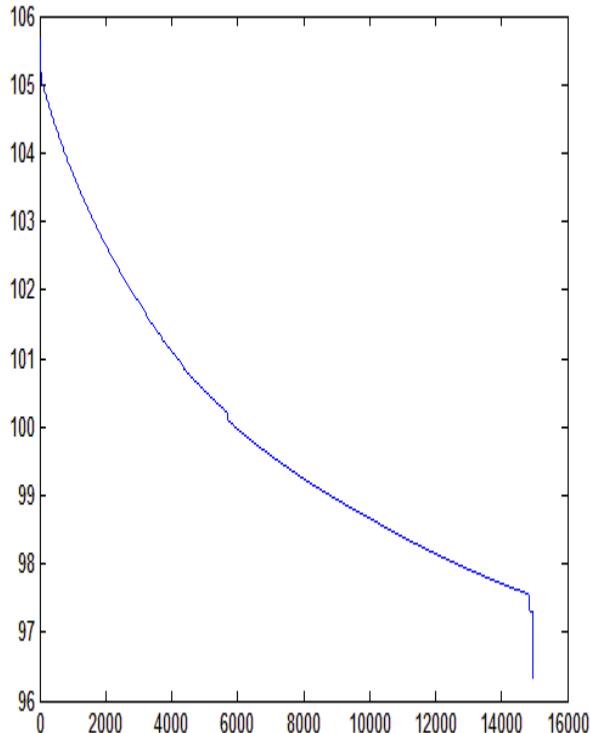
ETSS 1215.8

Sensitivity= 0.9130

Specificity= 0.5682

Alpha for Momentum = 0.52

As we can see, momentum allows weights to converge faster at local minima



Case # 5: Weight Decay

Common Parameters:

Weight Initialization : From ROM

LRATE = 0.00005/SIZE_TRAIN

Epoch Iterations = 10000

Without Weight decay

ETSS= 1270.05

Sensitivity= 0.9130

Specificity= 0.5522

WITH Weight Decay:

WEIGHTS_initial: ROM

With Weight Decay :

Beta=0.99999

Sensitivity= 0.9130

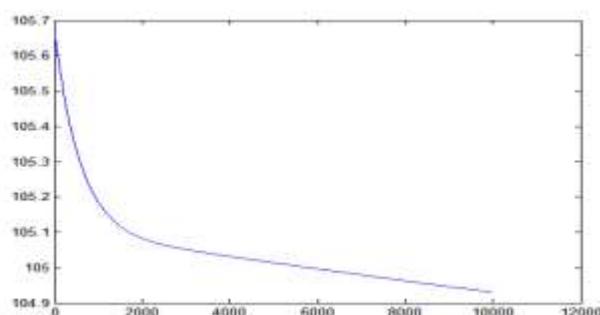
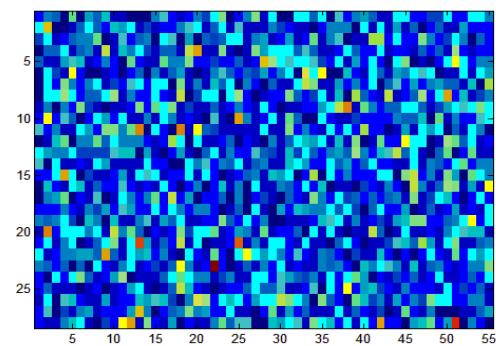
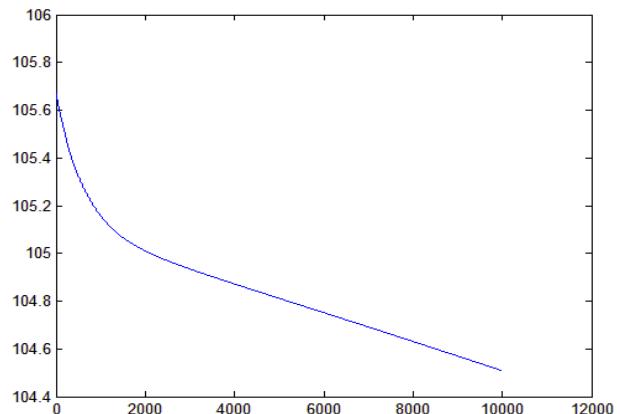
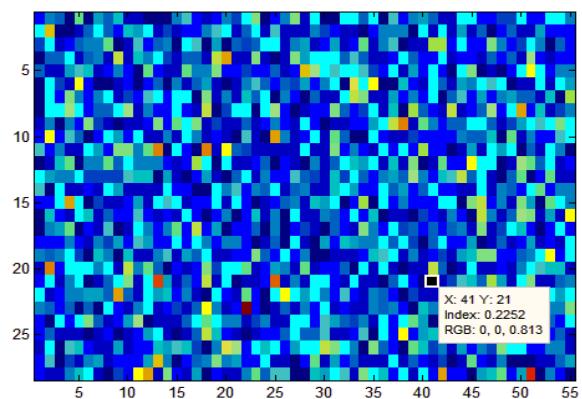
Specificity = 5526

ETSS= 1247.6

Figures:

1,3: Imagesc op of absolute weights

2,4: ETSS vs iterations



Case 6 Karnin:

Method of pruning: By 5 percent, based upon abs(S) values:

Abs(S) value gives sensitivity of the Weight wrt Error. Hence it is used to prune the network. 5 percent weights in 28×55 weights are pruned whose sensitivities were lowest.

Without pruning:

ROM weight initialization (Same as case 3)

GDR Epoch iterations= 10000

Sensi 0.9130

Speci 5522

ETSS 1270.5

LRATE=0.00005/SIZE_TRAIN

Same except

Sensitivity 9565

Specificity 4349

ETSS 1588.4

Figures:

1. Abs(weights) after Pruning
2. Abs(weights) before Pruning
3. Weight Sensitivities
4. E per Iterations: retesting network

