

# CHINMAY AMRUTKAR

[chinmay.amrutkar@asu.edu](mailto:chinmay.amrutkar@asu.edu) | 623-217-7539 | 1255 E University Dr, Tempe, AZ  
[www.linkedin.com/in/chinmay-amrutkar-153375209](https://www.linkedin.com/in/chinmay-amrutkar-153375209)

## Education

### Arizona State University (Tempe, AZ)

Aug 2024 – Present

Master of Science in **Robotics and Autonomous Systems in AI**

### MIT World Peace University (Pune, India)

Aug 2019 – May 2023

Bachelor of Technology, **Robotics and Automation** (CGPA: 9.77/10)

## Work Experience

### Jabil Circuit India Private

Pune, India

#### Graduate Engineer Trainee

Jan 2024 – July 2024

- Integrated Jabil Eye computer vision technology at component inspection stage, resulting in a 70% increase in defect detection and reduced rework.
- Conceived and developed a temperature monitoring and cooling system to optimize PCB post-wave soldering, resulting in 27% reduction in cycle time.
- Pioneered an automated ESD wristband monitoring system, ensuring strict adherence to industry standards and significantly reducing the risk of electrostatic discharge (ESD) damage to sensitive components.
- Developed a real-time production monitoring dashboard utilizing data mining and processing techniques, resulting in a 60% increase in production visibility and enabling data-driven decision-making.
- Effectively collaborated and coordinated with cross-functional teams to understand their exact requirement and develop tailored solutions.

### Hexagon Manufacturing Intelligence

Pune, India

#### R&D Intern

Feb 2023 – Aug 2023

- Achieved expertise in end-to-end software testing, including the creation of 1000+ manual test cases and further automated it using Sikuli as an OCR tool.
- Developed a tool for generating scripts required for test automation. This tool enabled non-coders to generate test automation scripts, resulting in increased efficiency and productivity.
- Acquired a deep understanding of both Virtual Test Drive Software and MSC Adams Software.

## Projects

### Design and Prototyping of Robotic Arm for Waste Sorting using Computer Vision

Sep 2022 – Nov 2022

- Trained a YOLOv7 model on a dataset of 2000+ images, achieving 47% object detection accuracy for glass, paper, cardboard and tin cans (recyclable waste).
- Designed and prototyped a 3 DOF Robotic Arm with Arduino control, capable of handling payload up to 200 grams.

## Skills

- **Software:** Adams, Virtual Test Drive, SolidWorks, Fusion 360, MATLAB, MS Office
- **Programming Languages:** Python, C++, C, Java

## Publications

- "Overview of Autonomous Vehicles and Its Challenges", *Techno-Societal 2022. ICATSA 2022. Springer, Cham*
- "A state-of-the-art review on robotics in waste sorting: scope and challenges", *International Journal on Interactive Design and Manufacturing (IJIDeM)*, vol. 17, 2789–2806 (2023)

## Leadership and Volunteer Work

### Team Captain – Design and Manufacturing of Electric Vehicles

Jan 2020 - Jan 2023

- Led a team of 14 members having cross-functional teams like CAD/CAE, Manufacturing, Chassis, Braking, and Suspension. Resulting to a first-place finish for acceleration category in electric vehicle design competition.

### Robotics Instructor, Volunteer

Jan 2023

- Successfully led hands on learning program in robotics and IoT to enhance technological skills in rural India.